

MATRIX CHARACTERIZATIONS OF  
TOPOLOGICAL PROPERTIES

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1. Introduction. In [S], H. Sharp characterizes each topology on a finite set  $S = \{s_1, s_2, \dots, s_n\}$  with a  $n \times n$  zero-one matrix  $T = (t_{ij})$  where  $t_{ij} = 1$  if and only if  $s_j \in \overline{s_i}$ . In this paper we seek matrix characterizations of certain topological properties of finite spaces. Such characterizations will provide purely mechanical ways of determining if a space has a certain topological property.

We give matrix characterizations of the  $T_Y$  separation axiom of Youngs [Y]; the  $R_0$  and  $R_1$  separation axioms of Davis [D], the strong  $T_0$  separation axiom of Robinson and Wu [RW], and the six separation axioms introduced by Aull and Thron [AT]. Also, we include matrix characterizations of regular, completely regular, normal, completely normal, 0-dimensional, and extremally disconnected spaces.

2. Preliminaries. If  $(S, \tau)$  is a finite topological space and if  $T$  is the matrix corresponding to  $\tau$ , we will denote the space  $(S, \tau)$  by  $(S, T)$ . For each  $s_i \in S$ , we let  $F_i = \{\overline{s_i}\}$  and  $B_i$  be the minimal open set containing  $s_i$ . For each  $A \subset S$ , let  $B_A = \bigcup_{s_i \in A} B_i$ ; clearly,  $B_A$  is the minimal open set containing  $A$ . A useful fact proven in [S] is that  $B_i \subset B_j$  if and only if  $F_j \subset F_i$ . The identity matrix is denoted by  $\mathbf{1}$ .

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For each  $s_i \in S$  we associate the  $1 \times n$  row vector  $\epsilon_i = (\delta_{1i}, \delta_{2i}, \dots, \delta_{ni})$  where  $\delta_{ij}$  is the Kronecker delta. For each  $A \subset S$  we associate the vector  $A_v = \sum \epsilon_i (s_i \in A)$ . In particular, the  $i$ th row of  $T, T_i$ , is  $(\{\bar{s}_i\})_v$ , and the  $i$ th column of  $T, T^i$ , is  $(B_i)_v$ .

**THEOREM 2.1.** Let  $A$  be a subset of a finite topological space  $(S, T)$ , then  $(\bar{A})_v = A_v \cdot T$  where matrix multiplication is with respect to Boolean algebra.

Proof. Since  $\bar{A} = \bigcup \{\bar{s}_i\} (s_i \in A)$ , we need only show that  $(\{\bar{s}_i\})_v = \{s_i\}_v \cdot T$ ; that is,  $T_i = \epsilon_i \cdot T$  since  $\{s_i\}_v = \epsilon_i$  and  $(\{\bar{s}_i\})_v = T_i$ . Let  $V_j$  denote the  $j$ th entry of  $\epsilon_i \cdot T$ .

Thus,  $V_j = \sum_{k=1}^n \delta_{ki} t_{kj} = t_{ij}$  and  $T_i = \epsilon_i \cdot T$ .

**THEOREM 2.2.** Let  $A$  be a subset of a finite topological space  $(S, T)$ , then  $T \cdot (A_v)' = (B_A)_v'$  where matrix multiplication is with respect to Boolean algebra.

Proof. The proof is similar to the proof of 2.1.

**COROLLARY 2.3.** Let  $A$  be a subset of a finite topological space  $(S, T)$ .  $A$  is open if and only if  $T \cdot (A_v)' = (A_v)'$  where matrix multiplication is with respect to Boolean algebra.

Let  $\tau' = \{U \subset S \mid S - U \in \tau\}$ ; it is straightforward to prove that  $\tau'$  is a topology. Sharp [S] has proved that the matrix associated with  $\tau'$  is the transpose of  $T, T'$ . The conclusion of 2.2 may be restated as  $A_v \cdot T' = (B_A)_v'$ .

