



RESEARCH ARTICLE

Rigidity of symmetric simplicial complexes and the lower bound theorem

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Abstract

We show that if Γ is a point group of \mathbb{R}^{k+1} of order two for some $k \geq 2$ and \mathcal{S} is a k -pseudomanifold which has a free automorphism of order two, then either \mathcal{S} has a Γ -symmetric infinitesimally rigid realisation in \mathbb{R}^{k+1} or $k = 2$ and Γ is a half-turn rotation group. This verifies a conjecture made by Klee, Nevo, Novik and Zheng for the case when Γ is a point-inversion group. Our result implies that Stanley’s lower bound theorem for centrally symmetric polytopes extends to pseudomanifolds with a free simplicial automorphism of order 2, thus verifying (the inequality part of) another conjecture of Klee, Nevo, Novik and Zheng. Both results actually apply to a much larger class of simplicial complexes – namely, the circuits of the simplicial matroid. The proof of our rigidity result adapts earlier ideas of Fogelsanger to the setting of symmetric simplicial complexes.

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1. Introduction

Let \mathcal{S} be an abstract simplicial k -complex with vertex set $V(\mathcal{S})$ and edge set $E(\mathcal{S})$. The lower bound theorem concerns the quantity $g_2(\mathcal{S})$ defined by

$$g_2(\mathcal{S}) = |E(\mathcal{S})| - (k + 1)|V(\mathcal{S})| + \binom{k + 2}{2}. \quad (1.1)$$

Barnette [3] showed that $g_2(\mathcal{S}) \geq 0$ if \mathcal{S} is the boundary complex of a $(k + 1)$ -dimensional convex polytope. This was later generalised to simplicial spheres (Stanley [18]) and pseudomanifolds (Kalai [10], Tay [20]).

Readers familiar with the rigidity theory of bar-joint frameworks will note that the right-hand side of (1.1) arises naturally in that theory and indeed is nonnegative if the 1-skeleton of \mathcal{S} is a generically rigid graph in \mathbb{R}^{k+1} . This was proved by Asimov and Roth [2]. This connection between rigidity theory and polytopal combinatorics, noted by Kalai [10] and Gromov [8], has been fundamental to much of the work on lower bound theorems for various classes of simplicial complexes.

Around the same time as [10], Fogelsanger proved that the 1-skeleton of a minimal homology k -cycle is generically rigid in \mathbb{R}^{k+1} for $k \geq 2$ [7]. It is not difficult to see that a k -pseudomanifold is a minimal homology k -cycle; see Section 3 for definitions. Thus, Fogelsanger's result provides a generalisation and independent proof of the lower bound theorem for pseudomanifolds. Fogelsanger's proof technique is different to the previous proofs of the lower bound theorem: it is a direct proof based on a rigidity lemma of Whiteley for vertex splitting [23], and an ingenious decomposition result (more on this below).

In the present paper we consider \mathbb{Z}_2 -symmetric simplicial complexes (i.e., simplicial complexes \mathcal{S} with a free automorphism of order two). Such complexes were referred to as centrally symmetric simplicial complexes in [11]. The term \mathbb{Z}_2 -symmetric is more suitable for our purposes since we will consider realisations of k -dimensional complexes in \mathbb{R}^{k+1} which have an arbitrary symmetry of order two, not just a point inversion through the origin.

Note that if P is a centrally symmetric simplicial polytope in \mathbb{R}^{k+1} , that is, $-P = P$, then the boundary complex of P is a \mathbb{Z}_2 -symmetric simplicial complex of dimension k . Stanley [19] showed, in particular, that if \mathcal{S} is the boundary complex of such a polytope, then

$$g_2(\mathcal{S}) \geq \binom{k + 1}{2} - (k + 1). \quad (1.2)$$

Later, Sanyal, Werner and Ziegler [13] used a rigidity-based approach to obtain further properties of the f -vector of centrally symmetric polytopes. In particular, their results imply that (1.2) follows from an earlier rigidity result of Whiteley [22] that the 1-skeleton of every convex $(k + 1)$ -polytope is infinitesimally rigid in \mathbb{R}^{k+1} . More recently, Klee, Nevo, Novik and Zheng [11] used techniques from rigidity theory to characterise the cases for which equality can hold in Stanley's Theorem. While centrally symmetric simplicial polytopes have been the topic of much research since Stanley's paper, the extension of this theory from simplicial polytopes to more general families of simplicial complexes is less developed than in the non-symmetric case. One significant result in that direction is the recent proof by Novik and Zheng of the \mathbb{Z}_2 -symmetric upper bound conjecture for simplicial spheres [12]. In this paper, we address the lower bound conjecture for a larger class of \mathbb{Z}_2 -symmetric simplicial complexes – namely, the circuits of the simplicial matroid. Precise definitions will be given in Section 3, but for now, it suffices to note that a simplicial k -circuit is a minimal homology k -cycle over \mathbb{Z}_2 in Fogelsanger's terminology.

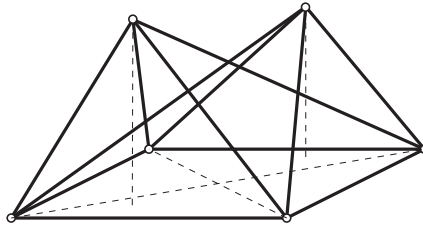


Figure 1. The Bricard octahedron.

Our approach is to extend Fogelsanger’s rigidity theorem and proof techniques to the \mathbb{Z}_2 -symmetric setting. The extension is not straightforward and, in particular, makes use of a new notion of a framework with partial symmetry which we have not seen in the rigidity literature. Our extension of Fogelsanger’s decomposition technique is powerful enough to show that the graph of any \mathbb{Z}_2 -symmetric simplicial k -circuit can be realised as an infinitesimally rigid framework having a specified point group symmetry of order two in \mathbb{R}^{k+1} , unless $k = 2$ and the point group is the half-turn rotation group in \mathbb{R}^3 .

We shall see that when $k = 2$ and the point group is the half-turn rotation group in \mathbb{R}^3 , every symmetric realisation of a \mathbb{Z}_2 -symmetric planar graph is infinitesimally flexible. The smallest such example is the famous Bricard octahedron [4], given in Figure 1. The Bricard octahedron was the source of inspiration for Connelly’s flexible polytope [5]. More generally, the rigidity of symmetric and non-convex realisations of 1-skeletons of polytopes has been one of the central topics in rigidity theory; see, for example, [17, 14]. We believe that our rigidity theorem will have a substantial impact in rigidity theory because it gives the first extension of rigidity results on symmetric convex polytopes to a more general family including non-convex symmetric realisations of polytopes and a larger family of simplicial complexes that includes pseudomanifolds.

The paper is organised as follows. We first give preliminary facts on the infinitesimal rigidity of frameworks under a point group symmetry in Section 2. In Section 3, we review Fogelsanger’s decomposition technique for simplicial circuits using an approach from [6]. We then provide an extension of Fogelsanger’s rigidity theorem to realisations of simplicial k -circuits in which several pairs of vertices are constrained to lie symmetrically in \mathbb{R}^{k+1} . In Section 5, we extend Fogelsanger’s decomposition result to \mathbb{Z}_2 -symmetric simplicial k -circuits and use this to prove our main theorem on the rigidity of \mathbb{Z}_2 -symmetric simplicial circuits. The application to the lower bound theorem is given in Section 6. We close the paper by giving some final remarks and open problems in Section 7.

2. Preliminaries on rigidity and symmetry

In this section, we introduce some basic results on the infinitesimal rigidity of frameworks and their extensions to the symmetric case.

Throughout the paper, we use the following basic conventions and notation. All graphs considered will be finite, undirected and simple (i.e., without loops or multiple edges). For $X \subseteq V(G)$, let $E_G[X] = \{uv \in E(G) : u, v \in X\}$. The subgraph of G induced by X is given by $G[X] = (X, E_G[X])$. For $v \in V(G)$, $N_G(v)$ denotes the set of vertices adjacent to v in G .

2.1. Infinitesimal rigidity

A graph drawn in Euclidean space with straight line edges is called a (*bar-joint*) *framework* and denoted by a pair (G, p) of the graph G and the point configuration $p : V(G) \rightarrow \mathbb{R}^d$. We will also refer to (G, p) as a *realisation* of G in \mathbb{R}^d .

An *infinitesimal motion* of a framework (G, p) is a map $\dot{p} : V(G) \rightarrow \mathbb{R}^d$ satisfying

$$(p(i) - p(j)) \cdot (\dot{p}(i) - \dot{p}(j)) = 0 \quad (ij \in E(G)). \tag{2.1}$$

For a skew-symmetric matrix S and $t \in \mathbb{R}^d$, it is not difficult to check that \dot{p} defined by $\dot{p}(v) = Sp(v) + t$ ($v \in V(G)$) is an infinitesimal motion of (G, p) . Such an infinitesimal motion is called *trivial*. The framework (G, p) is *infinitesimally rigid* if every infinitesimal motion of (G, p) is trivial. We say that the graph G is *rigid* in \mathbb{R}^d if G has an infinitesimally rigid realisation in \mathbb{R}^d .

Since (2.1) is a system of linear equations in \dot{p} , we can represent it by a matrix of size $|E(G)| \times d|V(G)|$. This matrix is called the *rigidity matrix* $R(G, p)$ of (G, p) . The rows of $R(G, p)$ are indexed by edges of G . In addition, for each vertex $v \in V(G)$, we have a corresponding set of d columns. For an edge $uv \in E(G)$, the corresponding row of $R(G, p)$ has the d -dimensional vector $p(u) - p(v)$ in the column-set corresponding to u and $p(v) - p(u)$ in the column-set corresponding to u . All other entries of the row are zero.

When the affine span of $p(V(G))$ has dimension at least $d - 1$, the dimension of the space of trivial motions is $\binom{d+1}{2}$, so (G, p) is infinitesimally rigid if and only if $\text{rank } R(G, p) = d|V(G)| - \binom{d+1}{2}$. In particular, if (G, p) is infinitesimally rigid and G has at least d vertices, then

$$|E(G)| - d|V(G)| + \binom{d+1}{2} \geq 0. \tag{2.2}$$

Kalai [10] and Gromov [8] exploited the close relationship between (1.1) and (2.2) to use rigidity theory to prove their extensions of the Lower Bound Theorem. We will use a similar approach to obtain our lower bound theorem for \mathbb{Z}_2 -symmetric simplicial complexes.

2.2. Rigidity under symmetry

A *graph with a vertex pairing* is a pair $(G, *)$ of a graph G and a free involution $*$ acting on some $X \subseteq V(G)$. (Thus, $*$: $X \rightarrow X$ and satisfies $*(*(u)) = u$ and $*(u) \neq u$ for all $u \in X$.) We will denote $*(u)$ by u^* for each $u \in X$ and put $Y^* = \{u^* : u \in Y\}$ for all $Y \subseteq X$. In addition, for each $W \subset V(G)$, we put

$$X_W = (X \cap W) \cup (X \cap W)^*.$$

Then $*$ induces a free involution $*_W : X_W \rightarrow X_W$. We will simply denote $*_W$ by $*$ when W is clear from the context. Similarly, for a subgraph H of G , $(H, *_V(H))$ is simply denoted by $(H, *)$.

We will use the free involution $*$ to force a symmetry on the point configuration in a possible realisation of G . Let Γ be a point group of \mathbb{R}^d of order two – that is, a subgroup of $O(d)$ of order two. A Γ -*framework* is a triple $(G, *, p)$ of a graph G , a free involution $*$: $X \rightarrow X$ for some $X \subseteq V(G)$, and a point-configuration p such that $p(u^*) = \gamma(p(u))$ for all $u \in X$, where γ is the non-identity element in Γ . By ignoring $*$, $(G, *, p)$ can be considered as a realisation of G , and hence, we can apply the terminology from Section 2.1 to $(G, *, p)$. We will sometimes refer to a Γ -framework $(G, *, p)$ as a Γ -*symmetric realisation* of $(G, *)$. We say that $(G, *)$ is Γ -*rigid* if $(G, *)$ has an infinitesimally rigid Γ -symmetric realisation.

A Γ -framework $(G, *, p)$ is *generic* if the transcendence degree of the set of coordinates of all the points in $p(V)$ over \mathbb{Q} takes the maximum possible value $d(|V| - |X|/2)$. Thus, $(G, *)$ is Γ -rigid if and only if every (or equivalently, some) generic Γ -symmetric realisation of $(G, *)$ is infinitesimally rigid.

Example 2.1. This example illustrates that the Γ -rigidity of a fixed $(G, *)$ may depend on the group Γ . Consider the case when $d = 3$. Then there are three different types of point groups of order two corresponding to point inversion, rotation and reflection. Suppose that G is the graph of the octahedron and $*$ maps each vertex to its antipodal vertex. If Γ is a rotation group, then any Γ -framework $(G, *, p)$ is the 1-skeleton of a Bricard octahedron, which is infinitesimally flexible; see Example 2.3 below. Conversely, we will show that every generic Γ -framework $(G, *, p)$ is infinitesimally rigid when Γ is a point inversion or reflection group.

We will concentrate our attention on graphs G with a vertex pairing $*$: $X \rightarrow X$ with the property that $xx^* \notin E$ for all $x \in X$. We will refer to such a vertex pairing as a *non-adjacent vertex pairing*. Note

that if $* : X \rightarrow X$ is a non-adjacent vertex pairing of G , then the induced bijection $*_W : X_W \rightarrow X_W$ is again a non-adjacent vertex pairing of $G[W]$ for all $W \subseteq V(G)$.

We emphasise that a non-adjacent vertex pairing $* : X \rightarrow X$ need not, in general, induce an involution on the edge set $E[X]$. Our main concern, however, is the special case when $X = V(G)$ and $*$ is an automorphism of G without fixed edges. In this case, $(G, *)$ is said to be a $d\mathbb{Z}_2$ -symmetric graph. Since $*$ is an automorphism, $*(e)$ is well defined, and we abbreviate $*(e)$ by e^* for each edge e . We consider the more general class of graphs with a non-adjacent vertex pairing because it arises naturally in our analysis of the \mathbb{Z}_2 -symmetric case.

We next derive a stronger inequality than (2.2) for the number of edges in a Γ -rigid \mathbb{Z}_2 -symmetric graph. For integers $d \geq 1$ and $0 \leq t \leq d$, let $I_{t,d}$ be the diagonal matrix of size d whose first t diagonal entries are 1 and remaining $d - t$ diagonal entries are -1 . Let $\Gamma_{t,d}$ be the point group generated by $I_{t,d}$. Observe that if Γ is a point group of order 2 in \mathbb{R}^d , then we can always choose a coordinate system so that $\Gamma = \Gamma_{t,d}$ for some $0 \leq t \leq d - 1$.

