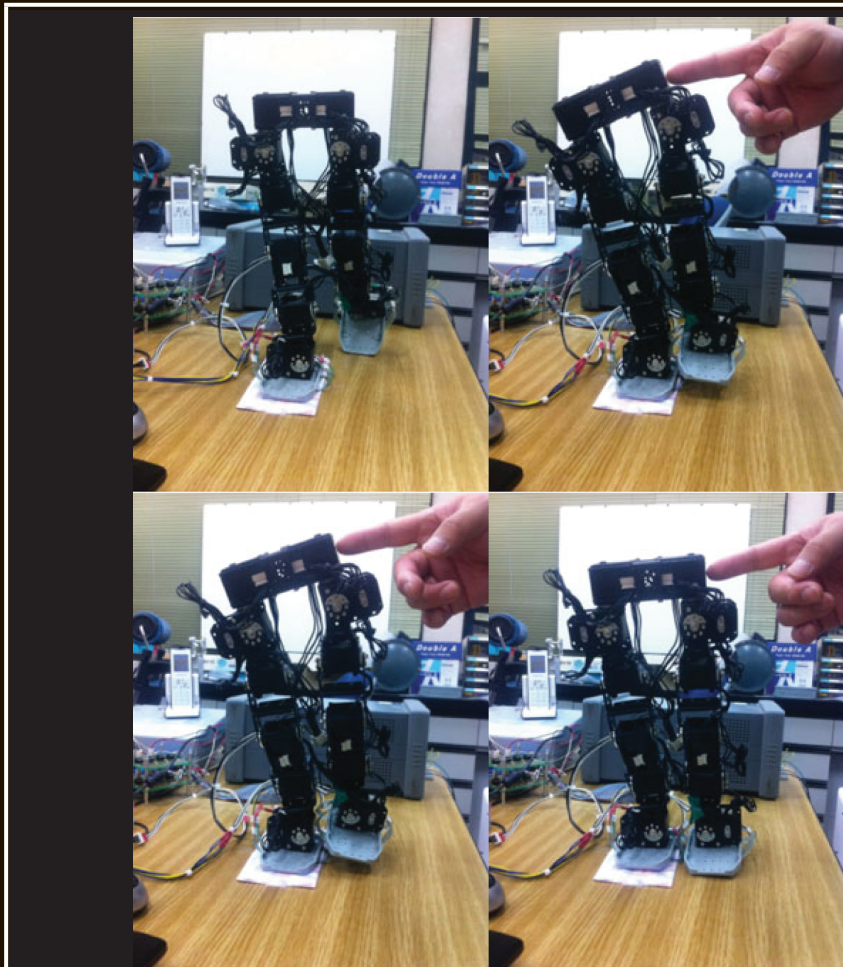


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An IFAC-Affiliated Journal, and an
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International Journal of Information, Education and Research
in Robotics and Artificial Intelligence

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Robotica (ISSN 0263-5747) is published as twelve Issues per Volume in January, February, March, April, May, June, July, August, September, October, November and December. The electronic-only price for Volume 34, 2016 available to institutional subscribers is £1138 (US \$2010 in USA, Canada and Mexico). EU subscribers (outside the UK) who are not registered for VAT should add VAT at their country's rate. VAT registered subscribers should provide their VAT registration number. Orders, which must be accompanied by payment, may be sent

to a bookseller, subscription agent or direct to the publishers: Cambridge University Press, University Printing House, Shaftesbury Road, Cambridge CB2 8RU, UK. Orders from the USA, Canada and Mexico should be sent to Cambridge University Press, Journals Fulfillment Department, 100 Brook Hill Drive, West Nyack, New York 10994–2133. Japanese prices for institutions are available from Kinokuniya Company Ltd, P.O. Box 55, Chitose, Tokyo 156, Japan. Prices include delivery by air.

Periodicals postage paid at New York, NY and additional mailing offices. POSTMASTER: send address changes in USA, Canada and Mexico to *Robotica*, Cambridge University Press, 100 Brook Hill Drive, West Nyack, New York 10994–2133.

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Cover Image: Figure 17 from **A force-resisting balance control strategy for a walking biped robot under an unknown, continuous force** - by Yeoun-Jae Kim, Joon-Yong Lee, and Ju-Jang Lee.