



Elasto-inertial dissipation in particle-laden viscoelastic Taylor–Couette flow

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Many natural and industrial processes involve the flow of fluids made of solid particles suspended in non-Newtonian liquid matrices, which are challenging to control due to the fluid's nonlinear rheology. In the present work, a Taylor–Couette canonical system is used to investigate the flow of dilute to semi-dilute suspensions of neutrally buoyant spherical particles in highly elastic base polymer solutions. Friction measurement synchronized with direct flow visualization are combined to characterize the critical conditions for the onset of elasto-inertial instabilities, expected here as a direct transition to elasto-inertial turbulence (EIT). Adding a low particle volume fraction ($\leq 2\%$, dilute regime) does not affect the nature of the primary transition and reduces the critical Weissenberg number for the onset of EIT, despite a significant decrease in the apparent fluid elasticity. However, for particle volume fractions $\geq 6\%$ (semi-dilute regime), EIT is no longer observed in the explored Reynolds range, suggesting an apparent relaminarization with yet not further decrease in fluid elasticity. Instead, a new regime, termed here elasto-inertial dissipative (EID), was uncovered. It originates from particle–particle interactions altering particle–polymer interactions and occurring under elasto-inertial conditions comparable to those of EIT. Increasing particle volume fraction in the semi-dilute regime and, in so, the particle contribution to the overall viscosity, delays the onset of EID similarly to what was observed previously for EIT in lower elasticity fluids. After this onset, a decrease in the pseudo-Nusselt number observed with increasing inertia and particle-to-polymer concentration ratio confirms a particle-induced alteration of energy transfer in the flow.

Key words: suspensions, Taylor-Couette flow, viscoelasticity

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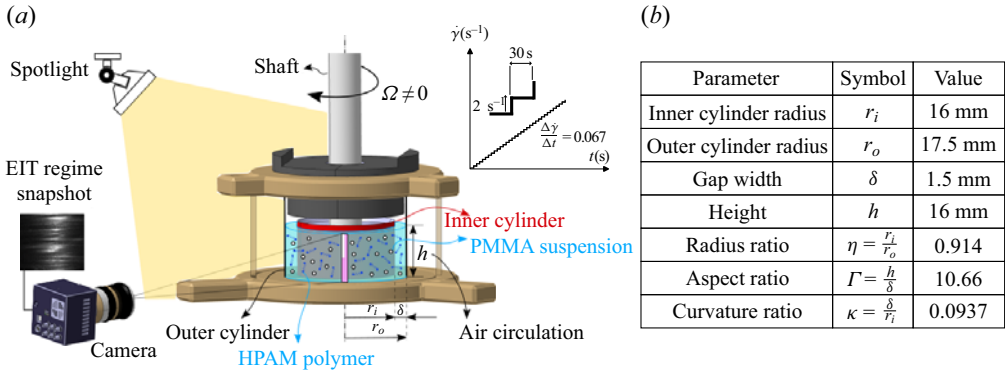


Figure 1. (a) Taylor–Couette cell mounted on an MCR102 Anton Paar rheometer with geometrical parameters symbols and illustration of the imaging system (see details in Moazzen *et al.* 2022, 2023) and quasi-steady inner cylinder ramp-up protocol. (b) Geometrical cell parameters values.

1. Introduction

Suspensions of solid particles in a Newtonian or non-Newtonian liquid matrix are frequently encountered in nature and industrial applications (cement, toothpaste, three-dimensional printing material, avalanches, blood flow, to name a few). When flowing at various scales, such fluids demonstrate a wide variety of nonlinear dynamic behaviours, arising from inertia, complex rheology of the suspending liquid phase, fluid–particle interactions or particle–particle interactions. They induce a dynamic complexity of the flow, making it difficult to control its stability, mixing and heat transfer efficiency as well as to predict overall process performance. Despite recent studies (Tanner 2020; Baroudi *et al.* 2023; Boulaferis *et al.* 2023; Zhang & Shaqfeh 2023; Boulaferis *et al.* 2024), experimental data are still needed to better understand the hydrodynamic behaviour of complex suspensions and confront numerical models (Kang & Mirbod 2021; Song *et al.* 2021; Lin *et al.* 2023; Kang, Schatz & Mirbod 2024; Lin *et al.* 2024).

To gather experimental data and deepen understanding on complex fluid flows, it is convenient to consider well-studied canonical flows. In the present work, the canonical Taylor–Couette flow (TCF) is used (Andereck, Liu & Swinney 1986; Taylor 1922; Fardin, Perge & Taberlet 2014). It consists in two concentric cylinders of radii r_i and r_e (with $r_e > r_i$, see figure 1) and height h . Here the case considered is that where only the inner cylinder is rotated at rotation speed Ω and the outer cylinder is fixed. The fluid entrapped in the gap $\delta = r_e - r_i$ is subjected to a shear rate $\dot{\gamma} = \Omega r_i / \delta$. This configuration has been widely used in the recent literature to characterize instabilities and transition to chaos in a wide range of complex fluids (Fardin *et al.* 2014; Boulaferis *et al.* 2023). In that context, it was for example found that the presence of non-colloidal neutrally buoyant particles in a viscous Newtonian base fluid alters the nature and onset of the primary bifurcation (Majji, Banerjee & Morris 2018; Ramesh, Bharadwaj & Alam 2019), as well as the friction dynamics, as evidenced by the evolution of the torque exerted on the inner cylinder τ as a function of the Reynolds number \mathcal{R} (Dash, Anantharaman & Poelma 2020; Kang & Mirbod 2021; Moazzen *et al.* 2022):

$$\mathcal{R} = \frac{\rho r_i \Omega \delta}{\mu} = \frac{\rho \dot{\gamma} \delta^2}{\mu}, \quad (1.1)$$

where \mathcal{R} is the non-dimensional flow control parameter characterizing the onset of inertial instabilities (see (1.1)) (with ρ is the fluid density and μ is the suspension

dynamic viscosity). However, particle-free viscoelastic fluids exhibit their own rich set of specific dynamics: low \mathcal{R} transitions to modes that are not evidenced in Newtonian fluids (Boulafentis *et al.* 2023), transitions to well-known modes but triggered by elastic or elasto-inertial mechanisms (Larson, Shaqfeh & Muller 1990) or ultimately transitions to a form of chaos resembling turbulence at much lower (Dutcher & Muller 2013; Boulafentis *et al.* 2023) or even negligible inertia (elastic turbulence, Groisman & Steinberg 1998, 2000, 2004). The flow control parameter for such behaviours is the Weissenberg number $\mathcal{W} = \lambda\dot{\gamma}$, with λ the relaxation time of the viscoelastic solution. Here, \mathcal{W} compares elastic to viscous forces. Additionally, it is worth defining the elastic number \mathcal{E} , which quantifies the importance of the elastic behaviour in the given Taylor–Couette geometry:

$$\mathcal{E} = \frac{\mathcal{W}}{\mathcal{R}} = \frac{\lambda\mu}{\rho\delta^2} \quad (1.2)$$