Lemma 2.2. *Let $\Gamma = \Gamma_{t,d}$ where $0 \leq t \leq d - 1$. Suppose that a \mathbb{Z}_2 -symmetric graph $(G, *)$ is Γ -rigid and $|V(G)| \geq 2d$. Then*

$$|E(G)| \geq d|V(G)| - 2 \min \left\{ \binom{t+1}{2} + \binom{d-t}{2}, \binom{d+1}{2} - \binom{t+1}{2} - \binom{d-t}{2} \right\}. \tag{2.3}$$

Proof. Let $n = |V(G)|$ and $m = |E(G)|$. Since $(G, *)$ is Γ -rigid, there is a Γ -symmetric infinitesimally rigid realisation $(G, *, p)$ of $(G, *)$. Since $|V(G)| \geq 2d$, we can take such a realisation so that the affine span of $p(V(G))$ is at least $d - 1$. In particular, the space of trivial motions of $(G, *, p)$ has dimension $\binom{d+1}{2}$.

Recall that the rigidity matrix $R(G, p)$ represents a linear map from \mathbb{R}^{dn} to \mathbb{R}^m . We shall decompose \mathbb{R}^{dn} and \mathbb{R}^m into two subspaces whose elements are either symmetric or anti-symmetric with respect to Γ and $*$. Specifically, let

$$\begin{aligned} M_{\text{sym}} &:= \{ \dot{p} : V(G) \rightarrow \mathbb{R}^d \mid \dot{p}(u^*) = I_{t,d} \dot{p}(u) \text{ for all } u \in V(G) \}, \\ M_{\text{ant}} &:= \{ \dot{p} : V(G) \rightarrow \mathbb{R}^d \mid \dot{p}(u^*) = -I_{t,d} \dot{p}(u) \text{ for all } u \in V(G) \}, \\ S_{\text{sym}} &:= \{ w : E(G) \rightarrow \mathbb{R} \mid w(e^*) = w(e) \text{ for all } e \in E(G) \} \text{ and} \\ S_{\text{ant}} &:= \{ w : E(G) \rightarrow \mathbb{R} \mid w(e^*) = -w(e) \text{ for all } e \in E(G) \}. \end{aligned}$$

Then $\mathbb{R}^{dn} = M_{\text{sym}} \oplus M_{\text{ant}}$ and $\mathbb{R}^m = S_{\text{sym}} \oplus S_{\text{ant}}$. Observe further that the rigidity matrix maps M_{sym} to S_{sym} and M_{ant} to S_{ant} . Indeed, if $\dot{p} \in M_{\text{sym}}$, then for any edge $e = uv$, we have

$$\begin{aligned} (p(u^*) - p(v^*)) \cdot (\dot{p}(u^*) - \dot{p}(v^*)) &= (I_{t,d}(p(u^*) - p(v^*))) \cdot I_{t,d}(\dot{p}(u^*) - \dot{p}(v^*)) \\ &= (p(u) - p(v)) \cdot (\dot{p}(u) - \dot{p}(v)), \end{aligned}$$

which implies that the image of \dot{p} belongs to S_{sym} . A similar calculation shows the corresponding property for M_{ant} .

Let T be the space of trivial infinitesimal motions of (G, p) . A canonical basis of T consists of $\binom{d}{2}$ infinitesimal rotations about the subspaces spanned by each set of $(d - 2)$ axes and d translations along each axis. Due to the structure of $I_{t,d}$, it follows that the $\binom{t+1}{2}$ -dimensional space of isometries in the subspace spanned by the first t axes and the $\binom{d-t}{2}$ -dimensional space of rotations rotating in the subspace spanned by the last $d - t$ axes are contained in M_{sym} . One can also directly check that the remaining $\binom{d+1}{2} - \binom{t+1}{2} - \binom{d-t}{2}$ elements of the canonical basis belong to M_{ant} . Hence,

$$\dim T \cap M_{\text{sym}} = \binom{t+1}{2} + \binom{d-t}{2} \text{ and } \dim T \cap M_{\text{ant}} = \binom{d+1}{2} - \binom{t+1}{2} - \binom{d-t}{2}.$$

The infinitesimal rigidity of (G, p) implies that $\ker R(G, p) = T$. Since the rigidity matrix maps M_{sym} to S_{sym} and M_{ant} to S_{ant} , this gives

$$\begin{aligned} \frac{m}{2} &= \dim S_{\text{sym}} \geq \dim M_{\text{sym}} - \dim T \cap M_{\text{sym}} = \frac{dn}{2} - \left(\binom{t+1}{2} + \binom{d-t}{2} \right) \text{ and} \\ \frac{m}{2} &= \dim S_{\text{ant}} \geq \dim M_{\text{ant}} - \dim T \cap M_{\text{ant}} = \frac{dn}{2} - \left(\binom{d+1}{2} - \binom{t+1}{2} - \binom{d-t}{2} \right), \end{aligned}$$

as required. □

Example 2.3. Suppose a \mathbb{Z}_2 -symmetric graph $(G, *)$ is Γ -rigid in \mathbb{R}^3 . Then Lemma 2.2 implies

$$|E(G)| \geq 3|V(G)| - \begin{cases} 6 & \text{if } t = 0 \text{ i.e. } \Gamma \text{ is generated by a point inversion,} \\ 4 & \text{if } t = 1 \text{ i.e. } \Gamma \text{ is generated by a half turn rotation,} \\ 6 & \text{if } t = 2 \text{ i.e. } \Gamma \text{ is generated by a reflection.} \end{cases}$$

If G is the graph of the octahedron, $|E(G)| = 12$ and $|V(G)| = 6$. So it cannot be Γ -rigid if Γ is generated by a half turn rotation, which is the case of the Bricard octahedron.

Note that the case when $d = 3$ is exceptional since the right side of (2.3) is maximised at $t = 1$ when $d = 3$, and at $t = 0$ when $d \geq 4$.

The infinitesimal rigidity of frameworks having a point group symmetry is an extensively studied topic in rigidity theory. See, for example, [15, 16] for symmetric extensions of classical rigidity theorems.

2.3. Gluing properties

We write $\text{aff}(Y)$ for the affine span of a subset Y of \mathbb{R}^d and $\text{lin}(Y)$ for its linear span. The gluing properties of rigid frameworks and graphs are important ingredients in the proof of Fogelsanger’s Rigidity Theorem. For completeness, and since we cannot find an authoritative source for these results in the literature, we include details of these gluing properties in the classical non-symmetric setting.

Theorem 2.4. *Let (G, p) be a framework in \mathbb{R}^d . Suppose that G_1, G_2 are subgraphs of G such that $(G_i, p|_{V(G_i)})$ is infinitesimally rigid for $i = 1, 2$ and $\text{aff}(p(V(G_1) \cap V(G_2)))$ has dimension at least $d - 1$. Then (G, p) is infinitesimally rigid.*

Proof. Suppose that \dot{p} is an infinitesimal flex of (G, p) . By assumption, there exist skew symmetric matrices A_i of size d and $t_i \in \mathbb{R}^d$ for $i = 1, 2$ such that $\dot{p}(v) = A_i p(v) + t_i$ for $v \in V(G_i)$. We can choose coordinates so that $p(w) = 0$ for some $w \in V(G_1) \cap V(G_2)$. It follows that $A_1 0 + t_1 = \dot{p}(w) = A_2 0 + t_2$. Therefore, $t_1 = t_2$, and so $A_1 p(v) = A_2 p(v)$ for all $v \in V(G_1) \cap V(G_2)$. Therefore, the skew symmetric matrix $A_1 - A_2$ vanishes on a space of dimension $d - 1$, and so must be 0, as required. □

Corollary 2.5. *Let G_1 and G_2 be graphs that are both rigid in \mathbb{R}^d . Suppose that $|V(G_1) \cap V(G_2)| \geq d$. Then $G_1 \cup G_2$ is rigid in \mathbb{R}^d .*

Now we extend Corollary 2.5 to Γ -rigidity. First, we prove a lemma about the affine span of Γ -symmetric subsets of \mathbb{R}^d .

Lemma 2.6. *Let $\gamma = I_{t,d}$ for $0 \leq t \leq d - 1$. Suppose that P is a generic set of points in \mathbb{R}^d and $|P| = n$. Then $\dim(\text{aff}(P \cup \gamma(P))) = \min\{n, d - t\} + \min\{n - 1, t\}$.*

Proof. Let V , respectively W , be the eigenspace of γ corresponding to the eigenvalue 1, respectively -1 , and let π_V , respectively π_W , be the orthogonal projection from \mathbb{R}^d onto V , respectively W . Since P is generic in \mathbb{R}^d and π_V, π_W are projections onto coordinate subspaces, it follows that $\pi_V(P)$ is generic in V and $\pi_W(P)$ is generic in W . Therefore, $\dim(\text{aff}(\pi_V(P))) = \min\{n - 1, t\}$ and $\dim(\text{lin}(\pi_W(P))) = \min\{n, d - t\}$.

Claim 2.7. $\text{aff}(P \cup \gamma(P)) = \text{aff}(\pi_V(P)) + \text{lin}(\pi_W(P))$.

Proof of claim. Suppose $x = \sum_{q \in P \cup \gamma(P)} c_q q \in \text{aff}(P \cup \gamma(P))$ for scalars c_q with $\sum_q c_q = 1$. Now $x = \pi_V(x) + \pi_W(x)$ and $\pi_V(x) = \sum_{p \in P} (c_p + c_{\gamma(p)}) \pi_V(p)$ and $\pi_W(x) = \sum_{p \in P} (c_p - c_{\gamma(p)}) \pi_W(p)$. Since $\sum_{p \in P} (c_p + c_{\gamma(p)}) = \sum_{q \in P \cup \gamma(P)} c_q = 1$, it follows that $\text{aff}(P \cup \gamma(P)) \subset \text{aff}(\pi_V(P)) + \text{lin}(\pi_W(P))$.

To see the reverse containment holds, consider $\sum_{p \in P} d_p \pi_V(p) \in \text{aff}(\pi_V(P))$ and $\sum_{p \in P} b_p \pi_W(p) \in \text{lin}(\pi_W(P))$. Set $c_p = \frac{d_p + b_p}{2}$ and $c_{\gamma(p)} = \frac{d_p - b_p}{2}$ for each $p \in P$. Then $\sum_{q \in P \cup \gamma(P)} c_q = \sum_{p \in P} d_p = 1$. It follows that $\text{aff}(\pi_V(P)) + \text{lin}(\pi_W(P)) \subset \text{aff}(P \cup \gamma(P))$. □

The facts that $\text{aff}(\pi_V(P)) \subseteq V$, $\text{lin}(\pi_W(P)) \subseteq W$ and $V \cap W = \{0\}$ (since V, W are eigenspaces for distinct eigenvalues of γ) now give

$$\begin{aligned} \dim(\text{aff}(P \cup \gamma(P))) &= \dim(\text{aff}(\pi_V(P)) + \text{lin}(\pi_W(P))) = \dim \text{aff}(\pi_V(P)) + \dim \text{lin}(\pi_W(P)) \\ &= \min\{n, d - t\} + \min\{n - 1, t\}, \end{aligned}$$

as required. □

Theorem 2.8 (Gluing Theorem). *Let $\Gamma = \Gamma_{t,d}$ for $0 \leq t \leq d - 1$. Let $(G, *)$ be a graph with a vertex pairing $* : X \rightarrow X$. Suppose that $H_1 = (V_1, E_1)$ and $H_2 = (V_2, E_2)$ are subgraphs of G whose union is G and that, for $i = 1, 2$, $(H_i, *)$ is Γ -rigid in \mathbb{R}^d . Let $m = |X_{V_1} \cap X_{V_2}|$. Suppose that*

$$|V_1 \cap V_2| \geq d + m - 1 - \min\{m/2, d - t\} - \min\{m/2 - 1, t\}.$$

*Then $(G, *)$ is Γ -rigid.*

Proof. Let $(G, *, p)$ be a generic Γ -framework. Then, for $i = 1, 2$, $(H_i, *, p|_{V_i})$ is generic and therefore infinitesimally rigid. Now we observe that, by Lemma 2.6, the dimension of $\text{aff}(p(V_1 \cap V_2))$ is $\min\{|V_1 \cap V_2| - m + \min\{m/2, d - t\} + \min\{m/2 - 1, t\}, d\}$. The theorem now follows by applying Theorem 2.4 to the frameworks $(H_i, p|_{V_i})$, $i = 1, 2$. □

2.4. Vertex splitting

Whiteley’s Vertex Splitting Lemma [23, Proposition 1] is a fundamental result in rigidity theory and plays a key role in the proof of Fogelsanger’s Rigidity Theorem. We will derive a version of this lemma for Γ -rigidity.

First, we fix some terminology. Let G be a graph, $u \in V(G)$, $C \subset N_G(u)$ and $D \subset N_G(u) \setminus C$. Let G' be the graph obtained from G by deleting the edges uw for all $w \in D$, adding a new vertex u' and adding edges $u'z$ for all $z \in C \cup D \cup \{u\}$. We say that G' is obtained from G by splitting u' from u along C , or more succinctly, by vertex splitting at u .

The following theorem is one of the central results in rigidity theory. We include details of Whiteley’s original proof [23] for the benefit of readers who may not be familiar with it, and since one of our later variations is proved using essentially the same method.

Theorem 2.9 (Whiteley’s Vertex Splitting Theorem). *Let (G, p) be a framework in \mathbb{R}^d such that $R(G, p)$ is row-independent. Also, let $u \in V(G)$ and $C \subset N_G(u)$ such that $|C| \leq d - 1$ and $\{p(w) - p(u) : w \in C\}$ is linearly independent. Let G' be the graph obtained from G by splitting u' from u along C . Then there is some $z \in \mathbb{R}^d$ such that $R(G', q)$ is row-independent, where $q(w) = p(w)$ for all $w \in V(G)$ and $q(u') = p(u) + z$.*

Proof. Since $|C| \leq d - 1$, we can choose $y \in \mathbb{R}^d$ so that $y \notin \text{lin}\{p(w) - p(u) : w \in C\}$. Now, for each $t \in \mathbb{R}$, define $q_t : V(G') \rightarrow \mathbb{R}^d$ by

$$q_t(v) = \begin{cases} p(v) & \text{if } v \in V(G), \\ p(u) + ty & \text{if } v = u'. \end{cases}$$

It will suffice to show that for sufficiently small nonzero t , $R(G', q_t)$ is row-independent.

