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Gas-sheared falling liquid films beyond the absolute instability limit

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We study the effect of a confined turbulent counter-current gas flow on the waviness of a weakly inclined falling liquid film. Our study is centred on experiments in a channel of 13 mm height, using water and air, where we have successively increased the counter-current gas flow rate until flooding. Computations with a new low-dimensional model and linear stability calculations are used to elucidate the linear and nonlinear wave dynamics. We find that the gas pressure gradient plays an important role in countering the stabilizing effect of the tangential gas shear stress at the liquid–gas interface. At very low inclination angles, the latter effect dominates and can suppress the long-wave Kapitza instability unconditionally. By contrast, for non-negligible inclination, the gas effect is linearly destabilizing, amplifies the height of nonlinear Kapitza waves, and exacerbates coalescence-induced formation of large-amplitude tsunami waves. Kapitza waves do not undergo any catastrophic transformation when the counter-current gas flow rate is increased beyond the absolute instability (AI) limit. On the contrary, we find that AI is an effective linear wave selection mechanism in a noise-driven wave evolution scenario, leading to highly regular downward-travelling nonlinear wave trains, which preclude coalescence events. In our experiments, where Kapitza waves develop in a protected region before coming into contact with the gas, flooding is eventually caused far beyond the AI limit by upward-travelling short-wave ripples. Based on our linear stability calculations for arbitrary wavenumbers, we have uncovered a new short-wave interfacial instability mode with negative linear wave speed, causing these ripples.

Key words: thin films, gas/liquid flow, solitary waves

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1. Introduction

Falling liquid films intervene in many engineering applications (Alekseenko *et al.* 2007; Azzopardi *et al.* 2011; Lapkin & Anastas 2018). One example is rectification columns containing structured packings for cryogenic air separation (Fair & Bravo 1990), where the liquid film is subject to a turbulent counter-current gas flow within narrow channels (Valluri *et al.* 2005). Surface waves, forming at the liquid–gas interface due to the inertia-driven Kapitza instability (Kapitza 1948), which consist of large humps preceded by several precursory capillary ripples, are known to greatly intensify inter-phase heat and mass transfer (Yoshimura, Nosoko & Nagata 1996; Miyara 1999; Dietze 2019). At the same time, they can trigger flooding events (Bankoff & Lee 1986) that are detrimental to adequate process operation. Such events include obstruction of the channel cross-section (Vlachos *et al.* 2001), wave reversal (Tseluiko & Kalliadasis 2011), fragmentation and droplet entrainment (Zapke & Kröger 2000), and (partial) liquid reversal (Trifonov 2010*b*, 2019). In light of these two competing roles played by surface waves, numerous experimental (Vlachos *et al.* 2001; Drosos, Paras & Karabelas 2006; Kofman, Mergui & Ruyer-Quil 2017), numerical (Trifonov 2010*a*, 2019; Vellingiri, Tseluiko & Kalliadasis 2015; Schmidt *et al.* 2016; Lavalle *et al.* 2019) and modelling (Tseluiko & Kalliadasis 2011; Dietze & Ruyer-Quil 2013; Lavalle *et al.* 2020, 2021) works have been dedicated to unravelling the effect of a counter-current gas flow on the linear and nonlinear dynamics of wavy falling liquid films. Our current paper seeks to further contribute to this task.

We study the configuration of a laminar falling liquid film sheared by a turbulent counter-current gas flow confined in a rectangular channel of height $H^\star \sim 10$ mm (the star superscript denotes dimensional quantities throughout), according to the experimental set-up sketched in figure 1. The confinement level chosen here is representative of structured packings (Fair & Bravo 1990) and lies in between those used in the experiments of Lavalle *et al.* (2019), $H^\star \sim 5$ mm, where the gas flow was laminar, and those of Kofman *et al.* (2017), $H^\star \sim 20$ mm, where the confinement was weak and the gas flow was turbulent. We have applied three different approaches to study this flow: (i) experiments, where developed surface waves of prescribed frequency were produced within a protected zone before being submitted to the counter-current gas flow; (ii) linear stability analysis based on the full governing equations; and (iii) nonlinear numerical computations with a new integral boundary layer model. Our study is guided by a set of experimental runs, where we have successively increased the counter-current gas flow rate, starting from conditions where the gas effect is weak, up until breakdown of the experiment due to flooding. Computations with our low-dimensional model and linear stability calculations have allowed us to elucidate the linear and nonlinear wave dynamics associated with this transition.

We focus mainly (but not exclusively) on weakly inclined falling liquid films, which allows us to investigate weakly supercritical flow regimes. According to Brooke Benjamin (1957) and Yih (1963), the onset of the Kapitza instability for a liquid film falling in a passive atmosphere is given by $Re_L = 5/6 \cot(\phi)$, where ϕ denotes the inclination angle, and $Re_L = q_L^\star/\nu_L$ is the liquid Reynolds number based on the liquid flow rate per unit width $q_L^\star$ and liquid kinematic viscosity ν_L. Thus the smaller ϕ, the more closely the instability threshold can be approached while maintaining an experimentally realizable film thickness $h_0^\star = (3\,Re_L\,\nu_L^2/g/\sin(\phi))^{1/3}$, where the subscript 0 denotes the primary flow, and g is the gravitational acceleration. Closer to the instability threshold, the interfacial dynamics are less complicated, and surface waves are predominantly two-dimensional (Kofman, Mergui & Ruyer-Quil 2014).
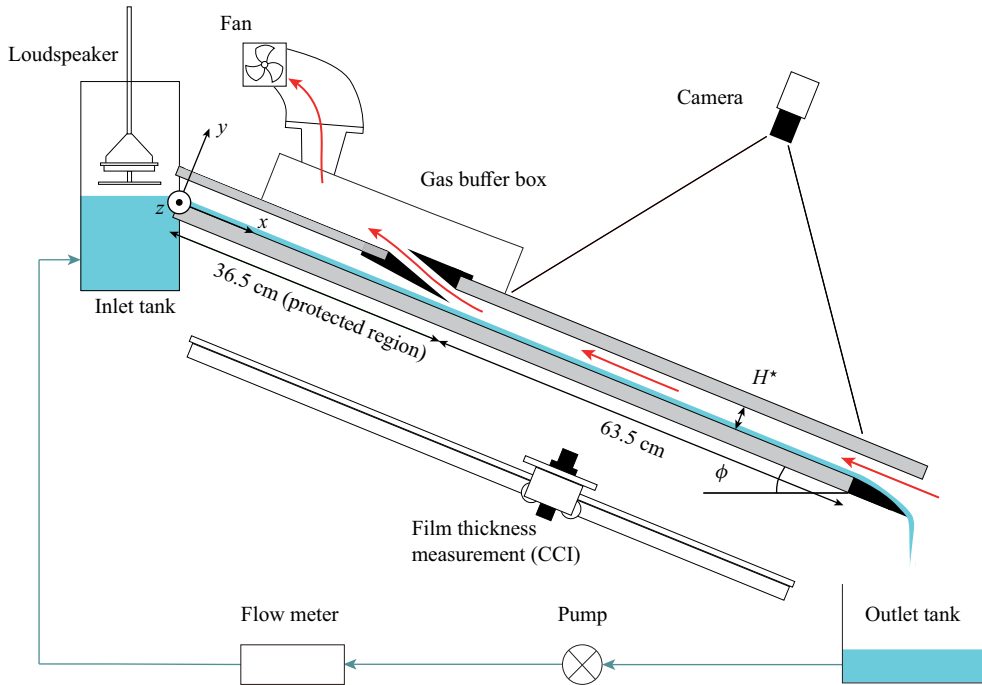
Figure 1. Sketch of our experimental set-up. A falling liquid film of water flows down a glass plate inclined at an angle $\phi = 5°$, and enters into contact with a counter-current turbulent air flow within a rectangular channel of height $H^\star = 13$ mm and width $W^\star = 27$ mm. A loudspeaker is used to force Kapitza waves on the surface of the liquid film, which grow and saturate within a protected region.

Our current work is inspired by several recent findings reported in the literature, which we discuss next. Lavalle *et al.* (2019) demonstrated that the onset of the Kapitza instability can be delayed significantly at low inclination angles, by strongly confining the surrounding gas, as conjectured by Tilley, Davis & Bankoff (1994). Moreover, they discovered that the gas-induced stabilization is strongest in the counter-current configuration, and increases with increasing magnitude of the gas flow rate. Kushnir *et al.* (2021) showed subsequently that stabilization also occurs in the case of a confined recirculating gas, i.e. when the net gas flow rate is zero. In the above three studies, the gas flow was considered laminar and the stabilization occurred for strong confinement, i.e. $H^\star \leq 5$ mm. As demonstrated by Lavalle *et al.* (2019), it is caused by the linear response of the interfacial tangential gas shear stress T_G to a perturbation of the liquid film thickness. Potentially, gas-induced stabilization may thus be achieved for weaker confinement if the gas flow is turbulent, as turbulence increases the magnitude of T_G. In the current paper, we have checked this hypothesis based on linear stability calculations. In particular, we find that the Kapitza instability can be suppressed fully by a turbulent counter-current gas flow for $H^\star \sim 10$ mm when the inclination angle is very small ($\phi \sim 1°$). By 'full suppression' we mean that the falling liquid film becomes unconditionally stable to long-wave disturbances, i.e. for all Re_L. By contrast, at non-negligible inclination ($\phi \sim 5°$), the linear gas effect is destabilizing and the counter-current gas flow can render the liquid film unconditionally unstable to long-wave disturbances, as reported previously for laminar flow conditions (Trifonov 2017; Kushnir *et al.* 2021). We find that turbulence can significantly delay the onset of this unconditional instability.

Recent numerical (Lavalle *et al.* 2021) and experimental (Mergui *et al.* 2023) investigations of weakly inclined falling liquid films have shown that a strongly confined laminar counter-current gas flow can attenuate the amplitude of nonlinear travelling-wave solutions (TWS), even though the linear gas effect is destabilizing. In our current configuration, where the inclination angle is similar but the confinement is weaker and the gas flow is turbulent, both the TWS amplitude and the linear spatial growth rate increase with increasing counter-current gas flow rate, at least until the absolute instability (AI) limit is reached.

Several works on gas-sheared falling liquid films in narrow (vertical) channels have identified wave coalescence as a possible route towards flooding. For example, Drosos *et al.* (2006) measured the probability density function of the wave height and found that the dominant wave frequency strongly decreases as the flooding limit is approached. Later, Dietze & Ruyer-Quil (2013) computed the noise-driven spatial evolution of Kapitza waves sheared by a superconfined laminar gas flow, and showed that coalescence can trigger an intermittent obstruction of the channel. Geometrical obstruction is not possible in our current configuration, where $H^\star$, although smaller than the typical wavelength $\Lambda^\star$, is much greater than $h_0^\star$. Nonetheless, we find that the counter-current gas flow exacerbates coalescence events, entailing very large waves that form via the successive absorption of smaller waves. Such waves have been designated as tsunami waves (Meza & Balakotaiah 2008), and we will employ this term throughout. In particular, the onset of coalescence moves upstream significantly when the counter-current gas flow rate is increased, precipitating the usual wave coarsening dynamics observed in liquid films falling in a quiescent gas (Chang *et al.* 1996*b*).