3. Separation Axioms. Let  $(X, \tau)$  be a topological space (not necessarily finite).  $(X, \tau)$  is  $T_Y$  if and only if for  $x, y$  in  $X, x \neq y, \{\bar{x}\} \cap \{\bar{y}\}$  is degenerate ( $\{\bar{x}\} \cap \{\bar{y}\}$  is either empty or a singleton). The next six separation axioms were introduced in [AT].  $(X, \tau)$  is  $T_D$  if and only if for each  $x$  in  $X, \{x\}'$  is a closed set.  $(X, \tau)$  is  $T_{UD}$  if and only if for each  $x \in X, \{x\}'$  is the union of disjoint closed sets.

$(X, \tau)$  is  $T_{DD}$  if and only if  $(X, \tau)$  is  $T_D$  and for every  $x, y$  in  $X$ ,  $x \neq y$ ,  $\{x\}' \cap \{y\}' = \phi$ .  $(X, \tau)$  is  $T_F$  if and only if for each  $x$  in  $X$  and disjoint finite set  $F$ , either  $x \notin \bar{F}$  or  $F \cap \{\bar{x}\} = \phi$ .  $(X, \tau)$  is  $T_{FF}$  if and only if given any two disjoint finite sets  $F_1$  and  $F_2$  in  $X$ , either  $F_1 \cap \bar{F}_2 = \phi$  or  $\bar{F}_1 \cap F_2 = \phi$ .  $(X, \tau)$  is said to be  $T_{YS}$  if and only if for all  $x, y \in X$ ,  $x \neq y$ ,  $\{\bar{x}\} \cap \{\bar{y}\}$  is either  $\phi$ ,  $\{x\}$ , or  $\{y\}$ . To this list we add three additional separation axioms. For each  $x$  in  $X$ , let  $\{\hat{x}\}$  denote the intersection of all open sets in  $(X, \tau)$  containing  $x$ .  $(X, \tau)$  is  $T_Y$  if and only if  $x, y$  in  $X$ ,  $x \neq y$ ,  $\{\hat{x}\} \cap \{\hat{y}\}$  is either  $\phi$ ,  $\{x\}$ , or  $\{y\}$ .  $(X, \tau)$  is  $T_\alpha$  if and only if  $\{\hat{x}\} - \{x\}$  is empty for all but at most one  $x$  in  $X$ .  $(X, \tau)$  is  $T_\beta$  if and only if  $\{x\}'$  is empty for all but at most one  $x$  in  $X$ .  $(X, \tau)$  is  $T_{\alpha\beta}$  if and only if it is both  $T_\alpha$  and  $T_\beta$ . The strong  $T_D$  (denoted by  $T_{SD}$ ) and the strong  $T_0$  (denoted by  $T_{S0}$ ) were introduced in [WR].  $(X, \tau)$  is  $T_{S0}$  if and only if for each  $x \in X$ ,  $\{x\}' = \bigcup \{\bar{y}\} (y \in \{x\}'), \phi = \bigcap \{\bar{y}\} (y \in \{x\}')$ , and  $\{\bar{y}\}$  is compact for some  $y \in \{x\}'$ .  $(X, \tau)$  is  $T_{SD}$  if and only if for each  $x \in X$ ,  $\{x\}'$  is the union of a finite family of closed sets, such that the intersection of the non-empty members of this family is empty.  $(X, \tau)$  is  $R_0$  if and only if every open set contains the closure of each of its points.  $(X, \tau)$  is  $R_1$  if and only if for every pair of points  $x, y$  in  $X$ ,  $\{\bar{x}\} \neq \{\bar{y}\}$  implies that  $\{\bar{x}\}$  and  $\{\bar{y}\}$  have disjoint neighborhoods. Aull and Thron [AT] proved that a space is  $T_{FF}$  if and only if it is either  $T_\alpha$  or  $T_\beta$ .

In finite topological spaces, some of the above axioms become equivalent. In [AT],  $T_0$  was shown to be equivalent to  $T_D$  and  $T_{UD}$ . From the definitions we observe that  $T_{S0}$  and  $T_{SD}$  are equivalent. In theorem 3.6 we show that  $R_0$  is equivalent to  $R_1$ . In [AT], a space satisfying  $T_{DD}$  was proven to satisfy  $T_{YS}$ , and since  $T_0$  is equivalent to  $T_D$  in finite spaces, it follows immediately that  $T_{DD}$  and  $T_{YS}$

are equivalent. Figure 1 shows the order relationship between the separation axioms for finite spaces.

