

Mercer's Theorem and Fredholm resolvents

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Multivariate versions of Mercer's Theorem and the usual expansions of the resolvent and Fredholm determinant are shown to hold for an $n \times n$ symmetric kernel $N(x, y)$ with arbitrary domain in \mathbb{R}^D under weakened continuity conditions. Further, the resolvent and determinant of $N(x, y) - a(x)b(y)$ are given in terms of those of $N(x, y)$.

1. Introduction

Our main result, given in §3, deals with eigenfunction expansions of the $n \times n$ matrix kernel $N(x, y)$ (Mercer's Theorem) and its iterates $N_j(x, y)$ and resolvent $N(x, y, \lambda)$. As well as allowing n to be arbitrary and the domain to be unbounded, we weaken the usual continuity assumptions of this important theorem, which has found applications in optimum detection theory (for example, Deutsch [2], p. 244) and statistics. These expansion formulae are basic to the study of the distribution of the random variable $\int |X(t)|^2 dt$ where $X : \mathbb{R}^D \rightarrow \mathbb{R}^n$ is a Gaussian process with covariance N . Such random variables arise in connection with the asymptotic distribution and power of certain statistical tests; see Withers [8].

In §4 we give a simple but useful result: formulae for the resolvent and Fredholm determinant of $N(x, y) - a(x)b(y)$ in terms of those of $N(x, y)$, where $a(x), b(y)$ are $n \times q$ and $q \times n$ functions. This

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section was motivated by the study of the random variable $\int |Y(t)|^2 dt$ where

$$Y(t) = X(t) + f(t) \int g(x)X(s)ds ,$$

and f, g are matrix functions, and X is as above; see Withers [9] for statistical applications where such variables arise naturally. The basic results of Fredholm integral equation theory for a matrix kernel $N(x, y)$ defined on a domain $\Omega \times \Omega$ where Ω is an arbitrary domain in p -dimensional euclidean space R^p appear to have been stated only for the case $n = p = 1$ and Ω a bounded interval. However the technique of deducing these results for general n is well known and some authors have realised such extensions are possible (cf. Riesz and Nagy [6], p. 145), although others have suggested that Ω must be bounded (cf. Pogorzelski [5], p. 95). We therefore begin with a summary of these results for general n and arbitrary domain in R^p .

2. Some basic results

We give here generalisations of some basic results. These are easily deduced by the method of Carleman [1] (given for $n = p = 1$, $\Omega = [a, b]$, N real), the technique of reducing to $n = 1$ (for example, Pogorzelski [5], p. 181) and the standard proofs.

Throughout this paper we shall use A^* to denote the conjugate transpose of a complex matrix $A = (A_{ij})$, and $\|\cdot\|$ to denote the norm defined by $\|A\|^2 = \sum |A_{ij}|^2$. All integrals will be with respect to Lebesgue measure over Ω , an arbitrary subset of R^p .

Given $\Omega \subset R^p$ consider a complex measurable $n \times n$ function $N(x, y)$ on $\Omega \times \Omega$ such that

$$(1) \quad 0 < \iint \|N(x, y)\|^2 dx dy < \infty .$$

For f a complex measurable $n \times q$ function on Ω such that

$$\|f\|^2 < \infty , \text{ let } Nf(x) = \int N(x, s)f(s)ds \text{ and } f(y)^*N = \int f(s)^*N(s, y)ds .$$

Let $N_j = N^{j-1}N$, $j \geq 1$, where $N^0 = I$, the identity operator.

Then $N(x, y, \lambda)$, the *resolvent* of $N(x, y)$ exists and for y in Ω , $h(x) = N(x, y, \lambda)$ is the unique solution of

$$h = N(\cdot, y) + \lambda N h,$$

and for x in Ω , $g(y) = N(x, y, \lambda)$ is the unique solution of

$$g = N(x, \cdot) + \lambda g N.$$

When

$$(2) \quad \sum \int |N_{ii}(x, x)| dx < \infty,$$

then the *Fredholm determinant* $D(\lambda)$ exists and is given by

$$\frac{d}{d\lambda} \log D(\lambda) = - \int \text{trace } N(x, x, \lambda) dx, \quad D(0) = 1.$$

When

$$(3) \quad N^*(y, x) = N(x, y) \text{ for } x, y \text{ in } \Omega,$$

then there exist real numbers $\{\lambda_1, \lambda_2, \dots\}$ (*eigenvalues*) and complex n -vectors on Ω , $\{\phi_1, \phi_2, \dots\}$ (*eigenvectors*) satisfying

$$\lambda_i N \phi_i = \phi_i, \quad \int \phi_i^* \phi_j = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}, \quad 0 < |\lambda_1| \leq |\lambda_2| \leq \dots,$$

such that if

$$(4) \quad \lambda N \phi = \phi, \quad \int |\phi|^2 < \infty, \quad \phi \text{ } n \times 1,$$

then $\lambda = \lambda_k$ for some k , and ϕ is a linear combination of those ϕ_r such that $\lambda_r = \lambda$.

