

## SOME RESULTS OF CCD-CAMERA BASED ASTROMETRIC PLATE MEASUREMENTS

N. ZACHARIAS<sup>1</sup>, C. de VEGT<sup>2</sup>, L. WINTER<sup>2</sup> and W. WENEIT<sup>2</sup>

<sup>1</sup> *U.S. Naval Observatory, 3450 Mass. Av. NW., Washington D.C. 20392-5400, U.S.A.*

<sup>2</sup> *Hamburger Sternwarte, Gojenbergsweg 112, W-2050 Hamburg 80, Germany*

**ABSTRACT.** A measuring accuracy of about 0.3  $\mu\text{m}$  per coordinate for well exposed stellar images is achieved over the entire usable measuring area of more than 200 x 200 mm<sup>2</sup> with the CCD-camera upgrade of the 'old' Mann comparator.

The external plate-to-plate comparison shows that the error due to emulsion shifts dominates, which results in an overall accuracy of about 0.8  $\mu\text{m}$ .

### 1. The HAM I System

The Hamburg Observatory Mann 422F comparator has been upgraded with a Hamamatsu (256 pix)<sup>2</sup> CCD camera and is fully controlled by a MicroVAX II computer. This system, the first Hamburg Astrometric Measuring Machine (HAM I), has been in routine operation since 1991.

### 2. Calibration of the x, y Table

Each axis was calibrated separately with the help of a calibrated glass scale, and a straightness calibration was achieved using a wire in two orientations. Then a high precision grid-plate ( $\sigma = 0.2 \mu\text{m}$ ) was measured in two orientations. The standard deviation of (HAM I – grid) is  $\sigma_x = 0.24 \mu\text{m}$  and  $\sigma_y = 0.27 \mu\text{m}$ , thus only a noise of about  $\sigma = 0.17 \mu\text{m}$  is introduced by the HAM I measurement (residual calibration errors).

### 3. Repeatability

For testing the stability of the camera and the illumination system, a fiducial mark was measured without moving the carriage. After the usual warming-up period of 2 hours, a standard deviation of  $\sigma = 0.05 \mu\text{m}$  for the static repeatability is reached.

A list of 10 uniformly distributed fiducial marks on the grid plate were measured in one orientation 100 times in a single 16-hour run. A standard deviation of  $\sigma = 0.25 \mu\text{m}$  for this dynamic repeatability was obtained.

#### 4. Position Comparison of Radio Stars

To provide an external accuracy estimation, plates of six radio stars (Black Birch Astrograph, 100"/mm) were used. Taking all individual positions of individual exposures of one star, the standard deviation (of one image) can be calculated (Table 1). Note that the numbers quoted in Table 1 include also error contributions from the plate adjustment process to the reference stars, emulsion shifts and effects due to the Earth atmosphere.

**Table 1.** Plate to plate accuracy of an object at the centre of the plate. The numbers given are standard deviations for a single observation (image). The plate scale is 100"/mm (100 mas = 1 $\mu$ m).

Star	$n_{plates}$	$n_{exp}$	order	$\sigma_{\text{total}}$	$\sigma_s$
S Crt	5	10	0	40 mas	29 mas
HD 50896	4	7	0	119 mas	110 mas
		8	1	89 mas	30 mas
HD 50896	4	8	0	87 mas	52 mas *)
FR Sct	4	8	0	88 mas	134 mas
KQ Pup	4	8	0	111 mas	85 mas
		8	1	78 mas	107 mas
RV Lib	4	8	0	48 mas	59 mas
TY Pyx	4	8	0	33 mas	67 mas
quadratic mean:				82 mas	82 mas

$n_{plates}$  = number of plates for object  
 $n_{exp}$  = number of exposures used for statistics  
 (there are 1 or 2 exposures on a plate)  
 order = diffraction grating order,  
 0 = central image, 1 = first order diffraction images

\*) a second epoch observation of HD 50896

#### 5. Measuring Accuracy over the Entire Plate Area

A total of 2700 GSC stars down to 13.5 mag have been measured in a plate area of about 6 x 6 deg<sup>2</sup> on four plates of the field 0912+298 taken during one night (Hamburg Zone Astrograph, 100"/mm).

Each plate was measured in 2 orientations. The measurements of the first orientation were transformed onto the second using an orthogonal model after applying the calibration model to the raw x, y data. A subset of stars (6th to 9th mag) distributed over the entire plate area was used. A standard error for the transformation of  $\sigma_T = 0.49 \mu\text{m}$  is obtained, thus the error of a single measurement is about 0.35  $\mu\text{m}$ . This includes fit errors of the measured star profiles as well as residual calibration errors.

## 6. Plate to Plate Accuracy over the Entire Plate Area

For each of the 4 plates of the above example, mean  $x$ ,  $y$  coordinates of measurements in 2 orientations have been calculated. Then a plate-to-plate comparison was performed using a suitable transformation model (Table 2), and the position differences in  $x$ ,  $y$  for all stars (quadratic mean) were calculated. Thus the error of one star position on one plate is about  $0.75 \mu\text{m}$ . This error includes besides all measuring machine dependent errors, the contribution of the emulsion shift. The significant difference between  $\sigma_T$  and  $\sigma_x$ ,  $\sigma_y$  can be accounted for by a magnitude equation between plates. Thus a clear separation of measuring machine dependent errors and other errors is demonstrated here, proving the high measuring precision of HAM I.

Table 2. Transformation of  $x$ ,  $y$  coordinates on a plate to plate basis

Plates	Model	$n_T$	$\sigma_T$ / [ $\mu\text{m}$ ]	$n_{stars}$	$\sigma_x$ / [ $\mu\text{m}$ ]	$\sigma_y$ / [ $\mu\text{m}$ ]
641 - 642	mod 2	2625	1.18 (x)			
		2625	1.13 (y)			
641 - 642	mod 3	126	1.00	2636	1.32	1.31
641 - 643	mod 3	118	1.16	2614	1.53	1.78
641 - 644	mod 3	122	1.06	2650	1.47	1.35
642 - 643	mod 3	118	0.93	2584	1.49	1.82
642 - 644	mod 3	122	1.02	2619	1.37	1.29
643 - 644	mod 3	116	0.94	2621	1.41	1.64

model: mod 2 = affine transformation, separate for each coordinate

mod 3 = affine + tilt terms,  $x$ ,  $y$  coupled

$n_T$  = number of transformation stars used

$\sigma_T$  = standard error of transformation

$n_{stars}$  = number of stars for difference statistics

$\sigma_x$  = quadratic mean differences in  $x$

$\sigma_y$  = quadratic mean differences in  $y$