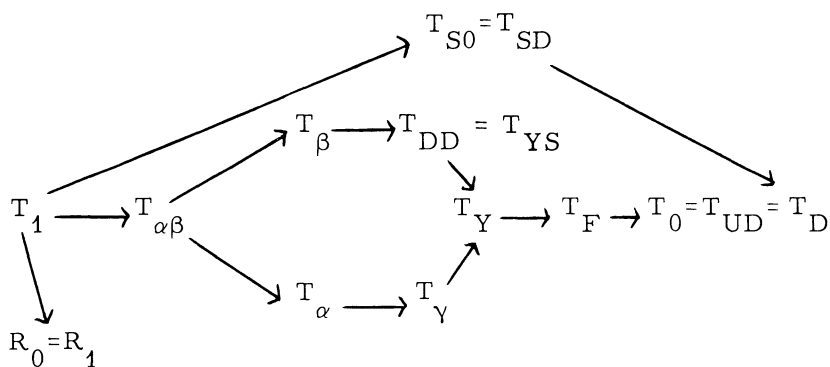


FIGURE 1

It is clear that  $(S, T)$  is  $T_1$  if and only if  $T$  is the identity matrix. Sharp [S] proved that  $(S, T)$  is  $T_0$  if and only if  $T$  is anti-symmetric.

**THEOREM 3.1.** In a finite topological space  $(S, T)$ , the following are equivalent:

- (a)  $(S, T)$  is  $T_{S0}$ ,
- (b)  $(S, T)$  is  $T_0$  and the derived set of any singleton is never a singleton, and
- (c)  $T$  is anti-symmetric and no  $i$ th row of  $T^{-1}$  is a unit vector.

**Proof.** Clearly, (b) is equivalent to (c) and (a) implies (b). We need only show that (b) implies (a). Suppose that  $(S, T)$  is  $T_0$  and the derived set of any singleton is never a singleton.

Let  $N = \{a \in S \mid \{a\}' = \{a_1, \dots, a_m\} \text{ where } m \geq 2 \text{ and } \bigcap_{j=1}^m \{\bar{a}_j\} \neq \emptyset\}$ .

We will show  $N = \emptyset$  by an induction proof on the cardinality of the derived set of any element of  $N$ . First, assume that there is an element in  $N$ , say  $a$ , such that the cardinality of  $\{a\}' = 2$ ; so  $\{a\}' = \{a_1, a_2\}$  and  $\bigcap_{i=1}^2 \{\bar{a}_i\} \neq \emptyset$ .

Without loss of generality we may assume  $a_1 \in \{\bar{a}_2\}$ . Since  $(S, T)$  is  $T_0$ ,  $\{a\}'$  is closed; so,  $\{\bar{a}_2\} = \{a_1, a_2\}$  implying that  $\{a_2\}' = \{a_1\}$  which is a contradiction to the fact that no derived set of any singleton of  $S$  is a singleton. We conclude that no element of  $N$  has a two element derived set. Now suppose that there is no  $a \in N$  such that  $2 \leq$  cardinality of  $\{a\}' < m$ . If  $a \in N$  with the cardinality of  $\{a\}' = m$ , we would have  $\{a\}' = \bigcup_{j=1}^m \{\bar{a}_j\}$  and  $\bigcap_{j=1}^m \{\bar{a}_j\} \neq \phi$ . Since  $\bigcap_{j=1}^m \{\bar{a}_j\} \neq \phi$ , there is an  $a_k$  in  $\{\bar{a}_i\}$  for each  $i$ . Let  $j \in \{1, 2, \dots, m\} - \{k\}$ .  $a_k \in \{a_j\}'$ , so  $\{a_j\}' \neq \phi$ . Since no derived set of any singleton is a singleton, we know that the cardinality of  $\{a_j\}' \geq 2$ . Since  $\{a\}'$  is closed, then  $\{a_j\}' \subset \{a\}' - \{a_j\}$ . Therefore,  $2 \leq$  cardinality of  $\{a_j\}' \leq m-1$ . Also,  $a_k \in \bigcap_{b \in \{a_j\}'} \{\bar{b}\}$ . Thus,  $a_k \in N$  which is a contradiction to the induction hypothesis. Hence,  $N = \phi$  and  $(S, T)$  is  $T_{S0}$ .