In this work, emphasis is placed on fluids of moderate to high elasticity ($\mathcal{E} \gg 10^{-2}$, Dutcher & Muller 2013) flowing at commensurate inertia for which viscoelastic properties give rise to elasto-inertial transitions: instabilities that are either due to elastic mechanisms but arising at non-negligible \mathcal{R} values or inertial but modified by elasticity. There, transition to a chaotic flow state labelled elasto-inertial turbulence (EIT) is observed (Groisman & Steinberg 1996; Boulafentis *et al.* 2023; Lin *et al.* 2023). The onset and the pathway towards EIT, as well as its final structure, have been found to depend on various parameters, among which the nature, conformation and concentration of the additives (most of the time polymers) confer viscoelastic properties to the fluid. In particular, the dynamic properties of EIT differ from those of inertial turbulence both in terms of friction scaling and spectral distribution (Boulafentis *et al.* 2023, 2024; Moazzen *et al.* 2023).

The aim of the present paper is to investigate the behaviour of fluids combining both complex features, particles and elasticity, and to characterize elasto-inertial transitions in such systems. A first experimental study on this topic in a Taylor–Couette configuration (Lacassagne *et al.* 2021) indicated that a low particle volume fraction may promote faster transition to EIT in terms of \mathcal{R} , whereas higher particle volume fractions (more than 5 %) were found to delay transition to EIT. This former study employed visualization to detect transitions and characterize EIT properties for a single moderately elastic base fluid ($\mathcal{E} = O(10^{-1})$, one polymer concentration) and four particle volume fractions. The present work sets at pushing the investigation further and unravel physical mechanisms by: (1) coupling flow visualization with torque measurements to get information on the friction dynamics during transitions and flow states; (2) extending the approach to more elastic base fluids ($\mathcal{E} = O(10^1)$) for which direct transition from the base laminar state to fully chaotic EIT is evidenced (Groisman & Steinberg 1996; Moazzen *et al.* 2023); and (3) covering a wider range of particle concentrations ($\Phi = 0, 2, 6, 10, 14\%$).

2. Materials and methods

2.1. Experimental set-up

The experimental set-up is similar to that used by Moazzen *et al.* (2022, 2023), and its geometrical parameters are represented in [figure 1](#).

With the outer cylinder was kept at rest, the inner cylinder was rotated with angular velocity Ω , controlled by the rheometer’s motor. The maximum inner cylinder rotation frequency achievable bounded the maximum respective \mathcal{R} and \mathcal{W} experimentally accessible to values \mathcal{R}_{max} and \mathcal{W}_{max} reported in [table 1](#), depending on each working

\tilde{C} (ppm)	Φ (%)	μ (Pa s)	λ_{N_1} (s)	λ_e (s)	\mathcal{E}^0	\mathcal{E}	\mathcal{W}_c	\mathcal{W}_{max}	\mathcal{R}_c	\mathcal{R}_{max}	\mathcal{R}_p^{max}
300	0	0.0508	0.1092	0.482	2.07	2.1	93.8	153.5	45.3	74.2	0.0190
	2	0.0503	0.0332	0.122		0.6	26.5	46.7	42.5	74.9	0.0192
	6	0.0484	0.0456	0.142		1.1	29.1	64.1	27.5	60.4	0.0155
	10	0.0566	0.0217	0.121		0.5	13.0	30.5	28.4	66.6	0.0170
	14	0.0782	0.0713	0.108		2.1	50.7	100.1	24.4	48.2	0.0123
400	0	0.0584	0.1971	0.795	4.28	4.3	197.3	276.9	46.0	64.6	0.0165
	2	0.0599	0.1538	0.579		3.4	134.0	216.0	39.0	62.9	0.0161
	6	0.0743	0.1647	0.485		4.6	145.1	231.4	31.8	50.7	0.0130
	10	0.0756	0.1282	0.412		3.6	137.0	180.1	37.9	49.9	0.0128
	14	0.0694	0.1169	0.324		3.0	99.0	164.2	32.7	54.3	0.0139
500	0	0.0680	0.3793	1.020	9.61	9.6	398.5	532.9	41.4	55.4	0.0142
	2	0.0674	0.1199	0.486		3.0	147.1	168.5	48.8	55.9	0.0143
	6	0.0768	0.1973	0.435		5.7	144.6	277.1	25.59	49.0	0.0126
	10	0.0910	0.1971	0.485		6.7	170.1	277.0	25.45	41.4	0.0106
	14	0.1006	0.2309	0.422		8.7	263.2	324.4	30.40	37.5	0.0096

Table 1. Rheological viscoelastic suspensions properties and associated dimensionless numbers. $\mathcal{W}_c = \lambda_{N_1} \times \dot{\gamma}_c$, $\mathcal{R}_c = \rho \delta^2 \dot{\gamma}_c / \mu$ and $\dot{\gamma}_c$ are the respective critical Wiessenberg number, Reynolds number and shear-rate for the onset of EIT for $\Phi = 0$ or 2%, or new elasto-inertial dissipative (EID) mechanisms (in italics, for $\Phi \geq 6\%$). Superscript 0 indicates quantities computed using the base fluid relaxation time $\lambda^0 = \lambda_{N_1} (\Phi = 0\%)$. Apparent relaxation time scales $\lambda = \lambda_{N_1} (\Phi, \tilde{C})$ are used otherwise. The maximum particle Reynolds number is $\mathcal{R}_p^{max} = \rho \dot{\gamma}_{max} dp^2 / 4\mu$.

fluid viscosity and elasticity. Experiments were performed using slow acceleration (or ramp-up) protocol (see figure 1). The difference maximum shear rate was kept constant at $\dot{\gamma}_{total} = 750 \text{ s}^{-1}$ and $\dot{\gamma}$ was increased in steps of 2 s^{-1} . At each step, the shear rate was held constant for a period of $t = 30 \text{ s}$. This resulted in non-dimensional acceleration rates of order (10^{-4}) at most, well into the quasi-steady assumption (Dutcher & Muller 2013; Boulaferis *et al.* 2023).