The transition between convective instability (spatial growth) and AI (temporal growth), which occurs when the counter-current gas flow rate is increased, has been suggested as another potential cause for the onset of flooding. For example, Vellingiri *et al.* (2015) showed that the AI limit predicted by their linear stability analysis lies not too far from the flooding threshold reported in the experiments of Zapke & Kröger (2000), where a vertically falling liquid film was sheared by a counter-current gas flow. However, the trends of the two limits versus the liquid Reynolds number Re_L were opposed, i.e. the flooding onset, expressed in terms of the superficial gas velocity, increased with increasing Re_L, whereas the AI limit diminished. In the current work, we have thus explored the spatio-temporal evolution of nonlinear Kapitza waves beyond the AI limit, based on experiments and numerical computations. We find that AI is not necessarily dangerous in our configuration, i.e. no catastrophic events occur until far beyond the AI limit. Moreover, in the case of a noise-driven wave evolution scenario, AI can act as an effective linear selection mechanism, leading to a regular train of downward-travelling nonlinear surface waves, thus precluding dangerous coalescence events.

Lavalle *et al.* (2020) studied vertically falling wavy liquid films sheared by a superconfined laminar counter-current gas flow, and discovered an oscillatory secondary instability. This instability entails a regular spatial modulation of TWS generated by coherent inlet forcing. We have performed computations for the same liquid-side parameters, but with our moderate confinement, i.e. $H^\star \sim 10$ mm. Although we do not observe any oscillatory instability, wave amplitude modulations occur nonetheless, albeit due to an entirely different mechanism, which sets in beyond the AI limit. There, a competition between the forcing frequency and the absolute frequency can lead to coalescence-induced tsunami waves that are separated by a long and thin residual film, on which small-amplitude standing ripples form as a result of AI. These ripples continually perturb the tsunami waves passing over them, similar to the effect of wall corrugations (Dietze 2019).

Several numerical works have suggested that a counter-current gas flow may provoke the reversal of nonlinear Kapitza waves, which can be viewed as another manifestation of flooding. Tseluiko & Kalliadasis (2011) observed this for a vertically falling liquid film sheared by a weakly confined turbulent gas flow. However, in their computations, the average film thickness $\bar{h}$ was fixed instead of the liquid flow rate, which is more representative of a sudden gas flow rate increase in an experiment. Trifonov (2017) observed the reversal of travelling Kapitza waves in the case of an inclined falling liquid film sheared by a laminar gas flow. However, the gas Reynolds number in his computations was far greater than the turbulence threshold, i.e. $|Re_G| > 10\,000$. Lavalle *et al.* (2020) observed wave reversal due to a gas-induced secondary instability of TWS in the case of extreme confinement ($H^\star \sim 1\,\text{mm}$). In our current configuration, where the liquid flow rate is imposed, the gas flow is turbulent and the confinement is moderate, we did not observe any reversal of Kapitza waves, either in terms of TWS or in the case of spatially evolving waves.

In our experiments, flooding is triggered (far beyond the AI limit) by upward-travelling short ripples that first coexist with the initial Kapitza waves and then overpower the latter. As soon as these ripples appear, liquid, in the form of small droplets, starts to accumulate in the gas loop, eventually forcing a shutdown of the experiment. Such ripples were first observed in the experiments of Kofman *et al.* (2017). In the current paper, we elucidate their origin, which has remained an open question.

Kofman *et al.* (2017) pointed out that the ripples observed in their experiments have wavelengths and amplitudes similar to those of ripples forming in horizontal liquid films sheared by an unconfined co-current turbulent gas flow (Özgen, Carbonaro & Sarma 2002). Those ripples are caused by a short-wave interfacial instability mode (Miesen & Boersma 1995). They have also been observed when the co-current gas flow is confined, e.g. in the experiments of Hanratty & Engen (1957), where $H^\star = 25.4\,\text{mm}$, and where the ripples were seen to coalesce into fast-travelling slugs. The corresponding instability mode was identified by McCready & Chang (1994). They showed that the dispersion curve of the linear temporal growth rate kc_i, where k and c_i denote the wavenumber and complex celerity, originates at $k = c_i = 0$, and displays two unstable ($kc_i > 0$) humps, one at small and another at large k, the short-wave hump being dominant. However, no short-wave instability mode has ever been identified for falling liquid films sheared by a counter-current (turbulent) gas flow, despite several previous linear stability investigations. And the ripples observed in our experiments move upstream, i.e. in the opposite direction to the liquid.

Schmidt *et al.* (2016) applied the Chebyshev collocation approach (Orszag 1971; Barmak *et al.* 2016a) to study this problem in the vertical configuration at $|Re_G| > 35\,000$, where $Re_G = q_G^\star/\nu_G$ designates the gas Reynolds number based on the gas flow rate per unit width $q_G^\star$ and the gas kinematic viscosity ν_G. Although the gas flow under these conditions would be turbulent in an experiment, the laminar Navier–Stokes equations were used. The authors identified four instability modes: (1) the long-wave Kapitza mode (Brooke Benjamin 1957; Yih 1963), which is an interfacial mode; (2) the liquid-side short-wave Tollmien–Schlichting mode (Floryan, Davis & Kelly 1987; Samanta 2020), which travels in the direction of the liquid and occurs at very large Re_L; (3) the gas-side short-wave Tollmien–Schlichting mode; and (4) a so-called long-wave internal mode, which appears at $|Re_G| \sim 10 \times 10^4$ and can merge with the Kapitza mode. Trifonov (2017) applied the same approach to the case of an inclined falling liquid film, and showed that the gas-side Tollmien–Schlichting mode corresponds to the classical result for channel flow, i.e. $|Re_G| = \frac{4}{3} \times 5772 = 7696$ (Orszag 1971). This mode always travels in the direction of

the gas flow, but it does not perturb the liquid–gas interface meaningfully. Thus it cannot generate the upward-travelling ripples observed in our experiment, which, moreover, occur at $|Re_G| \sim 6000$.

The works of Schmidt *et al.* (2016) and Trifonov (2017) did not account for turbulence in the primary flow, even though the gas Reynolds number $|Re_G|$ was far greater than the experimental turbulence threshold $|Re_G| \sim 1800$ (Pope 2000). Following the seminal work of Náraigh *et al.* (2011), this shortcoming was remedied by Vellingiri *et al.* (2015), who represented the turbulent gas flow via the Reynolds averaged Navier–Stokes (RANS) equations, using curvilinear coordinates and Prandtl's mixing-length approach. These authors observed a transition of the long-wave Kapitza instability from downward-convective to upward-convective upon increasing the counter-current gas flow rate q_{L0}. However, as the liquid film thickness h_0 and not q_{L0} was fixed in these calculations, upward-travelling waves were associated with $q_{L0} < 0$. By contrast, q_{L0} is fixed and positive in our experiments. Vellingiri *et al.* (2015) did not identify any short-wave instability mode. Nonetheless, they reported a non-monotonic variation of the cut-off wavenumber k_c upon increasing $|Re_G|$ for the long-wave instability mode, i.e. a decrease followed by an increase in k_c. Trifonov (2017) later made a similar observation. We will show that this behaviour results from an interaction between the long-wave Kapitza instability mode and a new short-wave interfacial instability mode, which we have detected via temporal linear stability calculations at fixed $q_{L0} > 0$, using the Chebyshev collocation approach.

This new short-wave mode emerges around the AI limit of the long-wave Kapitza instability mode, upon increasing the counter-current gas flow rate. Initially, the long-wave and short-wave modes coexist, but, at sufficiently large $|Re_G|$, they merge to form a two-humped dispersion curve originating at $k = c_i = 0$, and the short-wave maximum eventually becomes dominant. Linear waves corresponding to this maximum display a negative wave celerity $c_r < 0$, and both their wavelength Λ and c_r agree well with the upward-travelling ripples observed in our experiment. The wave celerity c_r of the new short-wave instability mode is always negative at the most-amplified wavenumber $k = k_{max}$, but it can change sign at lower k. This is a fundamental difference with the gas-side Tollmien–Schlichting mode. Conversely, when $c_r < 0$, the liquid film surface velocity is not necessarily negative. Thus ripples travel upwards, even when the liquid travels downwards across the entire film thickness. This is a difference with the interfacial mode observed in co-current liquid/gas flows (Miesen & Boersma 1995).

Nonlinear computations in the current paper have been performed with a new low-dimensional model, which we introduce. Therein, the liquid film is represented via the weighted residual integral boundary layer (WRIBL) approach of Ruyer-Quil & Manneville (1998), leading to two coupled evolution equations for the local instantaneous film thickness h and liquid flow rate q_L. We develop these equations up to second order in the long-wave parameter, and account for the effect of an adjacent gas via the gas shear stress T_G and the gas pressure P_G, acting at the liquid–gas interface. Following Camassa, Ogrosky & Olander (2017), we obtain these coupling quantities from a first-order long-wave (LW) approximation of the gas-side RANS equations written in curvilinear coordinates (Thorsness, Morrisroe & Hanratty 1978), while assuming a frozen liquid–gas interface. Our thus obtained WRIBL-LW model represents several improvements with respect to previous works, which we will discuss next.

Demekhin (1981) used the integral boundary layer approach of Shkadov (1967) to model the liquid film, and accounted for the effect of a turbulent gas flow, via T_G and P_G, through the linear response of the gas-side RANS equations to a waviness of the liquid–gas

interface (assumed frozen). This linearized approach is valid in the limit $h/H \ll 1$, i.e. assuming a large channel height versus the film thickness. Further, the authors invoked the quasi-laminar assumption (Miles 1957; Brooke Benjamin 1959), where turbulence enters only via the unperturbed flow and linear perturbations of the Reynolds stresses are neglected, which is usually valid in gas-sheared wavy liquid films (Náraigh *et al.* 2011). However, the liquid-side integral boundary layer approach is known to significantly over-predict the instability threshold of an inclined falling liquid film.

Tseluiko & Kalliadasis (2011) remedied this shortcoming by combining the gas-side description of Demekhin (1981) with a WRIBL representation of the liquid film. However, their liquid-side WRIBL model was developed only up to first order in the long-wave parameter, thus in conjunction with the linear gas-side approach, the gas pressure P_G did not enter the problem. We will show that this changes the linear response of the liquid film qualitatively in our configuration, and that a second-order liquid-side WRIBL development, accounting for P_G, is needed to capture accurately the effect of the counter-current gas flow.

Such a liquid-side treatment was applied by Samanta (2014), but the author made several simplifications in the gas-side description, i.e. P_G was neglected altogether, and T_G was assumed constant. The latter assumption entails that the gas-induced stabilization observed in superconfined falling liquid films (Lavalle *et al.* 2019), which relies on the linear response of T_G, cannot be captured.

Camassa *et al.* (2017) accounted for variations in P_G and T_G in their gas-side description. Moreover, their gas-side description relies on a long-wave rather than low-amplitude expansion of the RANS equations, thus finite confinement levels can be studied. However, their description of the liquid film relied on the lubrication approach. Thus the inertia-driven Kapitza instability, which is responsible for generating long waves in our configuration but was irrelevant in theirs, cannot be captured.

By coupling the gas-side approach of Camassa *et al.* (2017) with a second-order WRIBL description of the liquid film, our WRIBL-LW model remedies the different limitations discussed above. Our model is aimed at moderate confinement levels, where the gas flow is turbulent and the gas pressure is relevant. In that sense, it complements the model of Dietze & Ruyer-Quil (2013), for superconfined laminar liquid–gas flows, and the models of Demekhin (1981) and Tseluiko & Kalliadasis (2011), for weakly confined falling liquid films sheared by a turbulent gas flow, where the effect of P_G is negligible. For completeness, we point out that our model does not rely on the quasi-laminar assumption (Alekseenko *et al.* 2009; Trifonov 2010*a*; Tseluiko & Kalliadasis 2011; Vellingiri *et al.* 2015). We will show that it predicts accurately the dynamics of Kapitza waves under the effect of a counter-current turbulent gas flow, in good agreement with experiments.