**THEOREM 3.2.** Let  $(S, T)$  be a finite topological space. The following are equivalent:

- (a)  $(S, T)$  is  $T_F$ ,
- (b) for each  $s_i$  in  $S$ , either  $F_i = \{s_i\}$  or  $B_i = \{s_i\}$ , and
- (c) for each  $i$ , either the  $i$ th row or the  $i$ th column of  $T-1$  is zero.

Proof. (b) is clearly equivalent to (c). It remains to show that (a) is equivalent to (b). Suppose  $(S, T)$  is  $T_F$ , and let  $s_i \in S$ . Since  $s_i \notin S - \{s_i\}$ , we have that either  $\{\bar{s}_i\} \cap (S - \{s_i\}) = \phi$  or  $\{s_i\} \cap \overline{S - \{s_i\}} = \phi$ . Thus,  $\{s_i\} = F_i$  or  $\{s_i\} = B_i$ . Clearly (b) implies (a).

DEFINITION. Let  $v = (v_1, \dots, v_n)$  and  $w = (w_1, \dots, w_n)$  be vectors with  $n$  real-valued components. The intersection of  $v$  and  $w$  is  $w \cap v = (\min(v_1, w_1), \min(v_2, w_2), \dots, \min(v_n, w_n))$ .

THEOREM 3.3. Let  $(S, T)$  be a finite topological space. The following are equivalent:

(a)  $(S, T)$  is  $T_Y$ ,

(b) the intersection of  $T_i$  and  $T_j$  has at most one non-zero entry for all  $i \neq j$ , and

(c) the matrix  $T \cdot T'$ , with respect to ordinary multiplication, is zero or one everywhere except possibly on the diagonal.

Proof. Since the intersection of  $T_i$  and  $T_j$  is the intersection of  $(\{\bar{s}_i\})_v$  and  $(\{\bar{s}_j\})_v$  which is  $(\{\bar{s}_i\} \cap \{\bar{s}_j\})_v$ , then (a) is equivalent to (b). Clearly, (b) is equivalent to (c).

THEOREM 3.4. Let  $(S, T)$  be a finite topological space.

(a)  $(S, T)$  is  $T_{DD}$  if and only if  $T$  is anti-symmetric and  $(T-1)(T-1)'$  is a diagonal matrix.

(b)  $(S, T)$  is  $T_Y$  if and only if  $T$  is anti-symmetric and  $(T-1)'(T-1)$  is a diagonal matrix.

Proof of (a). Suppose  $T$  is anti-symmetric and  $(T-1)(T-1)' = [v_{ij}] = T^*$  is a diagonal matrix; that is,

$v_{ij} = \sum_{k=1}^n t_{ik} \cdot t_{jk} = 0$  for  $i \neq j$ ; therefore, for each  $k$ ,

$t_{ik} \cdot t_{jk} = 0$ , implying that  $t_{ik} = 0$  or  $t_{jk} = 0$ . So, for each  $k$ ,

$s_k \notin \{s_i\}'$  or  $s_k \notin \{s_j\}'$ , thus giving  $\{s_i\}' \cap \{s_j\}' = \phi$ .

Since  $T$  is anti-symmetric  $s_i \notin \{s_j\}'$  or  $s_j \notin \{s_i\}'$ .

Thus,  $(S, T)$  is  $T_{DD}$ . Conversely, suppose  $(S, T)$  is  $T_{DD}$ .

For  $i \neq j, \{s_i\}' \cap \{s_j\}' = \phi$ . For each  $k, s_k \notin \{s_i\}'$  or

$s_k \notin \{s_j\}'$  implying that  $t_{ik} = 0$  or  $t_{jk} = 0$ . So,

$t_{ik} \cdot t_{jk} = 0$  and  $v_{ij} = 0$  for  $i \neq j$ . Thus,  $T^* = (T-1)(T-1)'$

is a diagonal matrix, and  $T$  is anti-symmetric since  $T_{DD}$  implies  $T_0$ .

Proof of (b). (b) follows from an argument similar to that of (a).