Let L be the matrix obtained by replacing the uu' row of $R(G, q_0)$ by the row vector that has y in the u column-set, $-y$ in the u' column-set and zeroes in all other entries.

Claim 2.10. L is row-independent.

Proof of claim. Suppose that λ is an element of the left kernel of L . We can think of λ as a real valued function on $E(G')$. Define $\pi : E(G) \rightarrow \mathbb{R}$ by

$$\pi(e) = \begin{cases} \lambda(e) & \text{if } e \notin \{uw : w \in C\}, \\ \lambda(uw) + \lambda(u'w) & \text{if } e = uw, w \in C. \end{cases}$$

Now, using the facts that $q_0(u) = q_0(u') = p(u)$, $q_0(w) = p(w)$ for $w \in V(G)$ and $\lambda L = 0$, we can readily show that π , considered as row vector with entries indexed by $E(G)$, is an element of the left kernel of $R(G, p)$. Since $R(G, p)$ is row-independent, it follows that $\pi = 0$. Therefore, $\lambda(e) = 0$ for all $e \notin \{uw : w \in C\} \cup \{u'w : w \in C\}$ and $\lambda(uw) + \lambda(u'w) = 0$ for $w \in C$. Now, using the fact that $\lambda L = 0$, and considering the u th column-set of L , we have

$$\lambda(uu')y + \sum_{w \in C} \lambda(uw)(p(u) - p(w)) = 0.$$

Our choice of y and the fact that $\{p(u) - p(w) : w \in C\}$ is linearly independent implies that $\lambda(uw) = 0$ for $w \in C$ and $\lambda(uu') = 0$. So $\lambda = 0$, and the claim is proved. \square

Finally, we consider, for $t \neq 0$, the matrix M_t which is obtained by multiplying the uu' row of $R(G', q_t)$ by $\frac{1}{t}$. It is clear that $\text{rank}(M_t) = \text{rank}(R(G', q_t))$. It is also clear that $\lim_{t \rightarrow 0}(M_t) = L$. Using the lower semicontinuity of the rank function and Claim 2.10, we see that, for sufficiently small nonzero t , $\text{rank}(R(G, q_t)) = \text{rank}(M_t) \geq \text{rank}(L) = |E(G')|$. This completes the proof of the theorem. \square

We remark that the inverse operation to vertex splitting is edge contraction. Given a graph G and an edge $uv \in E(G)$, we use G/uv to denote the simple graph obtained from G by contracting v onto u . More precisely, $G/uv = (G - v) \cup \{uz : z \in N_G(v)\}$. Observe that G is obtained from G/uv by splitting v from u along $N_G(u) \cap N_G(v)$.

Note that if $* : X \rightarrow X$ is a non-adjacent vertex pairing and either $X \cap \{u, v\} = \emptyset$, or $u \in X$, $v \notin X$ and $u^*v \notin E(G)$, then $*$ is also a non-adjacent vertex pairing on G/uv .

Now we will apply Theorem 2.9 to derive a sufficient condition that ensures that vertex splitting preserves Γ -rigidity of a graph with a non-adjacent vertex pairing. We find it convenient to state this theorem in terms of edge contraction.

Lemma 2.11. *Suppose Γ is a point group of \mathbb{R}^d of order two. Let $(G, *)$ be a graph with a non-adjacent vertex pairing $* : X \rightarrow X$ and $uv \in E(G)$ with $u, v \notin X$. Suppose that there is $C \subset N_G(u) \cap N_G(v)$ such that $|C| = d - 1$ and $|X_C| \leq 2$. If $(G/uv, *)$ is Γ -rigid in \mathbb{R}^d , then $(G, *)$ is Γ -rigid in \mathbb{R}^d .*

Proof. Observe that $X_{C \cup \{u\}} = X_C$ since $u \notin X$. If $|X_C| = 0$, then for any Γ -generic framework $(G/uv, *, p)$ in \mathbb{R}^d , $p(C \cup \{u\})$ is a generic set of d points in \mathbb{R}^d . If $|X_C| = 2$, then $p(C \cup \{u\})$ is an affinely independent set of d -points in \mathbb{R}^d . In both cases, it follows that $\{p(u) - p(z) : z \in C\}$ is linearly independent, and so we can use Theorem 2.9 to construct a Γ -framework $(G, *, q)$ that is infinitesimally rigid in \mathbb{R}^d . \square

Lemma 2.11 deals with vertex splitting when the split vertex does not belong to X . We also will need a vertex splitting result for the situation where we simultaneously split a pair of vertices u, u^* for some $u \in X$. In order to achieve this, we first derive a variation of Theorem 2.9, which involves simultaneously splitting two vertices of a framework in a carefully prescribed way.

The proof of Theorem 2.12 closely follows the proof of Theorem 2.9, so we only outline it, emphasising the few details which differ from the case of Theorem 2.9.

Theorem 2.12. Let $\tau : \mathbb{R}^d \rightarrow \mathbb{R}^d$ be a non-singular linear transformation. Suppose that (G, p) is a framework in \mathbb{R}^d such that $R(G, p)$ is row-independent. Also, let $u, v \in V(G)$ be non-adjacent vertices, $C_1 \subset N_G(u), C_2 \subset N_G(v)$ such that $|C_1|, |C_2| \leq d - 1$, and the sets $\{p(w) - p(u) : w \in C_1\}$ and $\{p(x) - p(v) : x \in C_2\}$ are both linearly independent. Let G' be the graph obtained by splitting u from u' along C_1 and then splitting v from v' along C_2 . Then there is some $z \in \mathbb{R}^d$ such that $R(G', q)$ is row-independent, where $q(w) = p(w)$ for all $w \in V(G)$, $q(u') = p(u) + z$ and $q(v') = p(v) + \tau(z)$.

Proof. Choose $y \in \mathbb{R}^d$ such that $y \notin \text{lin}\{p(u) - p(w) : w \in C_1\} \cup \text{lin}\{\tau^{-1}(p(v) - p(x)) : x \in C_2\}$. For $t \in \mathbb{R}$, let $q_t : V(G') \rightarrow \mathbb{R}^d$ be defined by $q_t(w) = p(w), w \in V(G), q_t(u') = p(u) + ty, q_t(v') = p(v) + \tau(ty)$. Let L be the matrix obtained from $R(G', q_0)$ by replacing the uu' row with the row that has y in the u column-set and $-y$ in the u' column-set, and replacing the vv' row with the row that has $\tau(y)$ in the v column-set and $-\tau(y)$ in the v' column-set.

Claim 2.13. L is row-independent.

Proof. This is proved in the same way as Claim 2.10, mutatis mutandis. In particular, note that the choice of y ensures that the sets $\{p(u) - p(w) : w \in C_1\} \cup \{y\}$ and $\{p(v) - p(x) : x \in C_2\} \cup \{\tau(y)\}$ are both linearly independent. □

Now let M_t be the matrix obtained from $R(G, q_t)$ by multiplying the uu' and vv' rows by $\frac{1}{t}$, and we complete the proof of the theorem in exactly the same way as the proof of Theorem 2.9. □

We next apply Theorem 2.12 to the setting of Γ -rigidity. Suppose that $G = (V, E)$ has a non-adjacent vertex pairing $* : X \rightarrow X$ and $x, y \in X$ with $xy, x^*y^* \in E$. If $x^*y, xy^* \notin E$, then the restriction of $*$ to $X \setminus \{y, y^*\}$ is a non-adjacent vertex pairing of $(G/xy)/x^*y^*$. We will abuse notation and continue to use $*$ for this vertex pairing of $(G/xy)/x^*y^*$.

Theorem 2.14. Let Γ be a point group of order two in \mathbb{R}^d . Let $(G, *)$ be a graph with a non-adjacent vertex pairing $* : X \rightarrow X, x, y \in X$ such that $xy, x^*y^* \in E(G)$ and $xy^*, x^*y \notin E(G)$. Suppose that there exist $C \subset N_G(x) \cap N_G(y)$ and $D \subset N_G(x^*) \cap N_G(y^*)$ such that $|C|, |D| = d - 1$ and $|X_C|, |X_D| \leq 2$. Let $G' = (G/xy)/x^*y^*$. If $(G', *)$ is Γ -rigid, then $(G, *)$ is Γ -rigid.

Proof. Let $(G', *, p)$ be a generic Γ -framework. Then (G', p) is infinitesimally rigid by assumption. Let $I = \{xv : v \in C\} \cup \{x^*w : w \in D\}$. Observe that $X_{C \cup \{x\}} = X_C$ and $X_{D \cup \{x^*\}} = X_D$. Since $(G', *, p)$ is a generic Γ -framework and $|X_C|, |X_D| \leq 2$, it follows that both $\{p(w) - p(x) : w \in C\}$ and $\{p(z) - p(x^*) : z \in D\}$ are linearly independent. This also implies that the set of rows of $R(G', p)$ labelled by I is linearly independent. Choose a maximal independent row-set that contains the row-set labelled by I and let J be the corresponding set of edges of G . Since (G', p) is infinitesimally rigid, it follows that J spans $V(G')$ and $|J| = d|V(G')| - \binom{d+1}{2}$. Let $G'[J] = (V(G'), J)$. We apply Theorem 2.12 (with τ being the non-identity element of Γ) to the framework $(G'[J], p)$ to obtain a Γ -framework $(G'', *, q)$, where G'' is obtained from $G'[J]$ by splitting x from y along C and then splitting x^* from y^* along D . By Theorem 2.12, (G'', q) is infinitesimally rigid. Since G'' is a spanning subgraph of G , $(G, *, q)$ is the required infinitesimally rigid Γ -symmetric realisation of $(G, *)$. □

We emphasise again that for an arbitrary graph $G = (V, E)$ with a non-adjacent vertex pairing $* : X \rightarrow X$, the hypothesis that $xy \in E[X]$ does not imply that $x^*y^* \in E$. Hence, in order to apply Theorem 2.14 to G , we must check that $xy, x^*y^* \in E$ and similarly that $xy^*, x^*y \notin E$.

3. Background on simplicial complexes

We now consider simplicial complexes. We summarise some notation and results from [6] that we will need later. We refer the reader to [6] for more details on this material.

Our main results will apply to a certain class of abstract simplicial k -complexes. However, as in [6], it will be convenient for us to consider a larger family of complexes in which multiple copies of the

same facet may exist. Thus, we define a *simplicial k -multicomplex* to be a multiset whose elements are $(k + 1)$ -sets. Suppose that \mathcal{S} is a simplicial k -multicomplex. For $0 \leq j \leq k$, a j -face of \mathcal{S} is a $(j + 1)$ -set F that is a subset of some element of \mathcal{S} . In the case that \mathcal{S} does not contain multiple copies of any k -face, we say that \mathcal{S} is a simplicial k -complex. We justify this terminology by noting that a pure abstract simplicial complex of dimension k , in the usual sense of that term,¹ corresponds to a unique simplicial k -complex in our sense. For $k \geq 1$, the graph of \mathcal{S} , denoted $G(\mathcal{S})$, is the simple graph whose vertex set, $V(\mathcal{S})$, is the set of 0-faces of \mathcal{S} and whose edge set, $E(\mathcal{S})$, is the set of 1-faces of \mathcal{S} .

The *boundary* of a simplicial k multicomplex \mathcal{S} is given by

$$\partial\mathcal{S} = \{F \subset V(\mathcal{S}) : |F| = k, F \text{ is contained in an odd number of elements of } \mathcal{S}\}.$$

By definition, $\partial\mathcal{S}$ is a simplicial $(k - 1)$ -complex. We say that \mathcal{S} is a *simplicial k -cycle* if $\partial\mathcal{S} = \emptyset$ and that \mathcal{S} is a *simplicial k -circuit* if \mathcal{S} is a nonempty simplicial k -cycle and no proper subset of \mathcal{S} is a simplicial k -cycle. A *trivial simplicial k -circuit* is a simplicial k -multicomplex comprising two copies of the same k -face. Our use of the word ‘circuit’ here comes from matroid theory since the set of simplicial k -circuits contained within any simplicial k -multicomplex \mathcal{S} forms the set of circuits of a matroid on \mathcal{S} . In particular, the simplicial 1-circuits in a multigraph are the circuits of its graphic matroid. Note that if \mathcal{S} is a simplicial k -multicomplex and $\mathcal{U} \subset \mathcal{S}$ is a simplicial k -cycle, then $\partial(\mathcal{S} \setminus \mathcal{U}) = \partial\mathcal{S}$. This implies that a nonempty simplicial k -cycle can be partitioned into a disjoint union of simplicial k -circuits. We will frequently consider the symmetric difference $\mathcal{S} \Delta \mathcal{T}$ of two simplicial k -complexes \mathcal{S}, \mathcal{T} and use the fact that $\partial(\mathcal{S} \Delta \mathcal{T}) = (\partial\mathcal{S}) \Delta (\partial\mathcal{T})$.²

We say that a simplicial k -multicomplex \mathcal{S} is *strongly connected* if for any distinct $U, W \in \mathcal{S}$, there is a sequence $U = U_1, \dots, U_\ell = W$ in \mathcal{S} , such that $|U_i \cap U_{i+1}| = k$ for $i = 1, \dots, \ell - 1$. Observe that if \mathcal{T} is a maximal strongly connected subset of \mathcal{S} , then $\partial\mathcal{T} \subset \partial\mathcal{S}$. In particular, it follows easily from this observation that any simplicial k -circuit is strongly connected.

A *k -pseudomanifold* is a strongly connected simplicial k -complex in which every $(k - 1)$ -face is contained in exactly two k -faces. It is not difficult to show that a k -pseudomanifold is a simplicial k -circuit [6, Lemma 3.2]. We also note here that \mathcal{S} is a simplicial k -circuit if and only if it is a minimal homology cycle over \mathbb{Z}_2 in the sense of Fogelsanger [7]. Fogelsanger’s Rigidity Theorem applies to minimal homology cycles over arbitrary abelian groups, and it might be interesting to investigate symmetric rigidity for arbitrary minimal homology cycles. We have not considered this extra generality in this paper since the class of simplicial k -circuits is already sufficiently general to include all pseudomanifolds.