Experiments were conducted with viscoelastic base fluids made of HPAM (partially hydrolyzed polyacrylamide; molecular weight $M_w = 15 - 20 \times 10^6 \text{ g mol}^{-1}$) at concentrations of $\tilde{C} = 300, 400, 500 \text{ ppm}$, dissolved in a solution of distilled water (31% in volume), glycerol (69% in volume) and sodium chloride (2% in mass), and loaded with mono-disperse spherical PMMA (polymethyl methacrylate) particles of diameter of $d_p = 50 \text{ }\mu\text{m}$ at volume fractions $\Phi = 0, 2, 6, 10, 14\%$. The particle Reynolds number $\mathcal{R}_p = \rho \dot{\gamma} dp^2 / 4\mu$ was such that $\mathcal{R}_p < 0.02$ for all fluids and experiments. The density of solid particles and viscoelastic base fluid were matched ($\rho = 1192 \text{ kg m}^{-3}$), resulting in neutrally buoyant particle suspensions.

2.2. Rheological characterization

The shear-viscosity of the working fluids was measured as a function of the shear rate $\dot{\gamma}$, using an MCR302 Anton Paar rheometer with a 50 mm diameter parallel-plate geometry (chosen over the conventional cone-plate one to limit inertial and centrifugal effects on particle loaded samples) at a 0.5 mm gap. Measurements confirmed that the working fluids could be considered as Boger fluids (Boger 1977; James 2009), their viscosity being shear-rate independent in the considered range (almost two order of magnitudes of $\dot{\gamma}$). This implies that the Reynolds number increased linearly as a function of the applied shear-rate in the Taylor–Couette set-up. Averaged viscosity values are reported in figure 2(a) and in

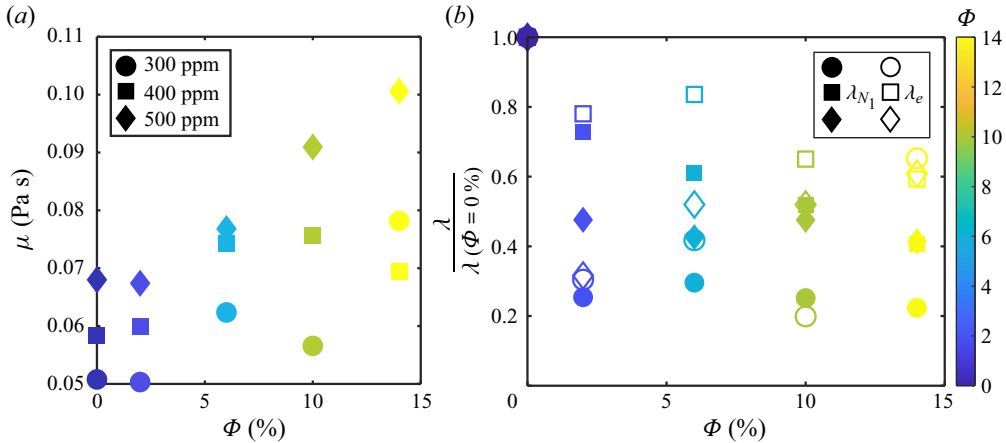


Figure 2. (a) Constant shear viscosity (averaged on a 10–100 s⁻¹ shear-rate range) for all polymer and particle concentrations. An MCR302 rheometer with parallel-plate 50 mm geometry with a 0.5 mm gap was used. (b) Elastic time scale λ for all fluid samples, normalized by the particle-free measured value, obtained from first normal stress differences (empty markers, same rheometer) or extensional measurements (full markers – bespoke extensional rheometer set-up).

table 1. As expected, the apparent viscosity of the fluid increased with increasing polymer concentration, but most importantly with particle volume fraction (Zhang & Shaqfeh 2023).

The elasticity of the working fluids was measured using first normal stress differences N_1 (Lin, Phan-Thien & Cheong Khoo 2014; Schäfer, Morozov & Wagner 2018; Moazzen *et al.* 2023), with the same parallel-plate geometry. For a Boger fluid, it is known that

$$N_1 = 2\mu_p\lambda_{N_1}\dot{\gamma}^2 \quad (2.1)$$

with μ_p the polymer viscosity contribution ($\mu_p = \mu - \mu_{sol}$, with $\mu_{sol} = 33.3$ mPa.s the solvent viscosity), and λ_{N_1} the relaxation time. Here, λ_{N_1} was estimated for all fluids inverting the previous equation and averaging on the range of $\dot{\gamma}$ over which the power 2 scaling is valid. The nominal elastic number of each base working fluid \mathcal{E}^0 was computed using the apparent overall suspension viscosity μ (reported in table 1) and the elastic time scale of the corresponding particle-free fluid (each fluid at the same polymer concentration displays the same \mathcal{E}^0 , reported in table 1, regardless of particle addition). Apparent elastic number values \mathcal{E} were computed for each fluid using directly measured λ_{N_1} and μ . Additionally, measurements of apparent extensional time scales λ_e were performed using a slow retraction capillary thinning protocol (Campo-Deaño & Clasen 2010) on a bespoke set-up (analogue to Boulafentis *et al.* 2024). Thread thinning dynamics of a fluid filament created between two plates slowly separating was fitted in the exponential-thinning regime such that

$$\lambda_e = \frac{-t}{3 \ln\left(\frac{d}{d_{max}}\right)} \quad (2.2)$$

with $d(t)$ the filament diameter evolving with time (t) and d_{max} the maximum (initial) diameter. All rheological data (shear and extension) were consolidated by averaging over at least three and up to six repeated tests. The evolution of apparent time scale normalized by that of particle-free samples for both normal stress and extensional methods is plotted as a function of Φ in figure 2.