**THEOREM 3.5.** Let  $(S, T)$  be a finite topological space.

(a)  $(S, T)$  is  $T_\beta$  if and only if  $(T-1)$  has at most one non-zero row.

(b)  $(S, T)$  is  $T_\alpha$  if and only if  $(T-1)'$  has at most one non-zero row.

(c)  $(S, T)$  is  $T_{\alpha\beta}$  if and only if both  $(T-1)$  and  $(T-1)'$  have at most one non-zero row.

(d)  $(S, T)$  is  $T_{FF}$  if and only if  $(T-1)$  or  $(T-1)'$  has at most one non-zero row.

Proof. To prove (a), note that since the  $i$ th row of  $T-1$  is  $(\{s_i\}')_v$ , then  $T-1$  has at most one non-zero row if and only if  $\{s_i\}' \neq \phi$  for at most one  $s_i$  in  $S$  which is equivalent to  $(S, T)$  being  $T_\beta$ . (b) and (c) follow similarly. (d) follows since  $(S, T)$  is  $T_{FF}$  if and only if it is  $T_\alpha$  or  $T_\beta$ .

We now show that  $R_0$  is equivalent to  $R_1$  in finite spaces and give a matrix characterization. Also, we prove that  $R_0$  is equivalent to 0-dimensional, regular, and completely regular.

**THEOREM 3.6.** Let  $(S, T)$  be a finite topological space. The following are equivalent;

- (a)  $T$  is a symmetric matrix,
- (b)  $(S, T)$  is 0-dimensional,
- (c)  $(S, T)$  is completely regular,

- (d)  $(S, T)$  is regular,
- (e)  $(S, T)$  is  $R_1$ , and
- (f)  $(S, T)$  is  $R_0$ .

Proof. It is well known that (b) implies (c), (c) implies (d), and (e) implies (f).

(f) implies (e): Let  $(S, T)$  be  $R_0$ . Let  $s_i \in S$ , then  $s_i \in \{\bar{s}_i\} = F_i \subset B_i$ . If  $s_j \in B - F_i$ , then  $F_j \subset B_i - F_i$ , so  $B_i - F_i$  is an open set containing  $s_i$  and properly contained in  $B_i$  which is a contradiction. So,  $F_i = B_i$ . If  $F_i \cap F_j \neq \phi$ , then  $s_k \in F_i \cap F_j$ . By a similar argument  $B_k = F_j$  and  $B_k = F_i$ , so,  $F_i = F_j$ . Thus, if  $F_i \neq F_j$ , then  $F_i \cap F_j = \phi$ . Since  $B_i = F_i$ ,  $B_j = F_j$  and  $B_i \cap B_j = \phi$ , we have proven that  $(S, T)$  is  $R_1$ .

(f) implies (a): Suppose  $(S, T)$  is  $R_0$  and  $s_i \in S$ . By the argument presented in the proof that (f) implies (e), we have proven that  $F_i = B_i$ . Hence,  $B_i = S - (S - F_i) \in \tau'$  and  $\tau \subset \tau'$ . If  $A \in \tau'$ , then  $S - A \in \tau$ .  $S - A = \bigcup_{i \in \mathcal{L}} B_i$  for some subset  $\mathcal{L}$  of  $\{1, 2, 3, \dots, n\}$ . Therefore,  $A = \bigcap_{i \in \mathcal{L}} S - B_i = \bigcap_{i \in \mathcal{L}} S - F_i$ , which is in  $\tau$ . So,  $\tau' \subset \tau$  which proves that  $\tau = \tau'$  and, hence,  $T$  is symmetric.

(a) implies (b): If  $T$  is symmetric, then  $B_i \in \tau'$  for all  $s_i \in S$ . So,  $S - B_i \in \tau$  and  $B_i$  is closed. Since  $B_i$  is smallest open set containing  $s_i$ ,  $(S, T)$  is zero dimensional.

(d) implies (f): Suppose  $(S, T)$  is regular and  $U \in \tau$  with  $s_i \in U$ . There is a  $V$  in  $\tau$  such that  $s_i \in V \subset \bar{V} \subset U$ , so  $\{\bar{s}_i\} \subset U$  and  $(S, T)$  is  $R_0$ .