We next define a contraction operation for two vertices u, v in a simplicial k -multicomplex \mathcal{S} . Let $\text{Ast}(\{u, v\}) = \{U \in \mathcal{S} : \{u, v\} \not\subset U\}$ be the *anti-star* of $\{u, v\}$ in \mathcal{S} . Then \mathcal{S}/uv is the simplicial k -multicomplex obtained from $\text{Ast}(\{u, v\})$ by replacing every k -face U that contains v with $U - v + u$. We say that \mathcal{S}/uv is obtained from \mathcal{S} by *contracting v onto u* . Let $\gamma : \text{Ast}(\{u, v\}) \rightarrow \mathcal{S}/uv$ be the canonical bijection. Note that our contraction operation may create multiple copies of a k -face in \mathcal{S}/uv even when \mathcal{S} is a simplicial complex. We allow this in order to have the useful property that the set of simplicial k -cycles is closed under the contraction operation. Note also that if every edge in $E(\mathcal{S}) \setminus \{u, v\}$ belongs to at least one k -face in $\text{Ast}(\{u, v\})$, then $G(\mathcal{S}/uv) = G(\mathcal{S})/uv$, where the right-hand side denotes the usual contraction operation on simple graphs.

We next describe the Fogelsanger decomposition of a simplicial k -circuit. Suppose that \mathcal{S} is a nontrivial simplicial k -circuit and $uv \in E(\mathcal{S})$. Then \mathcal{S}/uv is a simplicial k -cycle, so we can express it as $\mathcal{S}/uv = \mathcal{S}'_1 \sqcup \dots \sqcup \mathcal{S}'_m$, where \mathcal{S}'_j is a simplicial k -circuit for $1 \leq j \leq m$ (this partition is not necessarily unique). Let

¹An abstract simplicial complex in which every maximal face has cardinality $k + 1$.

²We will only use this operation for simplicial k -complexes and so do not need to give a definition for the symmetric difference of two multisets.

$$\begin{aligned} \mathcal{S}_j &= \gamma^{-1}(\mathcal{S}_j^+), \\ \mathcal{S}_j^+ &= \{K \subset V(\mathcal{S}) : \{u, v\} \subset K, K - u, K - v \in \partial\mathcal{S}_j\} \text{ and} \\ \mathcal{S}_j^+ &= \mathcal{S}_j \cup \mathcal{S}_j^+. \end{aligned}$$

We say that $(\mathcal{S}_1^+, \dots, \mathcal{S}_m^+)$ is a Fogelsanger decomposition for \mathcal{S} at uv . The properties of this decomposition are summarised in the following lemma, which is a restatement of [6, Lemma 3.9].

Lemma 3.1. *Suppose \mathcal{S} is a nontrivial simplicial k -circuit and $uv \in E(\mathcal{S})$. Let $(\mathcal{S}_1^+, \mathcal{S}_2^+, \dots, \mathcal{S}_m^+)$ be a Fogelsanger decomposition of \mathcal{S} at uv . Then,*

1. \mathcal{S}_i^+ / uv is a simplicial k -circuit for all $1 \leq i \leq m$;
2. \mathcal{S}_i^+ is a nontrivial simplicial k -circuit for all $1 \leq i \leq m$, and each $K \in \mathcal{S}_i^+ \setminus \mathcal{S}$ is a clique of $G(\mathcal{S})$ which contains $\{u, v\}$;
3. each k -face of $\text{Ast}(\{u, v\})$ is a k -face in a unique \mathcal{S}_i^+ ;
4. $\mathcal{S} = \Delta_{j=1}^m \mathcal{S}_j^+$;
5. $uv \in E(\mathcal{S}_i^+)$ for all $1 \leq i \leq m$ and $\bigcup_{i=1}^m E(\mathcal{S}_i^+) = E(\mathcal{S})$;
6. for all proper $I \subset \{1, 2, \dots, m\}$, there exists $j \in \{1, 2, \dots, m\} \setminus I$ and a $(k + 1)$ -clique K of $G(\mathcal{S})$ such that $K \not\subseteq \mathcal{S}$ and $K \in (\Delta_{i \in I} \mathcal{S}_i^+) \cap \mathcal{S}_j^+$.

4. Γ -rigidity of simplicial circuits with a non-adjacent vertex pairing

In this section, we will consider simplicial circuits with a non-adjacent vertex pairing and use the results of Section 2 to prove that their graphs are Γ -rigid in certain cases. We begin with an analysis of the graph of a crosspolytope in this context. These graphs will serve as the base case in the inductive proof of our main theorem.

For $k \geq 0$, let e_1, e_2, \dots, e_{k+1} be the standard basis for \mathbb{R}^{k+1} . The $(k + 1)$ -dimensional crosspolytope is the convex hull of the set of points $\{\pm e_1, \pm e_2, \dots, \pm e_{k+1}\}$. We will use \mathcal{B}_k to denote the boundary complex of this polytope. It is well known that \mathcal{B}_k is a simplicial k -complex whose vertex set is $\{\pm e_i : 1 \leq i \leq k + 1\}$. Moreover, the k -faces are precisely the transversals of $\{\{\pm e_1\}, \{\pm e_2\}, \dots, \{\pm e_{k+1}\}\}$. In particular, for any distinct vertices u, v of \mathcal{B}_k , uv is an edge of \mathcal{B}_k if and only if $v \neq -u$. Hence, there is the unique non-adjacent vertex pairing $*$: $V(\mathcal{B}_k) \rightarrow V(\mathcal{B}_k)$ that pairs the antipodal vertices of \mathcal{B}_k . Using this unique $*$, the graph $G(\mathcal{B}_k)$ of \mathcal{B}_k is \mathbb{Z}_2 -symmetric.

We now check the $\Gamma_{t,k+1}$ -rigidity of $(G(\mathcal{B}_k), *)$. We need the following operation and result due to Whiteley [21]. Given a graph $G = (V, E)$, the cone of G is the graph G^v obtained by adding a new vertex v and all edges from v to V .

Lemma 4.1 (The Coning Lemma). *Suppose that $G = (V, E)$ is a graph, G^v is the cone of G and p is a realisation of G^v in \mathbb{R}^{k+1} such that $p(V)$ is contained in a hyperplane H , $p(v) \notin H$ and $(G, p|_V)$ is infinitesimally rigid in H (viewed as a copy of \mathbb{R}^k). Then (G^v, p) is infinitesimally rigid in \mathbb{R}^{k+1} .*

Lemma 4.2. *Suppose $k \geq 2$ and $\Gamma = \Gamma_{t,k+1}$ for some $0 \leq t \leq k$. Let $G(\mathcal{B}_k)$ be the graph of the $(k + 1)$ -dimensional crosspolytope and $*$: $V(\mathcal{B}_k) \rightarrow V(\mathcal{B}_k)$ be the non-adjacent vertex pairing on $V(\mathcal{B}_k)$. Then $(G(\mathcal{B}_k), *)$ is Γ -rigid in \mathbb{R}^{k+1} unless $k = 2$ and Γ is a rotation group of order two.*

Proof. Denote the set of vertices of \mathcal{B}_k by $\{x_1, x_1^*, \dots, x_{k+1}, x_{k+1}^*\}$. We show by induction on k that $G(\mathcal{B}_k)$ has an infinitesimally rigid $\Gamma_{t,k+1}$ -symmetric realisation $p_{t,k}$ in \mathbb{R}^{k+1} . For the base case when $k = 2$, it is straightforward to check that $(G(\mathcal{B}_2), p_{0,2})$ is infinitesimally rigid when $p_{0,2}(x_i) = e_i$ and $p_{0,2}(x_i^*) = -e_i$ for all $1 \leq i \leq 3$; $(G(\mathcal{B}_2), p_{2,2})$ is infinitesimally rigid when $p_{2,2}(x_i) = e_i + e_3$ and $p_{2,2}(x_i^*) = e_i - e_3$ for all $1 \leq i \leq 3$. Hence, we may assume that $k \geq 3$.

The inductive step will follow immediately from the following:

Claim 4.3. *Suppose $(G(\mathcal{B}_{k-1}), *)$ has an infinitesimally rigid $\Gamma_{t,k}$ -symmetric realisation $p_{t,k-1}$ in \mathbb{R}^k for some $k \geq 3$ and $0 \leq t \leq k - 1$. Then $(G(\mathcal{B}_k), *)$ has both an infinitesimally rigid $\Gamma_{t,k+1}$ -symmetric realisation and an infinitesimally rigid $\Gamma_{t+1,k+1}$ -symmetric realisation in \mathbb{R}^{k+1} .*

Proof. We may assume that $p_{t,k-1}$ is a generic $\Gamma_{t,k}$ -symmetric realisation of $(G(\mathcal{B}_{k-1}), *)$ in \mathbb{R}^k and that $V(\mathcal{B}_{k-1}) = \{x_1, x_1^*, \dots, x_k, x_k^*\}$.

We first extend $p_{t,k-1}$ to an infinitesimally rigid $\Gamma_{t,k+1}$ -symmetric realisation $p_{t,k}$ of $(G(\mathcal{B}_k), *)$ in \mathbb{R}^{k+1} by putting $p_{t,k}(z) = (p_{t,k-1}(z), 0)$ for all $z \in V(\mathcal{B}_{k-1})$ and $p_{t,k}(x_{k+1}) = e_{k+1} = -p_{t,k}(x_{k+1}^*)$. Then the restrictions of $p_{t,k}$ to both $G(\mathcal{B}_k) - x_{k+1}$ and $G(\mathcal{B}_k) - x_{k+1}^*$ are infinitesimally rigid by Lemma 4.1. We can now use Theorem 2.8 to deduce that $p_{t,k}$ is an infinitesimally rigid realisation of $G(\mathcal{B}_k)$.

A similar proof works for $p_{t+1,k}$. We construct a realisation $p_{t+1,k}$ of $G(\mathcal{B}_k)$ from $p_{t,k-1}$ by putting $p_{t+1,k}(z) = (0, p_{t,k-1}(z))$ for all $z \in V(\mathcal{B}_{k-1})$ and $p_{t+1,k}(x_{k+1}) = e_1 = p_{t+1,k}(x_{k+1}^*)$. Then we can use Lemma 4.1 and Theorem 2.8 to deduce that $(G(\mathcal{B}_d), p_{t+1,k})$ is infinitesimally rigid. □

□

We next use Lemma 4.2 to analyse the case when $X \neq V(\mathcal{B}_k)$.

Lemma 4.4. *Let $k \geq 2$, $X \subseteq V(\mathcal{B}_k)$, $* : X \rightarrow X$ be a non-adjacent vertex pairing of $G(\mathcal{B}_k)$ and Γ be a point group of \mathbb{R}^{k+1} of order two. Suppose that $|X| \leq 2k$. Then $(G, *)$ is Γ -rigid in \mathbb{R}^{k+1} .*

Proof. It will suffice to show that $(G(\mathcal{B}_k), *)$ has an infinitesimally rigid Γ -symmetric realisation in \mathbb{R}^{k+1} . This follows immediately from Lemma 4.2 unless $k = 2$ and Γ is a rotation group. In the latter case, a realisation of $G(\mathcal{B}_k)$ as the regular octahedron is a Γ -symmetric realisation of $(G(\mathcal{B}_k), *)$ since $|X| \leq 4$. Hence, the Γ -rigidity of $(G(\mathcal{B}_2), *)$ follows from the infinitesimal rigidity of the 1-skeleton of the regular octahedron. □

We next show that Lemma 4.4 can be extended from \mathcal{B}_k to arbitrary simplicial k -circuits. This result will be a key ingredient in the proof of our main theorem (Theorem 5.8).

Theorem 4.5. *Let $G = (V, E)$ be the graph of a simplicial k -circuit \mathcal{S} for some $k \geq 2$, $X \subseteq V$, $* : X \rightarrow X$ be a non-adjacent vertex pairing of G , and Γ be a point group of \mathbb{R}^{k+1} of order two. Suppose that $|X| \leq 2k$. Then $(G, *)$ is Γ -rigid in \mathbb{R}^{k+1} .*

Proof. Suppose, for a contradiction, that \mathcal{S} is a counterexample with as few vertices as possible. Clearly, \mathcal{S} cannot be a trivial simplicial k -circuit. Let $(G, *, p)$ be a generic Γ -framework in \mathbb{R}^{k+1} . First, we record a useful observation. Suppose that $K \subset V$ is a clique in G . Then since $xx^* \notin E$ for all $x \in X$ (as $*$ is non-adjacent), it follows that

$$X_K = \emptyset \text{ and } p(K) \text{ is a generic set of points in } \mathbb{R}^{k+1}. \tag{4.1}$$

Claim 4.6. Every edge of G is incident to X .

Proof of claim. Suppose, for a contradiction, that $uv \in E$ and $u, v \notin X$. Let (S_1^+, \dots, S_m^+) be a Fogsanger decomposition of \mathcal{S} with respect to uv . Put $(V_i, E_i) = G_i = G(S_i^+)$ and $X_i = X_{V_i} = (V_i \cap X) \cap (V_i \cap X)^*$. Then $|X_i| \leq |X|$ for each i . Also, $*|_{X_i}$ is a non-adjacent vertex pairing for G_i by Lemma 3.1(e).

Suppose $|V_i| < |V|$ for all $i = 1, \dots, m$. Then, by the minimality of $|V|$, $(G_i, *|_{X_i})$ is Γ -rigid in \mathbb{R}^{k+1} . It follows that $(G_i, p|_{V_i})$ is infinitesimally rigid. Now, a straightforward induction argument using Lemma 3.1(6), Theorem 2.8(b) and (4.1) proves that (G, p) is infinitesimally rigid, contradicting our choice of \mathcal{S} .

Thus, we can assume without loss of generality that $V_1 = V$. Since S_1^+ / uv is a simplicial k -circuit, it follows from the minimality of $|V|$ that $(G_1 / uv, *)$ is Γ -rigid. By Lemma 3.1(b), we can choose $U \in S_1^+$ such that $u, v \in U$. Since S_1^+ is a nontrivial simplicial circuit, there is some $w \notin U$ such that $w \in N_{G_1}(u) \cap N_{G_1}(v)$. Now $C = U - \{u, v\} + w$ satisfies, $|C| = k$, and $|X_C| \leq 2$. Lemma 2.11 now implies that $(G_1, *)$ is Γ -rigid in \mathbb{R}^{k+1} and since G_1 is a spanning subgraph of G , that $(G, *)$ is also Γ -rigid in \mathbb{R}^{k+1} . This contradicts our choice of \mathcal{S} . □

For each $U \in \mathcal{S}$, Claim 4.6 gives $|U \cap X| \geq k$. Since $|X| \leq 2k$ and $xx^* \notin E(\mathcal{S})$ for all $x \in X$, we have

$$|X| = 2k \text{ and } |U \cap X| = k \text{ for all } U \in \mathcal{S}. \tag{4.2}$$

Claim 4.7. Some subcomplex of \mathcal{S} is isomorphic to \mathcal{B}_k .