When (3) and

$$(5) \quad \sup_y \int \|N(x, y)\|^2 dx < \infty,$$

then for x in Ω , and almost all y in Ω ,

$$N(x, y, \lambda) = N(x, y) + \lambda \sum_1^{\infty} \left\{ \frac{\phi_{i_1}(x)\phi_{i_1}(y)^*}{\lambda_{i_1}(\lambda_{i_1}-\lambda)} \right\}, \quad \lambda \text{ not an eigenvalue,}$$

and

$$(6) \quad N_j(x, y) = \sum_1^{\infty} \lambda_{i_1}^{-j} \phi_{i_1}(x)\phi_{i_1}(y)^*, \quad j \geq 2,$$

and the convergence of these series is (element-wise) absolute and uniform in Ω^2

3. Mercer's Theorem

Mercer's Theorem concerns the expansion of N in terms of its eigenfunctions and eigenvalues:

$$N(x, y) = \sum \phi_{i_1}(x)\phi_{i_1}(y)^*/\lambda_{i_1}.$$

Statements of the theorem in the literature all make unnecessary continuity and other assumptions. For example sometimes (5) is assumed (for example, Pogorzelski [5], p. 150). Our aim here is to impose as few conditions on N as seems possible. It is worth noting that a useful weakening of our continuity assumptions (9)-(11) may be made by excluding from Ω the set of points P at which they do not hold, provided P has Lebesgue measure zero.

Our version of Mercer's Theorem is as follows.

THEOREM 1. *Suppose N satisfies (1), (3), and the following*

$$(7) \quad \int \phi^* N \phi = \iint \phi^*(x) N(x, y) \phi(y) dx dy \geq 0$$

for all complex $n \times 1$ functions ϕ such that $\int |\phi|^2 < \infty$,

$$(8) \quad \sup_{x \in \Omega} \text{trace } N(x, x) < \infty,$$

$$(9) \quad N(x, y) \text{ is continuous at } y = x \in \Omega,$$

$$(10) \quad N_2(x, x)_{ii} \text{ is continuous in } \Omega, \quad 1 \leq i \leq n,$$

$$(11) \quad N_2(x, y)_{ii} \text{ is continuous at } y = x \text{ in } \Omega, \quad 1 \leq i \leq n,$$

then for $\{\lambda_i, \phi_i\}$ above, $\{\phi_i\}$ are continuous and $\sum_1^\infty \lambda_i^{-1} \phi_i(x) \phi_i(y)^*$ converges (elementwise) absolutely and uniformly in Ω^2 and equals $N(x, y)$ almost everywhere in Ω^2 .

NOTES. (i) Since a uniformly convergent series of continuous functions converges to a continuous function, equality holds at continuity points of N , such as $x = y$.

(ii) Since (4) implies $\phi = \lambda^m N^m \phi$, (10) and (11) may be replaced by (11)¹ for some $m \geq 1$, $N_{2m}(x, y)_{ii}$ and $N_{2m}(x, x)_{ii}$ are continuous at $y = x$ for x in Ω , $1 \leq i \leq n$; (cf. Hobson [3] who gives for continuity of $\{\phi_i\}$);

(11)² for some $m \geq 1$, $N_m(x, y)$ is continuous in x for almost all y in Ω and for $j \geq m$, N_j is bounded.

Proof of Theorem 1. We may without loss take $n = 1$. $\{\phi_i\}$ are continuous because (4) implies

$$|\phi(x) - \phi(y)|^2 \leq |\lambda|^2 I(x, y) \int |\phi|^2,$$

where $I(x, y) = \int |N(x, s) - N(y, s)|^2 ds \rightarrow 0$ by (3), (10), (11).

By (9) and the standard method (for example, [5], p. 151), $N(x, x)$ and $N(x, x) - \sum_1^q \lambda_i^{-1} |\phi_i(x)|^2$ are real and non-negative for $q \geq 1$. Hence by (8) for $\epsilon > 0$, there exists M such that

$$\sum_M^\infty \lambda_i^{-1} |\phi_i(x)|^2 < \epsilon \text{ in } \Omega,$$

so that for $n_2 \geq n_1 \geq M$,

$$\sum_{n_1}^{n_2} \lambda_i^{-1} |\phi_i(x) \phi_i(y)^*| < \epsilon \text{ in } \Omega^2.$$

Hence $\sum \lambda_i^{-1} \phi_i(x) \phi_i(y)^*$ converges absolutely and uniformly in Ω^2 , so that by [5], pp. 130, 131, the sum equals $N(x, y)$ almost everywhere.