Our paper is structured as follows. In § 2, we introduce our experimental set-up for studying surface waves in gas-sheared falling liquid films. In § 3, we present our low-dimensional WRIBL-LW model (§§ 3.1 and 3.2), and the numerical methods underlying our linear and nonlinear computations therewith (§ 3.4). Section 4 concerns linear stability calculations based on the full RANS equations in the gas, where the liquid-side description is based either on the WRIBL model (§ 4.1) or on the full Navier–Stokes equations (§ 4.2). In § 5, we validate our WRIBL-LW model versus linear stability calculations and experiments. Section 6 presents our results concerning the gas effect on linear and nonlinear wave dynamics. We first focus on waves resulting from the long-wave Kapitza instability (§ 6.1), and then discuss upward-travelling short-wave ripples (§ 6.2). Conclusions are drawn in § 7, followed by Appendices A and B, containing validation results, and Appendix C, where we justify one of our model assumptions.

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2. Experiments

Figure 1 sketches the set-up used for our experiments. A liquid film (index L) of water flows down a glass plate inclined at $\phi = 5°$, and enters into contact with a counter-current turbulent gas flow (index G) of air confined within a rectangular channel of height $H^\star = 13$ mm and width $W^\star = 27$ cm. This set-up is a slightly modified version of the set-up used in the work of Mergui *et al.* (2023), where $H^\star = 5$ mm and the gas flow was laminar.

The liquid flow rate $q_L^\star$ is controlled through a gear pump and measured with error ± 3 % using a conductance flow meter (IFM electonic, SM6000). In the current paper, we focus on two liquid-side regimes: $Re_L \sim 33$ and $Re_L \sim 45$. A loudspeaker integrated into the upstream liquid reservoir enables the forcing of Kapitza waves with prescribed frequency $f_0^\star$ on the surface of the liquid film. These waves are allowed to grow and saturate within a protected region spanning from $x^\star = 0$ to $x^\star = 36.5$ cm, before entering the gas-sheared section of the set-up (36.5 cm $\leq x^\star \leq 100$ cm). In our experiments, $f_0^\star$ is chosen such as to maximize the linear growth rate of the Kapitza waves, yielding a train of regular waves within the protected region. Also, the forcing amplitude is adjusted so that the waves reach a saturated amplitude before entering the gas-sheared section.

The gas flow rate $q_G^\star$ is controlled through a fan, and quantified via a calibration curve (relating the fan power to $q_G^\star$) obtained from gas velocity measurements in the dry channel. Details of the procedure are given in Mergui *et al.* (2023). An error on Re_G of 3 % was estimated for all our experiments. For a given liquid flow rate, the fan power was varied from zero up until breakdown of the experiment due to flooding, when liquid droplets accumulated in the gas buffer box. At zero fan power, the gas is subject to an aerostatic pressure drop, which is imposed by the quiescent ambient air. In this case, which we will designate as aerostatic configuration, the gas flows downwards under the shearing action of the falling liquid film, i.e. $q_G^\star > 0$. Conversely, in the case of a counter-current gas flow, we have $q_G^\star < 0$. Thus we consider $q_G^\star$, and the gas Reynolds number Re_G, as signed quantities.

In our counter-current experimental runs, Re_G was typically varied from $Re_G = -3000$ to $Re_G = -6800$, after an initial measurement under aerostatic conditions. Due to evaporation, the liquid temperature typically decreased by a few Kelvin between the aerostatic and counter-current configurations. As $q_L^\star$ remained fixed during each run, a corresponding variation of Re_L occurred due to changes in the fluid properties. To account for this, we have monitored the liquid temperature T_{inlet} in the inlet tank over the course of each experiment, using a thermocouple. The temperature decrease was observed as soon as the counter-current air flow was imposed, but the temperature varied little upon increasing the gas flow rate after that. Thus, when reporting experimental data, we will give Re_L^{as}, which corresponds to the aerostatic configuration, and Re_L, which corresponds to the counter-current configuration.

Representative values of the density and kinematic viscosity of water and air for our counter-current experiments ($T_{inlet} \simeq 19\,°C$) are $\rho_L = 998.3$ kg m^{-3}, $\nu_L = 1.03 \times 10^{-6}$ m^2 s^{-1} and $\rho_G = 1.21$ kg m^{-3}, $\nu_G = 14.9 \times 10^{-6}$ m^2 s^{-1}. The surface tension of our water was measured once and for all at $T = 19.9\,°C$ with a drop shape analyser (Krüss), yielding $\sigma = 71$ mN m^{-1}. Based on this, we obtain $Ka = \sigma/(\rho_L g^{1/3} \nu_L^{4/3}) = 3174$ for the Kapitza number. Conversely, for our experiments in the aerostatic configuration ($T_{inlet} \simeq 21\,°C$), we obtain $Ka = 3394$.

Two methods were applied to characterize the gas effect on the dynamics of nonlinear surface waves (for details, see Kofman *et al.* 2014; Mergui *et al.* 2023): (1) shadowgraphy
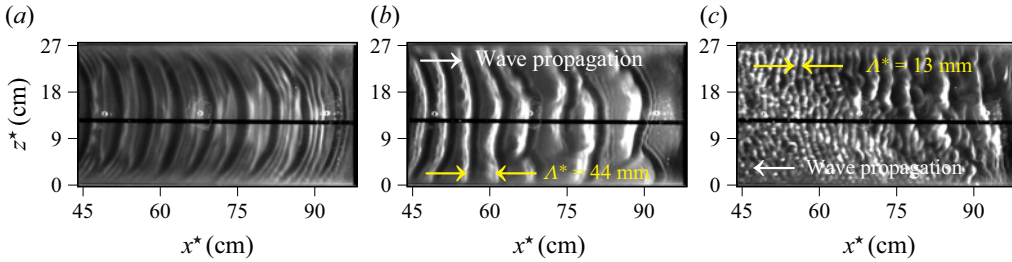
Figure 2. Transition of the wavy falling liquid film under a counter-current gas flow: water/air, $Re_L^{as} = 44.7$, $Re_L = 43.1$, $f_0^\star = 3$ Hz. Shadowgraphs of the liquid–gas interface for increasingly strong fan power: (*a*) zero fan power (aerostatic configuration), regularly-spaced Kapitza waves; (*b*) $Re_G = -5830$, coalescence of Kapitza waves; (*c*) $Re_G = -6760$, coexistence of Kapitza waves with upward-travelling short ripples.

of the wavy liquid–gas interface, using an sCMOS camera (PCO, pco.edge 5.5) with 100 Hz frame rate; (2) pointwise measurements of the film thickness time trace, using a confocal chromatic imaging (CCI) technique (Cohen-Sabban, Gaillard-Groleas & Crepin 2001; Lel *et al.* 2005) with 400 Hz acquisition frequency and accuracy $\pm 1\,\mu$m (Stil S.A., CL-MG CL4 line sensor).

Figures 2 and 3 show typical data obtained with these two methods. Figure 2 represents shadowgraphs for an experiment, where the fan power was increased step by step (from left to right), while maintaining $q_L^\star$ and $f_0^\star = 3$ Hz fixed. Each shadowgraph represents the entire width of the channel and almost the entire length of the gas-sheared section of the set-up, i.e. $44\,\text{cm} \leq x^\star \leq 100\,\text{cm}$. At zero fan power (figure 2*a*), regularly spaced Kapitza waves with quasi-two-dimensional wave fronts are observed. Applying and increasing a counter-current gas flow rate causes first coalescence events (figure 2*b*) and then the emergence of upward-travelling short ripples that coexist with the long Kapitza waves (figure 2*c*). This dynamics will be the focus of § 6.

Figure 3 represents measurement data obtained with the CCI technique for the aerostatic configuration at $Re_L^{as} = 33.7$ and $f_0^\star = 2.8$ Hz. In figure 3(*a*), we have plotted time traces of the film thickness $h^\star$ at streamwise positions representative for the regimes of linear growth, nonlinear growth and saturation of Kapitza waves. These time traces evidence the formation of characteristic precursory capillary ripples. Figure 3(*b*) represents spatial profiles of the ensemble-averaged (over at least 100 waves) maximum film thickness $h_{max}^\star$, minimum film thickness $h_{min}^\star$, and time-averaged (over at least 100 wave periods) film thickness $\bar{h}^\star$. Error bars illustrate the standard deviation. To obtain these profiles, the CCI probe was displaced incrementally using a rail (see figure 1).

3. Low-dimensional WRIBL-LW model

We consider the flow in figure 4. A two-dimensional laminar falling liquid film of thickness $h(x, t)$ flows along an inclined plane under the action of gravity, while being sheared by a counter-current turbulent gas flow. The gas flow is confined by a second wall at $y^\star = H^\star$ (the star superscript denotes dimensional quantities throughout), which is not represented. We impose a symmetry condition at the centreline of the average gas layer, i.e. $y^\star = D^\star$. In the case of a symmetrical vertical configuration with liquid films lining both walls (Vlachos *et al.* 2001), this condition is satisfied analytically, and we have $D^\star = H^\star/2$. In the case of an inclined configuration with a dry upper wall, which is the one considered here, the symmetry condition remains a reasonable approximation, provided that the liquid holdup $\bar{h}^\star/H^\star$, where $\bar{h}^\star$ designates the average film thickness, is not too large. In the
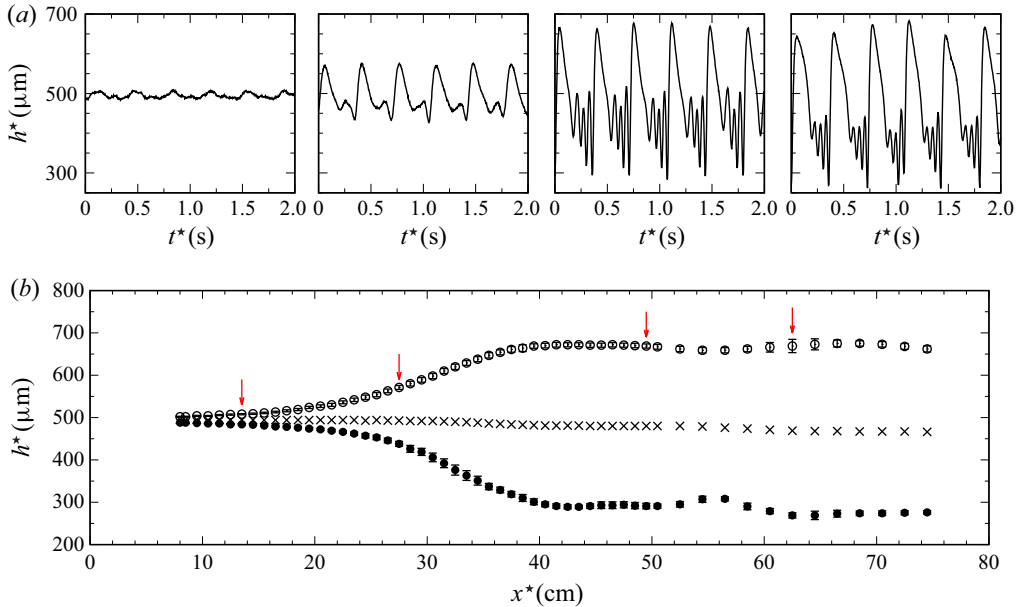
Figure 3. Typical CCI film thickness measurements in the aerostatic configuration: water/air, $Re_L^{as} = 33.7$, $f_0^\star = 2.8$ Hz. (*a*) Film thickness time traces measured at different positions. From left to right: $x^\star = 13.5, 27.5,$ 49.5 and 62.5 cm. (*b*) Spatial profiles of averaged quantities (at least 100 waves). Open/filled circles indicate ensemble-averaged wave height $h_{max}^\star$ and minimum film thickness $h_{min}^\star$; crosses indicate time-averaged film thickness $\bar{h}^\star$. Error bars indicate standard deviation, and red arrows mark positions for the traces in (*a*).

current work, $\bar{h}^\star/H^\star < 0.1$, thus the symmetry condition is acceptable. In that case, $D^\star = (H^\star + \bar{h}^\star)/2$. Moreover, due to the inter-phase coupling conditions that we will apply in our gas-side description (frozen-interface assumption), and the nature of our calculations (linear stability analysis and long-wave asymptotic expansion), the symmetry condition at $y^\star = D^\star$ holds analytically, even when the upper wall is dry. This will be explained further in §§ 3.2 and 4.1.