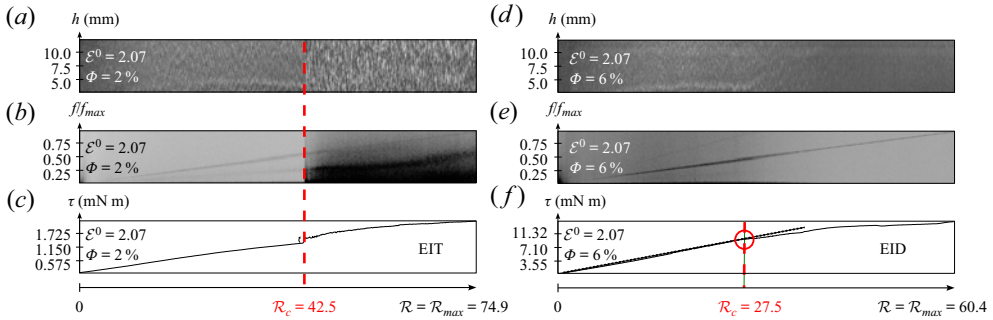


Figure 3. Coupling of flow visualization with (a,d) space–time diagrams, (b,e) frequency maps where $f_{max} = 2\pi/\Omega_{max}$ correspond to maximal inner cylinder frequency and (c,f) torque measurements, applied to samples with $\tilde{C} = 300$ ppm, (a–c) $\Phi = 2\%$ and (d–f) $\Phi = 6\%$. Vertical dashed red lines indicate the critical \mathcal{R}_c value for the onset of EIT when this flow state is evidenced in panels (a–c), or a new regime discussed hereinafter in panels (d–f), also indicated by a red circle. Linear ridges visible in frequency maps in panels (b,e) correspond to the rotation frequency of the inner cylinder detected by the method.

2.3. Measurement techniques

2.3.1. Flow visualization

The flow behaviour was probed using a coupling of direct visualization and torque measurement on the inner cylinder (using the built-in torque sensor of the rheometer). Flow visualization was achieved by seeding the flow with anisotropic reflective mica flakes, which enable the monitoring of the flow spatial structure (Boulaferis *et al.* 2023). The light reflected by the mica flakes was recorded using a camera at a frame rate of 70 images per second (see figure 1). From the reflected light signal along a vertical column of the test section, two types of visualization tools were constructed. First, space–time diagrams were built by stacking the intensity signal obtained for this vertical at various inner cylinder rotation speeds and thus \mathcal{R} values. The change in flow structure, due for example to a transition to EIT, (see figure 3 and also represented in the supplementary movie) is clearly visible on such graph: the laminar base flow, called circular Couette flow (CCF), is expressed by a uniform grey colour while EIT regime’s signature is a highly chaotic spatial signal. Second, the temporal fast Fourier transform (FFT) of intensity signals was computed according to a protocol detailed by Lacassagne *et al.* (2021) and Moazzen *et al.* (2023), and resulting spectra were stacked vertically as a function of control parameters (frequency map). This allows to distinguish between stationary flow states with no specific spectral signatures (such as CCF) and a flow state with characteristic frequencies or energy spectra, such as EIT, and thus detect the onset of the latter in an even more accurate way (see figure 3). In such figures, the straight darker lines correspond to the inner cylinder rotation frequency, which is captured by the method. Frequency axes are scaled by the maximal inner cylinder frequency $f_{max} = 2\pi/\Omega_{max}$.

2.3.2. Torque measurement

Simultaneously, the rheometer allowed to measure the torque needed to rotate the inner cylinder (Dash *et al.* 2020; Moazzen *et al.* 2022, 2023), providing insight into the friction dynamics and making it possible to evidence transitions to other friction regime, independently of any visual signature. This is further illustrated in figure 4. In the CCF (laminar) regime, the torque is expected to increase linearly with \mathcal{R} with a

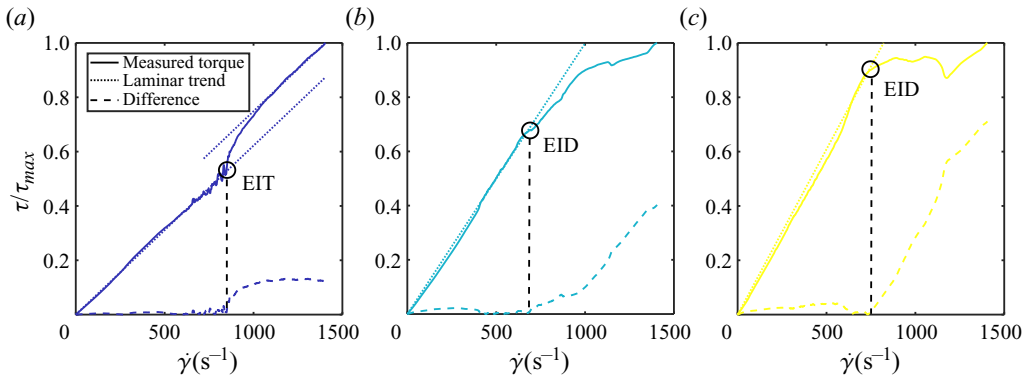


Figure 4. Detection of critical conditions (here $\dot{\gamma}_c$) for the transition to non-laminar friction regimes, for $\tilde{C} = 300$ ppm and $\Phi = 0, 6$ and 14% . Full line curves are measured torque signals, dotted lines are laminar trends and dashed lines are the norm of the difference between measured torque and laminar trend. All values are scaled by the maximum torque measured at the end of the run τ_{max} . Black circles and vertical dashed lines represent detected critical $\dot{\gamma}$ where laminar trend and torque curve diverge. The colour scheme for particle concentrations is the same as in figure 2. (a) $\Phi = 0\%$, (b) $\Phi = 6\%$, (c) $\Phi = 14\%$.

slope proportional to the fluid viscosity (Couette 1890; Dubrulle *et al.* 2005; Eckhardt, Grossmann & Lohse 2007). Any departure of the torque measurements (figure 4 full lines) from this linear trend (figure 4 dotted lines), which becomes even more visible when plotting the difference between the laminar prediction and the torque measurement (figure 4 dashed lines), indicates a change in the friction regime.

For EIT, this corresponds to a sudden jump in measured torque (Martínez-Arias & Peixinho 2017; Moazzen *et al.* 2023), followed by a gradual convergence towards a similar laminar-like torque– \mathcal{R} slope, yet shifted upwards (Moazzen *et al.* 2023, figure 3c, figure 4a). The coupling of all three indicators (space–time diagram, frequency map, torque dynamics) allows to detect the critical \mathcal{R} value for the onset of EIT when it arises, labelled \mathcal{R}_c , as illustrated in figure 3(a–c), with a high degree of accuracy (less than 0.5% of variation on \mathcal{R}_c obtained with the three methods, on all used fluids).