**THEOREM 3.7.** Let  $(S, T)$  be a finite topological space. The following are equivalent:



- (a)  $(S, T)$  is normal,
- (b) for each  $F_i$ ,  $B_{F_i}$  is closed, and
- (c)  $((F_i)_V \cdot T') \cdot T = (F_i)_V \cdot T'$ .

Proof. By 2.1 and the comment following 2.3, (b) is equivalent to (c). Clearly, (b) implies (a). To prove (a) implies (b), suppose  $(S, T)$  is normal. Let  $s_i \in S$ ; there is an open set  $V$  such that  $F_i \subset V \subset \bar{V} \subset B_{F_i}$ . Since  $B_{F_i}$  is the smallest open set containing  $F_i$ , then  $V \neq \bar{V} = B_{F_i}$  and  $B_{F_i}$  is closed.

**THEOREM 3.8.** Let  $(S, T)$  be a finite topological space. Let  $T' \cdot T = (t_{ij}^*)$  where multiplication is with respect to Boolean algebra. The following are equivalent:

- (a)  $(S, T)$  is completely normal,
- (b)  $s_i \notin F_j, s_j \notin F_i$  imply  $B_i \cap B_j = \phi$ , and
- (c)  $t_{ij}^* = 1$  implies  $t_{ij} = 1$  or  $t_{ji} = 1$ .

Proof.

(a) implies (b): Suppose  $(S, T)$  is completely normal, and suppose  $s_i \notin F_j$  and  $s_j \notin F_i$ . So,  $\{s_i\} \cap \{\bar{s}_j\} = \phi$  and  $\{\bar{s}_i\} \cap \{s_j\} = \phi$ . By complete normality,  $B_i \cap B_j = \phi$  since  $B_i$  and  $B_j$  are the smallest open sets containing  $s_i$  and  $s_j$ , respectively.

(b) implies (c): Suppose (b) is true and  $t_{ij}^* = 1$ ; there is a  $k$  such that  $t_{ki} = 1$  and  $t_{kj} = 1$ . So,  $B_i \cap B_j \neq \phi$ ; hence, either  $s_i \in F_j$  or  $s_j \in F_i$  implying  $t_{ji} = 1$  or  $t_{ij} = 1$ , respectively.

(c) implies (a): Suppose (c) is true and  $C, D \in S$  such that  $C \cap \bar{D} = \bar{C} \cap D = \phi$ . Let  $s_i \in C$  and  $s_j \in D$ ;  $s_i \notin F_i$  and  $s_j \notin F_i$ . So,  $t_{ij} = t_{ji} = 0$ . By (c),  $t_{ij}^* = 0$ . Hence,  $t_{kj} = t_{ki} = 0$

for all  $k$  implying  $B_i \cap B_j = \phi$ . Since this is true for any  $s_i \in C$  and any  $s_j \in D$ , then  $B_C \cap B_D = \phi$ . This proves that  $(S, T)$  is completely normal.

4. Connectedness. In [S], Sharp gives a matrix characterization of connectedness. Clearly, in finite spaces, totally disconnected is equivalent to  $T_1$ . Theorem 3.6 gives a matrix characterization of 0-dimensional. We conclude the article by giving a matrix characterization of extremally disconnected.

**THEOREM 4.1.** Let  $(S, T)$  be a finite topological space.  $(S, T)$  is extremally disconnected if and only if for each  $B_i$  in  $S$ ,  $T \cdot ((\bar{B}_i)_v)' = ((\bar{B}_i)_v)'$ .

Proof. Let  $(S, T)$  be extremally disconnected; that is the closure of each open set is also open. By 2.3, we have that  $T \cdot ((\bar{B}_i)_v)' = ((\bar{B}_i)_v)'$ . Conversely, suppose that for each  $B_i$  in  $S$ ,  $T \cdot ((\bar{B}_i)_v)' = ((\bar{B}_i)_v)'$ . By 2.3,  $\bar{B}_i$  is open. Let  $U$  be an open subset of  $S$ ,  $U = \bigcup_{s_i \in U} B_i \cdot \bar{U} = \bigcup_{s_i \in U} \bar{B}_i$ .

Since each  $B_i$  is open,  $\bar{U}$  is open; thus,  $(S, T)$  is extremally disconnected.

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