Following previous works (Halpern & Grotberg 2003; Tseluiko & Kalliadasis 2011; Samanta 2014; Camassa *et al.* 2017), we relax the inter-phase coupling conditions and apply a weakly coupled treatment of the two-phase flow. The liquid film (§ 3.1) is modelled with the WRIBL method (Kalliadasis *et al.* 2012), where the effect of the gas enters via the tangential gas shear stress T_G and the gas pressure P_G acting at the film surface $y^\star = h^\star$ (figure 4), neglecting the normal gaseous viscous stress. These inter-phase coupling quantities are obtained from the gas-side model (§ 3.2), which is derived via long-wave asymptotic expansion, following Camassa *et al.* (2017).

3.1. *Liquid-side WRIBL model*

The liquid film (subscript L), with density ρ_L, dynamic viscosity μ_L and surface tension σ, is governed by the dimensionless continuity and Navier–Stokes equations written in Cartesian coordinates x and y (figure 4):

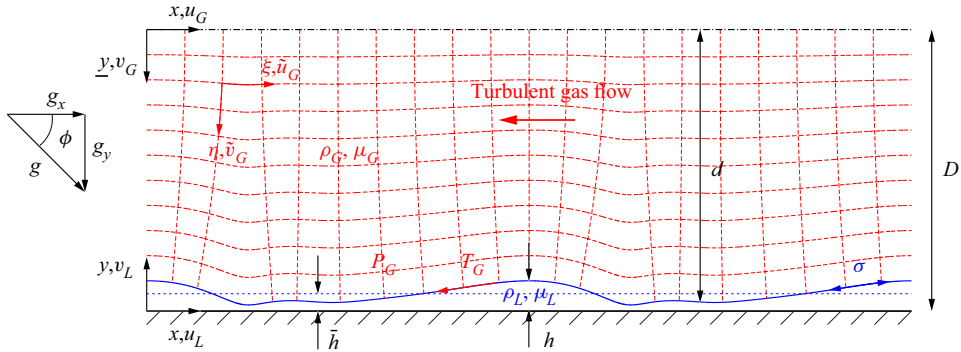$$\partial_x u_L + \partial_y v_L = 0, \tag{3.1a}$$

Figure 4. Falling liquid film (subscript L) on an inclined wall subject to a counter-current turbulent gas flow (subscript G). The flow is confined by an upper wall (not shown) at $y^\star = H^\star$ (stars denote dimensional quantities), and a symmetry condition is imposed at the centreline of the average gas layer $y^\star = D^\star$. Gas–liquid coupling is expressed via the tangential gas shear stress T_G and the gas pressure P_G at the film surface $y^\star = h^\star$. Red dashed lines illustrate the orthogonal curvilinear coordinate system (η, ξ), where $\eta = y\bar{d}/d$.

$$\epsilon(\partial_t u_L + u_L \, \partial_x u_L + v_L \, \partial_y u_L) = -\epsilon \, \partial_x p + \frac{1}{Re_L} (\epsilon^2 \, \partial_{xx} u_L + \partial_{yy} u_L) + \frac{\sin(\phi)}{Fr^2}, \qquad (3.1b)$$

$$\epsilon^3(\partial_t v_L + u_L \, \partial_x v + v_L \, \partial_y v_L) = -\epsilon \, \partial_y p_L + \frac{1}{Re_L} (\epsilon^4 \, \partial_{xx} v_L + \epsilon^2 \, \partial_{yy} v_L) - \epsilon \frac{\cos(\phi)}{Fr^2}, \tag{3.1c}$$

where $Re_L = \rho_L \mathcal{U}_L \mathcal{L}/\mu_L$ and $Fr = \mathcal{U}_L/\sqrt{\mathcal{L}g}$ denote the liquid Reynolds number and Froude number, and where we have applied the scaling

$$u_L = \frac{u_L^\star}{\mathcal{U}_L}, \quad v_L = \frac{v_L^\star}{\epsilon \mathcal{U}_L}, \quad x = \epsilon \frac{x^\star}{\mathcal{L}}, \quad y = \frac{y^\star}{\mathcal{L}}, \quad t = \epsilon t^\star \frac{\mathcal{U}_L}{\mathcal{L}}, \quad p_L = \frac{p_L^\star}{\rho_L \mathcal{U}_L^2}. \tag{3.1d}$$

Here, we have introduced the long-wave parameter $\epsilon = \mathcal{L}/\Lambda^\star$, which relates the cross-stream length scale $\mathcal{L}$ to the streamwise length scale given by the wavelength $\Lambda^\star$. For the purpose of the current derivation, it suffices to say that the scales $\mathcal{L}$ and $\mathcal{U}_L$ are representative of the film thickness $h^\star$ and streamwise liquid velocity $u_L^\star$. In § 3.3, we will rescale our problem and make the final choice for $\mathcal{L}$ and $\mathcal{U}_L$.

The system is closed with the boundary conditions at $y = 0$

$$u_L = v_L = 0, \tag{3.1e}$$

the kinematic condition

$$v_L|_{y=h} = u_L|_{y=h} \, \partial_x h + \partial_t h, \tag{3.1f}$$

and the inter-phase stress coupling conditions at $y = h$

$$-\partial_y u_L \frac{1}{1 + \epsilon^2 \, \partial_x h^2} (-\epsilon^4 \, \partial_x h^2 \, \partial_x v_L - 4\epsilon^2 \, \partial_x h \, \partial_x u_L + \epsilon^2 \, \partial_x v_L) = \frac{\Pi_\mu \Pi_u}{\Pi_L} T_G, \tag{3.1g}$$

$$\epsilon P_L + \frac{2}{1 + \epsilon^2 \, \partial_x h^2} \frac{1}{Re_L} (\epsilon^4 \, \partial_x h^2 \, \partial_x u_L - \epsilon^4 \, \partial_x h \, \partial_x v_L - \epsilon^2 \, \partial_x u_L - \epsilon^2 \, \partial_x h \, \partial_y u_L)$$

$$- \epsilon^3 \, We \, \partial_{xx} h = \frac{1}{Re_G} \frac{\Pi_\rho \Pi_u^2}{\Pi_L} P_G, \tag{3.1h}$$

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where $We = \sigma/(\rho_L \mathcal{L} \mathcal{U}_L^2)$ denotes the Weber number. The liquid–gas coupling enters through T_G and P_G, which are scaled as follows:

$$T_G = \frac{\mathcal{L}_G}{\mu_G \mathcal{U}_G} T_G^\star, \quad P_G = \epsilon \frac{\mathcal{L}_G}{\mu_G \mathcal{U}_G} P_G^\star, \tag{3.2a,b}$$

where $\mathcal{L}_G$, $\mathcal{U}_G$ and $\underline{\epsilon} = \mathcal{L}_G/\Lambda^\star = \epsilon \Pi_L$ denote the gas-side cross-stream length scale, velocity scale and long-wave parameter, which will be defined in § 3.2. As a result, the gas Reynolds number $Re_G = \rho_G \mathcal{U}_G \mathcal{L}_G/\mu_G$, the velocity scale ratio $\Pi_u = \mathcal{U}_G/\mathcal{U}_L$, the length scale ratio $\Pi_L = \mathcal{L}_G/\mathcal{L}$, and the viscosity and density ratios $\Pi_\mu = \mu_G/\mu_L$ and $\Pi_\rho = \rho_G/\rho_L$ enter (3.1g) and (3.1h).

Next, we apply the WRIBL approach to derive two evolution equations involving the local instantaneous liquid flow rate $q(x, t)$ and the film thickness $h(x, t)$. In principle, we follow the same steps as Samanta (2014), except that we account for the gas pressure P_G, which plays an important role in our current configuration, allow P_G and T_G to vary in space and time, and account for turbulence in the gas.

First, the governing equations (4.1a,b) are truncated at $O(\epsilon^2)$, except for inertial terms, which are truncated at $O(Re_L \epsilon)$. Next, we eliminate p from (3.1b) via an integrated form of (3.1c) using (3.1h). Then we substitute for the streamwise velocity u (v is obtained from (3.1a)) the decomposition

$$u_L = \hat{u}_L + \epsilon u_L^{(1)}, \tag{3.3}$$

where the base profile $\hat{u}_L$ is governed by

$$\left. \begin{array}{c} \partial_{yy}\hat{u}_L = \text{const.}, \quad \partial_y \hat{u}_L\big|_{y=h} = \dfrac{\Pi_\mu \Pi_u}{\Pi_L} T_G, \quad \hat{u}_L\big|_{y=0} = 0, \\[3mm] \displaystyle\int_0^{h(x,t)} \hat{u}_L \, \mathrm{d}y = q_L(x, t). \end{array} \right\} \tag{3.4}$$

Finally, the unknown $O(\epsilon)$ velocity correction $\epsilon u_L^{(1)}$ is eliminated from the problem by multiplying the truncated form of (3.1b) with a weight function $w(y)$, integrating the result across the film thickness $h(x, t)$, and applying the tangential inter-phase coupling condition (3.1g). The weight function w satisfies

$$\partial_{yy}w = \text{const.}, \quad w|_{y=0} = 0, \quad \partial_y w|_{y=h} = 0. \tag{3.5a–c}$$

As a final result, we obtain the integral momentum equation for the liquid film,

$$\partial_t q_L + \frac{17}{7} \frac{q_L}{h} \partial_x q_L - \frac{9}{7} \frac{q_L^2}{h^2} \partial_x h = \frac{5}{6} We\, h\, \partial_{xxx} h + \frac{5}{6} Fr^{-2} h \left\{ \sin(\phi) - \cos(\phi) \partial_x h \right\}$$

$$+ Re_L^{-1} \left\{ -\frac{5}{2} \frac{q_L}{h^2} + 4 \frac{q_L}{h^2} \partial_x h^2 - \frac{9}{2h} \partial_x q_L \, \partial_x h - 6 \frac{q_L}{h} \partial_{xx} h + \frac{9}{2} \partial_{xx} q_L \right\}$$

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$$+ \frac{\Pi_\mu \Pi_u}{\Pi_L} T_G \left\{ Re_L^{-1} \left[\frac{5}{4} + \frac{h}{6} \partial_{xx}h + \frac{1}{2} \partial_x h^2 \right] - \frac{5}{112} q_L \partial_x h - \frac{19}{336} \partial_x q_L h \right\}$$

$$- \frac{19}{672} \frac{\Pi_\mu^2 \Pi_u^2}{\Pi_L^2} h^2 \partial_x h T_G^2 - \frac{5}{6} Re_G^{-1} \frac{\Pi_\rho \Pi_u^2}{\Pi_L} h \partial_x P_G$$

$$+ \frac{\Pi_\mu \Pi_u}{\Pi_L} \left\{ \partial_x T_G \left[Re_L^{-1} \frac{3}{4} h \partial_x h - \frac{15}{224} h q_L \right] - \frac{25}{1344} \frac{\Pi_\mu \Pi_u}{\Pi_L} h^3 T_G \partial_x T_G - \frac{h^2}{48} \partial_t T_G \right\},$$
$$(3.6a)$$

to which is added an integral continuity equation obtained by integrating (3.1a) across the liquid film and applying (3.1f):

$$\partial_t h + \partial_x q_L = 0. \tag{3.6b}$$

In the limit $T_G = \partial_x P_G = 0$, (3.6a) reduces to (41) from Ruyer-Quil & Manneville (2000). In the limit $\partial_x T_G = \partial_t T_G = \partial_x P_G = 0$, it collapses with (3.9) from Samanta (2014), except for a typo in the $T_G \partial_x h^2$ term of that reference. Here, we will neglect the terms involving $\partial_x T_G$ and $\partial_t T_G$, but we will account for the space and time variation of $T_G(x, t)$ and $P_G(x, t)$ in the remaining terms. This amounts to a quasi-developed approach. See Appendix C for a justification of this approximation.