When no EIT is detected, no jump is reported. Yet, a change in trend is still observed. This takes the form of a decrease in the slope of the measured torque– \mathcal{R} curve at a given critical \mathcal{R} value (circle in figure 3f) or shear rate (circles in figure 4b,c), corresponding to a continuous increase in the measurement-to-laminar prediction difference (figure 4 dashed lines).

It is remarkable that in pure Newtonian or particle loaded Newtonian fluids, primary and higher order bifurcations are always accompanied by secondary flows and lead to an increase in the torque– \mathcal{R} curve slope (Ramesh *et al.* 2019; Dash *et al.* 2020; Kang & Mirbod 2021; Moazzen *et al.* 2022). Here, the milder slope suggests that additional energy dissipation may occur elsewhere in the flow reducing the friction dissipation at the inner cylinder as compared to the laminar trend, as will be discussed later.

3. Results and discussions

Figure 3 illustrates the two types of results encountered. For particle-free fluids, the direct transition from CCF to EIT as depicted by Groisman & Steinberg (1996), Moazzen *et al.* (2023) and expected in this set-up from our previous study (Moazzen *et al.* 2023) is indeed evidenced. A similar transition is also found in low particle volume fraction fluids (2%), as illustrated in figure 3(a–c) ($\tilde{C} = 300$ ppm, $\Phi = 2\%$). However, for all higher

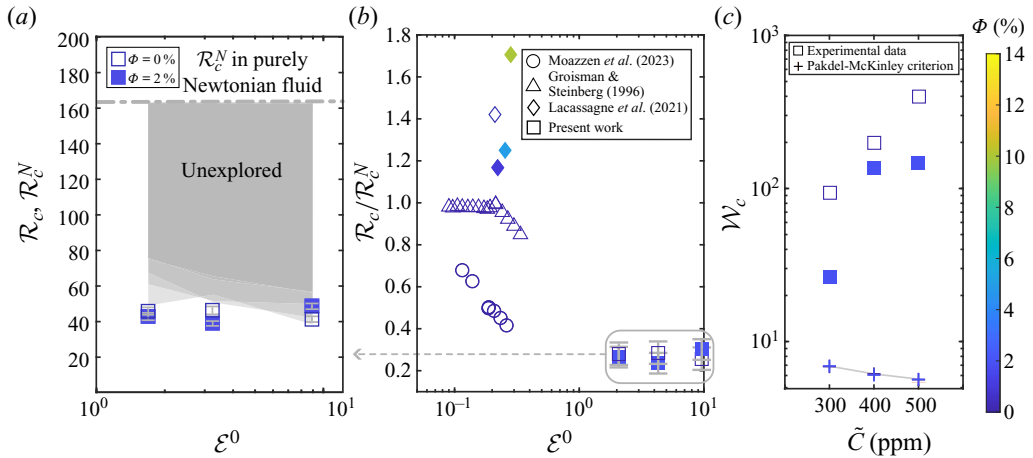


Figure 5. (a) Critical value \mathcal{R}_c for the onset of EIT as a function of the base fluid elastic number \mathcal{E}^0 compared with (b) previous literature data. The horizontal dashed line in panel (a) represents the critical Reynolds number \mathcal{R}_c^N for the onset of the primary instability in a Newtonian fluid in the same Couette geometry (Moazzen *et al.* 2022). Errors bars are derived from uncertainty propagation from viscosity (dominant) and detection (negligible) uncertainties. (c) Critical \mathcal{W}_c for the onset of EIT (squares) compared with the purely elastic instability threshold computed with the Pakdel–McKinley criterion adapted to the Taylor–Couette geometry (plus signs, see (3.1) proposed by Schäfer *et al.* 2018). Empty squares are present work values for $\Phi = 0\%$ and full ones for $\Phi = 2\%$.

particle volume fractions, no such transition is observed in the investigated \mathcal{R} range, as illustrated in figure 3(d–f) ($\tilde{C} = 300$ ppm, $\Phi = 6\%$): the space–time diagram displays no clear sign of chaotic behaviour, the frequency maps no clear change in spectral signature and the torque measurement no clear jump. The two types of behaviour will be discussed separately in what follows.

3.1. Particle-free and dilute cases: EIT

For all fluids where EIT has been evidenced (all polymer concentrations at $\Phi = 0\%$ and $\Phi = 2\%$), \mathcal{R}_c values for the onset of EIT are represented in figure 5(a) as a function of the base fluid \mathcal{E}^0 value. The \mathcal{E}^0 values are much higher than those reported in previous literature for elasto-inertial TCF of particle loaded viscoelastic fluids (Lacassagne *et al.* 2021) and also significantly higher than our previous work (Moazzen *et al.* 2023) (mostly owing to the difference in working fluids: increased solvent viscosity, high polymer molecular weight, high polymer concentrations – see figure 5b). A reduction in \mathcal{R}_c with increasing \mathcal{E}^0 could have been expected from previous studies (Groisman & Steinberg 1996; Moazzen *et al.* 2023). It here appears that in the particle-free ($\Phi = 0\%$) case, increasing \mathcal{E}^0 (through an increase in polymer concentration) only leads to a weak reduction of \mathcal{R}_c (figure 5, full markers). From figure 5(c), it can clearly be seen that the onset of EIT (square symbols) occurs at critical \mathcal{W}_c values much higher than what would have been expected from the Pakdel–McKinley criterion (plus symbols) for the onset of purely elastic instability in curved streamline flows (Pakdel & McKinley 1996; Schäfer *et al.* 2018). This criterion is expressed as

$$\mathcal{W}_c^{PMcK} = \frac{M_{crit}}{\sqrt{2(1-\beta)}} \times \frac{1}{\sqrt{\epsilon}}, \quad (3.1)$$