Proof. Choose $U \in \mathcal{S}$. Since $xx^* \notin E(\mathcal{S})$ for all $x \in X$, (4.2) implies that we can label the elements of X as $x_1, x_1^*, x_2, x_2^*, \dots, x_k, x_k^*$ with $U \cap X = \{x_1, x_2, \dots, x_k\}$. Let $U = \{x_1, x_2, \dots, x_k, u\}$. Since \mathcal{S} is a nontrivial simplicial k -circuit, (4.2) also implies that $U - x_i + x_i^*$ is a k -face of \mathcal{S} for all $1 \leq i \leq k$ and hence that $J + u$ is a k -face of \mathcal{S} for all transversals J of $\{\{x_1, x_1^*\}, \{x_2, x_2^*\}, \dots, \{x_k, x_k^*\}\}$.

These cannot be all of the k -faces of \mathcal{S} since they do not form a simplicial k -circuit. Therefore, there is some $u' \in V(\mathcal{S}) \setminus X$ such that $u' \neq u$, and the same argument as before shows that $J + u'$ is a k -face of \mathcal{S} for all transversals J of $\{\{x_1, x_1^*\}, \{x_2, x_2^*\}, \dots, \{x_k, x_k^*\}\}$. Hence, every transversal of $\{\{x_1, x_1^*\}, \{x_2, x_2^*\}, \dots, \{x_k, x_k^*\}, \{u, u'\}\}$ is a k -face of \mathcal{S} . These transversals induce a subcomplex of \mathcal{S} which is isomorphic to \mathcal{B}_k . □

Since both \mathcal{S} and \mathcal{B}_k are simplicial k -circuits, Claim 4.7 implies that $\mathcal{S} \cong \mathcal{B}_k$. We can now use Lemma 4.4 to deduce that $(G, *)$ is Γ -rigid. □

It is worth noting that the case $X = \emptyset$ in Theorem 4.5 is Fogelsanger’s theorem for simplicial k -circuits, so we can view Theorem 4.5 as a non-generic extension of this fundamental result in rigidity theory.

The Bricard octahedron shows that the hypothesis $|X| \leq 2k$ in Theorem 4.5 is necessary when $k = 2$ and Γ is a half turn rotation group.

5. \mathbb{Z}_2 -symmetric simplicial complexes

Suppose that \mathcal{S} is a simplicial k -multicomplex. Let $*$: $V(\mathcal{S}) \rightarrow V(\mathcal{S})$ be an involution. For $X \subseteq V(\mathcal{S})$ and $\mathcal{U} \subset \mathcal{S}$, let $X^* = \{x^* : x \in X\}$ and $\mathcal{U}^* = \{K^* : K \in \mathcal{U}\}$. The set X , respectively \mathcal{U} , is $*$ -invariant if $X^* = X$, respectively $\mathcal{U}^* = \mathcal{U}$. We say that $*$ is a *simplicial involution* if for every facet F of \mathcal{S} , F^* is a facet of \mathcal{S} of the same multiplicity as F , and that $*$ is *free* if $V(F^*) \neq V(F)$ for every face F of \mathcal{S} . A \mathbb{Z}_2 -symmetric simplicial k -multicomplex is a pair $(\mathcal{S}, *)$ where \mathcal{S} is a simplicial k -multicomplex and $*$ is a free simplicial involution on \mathcal{S} . This terminology is consistent with our terminology for graphs since $(\mathcal{S}, *)$ is a \mathbb{Z}_2 -symmetric k -multicomplex, then $(G(\mathcal{S}), *)$ is a \mathbb{Z}_2 -symmetric graph. We will often abuse notation by omitting explicit mention of the involution $*$ when it is obvious from the context.

5.1. \mathbb{Z}_2 -irreducible cycles and their structural properties

We will refer to a \mathbb{Z}_2 -symmetric k -multicomplex, which is also a simplicial k -cycle, as a \mathbb{Z}_2 -symmetric k -cycle. A \mathbb{Z}_2 -irreducible k -cycle is a nonempty \mathbb{Z}_2 -symmetric k -cycle $(\mathcal{S}, *)$ which is minimal in the sense that for all $\emptyset \neq \mathcal{T} \subsetneq \mathcal{S}$, $(\mathcal{T}, *|_{V(\mathcal{T})})$ is not a \mathbb{Z}_2 -symmetric k -cycle. We say that \mathcal{S} is a *trivial \mathbb{Z}_2 -irreducible k -cycle* if it consists of two vertex disjoint copies of the trivial simplicial k -circuit and the involution interchanges the vertex sets of these two trivial simplicial k -circuits. Otherwise, \mathcal{S} is a *nontrivial \mathbb{Z}_2 -irreducible k -cycle*.

Suppose that \mathcal{S} is a nonempty \mathbb{Z}_2 -symmetric k -cycle. It is straightforward to show that if $\mathcal{T} \subsetneq \mathcal{S}$ is a \mathbb{Z}_2 -symmetric k -cycle, then $\mathcal{S} \setminus \mathcal{T}$ is a \mathbb{Z}_2 -symmetric k -cycle. This implies that there exists a partition $\mathcal{S} = \mathcal{S}_1 \sqcup \dots \sqcup \mathcal{S}_m$ where \mathcal{S}_i is a \mathbb{Z}_2 -irreducible k -cycle for $i = 1, \dots, m$. This partition is not necessarily unique (even up to permutations).

An important class of examples is the following. Let P be a simplicial convex d -polytope. That is a convex polytope in \mathbb{R}^d that has dimension d and such that every face in the boundary of P is a simplex. Suppose also that that P is centrally symmetric. The *boundary complex* $B(P)$ is a simplicial $(d - 1)$ -complex whose facets are the vertex sets of the $(d - 1)$ -dimensional faces of P . Then $B(P)$ is a simplicial sphere and hence a simplicial $(d - 1)$ -circuit. Moreover, the involution $*$: $V(P) \rightarrow V(P)$ given by $v^* = -v$ makes $B(P)$ into a \mathbb{Z}_2 -irreducible $(d - 1)$ -cycle.

More generally, if \mathcal{S} is a simplicial k -circuit with a free simplicial involution, then since it does not properly contain any simplicial k -cycle ($*$ -invariant or otherwise), it must also be a \mathbb{Z}_2 -irreducible k -cycle.

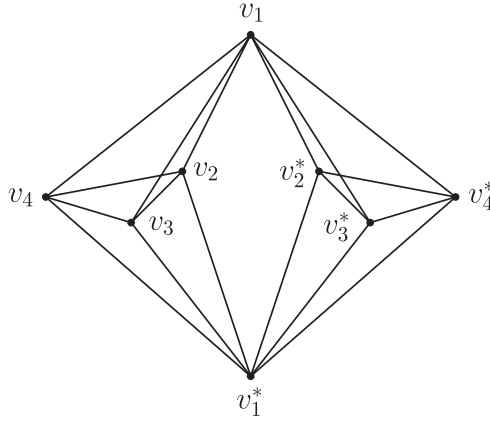


Figure 2. The 1-skeleton of a \mathbb{Z}_2 -irreducible 2-cycle \mathcal{S} , which is not a simplicial 2-circuit. We have $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$, where $\mathcal{T} = \{\{v_1, v_2, v_3\}, \{v_1, v_2, v_4\}, \{v_1, v_3, v_4\}, \{v_1^*, v_2, v_3\}, \{v_1^*, v_2, v_4\}, \{v_1^*, v_3, v_4\}\}$ is the simplicial 2-circuit given by the boundary complex of the hexahedron.

However, there are \mathbb{Z}_2 -irreducible k -cycles that are not simplicial k -circuits – the trivial \mathbb{Z}_2 -irreducible k -cycle is an example. A nontrivial example is given in Figure 2. Since our main motivation is to understand simplicial k -circuits that have a free involution, the reader might wonder why we introduce the more general notion of a \mathbb{Z}_2 -irreducible k -cycle. The reason is that \mathbb{Z}_2 -irreducible k -cycles that are not simplicial k -circuits can arise naturally from the the \mathbb{Z}_2 -symmetric version of the Fogelsanger decomposition, even if we start with a simplicial k -circuit with a free involution.

Our first structural result on \mathbb{Z}_2 -irreducible k -cycles characterises those which are not simplicial k -circuits.

Lemma 5.1. *Let $(\mathcal{S}, *)$ be a nontrivial \mathbb{Z}_2 -irreducible k -cycle. Then either \mathcal{S} is a simplicial k -circuit or $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$ where \mathcal{T} is a nontrivial simplicial k -circuit. Moreover, if the second alternative holds and \mathcal{U} is a simplicial k -circuit properly contained in \mathcal{S} , then $\mathcal{U} = \mathcal{T}$ or $\mathcal{U} = \mathcal{T}^*$.*

Proof. Suppose that \mathcal{S} is not a simplicial k -circuit. Then some simplicial k -circuit \mathcal{T} is properly contained in \mathcal{S} . Since \mathcal{S} is a \mathbb{Z}_2 -irreducible k -cycle, $\mathcal{T}^* \neq \mathcal{T}$. It follows that $\mathcal{T} \Delta \mathcal{T}^*$ is a nonempty $*$ -invariant simplicial k -cycle contained in \mathcal{S} , so $\mathcal{T} \Delta \mathcal{T}^* = \mathcal{S}$, whence $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$. If \mathcal{T} is a trivial simplicial k -circuit, then $K = V(\mathcal{T}) \cap V(\mathcal{T}^*)$ is a face of \mathcal{S} and $K^* = K$. Since $*$ is a free involution, it follows that $K = \emptyset$ and so \mathcal{S} is a trivial \mathbb{Z}_2 -irreducible k -cycle, contradicting the hypothesis. Hence, \mathcal{T} is nontrivial.

Now suppose that the second alternative in the lemma holds and \mathcal{U} is a simplicial k -circuit properly contained in \mathcal{S} . Then $\mathcal{S} = \mathcal{U} \sqcup \mathcal{U}^*$ by the same argument as the first paragraph, and $\mathcal{U} \Delta \mathcal{T} = (\mathcal{U}^* \cap \mathcal{T}) \cup (\mathcal{U} \cap \mathcal{T}^*)$ is a $*$ -invariant simplicial k -cycle contained in \mathcal{S} . Therefore, either $\mathcal{U} \Delta \mathcal{T} = \emptyset$ and so $\mathcal{U} = \mathcal{T}$ or, $\mathcal{U} \Delta \mathcal{T} = \mathcal{S}$ and so $\mathcal{U} = \mathcal{S} \setminus \mathcal{T} = \mathcal{T}^*$. □

An example illustrating the second alternative in Lemma 5.1 is given in Figure 2.

Lemma 5.2. *Suppose that $(\mathcal{S}, *)$ is a \mathbb{Z}_2 -irreducible k -cycle for some $k \geq 1$. Then $|V(\mathcal{S})| \geq 2k + 2$ with equality if and only if $(\mathcal{S}, *)$ is a trivial \mathbb{Z}_2 -irreducible k -cycle or \mathcal{S} is isomorphic to \mathcal{B}_k .*

Proof. We have $|V(\mathcal{S})| \geq 2k + 2$ since for any $U \in \mathcal{S}$, we have $U \cap U^* = \emptyset$, and hence, $|V(\mathcal{S})| \geq |U \sqcup U^*| = 2k + 2$.

Suppose that $|V(\mathcal{S})| = 2k + 2$. Let $V(\mathcal{S}) = \{x_i, x_i^* : 1 \leq i \leq k + 1\}$. If \mathcal{S} contains two copies of some k -face W , then it follows easily that $\mathcal{S} = \{\{W, W, W^*, W^*\}\}$, and so \mathcal{S} is a trivial \mathbb{Z}_2 -irreducible k -cycle. Thus, we may assume that each $W \in \mathcal{S}$ has multiplicity one. Then, for each $W \in \mathcal{S}$ and $w \in W$, we have $W - w + w^* \in \mathcal{S}$ since $W - w$ is contained in at least two k -faces of \mathcal{S} and $*$ is free. It follows that every transversal of $\{\{x_i, x_i^* : 1 \leq i \leq k + 1\}\}$ is a k -face of \mathcal{S} , and so, $\mathcal{S} \cong \mathcal{B}_k$. □

Lemma 5.3. *Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -irreducible k -cycle for some $k \geq 2$ and $X \subset V(\mathcal{S})$ be an inclusion-minimal $*$ -invariant vertex separator of $G(\mathcal{S})$. Suppose $|X| \leq 2k$. Then either $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$ for some simplicial k -circuit \mathcal{T} with $V(\mathcal{T}) \cap V(\mathcal{T}^*) = X$, or $|X| = 2k$ and the subgraph of $G(\mathcal{S})$ induced by X is isomorphic to $G(\mathcal{B}_{k-1})$.*

Proof. Choose $V_1, V_2 \subset V(\mathcal{S})$ such that $V_1 \cap V_2 = X$, $G(\mathcal{S}) = G(\mathcal{S})[V_1] \cup G(\mathcal{S})[V_2]$. Let $\mathcal{T}_i = \{W \in \mathcal{S} : W \subset V_i\}$. Since X is a vertex separator of $G(\mathcal{S})$, it follows that $\mathcal{S} = \mathcal{T}_1 \cup \mathcal{T}_2$ and that $\mathcal{T}_1, \mathcal{T}_2 \neq \mathcal{S}$. The hypothesis that X is $*$ -invariant and the fact that $|X| \leq 2k$ imply that, for any $W \in \mathcal{S}$, $W \not\subset X$; hence, $\mathcal{T}_1 \cap \mathcal{T}_2 = \emptyset$. Thus, $\mathcal{S} = \mathcal{T}_1 \sqcup \mathcal{T}_2$, $\partial\mathcal{T}_1 = \partial\mathcal{T}_2 =: \mathcal{U}$ and $V(\mathcal{U}) \subset X$.

Suppose $\mathcal{U} = \emptyset$. Then \mathcal{T}_i is a simplicial k -cycle for $i = 1, 2$. Lemma 5.1 now implies that \mathcal{T}_1 is a simplicial k -circuit, $\mathcal{T}_2 = \mathcal{T}_1^*$ and $\mathcal{S} = \mathcal{T}_1 \sqcup \mathcal{T}_1^*$. The minimality of X now gives $V(\mathcal{T}_1) \cap V(\mathcal{T}_1^*) = X$. Hence, we may assume that $\mathcal{U} \neq \emptyset$.