The usual expansions now follow:

COROLLARY. *Under the conditions of Theorem 1,*

$$(12) \quad \text{for } j \geq 1, \quad N_j(x, y) = \sum \lambda_i^{-j} \phi_i(x) \phi_i(y)^* \quad \text{almost everywhere in } \Omega^2,$$

$$(13) \quad N(x, y, \lambda) = \sum (\lambda_i - \lambda)^{-1} \phi_i(x) \phi_i(y)^* \quad \text{almost everywhere in } \Omega^2, \\ \text{if } \lambda \text{ is not an eigenvalue,}$$

$$(14) \quad \text{for } j \geq 1, \quad \int \text{trace } N_j(x, x) dx = \sum \lambda_i^{-j}, \quad (\text{possibly infinite for } j = 1), \\ \text{and the (elementwise) convergence in (12) and (13) is absolute and uniform.}$$

If also (2) holds, that is, $\int \text{trace } N(x, x) dx < \infty$, then

$$(15) \quad D(\lambda) = \prod_1^{\infty} (1 - \lambda/\lambda_i).$$

4. The kernel $N(x, y) - a(x)b(y)$

Carleman [1] gave expansions in λ for $D(x, y, \lambda)$ and $D(\lambda)$ for $N = G + H$ and $N = G \cdot H$ in terms of multiple integrals of determinants, akin to Fredholm's series. Here we give more convenient formulae for $K(x, y, \lambda)$ and $D_K(\lambda)$, the resolvent and Fredholm determinant for the particular case

$$K(x, y) = N(x, y) - a(x)b(y),$$

where we assume a, b are $n \times q$ and $q \times n$ functions on Ω such that

$$\int \|a\|^2 < \infty, \quad \int \|b\|^2 < \infty,$$

when $D_N(\lambda)$, $N(x, y, \lambda)$ are known, and where we set $D_N(\lambda) = D(\lambda)$ to avoid confusion with $D_K(\lambda)$.

THEOREM 2. *Let N satisfy (1) and (2). Let T denote the operator*

$(I-\lambda N)^{-1}$ so that

$$T\alpha(x) = a(x) + \lambda \int N(x, y, \lambda)a(y)dy$$

and

$$b(x)T = b(x) + \lambda \int b(y)N(y, x, \lambda)dy .$$

Let $B(\lambda) = 1_q + \lambda \int bT\alpha$, where $1_q = \text{diag}(1, \dots, 1)$. Then

$$(16) \quad K(x, y, \lambda) = N(x, y, \lambda) - T\alpha(x)B(\lambda)^{-1}b(y)T ,$$

for x, y in Ω and $D_K(\lambda) \neq 0$. Also

$$(17) \quad D_K(\lambda) = D_N(\lambda) \cdot \det B(\lambda) .$$

Further, if $\det B(\lambda) = 0$, then eigenfunctions of K with eigenvalue λ all have the form Tac where $c \neq 0$ is a q -vector such that

$$B(\lambda)c = 0 .$$

NOTE. Michlin [4] has given a special case of (16) without proof.

Proof. Suppose $D_N(\lambda) \neq 0$ and $D_K(\lambda) = 0$.

Then $f = \lambda Kf$ has a non-trivial solution where

$$Kf(x) = \int K(x, y)f(y)dy . \text{ Hence } c = \int bf \neq 0 \text{ and } f = -\lambda Tac . \text{ Hence } \det B(\lambda) = 0 .$$

Suppose $D_N(\lambda) \cdot \det B(\lambda) \neq 0$. Then $D_K(\lambda) \neq 0$ and for h such that

$$\int |h|^2 < \infty , \quad f = h + \lambda Kf \text{ has solution}$$

$$f = (I-\lambda K)^{-1}h = T(h-\lambda ac) .$$

Hence $c = Rh$ where $R = B(\lambda)^{-1}bT$, so that $(I-\lambda K)^{-1} = T(I-\lambda aR)$, which proves (16).

If $D_K(\lambda)D_N(\lambda) \neq 0$,

$$\begin{aligned} \frac{d}{d\lambda} \log(D_K(\lambda)/D_N(\lambda)) &= - \int \text{trace}(K(x, x, \lambda)-N(x, x, \lambda))dx \\ &= \text{trace } B(\lambda)^{-1}C, \text{ by (14),} \end{aligned}$$

where $C = \int bT^2 a$. For $|\lambda|$ small,

$$\frac{d}{d\lambda} \lambda T = I + 2\lambda N + 3\lambda^2 N^2 + \dots = T^2,$$

so that $C = d/d\lambda B(\lambda)$ for all λ by analytic continuation. (17) follows.

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