

PERIODIC SOLUTIONS FOR $\dot{x} = Ax + g(x, t) + \epsilon p(t)$

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We wish to establish the existence of a periodic solution to

$$(1) \quad \dot{x} = Ax + g(x, t) + \epsilon p(t), \quad (\dot{} \equiv d/dt)$$

where x, g and p are n -vectors, A is an $n \times n$ constant matrix, and ϵ is a small scalar parameter. We assume that g and p are locally Lipschitz in x and continuous and T -periodic in t , and that the origin is a point of asymptotically stable equilibrium, when $\epsilon = 0$.

Although the result below is not new ([1], [2]), the proof is simple and of some interest and provides an explicit bound on ϵ which will guarantee the existence of a T -periodic solution. It also gives a bound on the norm of the periodic solution.

In what follows, $\| \cdot \|$ denotes the Euclidean norm.

THEOREM. *If*

- (i) $p(t+T) = p(t)$ and $\|p(t)\| \leq 1$ for all t ,
- (ii) $g(x, t+T) = g(x, t)$ and $\|g(x, t)\| = o(\|x\|)$ uniformly in t ,
- (iii) the eigenvalues of A have negative real part, then (1) possesses a T -periodic solution for ϵ sufficiently small.

Proof. We wish to select the constant $c > 0$ such that the surface $V(x) = x^T B x = c^2$ confines interior trajectories, where B is the unique, real, symmetric, positive definite matrix which satisfies $A^T B + B A = -I$ (I , the unit matrix). Assuming the existence of such a constant, we may apply Brouwer's fixed point theorem to the region $V(x) \leq c^2$ and conclude that a fixed point exists for the transformation $x(t_0) \rightarrow x(t_0 + T)$, where $x(t_0)$ is in $V \leq c^2$ and is the initial condition for a solution $x(t)$ which remains in $V \leq c^2$. Since (1) is invariant with respect to a time translation of amount T , this fixed point will generate a T -periodic solution to (1).

We show that a constant c does exist.

Let $\lambda > 0$ and Λ be the smallest and largest eigenvalues of B , respectively. Then $\lambda \|x\|^2 \leq x^T B x \leq \Lambda \|x\|^2$ so that $V(x) = c^2$ lies in

$$(2) \quad c/\sqrt{\Lambda} \leq \|x\| \leq c/\sqrt{\lambda}$$

In order that the surface $V = c^2$ confine interior trajectories, it is sufficient to have $dV/dt < 0$ everywhere on the surface.

We have

$$dV/dt = -x^T x + 2(g^T + \epsilon p^T) B x.$$

Now $\|Bx\| \leq \Lambda\|x\|$, so that

$$dV/dt \leq -\|x\|^2 + 2(\|g\| + \epsilon)\Lambda\|x\|.$$

Hence $dV/dt < 0$ provided

$$(3) \quad \|x\| > 2\Lambda[\|g(x, t)\| + \epsilon].$$

We now show that, for ϵ sufficiently small, a c exists such that (2) implies (3). It will then follow that $V=c^2$ lies in a region where $dV/dt < 0$, hence will confine interior trajectories.

Since $\|g\| = o(\|x\|)$, then, for any $0 < k < 1$, $\Delta(k)$ exists such that $2\Lambda\|g\| < k\|x\|$ for $\|x\| < \Delta$. Hence, if x is restricted to the region

$$(4) \quad 2\epsilon\Lambda/(1-k) \leq \|x\| < \Delta$$

we will have $\|x\| \geq k\|x\| + 2\epsilon\Lambda > 2\Lambda[\|g\| + \epsilon]$ and (3) will be satisfied.

Note that (4) imposes an upper bound on ϵ , namely $\epsilon < (1-k)\Delta/2\Lambda$.

We now select c such that $V=c^2$ lies entirely in the region defined by (4), where $dV/dt < 0$. Using (2), we choose

$$(5) \quad 2\epsilon\Lambda\sqrt{\Lambda}/(1-k) \leq c < \Delta\sqrt{\Lambda}.$$

This is possible if

$$(6) \quad \epsilon < [(1-k)\Delta/2\Lambda]\sqrt{\Lambda/\Lambda}.$$

Consequently, if ϵ satisfies (6), for some $0 < k < 1$, then $V=c^2$ confines interior trajectories, where c is any number satisfying (5). Q.E.D.

Note that $V=c^2$ confines interior trajectories regardless of whether or not $p(t)$ and $g(x, t)$ are periodic. Indeed we can have $p=p(x, t)$, with $\|p\| \leq 1$ for all x and t . Also, if $x=\phi(t)$ is the periodic solution, then $\phi^T B \phi \leq c^2$, which gives an upper bound on the amplitude, namely $\|\phi\| \leq c/\sqrt{\Lambda}$.

Further, for $\epsilon=0$, (3) gives an estimate of the region of asymptotic stability for the null solution of $\dot{x}=Ax+g$. Also, for the linear system $\dot{x}=Ax+\epsilon p(t)$, $\dot{V} < 0$ for $\|x\| > 2\epsilon\Lambda$ from (3) and all solutions eventually enter the interior of $x^T B x = c^2$ with $c > 2\epsilon\Lambda\sqrt{\Lambda}$.

Note that

$$\dot{x} = B(t)x + g(x, t) + \epsilon p(t), \quad \text{with } B(t+T) = B(t),$$

reduces to the form (1) under the transformation $x=Q(t)y$ where $Q(t+T)=Q(t)$ is obtained from the principal matrix solution for $\dot{X}=B(t)X$ (i.e. $X=Q e^{At}$).

One further point of interest is that the number k is arbitrary, in $(0, 1)$. Note that the upper bound on ϵ , from (6), vanishes at $k=1$ and $k=0$ (in the latter case, $\Delta=0$). Presumably k might be chosen to maximize $(1-k)\Delta(k)$.

For example, the forced van der Pol equation,

$$\dot{x} = y, \dot{y} = \mu(x^2 - 1)y - x + \epsilon p(t)$$

has

$$\|g\| = \mu x^2 |y| = \mu r^3 \cos^2 \theta |\sin \theta| \leq \frac{2\mu r^3}{3\sqrt{3}}$$

where $r = \sqrt{x^2 + y^2}$. Hence $\|g\| \leq kr/2\Delta$ for $r < \Delta = \sqrt{3\sqrt{3}/4\mu\Lambda} k^{1/2}$, and $(1-k)\Delta$ is maximized for $k = \frac{1}{3}$.

REFERENCES

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2. H. I. Freedman, *Estimates on the existence region for periodic solutions of equations involving a small parameter*, SIAM J. Appl. Math. **16** (1968), 1341–1349.

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