The definition of the boundary operator implies that \mathcal{U} is a simplicial $(k - 1)$ -cycle and each of its facets has multiplicity one. Hence, $\mathcal{U}\Delta\mathcal{U}^*$ is a \mathbb{Z}_2 -symmetric $(k - 1)$ -cycle that does not contain a trivial simplicial $(k - 1)$ -circuit. Since $V(\mathcal{U}) \subseteq X$ and X is $*$ -invariant, $\mathcal{V} := \mathcal{U}\Delta\mathcal{U}^* \subseteq 2^X$. We can now apply Lemma 5.2 and the hypothesis that $|X| \leq 2k$ to \mathcal{V} to deduce that either $\mathcal{V} = \emptyset$ or $\mathcal{V} \cong \mathcal{B}_{k-1}$.

Suppose $\mathcal{V} \cong \mathcal{B}_{k-1}$. Then $|X| = 2k$, and \mathcal{V} is the \mathbb{Z}_2 -irreducible $(k - 1)$ -cycle consisting of all transversals of the following partition of X : $\{\{x_1, x_1^*\}, \dots, \{x_k, x_k^*\}\}$. Hence, every k -subset of X which contains no pair $\{x_i, x_i^*\}$ is contained in \mathcal{V} . Since $*$ is free and $V(\mathcal{U}) \subset X$, this implies that $\mathcal{U} \subset \mathcal{V}$. Since $\mathcal{U} \subset \mathcal{V}$ and $\mathcal{V} = \mathcal{U}\Delta\mathcal{U}^*$, $\mathcal{V} = \mathcal{U} \sqcup \mathcal{U}^*$, and hence, \mathcal{V} is a trivial \mathbb{Z}_2 -irreducible $(k - 1)$ -cycle. This contradicts the assumption that $\mathcal{V} \cong \mathcal{B}_{k-1}$.

Hence, $\mathcal{V} = \mathcal{U}\Delta\mathcal{U}^* = \emptyset$ so $\mathcal{U} = \mathcal{U}^*$. Then \mathcal{U} is a \mathbb{Z}_2 -symmetric $(k - 1)$ -cycle with at most $2k$ vertices that does not contain a trivial \mathbb{Z}_2 -irreducible $(k - 1)$ -cycle. Lemma 5.2 now implies that $\mathcal{U} \cong \mathcal{B}_{k-1}$, and hence, $G(\mathcal{S})[X]$ is isomorphic to $G(\mathcal{B}_{k-1})$. □

5.2. \mathbb{Z}_2 -symmetric Fogelsanger decomposition

We next adapt Fogelsanger’s decomposition technique for simplicial k -circuits to the context of \mathbb{Z}_2 -irreducible k -cycles. Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -irreducible k -cycle and put $G = (V, E) = G(\mathcal{S})$. Suppose that $xy \in E$ and $xy^* \notin E$. Then $x^*y^* \in E$, $x^*y \notin E$ and $(\mathcal{S}/xy)/x^*y^*$ is a \mathbb{Z}_2 -symmetric k -cycle under the free simplicial involution induced by $*$ on $V - y - y^*$. Recall that, for a face F of \mathcal{S} , the antistar of F in \mathcal{S} is given by $\text{Ast}(F) = \{U \in \mathcal{S} : F \not\subset U\}$. Observe that there is a bijection $\gamma : \text{Ast}(\{x, y\}) \cap \text{Ast}(\{x^*, y^*\}) \rightarrow (\mathcal{S}/xy)/x^*y^*$ given by $\gamma(U) = U$ if $y, y^* \notin U$, $\gamma(U) = U - y + x$ if $y \in U$, and $\gamma(U) = U - y^* + x^*$ if $y^* \in U$.

Choose a partition $\{\mathcal{S}'_1, \mathcal{S}'_2, \dots, \mathcal{S}'_m\}$ of $(\mathcal{S}/xy)/x^*y^*$ into \mathbb{Z}_2 -irreducible k -cycles. For $1 \leq i \leq m$, let $\mathcal{S}_i = \gamma^{-1}(\mathcal{S}'_i)$,

$$\mathcal{S}_i^\dagger = \{K \subset V(\mathcal{S}_i) : \{x, y\} \subset K, K - x \in \partial\mathcal{S}_i, K - y \in \partial\mathcal{S}_i\}$$

and

$$\mathcal{S}_i^+ = \mathcal{S}_i \cup \mathcal{S}_i^\dagger \cup (\mathcal{S}_i^\dagger)^*. \tag{5.1}$$

We say that $(\mathcal{S}_1^+, \dots, \mathcal{S}_m^+)$ is a \mathbb{Z}_2 -symmetric Fogelsanger decomposition for \mathcal{S} at xy . Note that a \mathbb{Z}_2 -symmetric Fogelsanger decomposition at xy is defined only when $xy^* \notin E$.

The \mathbb{Z}_2 -irreducible 2-cycle in Figure 2 can be used to illustrate this construction. We have $(\mathcal{S}/v_2v_4)/v_2^*v_4^* = \mathcal{S}'_1 \sqcup \mathcal{S}'_2$, where \mathcal{S}'_1 is a trivial \mathbb{Z}_2 -irreducible 2-cycle consisting of consisting of two copies of $\{v_1, v_2, v_3\}$ and two copies of $\{v_1^*, v_2^*, v_3^*\}$, and \mathcal{S}'_2 is a trivial \mathbb{Z}_2 -irreducible 2-cycle consisting of consisting of two copies of $\{v_1^*, v_2, v_3\}$ and two copies of $\{v_1, v_2^*, v_3^*\}$. The above definitions now give $\mathcal{S}_1 = \mathcal{T}_1 \cup \mathcal{T}_1^*$, where $\mathcal{T}_1 = \{\{v_1, v_2, v_3\}, \{v_1, v_2, v_4\}, \{v_1, v_3, v_4\}\}$, $\mathcal{S}_1^\dagger = \{\{v_2, v_3, v_4\}\}$ and \mathcal{S}_1^+ is the disjoint union of the boundary complexes of two tetrahedra on $\{v_1, v_2, v_3, v_4\}$ and $\{v_1^*, v_2^*, v_3^*, v_4^*\}$,

respectively. Similarly, S_2^+ is the disjoint union of the boundary complexes of two tetrahedra on $\{v_1^*, v_2, v_3, v_4\}$ and $\{v_1, v_2^*, v_3^*, v_4^*\}$, respectively.

The properties of \mathbb{Z}_2 -symmetric Fogelsanger decompositions given in the following lemma are analogous to those for Fogelsanger decompositions given in Lemma 3.1.

Lemma 5.4. *Let $(S, *)$ be a \mathbb{Z}_2 -irreducible k -cycle for $k \geq 2$ and $xy \in E(S)$ with $xy^* \notin E(S)$. Suppose that (S_1^+, \dots, S_m^+) is a \mathbb{Z}_2 -symmetric Fogelsanger decomposition for S at xy . Let $G(S_i^+) = (V_i, E_i)$ for $1 \leq i \leq m$. Then,*

1. $xy, x^*y^* \in E_i$ for $1 \leq i \leq m$;
2. $\bigcup_{i=1}^m E_i = E$ and $\bigcup_{i=1}^m V_i = V$;
3. $(S_i^+/xy)/x^*y^*$ is a \mathbb{Z}_2 -irreducible k -cycle for $1 \leq i \leq m$;
4. S_i^+ is a nontrivial \mathbb{Z}_2 -irreducible k -cycle, and each $K \in S_i^+ \setminus S$ is a clique of G that either contains $\{x, y\}$ or contains $\{x^*, y^*\}$;
5. if $U \in S$ and U contains neither $\{x, y\}$ nor $\{x^*, y^*\}$, then U belongs to a unique S_i^+ ;
6. $S = \Delta_{k=1}^m S_k^+$;
7. for all proper subsets I of $\{1, \dots, m\}$, there exists $j \in \{1, \dots, m\} \setminus I$ such that $S_j^+ \cap \Delta_{i \in I} S_i^+$ is nonempty.

Proof. We adopt the definitions of S_i', S_i and S_i^\dagger given in our description of a \mathbb{Z}_2 -symmetric Fogelsanger decomposition. Note that for all $1 \leq i \leq m$, $S_i \neq S$ since $xy \notin E(S_i)$. Suppose $F \in \partial S_i$. Then $F \cap \{x, y, x^*, y^*\} \neq \emptyset$ otherwise $F \in \partial S$, contradicting the fact that S is a simplicial k -cycle. For $v \in \{x, y, x^*, y^*\}$, let $\mathcal{U}_v = \{U \in \partial S_i : v \in U\}$. Since no edge in $E(S_i)$ joins two vertices of $\{x, y, x^*, y^*\}$, we have $\partial S_i = \mathcal{U}_x \sqcup \mathcal{U}_y \sqcup \mathcal{U}_{x^*} \sqcup \mathcal{U}_{y^*}$. Furthermore, since $\partial((S_i/xy)/x^*y^*) = \partial S_i' = \emptyset$, it follows that

$$\text{the mapping } F \mapsto F - y + x \text{ is a bijection } \mathcal{U}_y \rightarrow \mathcal{U}_x, \tag{5.2}$$

and

$$\text{the mapping } F \mapsto F - y^* + x^* \text{ is a bijection } \mathcal{U}_{y^*} \rightarrow \mathcal{U}_{x^*}. \tag{5.3}$$

In particular,

$$S_i^\dagger = \{F + y : F \in \mathcal{U}_x\}. \tag{5.4}$$

Also, $*$ induces a bijection $\mathcal{U}_x \rightarrow \mathcal{U}_{x^*}$, and hence,

$$|S_i^\dagger| = |\mathcal{U}_x| = |\mathcal{U}_y| = |\mathcal{U}_{x^*}| = |\mathcal{U}_{y^*}|. \tag{5.5}$$

Now if $xy \notin S_i^+$, then $S_i^\dagger = \emptyset$, and it follows from (5.5) that $\partial S_i = \emptyset$, contradicting the fact that S is a \mathbb{Z}_2 -irreducible k -cycle and $\emptyset \neq S_i \subsetneq S$. So $xy \in E(S_i^+)$, and since S_i^+ is $*$ -invariant, $x^*y^* \in E(S_i^+)$, proving (1).

The definition of S_i^+ implies that $(S_i^+/xy)/x^*y^* = S_i'$. Since S_i' is a \mathbb{Z}_2 -irreducible k -cycle, this gives (3).

Claim 5.5. $\partial(S_i^\dagger \cup (S_i^\dagger)^*) = \partial S_i$.

Proof of claim. From (5.5) and the definition of S_i^\dagger , it follows that for $0 \leq s \leq k-1$, the map $F \mapsto F + y$ is a bijection between the set of s -faces of \mathcal{U}_x that contain x and the set of $(s+1)$ -faces of S_i^\dagger that contain $\{x, y\}$. Since ∂S_i is a simplicial $(k-1)$ -cycle, every $(k-2)$ -face of \mathcal{U}_x that contains x belongs to an even number of $(k-1)$ -faces of \mathcal{U}_x . Therefore, every $(k-1)$ -face of S_i^\dagger that contains $\{x, y\}$ belongs to an even number of k -faces of S_i^\dagger . Hence, $\partial S_i^\dagger = \{K - x : K \in S_i^\dagger\} \cup \{K - y : K \in S_i^\dagger\} = \mathcal{U}_y \sqcup \mathcal{U}_x$. By symmetry, $\partial((S_i^\dagger)^*) = \mathcal{U}_{y^*} \sqcup \mathcal{U}_{x^*}$. Therefore, $\partial S_i = \mathcal{U}_x \sqcup \mathcal{U}_y \sqcup \mathcal{U}_{x^*} \sqcup \mathcal{U}_{y^*} = \partial(S_i^\dagger \cup (S_i^\dagger)^*)$. \square

Since $\mathcal{S}_i^+ = \mathcal{S}_i \Delta (\mathcal{S}_i^+ \cup (\mathcal{S}_i^+)^*)$, Claim 5.5 implies that $\partial \mathcal{S}_i^+ = \emptyset$, and hence, \mathcal{S}_i^+ is a \mathbb{Z}_2 -symmetric k -cycle.

Suppose $\mathcal{T} \subseteq \mathcal{S}_i^+$ is a \mathbb{Z}_2 -irreducible k -cycle. If $xy, x^*y^* \notin E(\mathcal{T})$, then $\mathcal{T} \subseteq \mathcal{S}$, contradicting the fact that \mathcal{S} is a \mathbb{Z}_2 -irreducible k -cycle. So $xy, x^*y^* \in E(\mathcal{T})$. Now $(\mathcal{T}/xy)/x^*y^*$ is a nonempty \mathbb{Z}_2 -symmetric k -cycle contained in the \mathbb{Z}_2 -irreducible k -cycle \mathcal{S}_i^+ . Hence, $(\mathcal{T}/xy)/x^*y^* = \mathcal{S}_i^+$ and $\mathcal{S}_i \subseteq \mathcal{T}$. Since $\partial \mathcal{T} = \emptyset$, it follows that $\mathcal{T} \supset \mathcal{S}_i^+$, and so $\mathcal{T} = \mathcal{S}_i^+$. Hence, \mathcal{S}_i^+ is a \mathbb{Z}_2 -irreducible k -cycle, which is nontrivial by (3). Since $\mathcal{S}_i^+ \setminus \mathcal{S} \subseteq \mathcal{S}_i^+ \cup (\mathcal{S}_i^+)^*$, each $K \in \mathcal{S}_i^+ \setminus \mathcal{S}$ is a clique of G that either contains $\{x, y\}$ or contains $\{x^*, y^*\}$. This completes the proof of (4).

If $U \in \mathcal{S}$ contains neither $\{x, y\}$ nor $\{x^*, y^*\}$, then U is an element of \mathcal{S}_i for a unique i , proving (5).

We next prove (6). Suppose, for a contradiction, that $\mathcal{R} = \mathcal{S} \Delta (\Delta_{i=1}^m \mathcal{S}_i^+) \neq \emptyset$ and choose $U \in \mathcal{R}$. By (5), either $\{x, y\} \subset U$ or $\{x^*, y^*\} \subset U$. Suppose $\{x, y\} \subset U$ (a similar argument works for the other case). Now \mathcal{R} is a simplicial k -cycle, and since \mathcal{S} and $\mathcal{S}_i^+, 1 \leq i \leq m$, are all nontrivial \mathbb{Z}_2 -irreducible k -cycles, \mathcal{R} does not contain any trivial simplicial k -circuit. It follows that there is some $U' \in \mathcal{R}$ such that $U \cap U' = U - x$. By (5), U' must contain $\{x^*, y^*\}$, and so $yy^* \in E(\mathcal{R}) \subset E(\mathcal{S})$, contradicting the assumption that $*$ is a simplicial involution on \mathcal{S} . Therefore, \mathcal{R} must be empty – this proves (6).