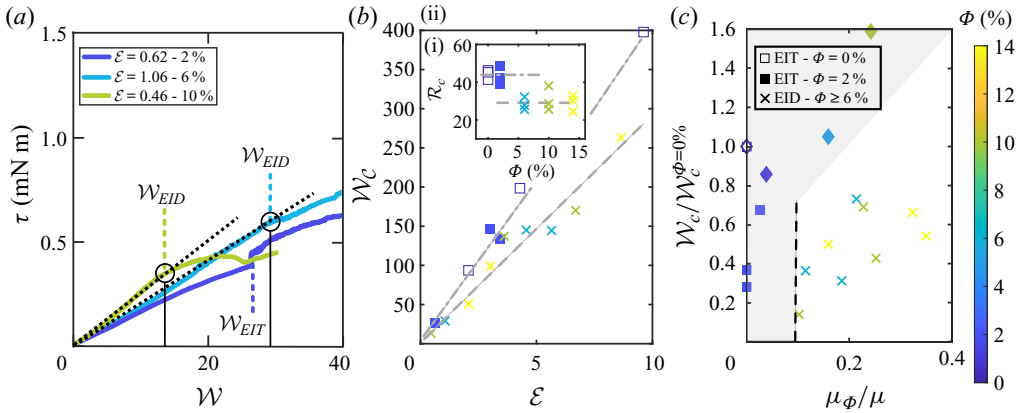


Figure 6. (a) Torque measured on the inner cylinder as a function of $W = \dot{\gamma} \lambda_{N1}$. Vertical dashed lines indicate the W_c values for trend change. Dashed black linear trends correspond to the laminar flow state. Panels (b i) and (b ii) are \mathcal{R}_c as a function of Φ , and W_c as a function of ϵ , respectively, with squares reporting the onset of EIT and crosses the onset of EID, at approximately constant \mathcal{R}_c values for each regime, indicated by dashed lines. (c) Values of W_c (same symbols) scaled by the zero-particle value $W_c(\Phi = 0\%)$, as a function of the particle-related viscosity increase (μ_Φ/μ). The grey area corresponds to EIT data points and the vertical dashed black line a $\mu_\Phi/\mu = 0.1$ limit from dilute to semi-dilute concentration regime.

where $M_{crit} = 1.8$, $\beta = \mu_s/\mu$ with μ_s is the solvent viscosity and $\epsilon = \delta/r_i$ (Pakdel & McKinley 1996). Thus, the chaotic behaviour is confirmed to be elasto-inertial (and not purely elastic) in nature, requiring both non-negligible inertia and elasticity to develop, even at such high ϵ^0 values.

When considering dilute ($\Phi = 0$ and 2% here) particle loaded fluids for which EIT is observed in the experimental range, it appears that this monotonic decrease in \mathcal{R}_c with ϵ is no longer observed, confirming that particles do mitigate the transition to EIT (figure 5, empty markers), as expected from Lacassagne *et al.* (2021). The \mathcal{R}_c values are essentially identical for the $\Phi = 0\%$ and $\Phi = 2\%$ cases for all three polymer concentrations, with possibly a slight decrease of \mathcal{R}_c upon particle addition for the two lower ϵ values ($\tilde{C} = 300$ and $\tilde{C} = 400$ ppm fluids), but a slightly delayed transition at $\Phi = 2\%$ in the higher ϵ case. The 2% particle addition yet causes a significant decrease of the critical W values, as illustrated in figure 6(c), (still much higher than the purely elastic instability threshold) which matches the trend observed when revisiting data from Lacassagne *et al.* (2021). It thus implies that in the dilute Φ limit, the effect of particle addition is mostly to promote elasto-inertial instabilities by reducing the amount of elasticity (W) needed at a given inertia (\mathcal{R}) for EIT to arise.

3.2. Absence of EIT in the semi-dilute regime

A striking result though is that for particle volume fractions higher than 2% , in what can be referred to as a semi-dilute particle concentration regime (Moazzen *et al.* 2022), no transition to EIT is observed in the investigated \mathcal{R} range (see figure 3d–f). The rheometer limit is reached when $\dot{\gamma} = 1405 \text{ s}^{-1}$ for each sample, which, since viscosity increase with particles concentration, leads to a decrease in the maximum attainable value \mathcal{R}_{max} and W_{max} . EIT not being observed here thus implies that it has been either delayed beyond \mathcal{R}_{max} or W_{max} , or completely suppressed, in such semi-dilute suspensions. The question naturally arising is then: *Could the effect of particle addition simply be to globally*

reduce the fluid's elasticity, resulting in apparent \mathcal{E} values low enough for elasto-inertial instabilities no longer to be expected? At this point, it is thus worth focusing on the effect of particle addition on the apparent viscoelastic time scales of particle loaded fluids. Those are measured by two protocols, as detailed in § 2.3: normal stress differences and elongational experiments. Results are reported in figure 2(b) (scaled by the $\Phi = 0\%$ value, λ^0) and in table 1. As a reminder, the apparent elastic numbers \mathcal{E} are computed for each fluid from λ_{N1} values and also reported in table 1. It appears that 2% particle addition leads to a steep decrease of λ and thus of \mathcal{E} . Although the elastic time scale keeps a weakly decreasing trend with particle addition beyond 2% (confirmed by both measurement techniques), the simultaneous increase in fluid viscosity makes it so that \mathcal{E} remains in the same range on the whole set of Φ investigated. It means that all fluids are still in the high elasticity regime ($\mathcal{E} \sim O(10^0)$), where direct transition from CCF to EIT would be expected (Groisman & Steinberg 1996; Moazzen *et al.* 2023). Thus, the suppression or delay of EIT upon particle addition beyond 6% cannot solely be explained by an apparent reduction of the fluid overall elasticity. Moreover, should that be the case, the difference in behaviour would be expected between the 0% and 2% cases for which the decrease in \mathcal{E} is the more evident, and not between the 2% and 6% cases for which \mathcal{E} stay equivalent or even increase. The change in behaviour between 2% and 6% has to be understood in light of local flow dynamics and fluid particle interactions, and in that context, torque measurements provide insightful information.