Versus the model of Tseluiko & Kalliadasis (2011), which is based on a linear representation of the gas response, our model accounts for the gas pressure P_G, which plays a role for the confinement considered here. It also accounts for streamwise viscous diffusion in the liquid, which is known to affect the dynamics of precursory capillary ripples (Ruyer-Quil & Manneville 2002).

3.2. *Gas-side asymptotic long-wave model*

We represent the turbulent flow of the gas (subscript G), with density ρ_G and dynamic viscosity μ_G, in two dimensions via the (dimensionless) Reynolds-averaged continuity and steady Navier–Stokes (RANS) equations, written here in the Cartesian gas-side coordinates x and $\underline{y}$ (see figure 4) as

$$\partial_x u_G + \partial_{\underline{y}} v_G = 0, \tag{3.7}$$

$$\underline{\epsilon}(u_G \partial_x u_G + v_G \partial_{\underline{y}} u_G) = -\frac{1}{Re_G} \partial_x p_G + \frac{\Pi_L}{\Pi_u^2} \frac{\sin(\phi)}{Fr^2} + \frac{1}{Re_G} \left\{ \partial_{\underline{yy}} u_G + \underline{\epsilon}^2 \partial_{xx} u_G \right\}$$

$$+ \frac{1}{Re_G} \left\{ \partial_{\underline{y}} \left(\frac{\mu_t}{\mu_G} \partial_{\underline{y}} u_G \right) + \underline{\epsilon}^2 \partial_x \left(\frac{\mu_t}{\mu_G} \partial_x u_G \right) \right\}, \tag{3.8a}$$

$$\underline{\epsilon}^3(u_G \partial_x v_G + v_G \partial_{\underline{y}} v_G) = -\frac{1}{Re_G} \partial_{\underline{y}} p_G + \underline{\epsilon} \frac{\Pi_L}{\Pi_u^2} \frac{\cos(\phi)}{Fr^2} + \frac{1}{Re_G} \left\{ \underline{\epsilon}^2 \partial_{\underline{yy}} v_G + \underline{\epsilon}^4 \partial_{xx} v_G \right\}$$

$$+ \frac{1}{Re_G} \left\{ \underline{\epsilon}^2 \partial_{\underline{y}} \left(\frac{\mu_t}{\mu_G} \partial_{\underline{y}} v_G \right) + \underline{\epsilon}^4 \partial_x \left(\frac{\mu_t}{\mu_G} \partial_x v_G \right) \right\}, \tag{3.8b}$$

where μ_t denotes the turbulent viscosity, $Re_G = \rho_G \mathcal{U}_G \mathcal{L}_G / \mu_G$ is the gas Reynolds number, and we have applied the scaling

$$u_G = \frac{u_G^\star}{\mathcal{U}_G}, \quad v_G = \frac{v_G^\star}{\underline{\epsilon} \mathcal{U}_G}, \quad x = \underline{\epsilon} \frac{x^\star}{\mathcal{L}_G}, \quad \underline{y} = \frac{\underline{y}^\star}{\mathcal{L}_G}, \quad p_G = p_G^\star \frac{\underline{\epsilon} \mathcal{L}_G}{\mu_G \mathcal{U}_G}, \tag{3.9a–e}$$

introducing the gas-side long-wave parameter $\epsilon = \mathcal{L}_G/\Lambda^\star$. For the gas-side reference scales, we choose once and for all

$$\mathcal{L}_G = H^\star, \quad \mathcal{U}_G = \frac{q_{G0}^\star}{H^\star}, \tag{3.10a,b}$$

where $q_{G0}^\star$ is the nominal gas flow rate per unit width of the primary flow (subscript 0), thus $\mathcal{U}_G$ corresponds to the superficial gas velocity. We have scaled pressure with a measure for the viscous shear stress, in contrast to (3.1d), where the dynamic pressure was used.

The turbulent viscosity μ_t is formulated via the mixing-length approach (Prandtl 1925):

$$\frac{\mu_t}{\mu_G} = Re_G \, l_t^2 \left| \partial_{\underline{y}} u_G \right|, \tag{3.11}$$

where $l_t = l_t^\star/\mathcal{L}_G$ denotes the dimensionless mixing length. At this point, a remark about choosing a turbulent viscosity model, such as (3.11), is in order. Luchini & Charru (2019) have shown that such models cannot fully reproduce the momentum redistribution induced by wall perturbations to a parallel turbulent flow. Nonetheless, comparisons with different experiments (Zilker, Cook & Hanratty 1977; Frederick & Hanratty 1988) have shown that turbulent viscosity models based on the van Driest equation, which will be introduced in (3.22), capture satisfactorily the linear (Russo & Luchini 2016) and nonlinear (Tseluiko & Kalliadasis 2011; Camassa *et al.* 2017) responses of the wall shear stress. Thus such models allow us to account adequately for the inter-phase coupling in our current configuration.

We assume a large gas/liquid velocity contrast $\Pi_u \gg 1$, which warrants two simplifications. First, we have neglected time derivatives in (3.8), as

$$O \left\{ \frac{\partial_{t^\star} u_G^\star}{u_G^\star \, \partial_{x^\star} u_G^\star} \right\} = \frac{1}{\Pi_u} \ll 1, \tag{3.12}$$

assuming that the time scale is dictated by the waviness of the liquid film, i.e. $\mathcal{T} = \Lambda^\star/\mathcal{U}_L$. Second, we set zero-velocity conditions at the film surface $\underline{y} = d$:

$$u_G = v_G = 0. \tag{3.13a}$$

Thus, from the point of view of the gas, the film surface is represented as a frozen wavy wall (Tseluiko & Kalliadasis 2011). Our system is closed via a symmetry condition at $\underline{y} = 0$:

$$\partial_{\underline{y}} u_G = v_G = 0. \tag{3.13b}$$

The ultimate aim of the gas-side model, to be derived next, is to obtain the inter-phase coupling quantities in (3.6a), which are evaluated at $\underline{y} = d$, implying $l_t = 0$:

$$P_G = p_G, \tag{3.14a}$$

$$T_G = \frac{T_G^\star}{\mu_G \mathcal{U}_G/\mathcal{L}_G} = -\partial_{\underline{y}} u_G - \left\{ \epsilon^2 \, \partial_x d^2 - 1 \right\}^{-1} \left\{ 2\epsilon^2 \, \partial_x d \, \partial_{\underline{y}} v_G \right.$$
$$\left. + 2\epsilon^2 \, \partial_x d \, \partial_x u_G + \epsilon^2 \, \partial_x v_G - \epsilon^4 \, \partial_x d^2 \, \partial_x v_G \right\}. \tag{3.14b}$$

Following Camassa *et al.* (2017), we introduce the curvilinear coordinates η and ξ (see figure 4), which will facilitate the account of turbulence:

$$\eta = \underline{y} \frac{\bar{d}}{d}, \quad \xi = x + \underline{\epsilon} F(\xi, \eta), \tag{3.15a,b}$$

where $\bar{d}$ denotes the spatial average of d, and orthogonality implies

$$\partial_\eta F = \underline{\epsilon} \frac{d}{\bar{d}^2} \, \partial_\xi d \, \frac{1}{\underline{\epsilon} \, \partial_\xi F - 1}. \tag{3.16}$$

Red dashed lines in figure 4 represent curves of constant η and ξ, where

$$\partial_x \underline{y} \Big|_\eta = - \left. \partial_{\underline{y}} x \right|_\xi = \frac{y}{\bar{d}} \, \partial_x d. \tag{3.17}$$

Next, we recast the governing equations (3.8) and (3.13) in the curvilinear coordinate system (tilde symbol), using the projection rules

$$u_G = \tilde{u}_G + O(\underline{\epsilon}^2), \quad v_G = \tilde{v}_G + \frac{\partial_\xi d}{\bar{d}} \, \eta \tilde{u}_G + O(\underline{\epsilon}), \tag{3.18a,b}$$

$$\partial_x = \partial_\xi - \eta \, \frac{\partial_\xi d}{d} \, \partial_\eta + O(\underline{\epsilon}), \quad \partial_{\underline{y}} = \frac{\bar{d}}{d} \, \partial_\eta + O(\underline{\epsilon}^2), \tag{3.19a,b}$$

and truncate the result at $O(\underline{\epsilon}^1)$. Upon eliminating the pressure variable p in (3.8a) via an appropriate integration of (3.8b), we obtain

$$\frac{\partial_\xi d}{d} \, \partial_\xi \tilde{u}_G + \partial_\xi \tilde{u}_G + \frac{\bar{d}}{d} \, \partial_\eta \tilde{v}_G = 0, \tag{3.20a}$$

$$\underline{\epsilon} \tilde{u}_G \, \partial_\xi \tilde{u}_G + \underline{\epsilon} \, \frac{\bar{d}}{d} \, \tilde{v}_G \, \partial_\eta \tilde{u}_G = -\frac{1}{Re_G} \, \partial_\xi P_G + \frac{\Pi_L}{\Pi_u^2} \, \frac{1}{Fr^2} \left(\sin(\phi) + \underline{\epsilon} \cos(\phi) \, \partial_\xi d \right)$$
$$+ \frac{1}{Re_G} \, \frac{\bar{d}^2}{d^2} \left\{ \partial_{\eta\eta} \tilde{u}_G + \partial_\eta \left[\frac{\tilde{\mu}_t}{\mu_G} \, \partial_\eta \tilde{u}_G \right] \right\}, \tag{3.20b}$$

where $P_G = p_G|_{\eta=\bar{d}}$, and $\tilde{\mu}_t$ satisfies

$$\frac{\tilde{\mu}_t}{\mu_G} = \frac{d}{\bar{d}} \, Re_G \, \tilde{l}_t^2 \left| \partial_\eta \tilde{u}_G \right|, \tag{3.21}$$

with $\tilde{l}_t = l_t \bar{d}/d$.