To verify (7), we suppose, for a contradiction, that there exists a proper subset I of $\{1, \dots, m\}$ such that $\mathcal{S}_j^+ \cap \Delta_{i \in I} \mathcal{S}_i^+ = \emptyset$ for all $j \in J = \{1, \dots, m\} \setminus I$. Then, by (6), $\mathcal{S} = \Delta_{i=1}^m \mathcal{S}_i^+ = \Delta_{i \in I} \mathcal{S}_i^+ \sqcup \Delta_{j \in J} \mathcal{S}_j^+$. This yields a partition of \mathcal{S} into two \mathbb{Z}_2 -symmetric k -cycles, contradicting the hypothesis that \mathcal{S} is a \mathbb{Z}_2 -irreducible k -cycle. This proves (7).

We can now complete the proof of the lemma by verifying (2). Observe that if $uv \in E(\mathcal{S})$ and $uv \notin \{xy, x^*y^*\}$, then since \mathcal{S} is a nontrivial \mathbb{Z}_2 -irreducible k -cycle and $xy, x^*y^* \notin E(\mathcal{S})$, there is some $U \in \mathcal{S}$ such that $u, v \in U$ and $\{x, y\}, \{x^*, y^*\} \not\subset U$. By (5), $uv \in E(\mathcal{S}_i^+)$ for some i . Using this, together with (1), we see that $\bigcup_{i=1}^m E(\mathcal{S}_i^+) = E$. Since $G(\mathcal{S})$ has no isolated vertices, this implies that $\bigcup_{i=1}^m V(\mathcal{S}_i^+) = V$. This proves (2). □

We need one more additional property of \mathbb{Z}_2 -symmetric Fogelsanger decompositions.

Lemma 5.6. *Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -irreducible k -cycle and $xy \in E(\mathcal{S})$ with $xy^* \notin E(\mathcal{S})$. Let $\{\mathcal{S}'_1, \mathcal{S}'_2, \dots, \mathcal{S}'_m\}$ be a partition of $(\mathcal{S}/xy)/x^*y^*$ into \mathbb{Z}_2 -irreducible k -cycles and $(\mathcal{S}'_1, \dots, \mathcal{S}'_m)$ be the \mathbb{Z}_2 -symmetric Fogelsanger decomposition for \mathcal{S} at xy corresponding to this partition. Suppose $\mathcal{S}'_j = \mathcal{T}'_j \sqcup \mathcal{T}'_{j^*}$ for some simplicial k -circuit \mathcal{T}'_j with $|V(\mathcal{T}'_j) \cap V(\mathcal{T}'_{j^*})| \leq 2k - 2$. Then $\mathcal{S}'_j = \mathcal{T}_j \sqcup \mathcal{T}'_{j^*}$ for some simplicial k -circuit \mathcal{T}_j with $|V(\mathcal{T}_j) \cap V(\mathcal{T}'_{j^*})| \leq |V(\mathcal{T}'_j) \cap V(\mathcal{T}'_{j^*})| + 2$.*

Proof. Since $\mathcal{S}'_j = (\mathcal{S}_j/xy)/x^*y^*$, the hypothesis that $|V(\mathcal{T}'_j) \cap V(\mathcal{T}'_{j^*})| \leq 2k - 2$ implies that $G(\mathcal{S}'_j)$ has a $*$ -invariant vertex separator X with $V(\mathcal{T}'_j) \cap V(\mathcal{T}'_{j^*}) \subseteq X \subseteq V(\mathcal{T}'_j) \cap V(\mathcal{T}'_{j^*}) + y + y^*$. In particular, $|X| \leq 2k$. By Lemma 5.3, either $\mathcal{S}'_j = \mathcal{T}_j \sqcup \mathcal{T}'_{j^*}$ for some simplicial k -circuit \mathcal{T}_j with $V(\mathcal{T}_j) \cap V(\mathcal{T}'_{j^*}) = X$ or $G(\mathcal{S}'_j)[X]$ is isomorphic to $G(\mathcal{B}_{k-1})$. In the former case, we have the statement. So let us assume the latter case. Then we have $|X| = 2k$, and hence, $|X| = |V(\mathcal{T}'_j) \cap V(\mathcal{T}'_{j^*})| + 2$, so $\{x, y, x^*, y^*\} \subseteq X$. Together with $G[X] \cong G(\mathcal{B}_{k-1})$, this implies that $xy^* \in E$, contradicting an hypothesis of the lemma. □

5.3. Main rigidity theorem

We can now establish our main result. We begin with the following special case.

Lemma 5.7. *Let $\Gamma = \Gamma_{t, k+1}$ for $0 \leq t \leq k$. Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -irreducible k -cycle such that $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$ for some simplicial k -circuit \mathcal{T} with $h := |V(\mathcal{T}) \cap V(\mathcal{T}^*)| \leq 2k$. Then $(G(\mathcal{S}), *)$ is Γ -rigid in \mathbb{R}^{k+1} if and only if $h \geq \max\{2(k - t), k + 1, 2t\}$.*

Proof. To prove sufficiency, we suppose $h \geq \max\{2(k - t), k + 1, 2t\}$. Let $*_{\mathcal{T}}$ be the non-adjacent vertex pairing induced on $V(\mathcal{T}) \cap V(\mathcal{T}^*)$ by $*$. Since $h \leq 2k$, we can apply Theorem 4.5 to $(G(\mathcal{T}), *_{\mathcal{T}})$ to deduce that $(G(\mathcal{T}), *_{\mathcal{T}})$ is Γ -rigid. Symmetrically, $(G(\mathcal{T}^*), *_{\mathcal{T}})$ is Γ -rigid. Now Theorem 2.8 (the gluing theorem) implies that the union of $(G(\mathcal{T}), *_{\mathcal{T}})$ and $(G(\mathcal{T}^*), *_{\mathcal{T}})$ is Γ -rigid

if $h \geq (k + 1) + h - 1 - \min\{h/2, d - t\} - \min\{h/2 - 1, t\}$, or equivalently, $\min\{h/2, k + 1 - t\} + \min\{h/2 - 1, t\} \geq k$. By an elementary calculation, one can check that this is equivalent to $h \geq \max\{2(k - t), k + 1, 2t\}$.

To prove necessity, we suppose $h < \max\{2(k - t), k + 1, 2t\}$ and let $(G(\mathcal{S}), *, p)$ be a generic Γ -symmetric framework. If \mathcal{T} and \mathcal{T}^* are trivial simplicial k -circuits then, by Lemma 5.1, $V(\mathcal{T}) \cap V(\mathcal{T}^*) = \emptyset$, and it is clear that $G(\mathcal{S})$ is not Γ -rigid. So we may assume that \mathcal{T} and \mathcal{T}^* are nontrivial simplicial k -circuits. It follows easily that

$$\dim(\text{aff}(p(V(\mathcal{T})))) = \dim(\text{aff}(p(V(\mathcal{T}^*)))) = k + 1.$$

However, the assumption $h < \max\{2(k - t), k + 1, 2t\}$ implies that $H = \text{aff}(p(V(\mathcal{T}) \cap V(\mathcal{T}^*)))$ has dimension at most $k - 1$, and so $(G(\mathcal{T}), *_{\mathcal{T}}, p)$ has a nontrivial infinitesimal flex induced by rotation about H . □

Theorem 5.8. *Let $(\mathcal{S}, *)$ be a nontrivial \mathbb{Z}_2 -irreducible k -cycle for some $k \geq 2$. Suppose that $\Gamma = \Gamma_{t, k+1}$ for some $0 \leq t \leq k$ and that Γ is not a rotation group when $k = 2$. Then the following statements are equivalent.*

- (i) $(G(\mathcal{S}), *)$ is Γ -rigid in \mathbb{R}^{k+1} ;
- (ii) \mathcal{S} is a simplicial k -circuit or $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$ for some simplicial k -circuit \mathcal{T} with $|V(\mathcal{T}) \cap V(\mathcal{T}^*)| \geq \max\{2(k - t), k + 1, 2t\}$;
- (iii) for every $X \subset V(\mathcal{S})$ such that $X^* = X$ and $|X| < \max\{2(k - t), k + 1, 2t\}$, $G(\mathcal{S}) - X$ is connected.

Proof. Let $c = \max\{2(k - t), k + 1, 2t\}$.

By Lemmas 5.1 and 5.7, (i) implies (ii). To see that (ii) and (iii) are equivalent, observe that $c \leq 2k$ since $0 \leq t \leq k$. Also, if X is a $*$ -invariant subset of $V(\mathcal{S})$ of size less than $2k$, then Lemma 5.3 implies that X is a vertex separator of $G(\mathcal{T})$ if and only if $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$ for some simplicial k -circuit \mathcal{T} with $V(\mathcal{T}) \cap V(\mathcal{T}^*) \subseteq X$. The equivalence between (ii) and (iii) now follows.

It remains to prove that (ii) and (iii) imply (i). Suppose, for a contradiction, that \mathcal{S} is a counterexample to this statement with $|V(\mathcal{S})|$ minimal and let $G(\mathcal{S}) = G = (V, E)$.

Claim 5.9. There exists an edge $xy \in E$ such that $x^*y \notin E$.

Proof of claim. Suppose, for a contradiction, that $x^*y \in E$ whenever $xy \in E$. Then, for every $U \in \mathcal{S}$, $G[U \sqcup U^*]$ can be obtained from the complete graph on $U \sqcup U^*$ by deleting the set of edges $\{xx^* : x \in U\}$. Hence, $G[U \sqcup U^*]$ is isomorphic to $G(\mathcal{B}_k)$. We can now apply Lemma 4.2 to deduce that

$$G[U \sqcup U^*] \text{ is } \Gamma\text{-rigid for all } U \in \mathcal{S}. \tag{5.6}$$

Suppose \mathcal{S} is a simplicial k -circuit. Then \mathcal{S} is a strongly connected simplicial k -complex so, for all $U, U' \in \mathcal{S}$, there exists a sequence of k -faces U_1, U_2, \dots, U_m of \mathcal{S} such that $U_1 = U, U_m = U'$ and $|U_i \cap U_{i+1}| = k$ for all $1 \leq i \leq m - 1$. Putting $H = \bigcup_{i=1}^m G[U_i \cup U_i^*]$, we can now use (5.6) and Theorem 2.8 to deduce that H is Γ -rigid. This implies that every vertex of G belongs to the unique maximal Γ -rigid subgraph of G which contains $U \sqcup U^*$, and hence, G is Γ -rigid. This contradicts the choice of \mathcal{S} .

Thus, \mathcal{S} is not a simplicial k -circuit. Then $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$ for some simplicial k -circuit \mathcal{T} with $|V(\mathcal{T}) \cap V(\mathcal{T}^*)| \geq c$ by the assumption that (ii) holds for \mathcal{S} . Then \mathcal{T} is strongly connected, so we can apply the argument in the previous paragraph to deduce that $V(\mathcal{T})$ is contained in a Γ -rigid subgraph of G . By symmetry, $V(\mathcal{T}^*)$ is also contained in a Γ -rigid subgraph of G . Since $V(G) = V(\mathcal{T}) \cup V(\mathcal{T}^*)$, we can now apply Theorem 2.8 to deduce that G is Γ -rigid, again a contradiction. This completes the proof of the claim. □

Claim 5.9 tells us we can choose an edge $xy \in E$ such that $x^*y \notin E$. Let $(\mathcal{S}_1^+, \dots, \mathcal{S}_m^+)$ be a \mathbb{Z}_2 -symmetric Fogelsanger decomposition of \mathcal{S} at xy , and put $\mathcal{S}'_i = (\mathcal{S}_i^+ / xy) / x^*y^*$ for all $1 \leq i \leq m$. By Lemma 5.4(3), \mathcal{S}'_i is a \mathbb{Z}_2 -irreducible k -cycle.

Claim 5.10. For all $1 \leq i \leq m$, either $G(\mathcal{S}_i^+)$ is Γ -rigid or $\mathcal{S}_i^+ = \mathcal{T}_i \sqcup \mathcal{T}_i^*$ for some simplicial k -circuit \mathcal{T}_i with $|V(\mathcal{T}_i) \cap V(\mathcal{T}_i^*)| \leq 2k$.

Proof. The proof splits into two cases depending on the Γ -rigidity of $\mathcal{S}'_i = (\mathcal{S}_i^+ / xy) / x^*y^*$.

Suppose \mathcal{S}'_i is Γ -rigid. Since $xy \in E(\mathcal{S}_i^+)$ and \mathcal{S}_i^+ is a nontrivial \mathbb{Z}_2 -irreducible k -cycle by Lemma 5.4(a)(d), there exist $U_1, U_2 \in \mathcal{S}_i^+$ such that $|U_1 \cap U_2| = k$ and $\{x, y\} \subseteq U_1 \cap U_2$. Let $C = (U_1 \cup U_2) \setminus \{x, y\}$. Then $C \subset N_{G(\mathcal{S}_i^+)}(x) \cap N_{G(\mathcal{S}_i^+)}(y)$, $|C| = k$ and $|C \cap C^*| \leq 2$. Similarly, we can choose $D \subset N_{G(\mathcal{S}_i^+)}(x^*) \cap N_{G(\mathcal{S}_i^+)}(y^*)$ such that $|D| = k$ and $|D \cap D^*| \leq 2$. Theorem 2.14 now implies that $G(\mathcal{S}_i^+)$ is Γ -rigid.