Figure 6(a) displays the evolution of the torque measured as a function of $\mathcal{W} = \lambda_{N1} \dot{\gamma}$ for the example of the $\tilde{C} = 300$ ppm ($\mathcal{E}^0 = 2.07$) fluid in one dilute case where EIT is observed (2%, $\mathcal{E} = 0.62$) and two semi-dilute cases for which it is not reported (6% – $\mathcal{E} = 1.06$ and 10% – $\mathcal{E} = 0.46$). As a confirmation of the above statement on the elasticity levels remaining high, it can be seen that the \mathcal{W} range covered is similar in all three cases. The transition to EIT in the dilute 2% case is evidenced by a clear jump in torque values (Martínez-Arias & Peixinho 2017; Moazzen *et al.* 2023). No such behaviour is observed for the two other cases. However, as mentioned in § 2.3, close inspection of the torque curves reveals a change in slope at \mathcal{W} values (reported in table 1) close to the critical one for the onset of EIT in the 2% case, where the torque– \mathcal{R} curve is found to depart from its laminar, CCF trend (see figures 3f and 4b,c). Thus, although there is neither visual nor dynamic (torque) evidence of EIT, the torque measurement suggests that there is indeed a modification of the dynamics, in terms of friction. The latter observation supports the assumption that EIT is not only delayed, but rather replaced by another mechanism qualified here as EID, which, to the best of the authors knowledge, has never been reported before. EID is not associated with observable flow structures and thus contributes to an apparent relaminarization of the flow by suppression of the large-scale chaotic patterns, but still corresponds to different friction dynamics than the initial laminar CCF. Indeed, the fact that the torque increases with increasing inertia is milder than the laminar prediction supports the hypothesis that additional energy dissipation is occurring in the flow, reducing friction at the inner cylinder, hence the term ‘dissipative regime’. It is expected that particle–particle and particle–polymer interactions are at the root of such a mechanism, considering that EIT can only be observed in the semi-dilute range ($\Phi > 6\%$). This assumption will be discussed further. It should here be recalled that EIT is instead characterized by a torque increase (jump) and then convergence towards a linear trend with similar slope as that found in CCF (see figure 3c) corresponding to a saturation in the EIT dynamics as reported by Moazzen *et al.* (2023, figure 6). This is thus a first fundamental difference between EIT and EID.

3.3. Onset of EID and EIT

Further information can be gained on this new transition by plotting the evolution of all \mathcal{R}_c and \mathcal{W}_c values (for the onset of EIT with squares or EID with crosses) as a function of Φ and \mathcal{E} in figures 6(b i) and 6(b ii), respectively. This shows that \mathcal{R}_c is both quasi Φ -independent and \mathcal{E} -independent, although slightly lower for the onset of EID than for EIT, suggesting that the EID mechanism is actually occurring sooner (in terms of \mathcal{R} during the ramp-up protocol) than EIT in semi-dilute particle loaded fluids, replacing it under comparable elasto-inertial conditions. Figure 6(c) compiles the previous results by plotting all \mathcal{W}_c (EIT or EID) normalized by the $\Phi = 0\%$ pure viscoelastic fluid value, as a function of the relative particle contribution to the overall viscosity $\mu_\Phi/\mu = (\mu - \mu(\Phi = 0))/\mu$. The graph splits up into two distinct regions. On the left-hand side, the viscosity increase upon particle addition remains negligible ($\mu_\Phi/\mu < 0.1$) and EIT is promoted, as discussed earlier, with $\mathcal{W}_c < \mathcal{W}_c(\Phi = 0)$. On the right-hand side, particles significantly increase the overall viscosity ($\mu_\Phi/\mu > 0.1$) and, in the present work, EIT is replaced by EID. In this second range, it appears that the critical \mathcal{W} values for the onset of EID increase with increasing Φ (and thus increasing μ_Φ/μ). The effect of particle addition in the semi-dilute regime can thus be understood as follows. First, the significant increase in overall viscosity μ leads to a stronger viscous dissipation mechanism, as illustrated by the steeper torque slopes in the laminar regime in figure 6(a) and in figure 4. Further increasing the inner cylinder rotational speed leads to an increase in \mathcal{W} and \mathcal{R} until the required elasto-inertial conditions for the onset of EID are reached and, in particular, the constant critical \mathcal{R} number. However, this requires higher $\dot{\gamma}$ and thus higher \mathcal{W} in the most particle loaded fluids, where the apparent increased viscosity promotes viscous dissipation and delays the onset of EID. Interestingly, Lacassagne *et al.* (2021) observed the same trend in the same $\mu_\Phi/\mu > 0.1$ range for the delay of the EIT onset in non-dilute particle suspensions (see figure 6c, diamonds).

Connection can be made with the recent work of Zhang & Shaqfeh (2023), who used numerical simulations to show that under conditions of $\beta = \mu_s/\mu \lesssim 0.5$ and $\mathcal{W} \gg 1$ similar to that of the present work, particle–particle interactions significantly affect the viscoelastic stress hardening mechanisms known to arise in such suspensions by altering the particle-induced fluid stresses, leading to an increased stresslet. Interestingly, this effect was evidenced for Φ values of 2.5% or 5% quite close to the critical concentration value reported here for the EIT–EID shift, suggesting a possible connection between this semi-dilute mechanism and the observation of EID.

3.4. Pseudo-Nusselt number in EID

Additional insight into the EID regime developing after the transition can here only be brought by the torque information, as no flow perturbation is observed from the outer-cylinder perspective of flow visualization. It is yet worth mentioning that the direct visualization method employed here only gives access to flow properties visible from the flow periphery and the outer cylinder, while torque measurements probe the flow behaviour closer to the inner cylinder. This suggests that the origin of EID could be spatially localized either in the bulk of the flow or close to the inner cylinder with yet no associated large-scale secondary flow structures, since they cause no apparent outer flow disturbance and no increase in apparent torque on the inner cylinder as would many well-known inertial, elastic or elasto-inertial Taylor–Couette instabilities (Moazzen *et al.* 2022, 2023).

A relevant parameter to infer radial energy transfer properties from torque measurements is the pseudo-Nusselt number \mathcal{N} as defined by Eckhardt, Grossmann & Lohse (2000) and

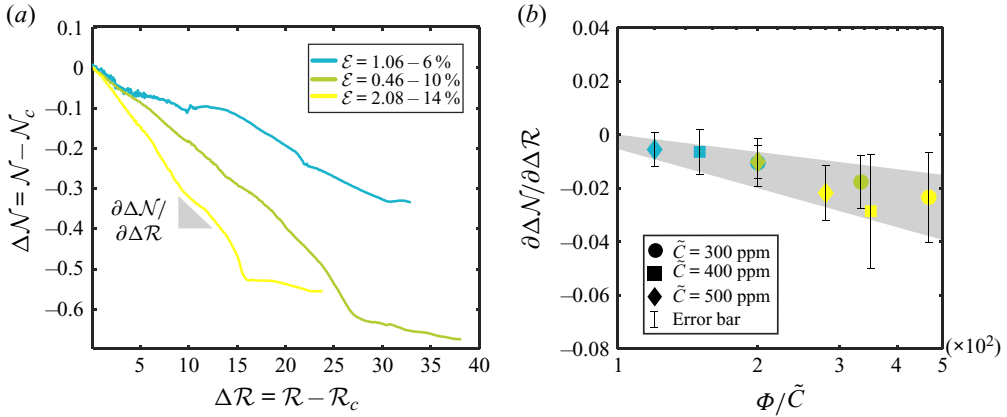


Figure 7. (a) $\Delta\mathcal{N} = \mathcal{N} - \mathcal{N}_c$ as a function of $\Delta\mathcal{R} = \mathcal{R} - \mathcal{R}_c$ in the EID regime for a 300 ppm fluids with $\Phi = 6, 10, 14\%$. (b) Mean of the slope calculated as $\partial\Delta\mathcal{N}/\partial\Delta\mathcal{R}$ for all experiments where EID was reported. Markers and colours are similar to those used in figures 2, 5 and 6.