In this curvilinear formulation, the variation of the mixing length $\tilde{l}_t$ is expressed in terms of η, i.e. normal to the film surface, thus correlations for parallel flows can be used. Following Tseluiko & Kalliadasis (2011), we employ the van Driest equation (Van Driest 1956)

$$\tilde{l}_t = \kappa \left(\bar{d} - \eta \right) \left\{ 1 - \exp \left[\sqrt{|T_{G0}| \, Re_G} \, \frac{\eta - \bar{d}}{A} \right] \right\}, \tag{3.22}$$

where $A = 26$, $\kappa = 0.41$ is the von Kármán constant, and T_{G0} denotes the primary-flow tangential stress, obtained by evaluating (3.30) in the limit $\underline{\epsilon} = 0$, which intervenes in the

traditional scaling based on the friction velocity $\mathcal{U}^+$:

$$\mathcal{U}^+ = \left\{\rho_G^{-1} \left|T_{G0}^\star\right|\right\}^{1/2}, \quad \mathcal{L}^+ = \frac{\mu_G}{\rho_G \mathcal{U}^+}. \tag{3.23a,b}$$

Finally, the boundary conditions (3.13) become

$$\tilde{u}_G|_{\eta=\bar{d}} = \tilde{v}_G|_{\eta=\bar{d}} = 0, \quad \partial_\eta \tilde{u}_G|_{\eta=0} = \tilde{v}_G|_{\eta=0} = 0. \tag{3.24a,b}$$

The boundary-value problem (BVP) given by (3.20) and (3.24a,b) is solved order by order based on a regular expansion in $\underline{\epsilon}$ around $\underline{\epsilon} = 0$ (Camassa *et al.* 2017):

$$\tilde{u}_G = \tilde{u}_G^{(0)} + \underline{\epsilon}\tilde{u}_G^{(1)} + O(\underline{\epsilon}^2), \tag{3.25a}$$

$$\tilde{v}_G = \tilde{v}_G^{(0)} + \underline{\epsilon}\tilde{v}_G^{(1)} + O(\underline{\epsilon}^2), \tag{3.25b}$$

$$P_G = P_G^{(0)} + \underline{\epsilon}P_G^{(1)} + O(\underline{\epsilon}^2). \tag{3.25c}$$

The zeroth-order problem is obtained by inserting (3.25a) into (3.20) and (3.24a,b), and then truncating at $O(\underline{\epsilon}^0)$. We anticipate a solution in the form of the product ansatz

$$\tilde{u}_G^{(0)} = g_0(\xi)\, U_0(\eta) = \frac{\bar{d}}{d}\, U_0(\eta), \tag{3.26}$$

which leads to the variable-separated zeroth-order momentum equation

$$\frac{d^3}{\bar{d}^3}\left\{\frac{1}{Re_G}\,\partial_\xi P_G^{(0)} - \frac{\Pi_L}{\Pi_u^2}\,\frac{1}{Fr^2}\,\sin(\phi)\right\} = \frac{1}{Re_G}\,\partial_{\eta\eta}U_0 + \partial_\eta\left\{\bar{l}_t^2\,\mathrm{sgn}\left(\partial_\eta U_0\right)\left(\partial_\eta U_0\right)^2\right\} = C_0, \tag{3.27a}$$

subject to the boundary conditions

$$U_0|_{\eta=\bar{d}} = \partial_\eta U_0|_{\eta=0} = 0, \tag{3.27b}$$

where we have employed the signum function sgn to substitute $|\partial_\eta U_0| = \mathrm{sgn}(\partial_\eta U_0)\,\partial_\eta U_0$, and the separation constant C_0 is obtained from the gauge condition

$$\int_0^d \tilde{u}_G^{(0)}\,\mathrm{d}\tilde{y} = \int_0^{\bar{d}} U_0\,\mathrm{d}\eta = \frac{q_{G0}}{2} = \frac{1}{2}. \tag{3.27c}$$

At the next order, i.e. $O(\underline{\epsilon}^1)$, we obtain in a similar way

$$\frac{d^2}{\bar{d}^2}\left\{\frac{1}{Re_G}\,\partial_\xi P_G^{(1)}\,\frac{d}{\partial_\xi d} - \frac{\Pi_L}{\Pi_u^2}\,\frac{1}{Fr^2}\,\cos(\phi)\,d\right\} = U_0^2 + \frac{1}{Re_G}\,\partial_{\eta\eta}U_1$$
$$+ \partial_\eta\left\{\bar{l}_t^2\,\mathrm{sgn}\left(\partial_\eta U_0\right)\partial_\eta U_0\,\partial_\eta U_1\right\} = C_1, \tag{3.28a}$$

$$U_1|_{\eta=\bar{d}} = \partial_\eta U_1|_{\eta=0} = 0, \tag{3.28b}$$

$$\int_0^d \tilde{u}_G^{(1)}\,\mathrm{d}\tilde{y} = \int_0^{\bar{d}} U_1\,\mathrm{d}\eta = 0, \tag{3.28c}$$

where we have employed the product ansatz

$$\tilde{u}_G^{(1)} = g_1(\xi)v U_1(\eta) = \frac{\partial_\xi d}{d}\, U_1(\eta), \tag{3.29}$$

and the separation constant C_1 is obtained from (3.28c).

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The two BVPs (3.27) and (3.28) are solved numerically for U_0, U_1, C_0 and C_1 via the continuation software Auto07P (Doedel 2008). The solution is obtained for a given $\bar{d}$ on a fixed domain spanning $0 \leq \eta \leq \bar{d}$. Based on this, the coupling quantities T_G and $\partial_x P_G$, which appear in the liquid-side model (3.6a), are constructed readily at $O(\underline{\epsilon}^1)$:

$$T_G = -\frac{\bar{d}}{d} \left. \partial_\eta \tilde{u}_G \right|_{\eta=\bar{d}} + O(\underline{\epsilon}^2) = -\frac{\bar{d}}{d} \left\{ \left. \partial_\eta \tilde{u}_G^{(0)} \right|_{\eta=\bar{d}} + \underline{\epsilon} \left. \partial_\eta \tilde{u}_G^{(1)} \right|_{\eta=\bar{d}} \right\} + O(\underline{\epsilon}^2),$$

$$= -\frac{\bar{d}^2}{d^2} \left\{ \left. \partial_\eta U_0 \right|_{\eta=\bar{d}} + \frac{\partial_{x^\star} d^\star}{\bar{d}} \left. \partial_\eta U_1 \right|_{\eta=\bar{d}} \right\} + O(\underline{\epsilon}^2), \tag{3.30a}$$

$$\partial_x P_G = \partial_\xi P_G^{(0)} + \underline{\epsilon}\, \partial_\xi P_G^{(1)} + O(\underline{\epsilon}^2)$$

$$= Re_G \left\{ \frac{\bar{d}^3}{d^3} \left(C_0 + C_1 \frac{\partial_{x^\star} d^\star}{\bar{d}} \right) + \frac{\Pi_L}{\Pi_u^2} \frac{1}{Fr^2} \left(\sin(\phi) + \cos(\phi)\, \partial_{x^\star} d^\star \right) \right\} + O(\underline{\epsilon}^2), \tag{3.30b}$$

where we have used the velocity expansion (3.25a):

$$\tilde{u}_G = \frac{\bar{d}}{d} U_0 + \frac{\partial_{x^\star} d^\star}{d} U_1 + O(\underline{\epsilon}^2). \tag{3.31}$$

Importantly, at fixed $\bar{d}$, T_G and $\partial_x P_G$ in (3.30) depend only on $d = D - h/\Pi_L$, which varies with x and t. By contrast, Samanta (2014) assumed $T_G = $ const and $\partial_x P_G = 0$.

In contrast to the gas-side description of Demekhin (1981) and Tseluiko & Kalliadasis (2011), (3.30) is obtained from a long-wave not small-wave amplitude expansion. Thus it works better when the liquid holdup is larger, whereas the cited models work better when the liquid holdup is small, i.e. $h^\star/\bar{d}^\star \to 0$.

As a result of our frozen-interface assumption ($\Pi_u \gg 1$) expressed via (3.13), one would obtain exactly the same relations for the functions U_0 and U_1 appearing in (3.30) should one apply no-slip and no-penetration conditions at $y^\star = H^\star$ instead of a symmetry condition at $y^\star = D^\star$. This is because the BVPs for U_0 (3.27) and U_1 (3.28) would remain symmetrical in that case. Thus, up to the order of expansion of our WRIBL-LW model, our symmetry condition (3.13b) is valid without loss of generality.

3.3. *Rescaling*

For the remainder of the paper, we rescale streamwise lengths by setting $\epsilon = \underline{\epsilon} = 1$, and we choose

$$\mathcal{L} = \mathcal{L}_G = H^\star, \quad \mathcal{U}_L = \frac{q_{L0}^\star}{H^\star}, \quad \mathcal{U}_G = \frac{q_{G0}^\star}{H^\star}. \tag{3.32a-c}$$

This implies $\Pi_L = 1$, i.e. all lengths are now scaled with the channel height $H^\star$. We recall that $q_{L0}^\star$ and $q_{G0}^\star$ are the primary-flow liquid and gas flow rates per unit width, thus $\mathcal{U}_L$ and $\mathcal{U}_G$ are the superficial velocities. The corresponding Reynolds numbers are

$$Re_L = \frac{q_{L0}^\star}{\nu_L}, \quad Re_G = \frac{q_{G0}^\star}{\nu_G}, \tag{3.33a,b}$$

where $\nu_L = \mu_L/\rho_L$ and $\nu_G = \mu_G/\rho_G$.

At some places, we will rescale quantities with the natural scales

$$\mathcal{L}_\nu = \nu_L^{2/3} g^{-1/3}, \quad \mathcal{U}_\nu = (\nu_L g)^{1/3}, \quad \mathcal{T}_\nu = \frac{\mathcal{L}_\nu}{\mathcal{U}_\nu} = \nu_L^{1/3} g^{-2/3}. \tag{3.34a-c}$$

3.4. *Model computations*

We perform three types of numerical computations based on our WRIBL-LW model (3.6), (3.30): linear stability calculations, nonlinear computations of TWS, and nonlinear computations of spatially evolving falling liquid films.

To obtain the linear stability formulation, we perturb the dependent variables q_L and h around their primary flow values q_{L0} and h_0:

$$q_L = q_{L0} + \check{q}_L(x, t) = q_0 + \hat{q}\exp\{i(kx - \omega t)\}, \qquad (3.35a)$$

$$h = h_0 + \check{h}(x, t) = h_0 + \hat{h}\exp\{i(kx - \omega t)\}, \qquad (3.35b)$$

where the check mark denotes infinitesimal perturbations, ω denotes the angular frequency, and $\hat{q}_L = \hat{h}\omega/k$ follows from (3.6b). Surface waves resulting from the Kapitza instability grow spatially, but a counter-current gas flow can cause the onset of AI. Both phenomena can be captured via a spatial stability formulation (Vellingiri *et al.* 2015). Thus we will usually (but not exclusively) assume $k \in \mathbb{C}$ and $\omega \in \mathbb{R}$, with

$$k = k_r + ik_i, \qquad (3.36)$$

where $k_r = 2\pi/\Lambda$ is the physical wavenumber, and $-k_i$ is the spatial growth rate.

The film surface perturbation (3.35b) translates to the gas-side problem via

$$d = d_0 + \check{d} = d_0 + \hat{d}\exp\{i(kx - \omega t)\}, \quad \hat{d} = -\frac{\hat{h}}{\Pi_L}. \qquad (3.37)$$

Inserting this in (3.30) and then linearizing yields the linear responses of the inter-phase coupling quantities:

$$T_G = T_{G0} + \check{T}_G = T_{G0} + \hat{T}_G\exp\{i(kx - \omega t)\}, \qquad (3.38a)$$

$$P_G = P_{G0} + \check{P}_G = P_{G0} + \hat{P}_G\exp\{i(kx - \omega t)\}, \qquad (3.38b)$$

with

$$T_{G0} = -\partial_\eta U_0|_{d_0}, \quad \hat{T}_G = \frac{\hat{d}}{d_0}\left\{2\,\partial_\eta U_0|_{d_0} + \Pi_L ik\,\partial_\eta U_1|_{d_0}\right\}, \qquad (3.39a,b)$$

$$\partial_x P_{G0} = Re_G\left\{C_0 + \frac{\Pi_L}{\Pi_u^2}\frac{\sin(\phi)}{Fr^2}\right\}, \quad \hat{P}_G = -Re_G\frac{\hat{d}}{ik}\left\{3\frac{C_0}{d_0} - \Pi_L\frac{C_1}{d_0} - \frac{\Pi_L^2}{\Pi_u^2}\frac{\cos(\phi)}{Fr^2}\right\}. \qquad (3.40a,b)$$

Introducing (3.35) and (3.38) into (3.6), and linearizing once again, yields the dispersion relation for the spatial stability problem:

$$
\begin{aligned}
DR = &-i\omega^2 + ik\omega\frac{17}{7}\frac{q_{L0}}{h_0} - ik^2\frac{9}{7}\frac{q_{L0}^2}{h_0^2} + \frac{5}{6}Fr^{-2}\left\{ik^2\cos(\phi)h_0 - k\sin(\phi)\right\}\\
&-i^3k^4\frac{5}{6}We\,h_0 + \frac{5}{2}\frac{1}{Re_L}\frac{1}{h_0^2}\left\{\omega - 2k\frac{q_{L0}}{h_0}\right\} + i^2k^3\frac{6}{Re_L}\frac{q_{L0}}{h_0} - i^2k^2\omega\frac{9}{2}\frac{1}{Re_L}\\
&+ \frac{\Pi_\mu\Pi_u}{\Pi_L}\left\{T_{G0}\left[ik\omega\frac{19}{336}h_0 - i^2k^3\frac{1}{6}\frac{1}{Re_L}h_0 + ik^2\frac{5}{112}q_{L0}\right] + k\frac{5}{4}\frac{1}{Re_L}\frac{1}{\Pi_L}\frac{\hat{T}_G}{\hat{d}}\right\}\\
&+ ik^2\frac{19}{672}\frac{\Pi_\mu^2\Pi_u^2}{\Pi_L^2}h_0^2 T_{G0}^2 + k\frac{5}{6}\frac{\Pi_\rho\Pi_u^2}{\Pi_L}\frac{1}{Re_G}\left\{\partial_x P_{G0} - \frac{h_0}{\Pi_L}ik\frac{\hat{P}_G}{\hat{d}}\right\} = 0, \qquad (3.41)
\end{aligned}
$$

where $\hat{d}$ will cancel, due to $\hat{T}_G \propto \hat{d}$ and $\hat{P}_G \propto \hat{d}$, according to (3.39*a,b*) and (3.40*a,b*).