Next, suppose \mathcal{S}'_i is not Γ -rigid. Then, by the minimality of $|V(\mathcal{S})|$, \mathcal{S}'_i does not satisfy (ii) in the statement of the theorem. Lemma 5.1 now implies that $\mathcal{S}'_i = \mathcal{T}' \sqcup \mathcal{T}'^*$ for some simplicial k -circuit \mathcal{T}' with $|V(\mathcal{T}') \cap V(\mathcal{T}'^*)| < c$. By Lemma 5.6, there is a simplicial k -circuit \mathcal{T} such that $\mathcal{S}_i^+ = \mathcal{T} \sqcup \mathcal{T}^*$ with $|V(\mathcal{T}) \cap V(\mathcal{T}^*)| \leq |V(\mathcal{T}') \cap V(\mathcal{T}'^*)| + 2$. Suppose $1 \leq t \leq k-1$. Then $c = \max\{2(k-t), k+1, 2t\} \leq 2k-1$. Hence, $|V(\mathcal{T}) \cap V(\mathcal{T}^*)| \leq |V(\mathcal{T}') \cap V(\mathcal{T}'^*)| + 2 \leq c + 1 \leq 2k$, as required. Hence, we may assume that $t = 0$ or $t = k$. Then $c = 2k$. Since $|V(\mathcal{T}') \cap V(\mathcal{T}'^*)|$ and c are both even, $|V(\mathcal{T}) \cap V(\mathcal{T}^*)| \leq |V(\mathcal{T}') \cap V(\mathcal{T}'^*)| + 2 \leq c = 2k$. This completes the proof. \square

We next define a sequence of simplicial k -cycles $\mathcal{W}_1, \mathcal{W}_2, \dots, \mathcal{W}_m$. For each $1 \leq i \leq m$, we set $\mathcal{W}_i = \mathcal{S}_i^+$ if $G(\mathcal{S}_i^+)$ is Γ -rigid. Otherwise, we put $\mathcal{W}_i = \mathcal{T}_i$, where \mathcal{T}_i is the simplicial k -circuit given by Claim 5.10 for \mathcal{S}_i^+ . We will show that

$$G(\mathcal{W}_i) \text{ and } G(\mathcal{W}_i^*) \text{ are both } \Gamma\text{-rigid.} \tag{5.7}$$

If $\mathcal{W}_i = \mathcal{S}_i^+$, then $G(\mathcal{W}_i)$ is Γ -rigid by definition, and we have $\mathcal{W}_i^* = (\mathcal{S}_i^+)^* = \mathcal{S}_i^+$ because \mathcal{S}_i^+ is a \mathbb{Z}_2 -irreducible k -cycle. Conversely, if $\mathcal{W}_i = \mathcal{T}_i$, then we have $|V(\mathcal{T}_i) \cap V(\mathcal{T}_i^*)| \leq 2k$, and we can apply Theorem 4.5 to deduce that $G(\mathcal{T}_i)$ and $G(\mathcal{T}_i^*)$ are both Γ -rigid. Thus, (5.7) holds.

We can now complete the proof of the theorem. Using Lemma 5.4(7) to reorder $(\mathcal{S}_1^+, \dots, \mathcal{S}_m^+)$ as necessary, and interchanging \mathcal{T}_i^* and \mathcal{T}_i where necessary, we can assume that

$$\mathcal{W}_j \cap (\Delta_{i=1}^{j-1} \mathcal{W}_i) \neq \emptyset \text{ for } 2 \leq j \leq m. \tag{5.8}$$

The hypothesis that $xx^* \notin E$ for all $x \in X$ implies that

$$U \cap U^* = \emptyset \text{ for all cliques } U \text{ of } G(\mathcal{S}). \tag{5.9}$$

We can now apply a straightforward induction argument using (5.7), (5.8), (5.9) and Theorem 2.8 to deduce that

$$\bigcup_{i=1}^m G(\mathcal{W}_i) \text{ and } \bigcup_{i=1}^m G(\mathcal{W}_i^*) \text{ are both } \Gamma\text{-rigid.} \tag{5.10}$$

If $\mathcal{W}_i = \mathcal{S}_i^+$ for some $1 \leq i \leq m$, then $\bigcup_{i=1}^m G(\mathcal{W}_i)$ and $\bigcup_{i=1}^m G(\mathcal{W}_i^*)$ intersect in at least $2k$ vertices. By Theorem 2.8, $G(\mathcal{S}) = (\bigcup_{i=1}^m G(\mathcal{W}_i)) \cup (\bigcup_{i=1}^m G(\mathcal{W}_i^*))$ is Γ -rigid contradicting our choice of \mathcal{S} .

So we can assume that for $i = 1, \dots, m$, $\mathcal{S}_i^+ = \mathcal{T}_i \sqcup \mathcal{T}_i^*$, where \mathcal{T}_i is simplicial k -circuit properly contained in \mathcal{S}_i^+ and $\mathcal{W}_i = \mathcal{T}_i$. If $\mathcal{T}_i \cap \mathcal{T}_j^* \neq \emptyset$ for some distinct i, j , then $\bigcup_{i=1}^m G(\mathcal{T}_i)$ and $\bigcup_{i=1}^m G(\mathcal{T}_i^*)$ intersect on a $(k+1)$ -clique in $G(\mathcal{S})$. Hence, their union is Γ -rigid by (5.9) and the gluing theorem (Theorem 2.8). Since the union is $G(\mathcal{S})$ by Lemma 5.4(b), this contradicts the choice of \mathcal{S} as a counterexample.

Therefore, $\mathcal{T}_i \cap \mathcal{T}_j^* = \emptyset$ for all $1 \leq i, j \leq m$. By Lemma 5.4(e), \mathcal{T}_i^* contains a simplex $U \in \mathcal{S}$ that is not contained in any \mathcal{S}_j^+ for $j \neq i$. This, and the facts that $\mathcal{T}_i \cap \mathcal{T}_j^* = \emptyset$ for all $1 \leq i, j \leq m$ and $\Delta_{i=1}^m \mathcal{S}_i^+ = \mathcal{S}$, imply that $\Delta_{i=1}^m \mathcal{T}_i$ is a simplicial k -cycle that is properly contained in \mathcal{S} , so \mathcal{S} is not a simplicial k -circuit. Since \mathcal{S} satisfies (ii) from the statement of the theorem, it follows from Lemma 5.1

that $\mathcal{S} = \mathcal{T} \sqcup \mathcal{T}^*$, where $\mathcal{T} = \bigcup_{i=1}^m \mathcal{T}_i$ and $|V(\mathcal{T}) \cap V(\mathcal{T}^*)| \geq \max\{2(k - t), k + 1, 2t\} =: c$. Moreover, also by Lemma 5.1, \mathcal{T} must be a simplicial k -circuit.

Note that $G(\mathcal{T}) \subseteq \bigcup_{i=1}^m G(\mathcal{T}_i)$ and $G(\mathcal{T}^*) \subseteq \bigcup_{i=1}^m G(\mathcal{T}_i^*)$, so $\bigcup_{i=1}^m G(\mathcal{T}_i)$ and $\bigcup_{i=1}^m G(\mathcal{T}_i^*)$ also have at least c common vertices. We can now use (5.10), Theorem 2.8 and Lemma 5.4(b) to deduce that $G(\mathcal{S})$ is Γ -rigid, contradicting our choice of \mathcal{S} . This final contradiction completes the proof of the theorem. \square

Theorem 5.8 immediately gives the following sufficient condition for the Γ -rigidity of \mathbb{Z}_2 -symmetric simplicial circuits.

Theorem 5.11. *Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -symmetric simplicial k -circuit with $k \geq 2$. Then $(G(\mathcal{S}), *)$ is Γ -rigid in \mathbb{R}^{k+1} if either $k \geq 3$ or $k = 2$ and Γ is not the half-turn rotation group.*

Since every pseudomanifold is a simplicial circuit, [11, Conjecture 8.3] follows immediately as a special case of Theorem 5.11.

6. The lower bound theorem

The lower bound theorem for \mathbb{Z}_2 -irreducible k -cycles is an immediate corollary of Theorem 5.8 and Lemma 2.2.

Theorem 6.1. *Let $(\mathcal{S}, *)$ be a nontrivial simplicial \mathbb{Z}_2 -irreducible k -cycle for some $k \geq 2$. Suppose that $G(\mathcal{S}) - X$ is connected for all $X \subset V$ which satisfy $X^* = X$ and $|X| \leq 2k$. Then $g_2(\mathcal{S}) = |E(\mathcal{S})| - (k + 1)|V(\mathcal{S})| + \binom{k+2}{2} \geq \binom{k+1}{2} - (k + 1)$.*

Proof. We can apply Theorem 5.8 in the case when $\Gamma = \Gamma_{0,k+1}$ is a point inversion to deduce that $(G(\mathcal{S}), *)$ is Γ -rigid. The case $t = 0$ of Lemma 2.2 now gives $g_2(\mathcal{S}) \geq \binom{k+1}{2} - (k + 1)$. \square

A similar argument using Theorem 5.11 and Lemma 2.2 gives the following:

Theorem 6.2. *Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -symmetric simplicial k -circuit with $k \geq 2$. Then $g_2(\mathcal{S}) \geq \binom{k+1}{2} - (k + 1)$.*

Since every pseudomanifold is a simplicial circuit, this immediately gives the following lower bound result for pseudomanifolds and hence verifies the inequality part of [11, Conjecture 8.1]

Corollary 6.3. *Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -symmetric k -pseudomanifold with $k \geq 2$. Then $g_2(\mathcal{S}) \geq \binom{k+1}{2} - (k + 1)$.*

7. Closing remarks

7.1. Characterising $\Gamma_{1,3}$ -rigid simplicial 2-circuits

Theorem 5.8 resolves the $\Gamma_{t,k+1}$ -rigidity question for \mathbb{Z}_2 -symmetric simplicial k -circuits in \mathbb{R}^{k+1} , except in the case when $t = 1$ and $k = 2$. In this case, Lemma 2.2 implies that the boundary complex of a \mathbb{Z}_2 -symmetric simplicial polyhedron cannot be $\Gamma_{1,3}$ -rigid in \mathbb{R}^3 . Other examples can be obtained from the boundary complex \mathcal{P} of a \mathbb{Z}_2 -symmetric simplicial polyhedron by choosing a face F of \mathcal{P} and ‘inserting’ an arbitrary simplicial 2-circuit \mathcal{T} into both F and F^* . More precisely, we choose a copy \mathcal{T}^* of \mathcal{T} , label the vertices of \mathcal{T} so that $F \in \mathcal{T}$ and $V(\mathcal{P}) \cap V(\mathcal{T}) = F$, and then put $\mathcal{S} = \mathcal{P} \Delta (\mathcal{T} \sqcup \mathcal{T}^*)$.

We believe that all examples of \mathbb{Z}_2 -symmetric simplicial 2-circuits which are not $\Gamma_{1,3}$ -rigid in \mathbb{R}^3 can be obtained by recursively applying this insertion operation to the boundary complex of a \mathbb{Z}_2 -symmetric simplicial polyhedron. This would imply the following conjecture.

Conjecture 7.1. *Suppose that $(\mathcal{S}, *)$ is a \mathbb{Z}_2 -symmetric simplicial 2-circuit such that $G(\mathcal{S})$ is 4-connected and non-planar. Then $G(\mathcal{S})$ is $\Gamma_{1,3}$ -rigid in \mathbb{R}^3 .*

A graph $G = (V, E)$ is *redundantly rigid* in \mathbb{R}^d if $G - e$ is rigid in \mathbb{R}^d for all $e \in E$. We showed in [6] that if G is the graph of a simplicial k -circuit for some $k \geq 3$ and G is $(k + 1)$ -connected, then G is redundantly rigid in \mathbb{R}^{k+1} , and we used this to deduce that equality in the Lower Bound Theorem can only hold for simplicial k -circuits when they are stacked k -spheres. We believe that an analogous approach may work for Γ -rigidity and our symmetric lower bound theorem.

7.2. Redundant Γ -rigidity of simplicial circuits

Conjecture 7.2. Let $(\mathcal{S}, *)$ be a \mathbb{Z}_2 -symmetric simplicial k -circuit such that $k \geq 3$, $\mathcal{S} \neq \mathcal{B}_k$ and $G(\mathcal{S})$ is $(k + 1)$ -connected. Then, for all point groups Γ in \mathbb{R}^{k+1} of order two and all $e \in E(\mathcal{S})$, $(G(\mathcal{S}) - e - e^*, *)$ is Γ -rigid in \mathbb{R}^{k+1} .

Conjecture 7.2 would imply that equality can only hold in Theorem 6.2 when \mathcal{S} is a symmetrically stacked sphere (see [11] for a definition) and would verify [11, Conjecture 8.1] as a special case.

7.3. Non-adjacent vertex pairings

The Bricard octahedron shows that Theorem 4.5 will become false if we remove the hypothesis that $|X| \leq 2k$. More generally, any \mathbb{Z}_2 -symmetric boundary complex of a polyhedron will not be Γ -rigid in \mathbb{R}^3 when Γ is the half turn rotation group by Lemma 2.2. It is conceivable, however, that the hypothesis that $|X| \leq 2k$ is not necessary in certain special cases. Indeed, [11, Conjecture 8.4] is precisely this statement in the case when $k = 2$, \mathcal{S} is a simplicial sphere and Γ is a point inversion group.

7.4. More general group actions

Adin [1], and later Jorge [9], extended Stanley’s lower bound theorem to rational polytopes with a cyclic linear symmetry group of prime power order. Their methods are very different from ours, relying on algebraic properties of the Stanley-Reisner ring of a simplicial complex.

It is natural to ask if the rigidity-based approach can be used to extend these results to simplicial circuits and/or other point groups. In this paper, we frequently use the fact that $*$ is free and Γ is a point group of order two. Relaxing either of these restrictions in a rigidity-based approach remains an open problem.

7.5. The lower bound conjecture for higher dimensional faces

Let $\phi_j(n, k)$ be the number of j -faces of a symmetrically stacked k -sphere with n vertices. One can easily verify by induction on n that

$$\phi_j(n, k) = \begin{cases} 2^{j+1} \binom{k+1}{j+1} + (n - 2k - 2) \binom{k+1}{j} & \text{if } j \leq k - 1 \\ 2^{k+1} + k(n - 2k - 2) & \text{if } j = k \end{cases}$$

For a simplicial complex \mathcal{S} , let $f_j(\mathcal{S})$ be the number of j -faces of \mathcal{S} .

Conjecture 7.3. Suppose that $k \geq 2$ and \mathcal{S} is a simplicial k -circuit with n vertices and $*$ is a free simplicial involution on \mathcal{S} . Then $f_j(\mathcal{S}) \geq \phi_n(n, k)$ for $j = 1, \dots, k$. Moreover, if equality occurs for any j , then \mathcal{S} must be a k -sphere and, in the case that $k \geq 3$, must be a symmetrically stacked k -sphere.

In the non-symmetric setting, the analogous conjecture for simplicial manifolds can be derived from the case $j = 1$ by an induction argument based on the fact that the link of any proper face in a simplicial manifold is a simplicial sphere of lower dimension (see [10] for details). However, in the \mathbb{Z}_2 -symmetric case, this argument does not generalise easily since the link of F is not \mathbb{Z}_2 -symmetric. One might consider the union of the links of F and F^* , but that is not necessarily a simplicial manifold, even when \mathcal{S} is a simplicial sphere.

A further difficulty for Conjecture 7.3, and indeed for the non-symmetric version [6, Conjecture 8.2], arises from the fact that the class of simplicial circuits is not link closed. In general, the link of a j -face in a nontrivial simplicial k -circuit will be a simplicial $(k - j - 1)$ -cycle but not necessarily a simplicial $(k - j - 1)$ -circuit.

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Competing interest. The authors have no competing interest to declare.

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