used for example by Moazzen *et al.* (2022, 2023):

$$\mathcal{N} = \frac{J}{J_{lam}} = \frac{\frac{\tau}{2\pi\rho h}}{2\nu r_o^2 r_i^2 \frac{\Omega}{r_o^2 - r_i^2}}. \tag{3.2}$$

This quantity represents the flow capacity to transfer momentum in the radial direction, J being the momentum transport term and J_{lam} its value in the laminar CCF state.

For all experiments in the EID regime, the critical pseudo-Nusselt value $\mathcal{N}_c = \mathcal{N}(\dot{\gamma}_c)$ is defined at the onset of EID, and the quantity $\Delta\mathcal{N} = \mathcal{N} - \mathcal{N}_c$ is plotted as a function of $\Delta\mathcal{R} = \mathcal{R} - \mathcal{R}_c$. The example of the $\tilde{C} = 300$ ppm base fluid is illustrated in figure 7(a). This represents the variations of radial momentum transfer from the laminar reference within the EID regime, upon increasing inertia.

In most particle-loaded Newtonian fluids, this pseudo-Nusselt number is increased compared with the laminar case by secondary flows at the primary bifurcation, showing an improved radial momentum transfer ability (Ramesh *et al.* 2019; Dash *et al.* 2020; Kang & Mirbod 2021; Moazzen *et al.* 2022). In EIT, one would also report $\Delta\mathcal{N} > 0$ and a $\Delta\mathcal{N}$ increase with increasing $\Delta\mathcal{R}$ (not shown here for the sake of plots' clarity) consistent with the observations of Moazzen *et al.* (2023). However, from $\Phi = 6\%$, this quantity decreases with increasing $\Delta\mathcal{R}$, showing an opposite \mathcal{N} behaviour between EIT and EID, and supporting the fact that momentum radial transfer is reduced with EID. Figure 7(a) also suggests that increasing Φ leads to an even steeper decrease of $\Delta\mathcal{N}$.

To investigate this point, the slope $(\partial\Delta\mathcal{N}/\partial\Delta\mathcal{R})(\Delta\mathcal{R})$ is locally computed for all fluids (those represented in figure 7a and all the 400 and 500 ppm cases) and average values over the full $\Delta\mathcal{R}$ range are represented in figure 7(b) (with the error bars obtained from the standard deviation on the same range), as a function of the particle-to-polymer concentration ratio Φ/\tilde{C} . A good collapse on a clear monotonic trend is observed positioning the particle-to-polymer concentration ratio as a key parameter of the EID behaviour. This is yet another indication of the possible connection to the mechanisms reported by Zhang & Shaqfeh (2023). The more particles and subsequent particle-particle interactions for a given number of polymer chains, the larger the stresslet increase and

the stress hardening effects on a limited number of polymer chains, and thus the stronger the resulting local energy dissipation, reducing the radial momentum transfer towards the outer cylinder.

4. Conclusion

This study aimed at describing the influence of particle addition on the transition to EIT in high elasticity base fluids. Spherical particles were added in concentration regimes ranging from dilute to semi-dilute, in base fluids with high \mathcal{E} values for which direct transition from CCF to EIT upon \mathcal{R} increase would be expected. Transitions were monitored using a coupling of flow visualization and inner-cylinder torque measurements. Transition to EIT in particle-free Boger fluids was indeed retrieved, at lower \mathcal{R}_c and milder \mathcal{E}^0 dependency than in previous studies (Groisman & Steinberg 1996; Moazzen *et al.* 2023), but still with a clear elasto-inertial nature. The addition particles at a low volume fraction ($\Phi = 2\%$) led to an earlier onset of EIT in terms of \mathcal{W}_c (but not obvious in terms of \mathcal{R}_c). However, the most striking result was that particle addition at higher volume fractions ($\Phi \geq 6\%$, semi-dilute regime) led to EIT being no longer observed in the \mathcal{R} and \mathcal{W} range investigated, suggesting an apparent relaminarization of the flow with either a delay or a replacement of EIT, which could not be ascribed to a reduction in apparent fluid elasticity. Instead, a new dissipative mechanism, termed here elasto-inertial dissipative (EID), was identified from the torque curves and friction properties. The critical conditions for the onset of EID also seem elasto-inertial and quite similar to those for the onset of EIT in pure fluids or dilute suspensions. It appears that the relative increase of fluid viscosity upon particle addition is a key parameter in the onset of EIT or EID, as confirmed by compiling results from the present work and Lacassagne *et al.* (2021): the dilute regime at $\Phi \leq 5\%$ corresponds to a minor increase in viscous dissipation ($\mu_\Phi/\mu \leq 0.1$) and earlier onset of EIT, while increasing Φ in the semi-dilute regime sees significant increase in viscous dissipation upon particle addition ($\mu_\Phi/\mu > 0.1$) and a delay in EIT or delayed onset of EID. The evolution of the pseudo-Nusselt number in the EID regime shows that particle addition reduces radial momentum transfers, commensurate with the Φ/\tilde{C} ratio. In summary, EID is thus expected to be: (1) a local mechanism; (2) elasto-inertial in that it requires non negligible values of both \mathcal{R} and \mathcal{W} ; and (3) driven by polymer–particle interactions as it arises only in the semi-dilute regime. The accurate determination of the critical conditions for the onset of EID (Φ , \mathcal{W} , \mathcal{R} and geometrical parameters) could be the object of a future study. More generally, future studies should aim at providing local quantitative information on flow velocity fields (Boulafentis *et al.* 2024) and possible particle migration phenomena. This would allow to investigate local particle–polymer interaction mechanisms and their effect on polymeric stress field in a semi-dilute context (Zhang & Shaqfeh 2023), which would be of great interest to unravel the mechanisms behind delayed EIT or EID in the Taylor–Couette flow of particle-loaded viscoelastic fluids.

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EID in particle-laden viscoelastic Taylor–Couette flow

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