To compute nonlinear TWS, we recast (3.6*a*) into an ordinary differential equation in terms of the wave coordinate $\gamma = x - ct$:

$$h''' = NL(h, h', h''; \bar{h}, c, q_L^{MF}), \tag{3.42a}$$

$$q_L^{MF} = q_L - hc = \bar{q}_L - \bar{h}c, \tag{3.42b}$$

where primes denote differentiation with respect to γ, bars signify averaging over the wavelength Λ in terms of γ, c denotes the nonlinear wave speed, and the superscript *MF* refers to the moving reference frame. Further, (3.42*b*) is the integral form of (3.6*b*), which we have used to eliminate q from (3.42*a*). The system is closed through periodicity boundary conditions

$$\left. h^{(j)} \right|_{\gamma=0} = \left. h^{(j)} \right|_{\gamma=\Lambda}, \quad j = 0, 1, 2, \tag{3.42c}$$

and it is solved for a fixed value of $\bar{q}_L$, enforced through the integral condition

$$\Lambda^{-1} \int_0^\Lambda q_L \, \mathrm{d}\gamma = \bar{q}_L. \tag{3.43}$$

We do this numerically via the continuation software Auto07P, after recasting (3.42*a*) into a dynamical system. First, we continue the fixed-point solutions ($h' = h'' = h''' = 0$) of (3.42*a*) at $q_L = q_{L0}$ and $h = h_0$ in terms of c, until reaching the Hopf bifurcation of the Kapitza instability. Then, starting from this point, periodic solutions are continued in terms of a selected control parameter, e.g. the liquid Reynolds number Re_L. The BVPs associated with the turbulent gas flow, (3.27) and (3.28), are solved simultaneously. In addition, we solve the linear dispersion relation (3.41) for the spatially most-amplified angular frequency ω_{max}:

$$DR(\omega_{max}, k) = 0, \quad \partial_\omega k_i|_{\omega=\omega_{max}} = 0. \tag{3.44a,b}$$

By imposing $f = f_{max} = \omega_{max}/2/\pi$, TWS most likely to emerge in an experiment can be tracked.

To compute the spatial evolution of nonlinear Kapitza waves, we solve (3.6*a*) and (3.6*b*) numerically on an open domain with inlet/outlet conditions. Details of the numerical scheme are given in Appendix F3 of Kalliadasis *et al.* (2012). In particular, we apply a second-order central-differences spatial discretization and a quasi-linearized Crank–Nicolson time integration. At the liquid outlet, we impose the soft boundary conditions of Richard, Ruyer-Quil & Vila (2016). At the liquid inlet, we prescribe explicitly h and q at the first two grid points ($i_x = 1, 2$), based on the primary flow:

$$h|_{i_x=1} = h|_{i_x=2} = h_0, \tag{3.45a}$$

$$q_L|_{i_x=1} = q_L|_{i_x=2} = q_{L0} \left[1 + F(t) \right], \tag{3.45b}$$

where the function $F(t)$ allows us to apply a tailored inlet forcing,

$$F(t) = \varepsilon_1 \sin(2\pi f t) + \varepsilon_2 \sum_{k=1}^N \sin(2\pi k \, \Delta f \, t + \varphi_{rand}), \quad \Delta f = 2f_c/N. \tag{3.46}$$

The first RHS term in (3.46) constitutes a harmonic perturbation of frequency f, and the second RHS term mimics white noise through a series of $N = 1000$ Fourier modes that are shifted by a random phase shift $\varphi_{rand} = \varphi_{rand}(k) \in [0, 2\pi]$ and span a frequency range of twice the linear cut-off frequency f_c (Chang, Demekhin & Kalaidin 1996a). When $\varepsilon_1 = 0$, the inlet perturbation consists of only white noise. This setting will be used to simulate the natural, noise-driven evolution of a wavy film as it would occur in a real system. In other computations, we will apply additional coherent inlet forcing by setting $\varepsilon_1 > 0$.

4. Linear stability analysis based on full RANS equations

The long-wave asymptotic expansion underlying the gas-side representation (3.30) in our WRIBL-LW model is truncated at order ϵ^1, whereas our liquid-side representation (3.6) is consistent up to order ϵ^2. To validate linear stability predictions based on this model, and to go beyond its limitations, we introduce two linear stability formulations that are based on the full RANS equations in the gas (4.3). The first formulation (§ 4.1) relies on the WRIBL model in the liquid (3.6), and we designate this approach as WRIBL-OS, where OS refers to the Orr–Sommerfeld equation. The second formulation (§ 4.2) relies on the full Navier–Stokes equations in the liquid (4.1*a,b*), and we designate that approach as OS-OS.

4.1. *The WRIBL-OS approach*

In our WRIBL-OS approach, the linear response of the liquid film is governed by the dispersion relation (3.41), but the perturbation amplitudes $\hat{T}_G$ and $\hat{P}_G$ are now obtained from the full (steady) RANS equations (3.8). For this, we recast (3.8) in terms of the curvilinear coordinates (3.15*a,b*) and introduce the gas stream function Ψ,

$$\tilde{u} = \frac{\bar{d}}{d} \partial_\eta \Psi, \quad \tilde{v} = -\partial_\xi \Psi, \tag{4.1a,b}$$

which we perturb, along with p_G and d, around the primary flow (subscript 0):

$$\Psi = \Psi_0 + \check{\Psi} = \Psi_0 + \psi(\eta) \exp\{i(k\xi - \omega t)\}, \tag{4.2a}$$

$$p_G = p_{G0} + \check{p}_G = p_{G0} + \hat{p}_G(\eta) \exp\{i(k\xi - \omega t)\}, \tag{4.2b}$$

$$d = d_0 + \check{d} = d_0 + \hat{d} \exp\{i(k\xi - \omega t)\}, \tag{4.2c}$$

where $k = k_r \in \mathbb{R}$, and the time dependence is included formally to account for the unsteadiness of the liquid film. Upon linearization and subtraction of the primary flow, we obtain the linearized curvilinear RANS equations OS_ξ in the ξ direction,

$$Re_G \, ik \left\{ \psi' \Psi_0' - \frac{\hat{d}}{d_0} \Psi_0'^2 - \psi \Psi_0'' \right\} + Re_G \, \tilde{l}_t \, |\Psi_0''| \left\{ \tilde{l}_t' \left[k^2 \left(-2\psi + 3 \frac{\hat{d}}{d_0} \eta \Psi_0' \right) \right. \right.$$

$$\left. - 4\psi'' + 6 \frac{\hat{d}}{d_0} \Psi_0'' \right] + \tilde{l}_t \left[-2\psi''' + 6 \frac{\hat{d}}{d_0} \Psi_0''' - 2 \frac{\Psi_0'''}{\Psi_0''} \psi'' \right.$$

$$\left. \left. + k^2 \left(-\psi' + \frac{3}{2} \frac{\hat{d}}{d_0} \Psi_0' + \frac{3}{2} \frac{\hat{d}}{d_0} \eta \Psi_0'' - \frac{\Psi_0'''}{\Psi_0''} \psi + \frac{3}{2} \frac{\hat{d}}{d_0} \eta \frac{\Psi_0''' \Psi_0'}{\Psi_0''} \right) \right] \right\}$$

$$= -i \, k\hat{p}_G + \psi''' - 3 \frac{\hat{d}}{d_0} \Psi_0''' - k^2 \left\{ \psi' - \frac{\hat{d}}{d_0} \Psi_0' - \frac{\hat{d}}{d_0} \eta \Psi_0'' \right\}, \tag{4.3a}$$

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and OS_η in the η direction,

$$
Re_G k^2 \left\{ \psi \Psi_0' - \frac{\hat{d}}{d_0} \eta \Psi_0'^2 \right\} + Re_G \tilde{l}_t |\Psi_0''| \, \mathrm{i}k \left\{ 2\tilde{l}_t' \frac{\hat{d}}{d_0} \eta \Psi_0'' + \tilde{l}_t \left[-2\psi'' + 2 \frac{\hat{d}}{d_0} \Psi_0'' \right. \right.
$$

$$
\left. \left. + 2\eta \frac{\hat{d}}{d_0} \Psi_0''' + k^2 \left(-\psi + \frac{3}{2} \frac{\hat{d}}{d_0} \eta \Psi_0' \right) \right] \right\} = -\hat{p}_G' - \mathrm{i}k^3 \left\{ -\psi + \frac{\hat{d}}{d_0} \eta \Psi_0' \right\}
$$

$$
- \mathrm{i}k \left\{ \psi'' - 2 \frac{\hat{d}}{d_0} \Psi_0'' - \frac{\hat{d}}{d_0} \eta \Psi_0''' \right\}, \tag{4.3b}
$$

where primes denote differentiation with respect to η. The pressure perturbation amplitude $\hat{p}_G$ can be removed from (4.3a) and (4.3b) via the final gas-side Orr–Sommerfeld equation

$$
\partial_\eta OS_\xi - \mathrm{i}k \, OS_\eta, \tag{4.3c}
$$

involving only ψ and its derivatives. The problem is closed with the boundary conditions (3.24a,b):

$$
\psi''|_{\eta=0} = 0, \quad \psi|_{\eta=0} = 0, \quad \psi'|_{\eta=d_0} = 0, \quad \psi|_{\eta=d_0} = 0. \tag{4.3d}
$$

We solve (4.3) numerically for ψ with the continuation software Auto07P, starting from the analytically tractable laminar long-wave limit ($\tilde{l}_t = k = 0$). The amplitudes of the linear perturbations of the inter-phase coupling quantities,

$$
\check{T}_G = \hat{T}_G \exp\{\mathrm{i}(k\xi - \omega t)\}, \quad \check{P}_G = \hat{P}_G \exp\{\mathrm{i}(k\xi - \omega t)\}, \tag{4.4a,b}
$$

can be obtained readily by recasting (3.14) in curvilinear coordinates, inserting (4.2), and linearizing:

$$
\hat{T}_G = -\psi''|_{\eta=d_0} + 2 \frac{\hat{d}}{d_0} \Psi_0''|_{\eta=d_0}, \tag{4.5a}
$$

$$
\mathrm{i}k\hat{P}_G = \left\{ \psi'''|_{\eta=d_0} - 3 \frac{\hat{d}}{d_0} \Psi_0'''|_{\eta=d_0} + k^2 \hat{d} \, \Psi_0''|_{\eta=d_0} \right\}. \tag{4.5b}
$$

We point out that $\psi \propto \hat{d}$, thus $\hat{d}$ once again cancels from (3.41), as it should. Also, the spatial variations prescribed in (3.37) and (4.2) are equivalent in the linear limit $\hat{d} \to 0$, where the curvilinear coordinates collapse with the Cartesian ones. Thus $\partial_x \check{P}_G = \partial_\xi \check{P}_G$.

Figures 5(a) and 5(b) represent spatial linear stability predictions obtained with our WRIBL-OS approach, based on (3.41) and (4.3c), for parameters according to the experiments of Kofman *et al.* (2017) in an $H^\star = 19$ mm channel. According to figure 5(a), the maximum of the growth rate dispersion curve increases with increasing counter-current gas flow rate, until forming a pinch point at $Re_G = -8490$, where the AI limit is reached (curve with crosses).

This destabilization of the liquid film is caused by the inter-phase pressure coupling, as can be deduced by confronting figure 5(a) with figure 5(b), where we have represented corresponding growth rate curves in the limit $\Pi_\rho = 0$. In that case, the gas effect enters only via T_G, and we observe a stabilization of the liquid film at large $|Re_G|$ (compare crosses and pentagons). Models that do not account for the gas pressure P_G – e.g. the weak-confinement first-order WRIBL model of Tseluiko & Kalliadasis (2011) – may thus
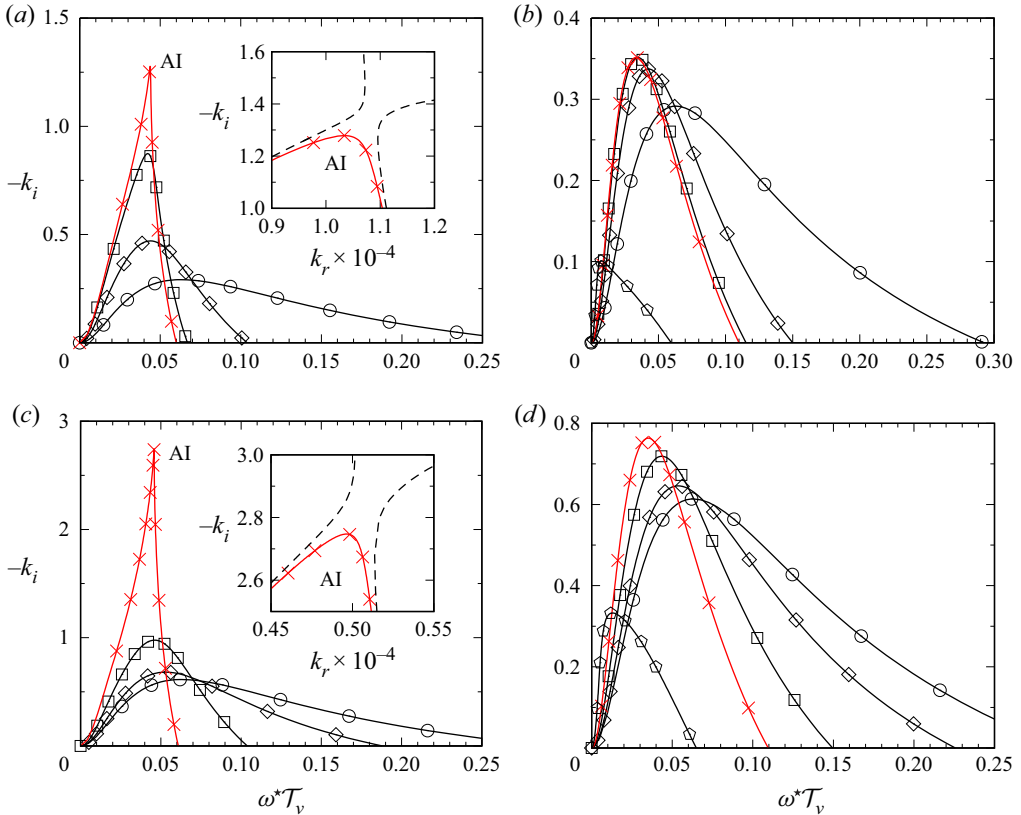
Figure 5. Spatial linear stability calculations with the WRIBL-OS approach. Parameters based on experiments of Kofman *et al.* (2017): $Ka = 3174$ (water and air I in table 1), $\phi = 5°$, $Re_L = 45$. Circles: passive-gas limit, $\Pi_\rho = \Pi_\mu = 0$ in (3.41). Values of $|Re_G|$ increase in the order diamonds, squares, crosses, pentagons. (*a,c*) Full model, (*b,d*) $\Pi_\rho = 0$ in (3.41), with (*a,b*) $H^\star = 19$ mm, (*c,d*) $H^\star = 40$ mm. Here: (*a*) $Re_G = [-6234, -8145, -8490 \text{ (AI)}]$, dashed line $Re_G = -8500$; (*b*) $Re_G = [-6234, -8145, -8490, -15\,000]$; (*c*) $Re_G = [-8145, -15\,000, -20\,430 \text{ (AI limit)}]$, dashed line $Re_G = -20\,440$; (*d*) $Re_G = [-8145, -15\,000, -20\,430, -35\,000]$. We have rescaled ω with $\mathcal{T}_v = 2.207 \times 10^{-3}$ s (see (3.34*a–c*)).

Fluids	ρ (kg m^{-3})	ν (m^2 s^{-1})	σ (N m^{-1})	Ka	T (°C)	figures
Water	998.3	1.03×10^{-6}	0.071	3174	19	5, 6, 8, 9, 11–13,
Air I	1.209	14.9×10^{-6}	—	—	19	18–21, 24–27
DMSO(83 %)–water	1098.3	2.85×10^{-6}	0.0484	509.5	25	22, 23
Glycerol(54 %)–water	1000	2.3×10^{-6}	0.0626	963	22	7
Air II	1.185	15.6×10^{-6}	—	—	25	7, 22, 23
Methanol	791	0.73×10^{-6}	0.022	1988	25	28, 29(*a*)
Helium	0.165	12.1×10^{-5}	—	—	25	

Table 1. Fluid combinations used in our computations. The Kapitza number is defined as $Ka = \sigma/(\rho_L g^{1/3} \nu_L^{4/3})$, where σ, ρ_L and ν_L denote the surface tension, density and kinematic viscosity of the liquid, and g designates the gravitational acceleration.

give qualitatively incorrect linear stability predictions for the current configuration. The same observation also holds at weaker confinement, as shown by confronting figures 5(*c*) and 5(*d*), where we have chosen $H^\star = 40$ mm.

As a result of our frozen-interface assumption ($\Pi_u \gg 1$) expressed through the last two equations in (4.3*d*), one would obtain exactly the same linear stability problem (4.3) should one apply no-slip and no-penetration conditions at $y^\star = H^\star$ instead of a symmetry condition at $y^\star = D^\star$. This is because the primary gas flow would remain symmetrical about the centreline of the gas layer. Thus for all linear stability calculations based on the gas-side OS BVP (4.3), our symmetry condition (4.3*d*) is valid analytically.

4.2. *The OS-OS approach*

Linear stability calculations based on our WRIBL-LW and WRIBL-OS approaches may be limited to long-wave instability modes. To capture short-wave instability modes (§ 6.2), we introduce a stability formulation based on the full Navier–Stokes equations (4.1*a*,*b*) in the liquid and the full RANS equations (4.3) in the gas.

The gas-side linear response is governed by the same equations as in the WRIBL-OS approach, i.e. (4.3) and (4.5), and we focus here on deriving the equations governing the liquid-side linear response. For this, we perturb the film thickness as

$$h = h_0 + \check{h} = h_0 + \hat{h} \exp\{ik(x - ct)\}, \tag{4.6}$$

assuming a temporal stability formulation this time, i.e. $k \in \mathbb{R}$ and $c = c_r + ic_i \in \mathbb{C}$, where c_r denotes the wave speed, and kc_i is the temporal growth rate.

We start with the full governing equations (4.1*a*,*b*). Considering these in the limit of fully developed flow with $h = h_0$ yields the liquid primary flow

$$u_{L0} = \frac{1}{2} Re_L \left\{ \Pi_\rho\, \partial_x p_{G0} - \frac{\sin(\phi)}{Fr^2} \right\} (y^2 - 2yh_0) + \frac{\Pi_\mu \Pi_u}{\Pi_L} T_{G0} y, \tag{4.7a}$$

$$\partial_y p_{L0} = -\frac{\cos(\phi)}{Fr^2}. \tag{4.7b}$$

Next, we introduce the liquid stream function Φ,

$$u_L = \partial_y \Phi, \quad v_L = -\partial_x \Phi, \tag{4.8a,b}$$

which we perturb around the primary flow:

$$\Phi = \Phi_0 + \check{\Phi} = \Phi_0 + \phi(y) \exp\{ik(x - ct)\}. \tag{4.9}$$

Substituting (4.8*a*,*b*) and (4.9) into (4.1*a*,*b*), linearizing with respect to $\check{\Phi}$, subtracting the primary flow, and applying standard manipulations, we obtain the liquid-side Orr–Sommerfeld equation

$$\phi^{iv} - 2k^2\phi'' + k^4\phi = ik\, Re_L \left\{ (c - u_{L0}) \left(k^2\phi - \phi'' \right) - \phi u_{L0}'' \right\}, \tag{4.10a}$$

the boundary conditions at $y = 0$

$$\phi'' = \phi = 0, \tag{4.10b}$$

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and the inter-phase coupling conditions at $y = h_0$,

$$\phi u''_{L0} + \tilde{c}\left\{\phi'' + k^2\phi\right\} = \Pi_\mu \Pi_u \tilde{c}\underline{\hat{T}}_G, \tag{4.10c}$$

$$-\frac{1}{Re_L}\left\{2k^2\phi u'_{L0} + \tilde{c}\left[3k^2\phi' - \phi'''\right]\right\} - ik\tilde{c}\left\{-\tilde{c}\phi' - \phi u_{L0}\right\}$$

$$+ ik\phi p'_{L0} = ik\frac{\Pi_\rho \Pi_u^2}{Re_G}\tilde{c}\underline{\hat{P}}_G + ik^3 \, We\,\phi, \tag{4.10d}$$

where primes denote differentiation with respect to y, and we have introduced $\tilde{c} = c - u_{L0}|_{y=h_0}$. The nonlinearity involving $\tilde{c}$ in (4.10d) can be eliminated via (4.10c). Further, $\underline{\hat{T}}_G$ and $\underline{\hat{P}}_G$ are rescaled versions of the amplitudes in (4.5):

$$\underline{\hat{T}}_G = -\hat{h}\frac{\hat{T}_G}{\hat{d}}, \quad \underline{\hat{P}}_G = \hat{h}\frac{\hat{P}_G}{\hat{d}}, \tag{4.11a,b}$$

where $\hat{d}$ is an arbitrary deflection amplitude used in the solution of the gas-side problem (4.3), and $\hat{h}$ is linked directly to ϕ via the kinematic condition (3.1f),

$$\hat{h} = \frac{\phi|_{y=h_0}}{\tilde{c}}. \tag{4.12}$$

The rescaling in (4.11a,b) allows us to solve the gas- and liquid-side problems sequentially.

We solve the two-phase BVP comprising (4.3) and (4.10) by expanding the stream function amplitudes ϕ and ψ in terms of Chebyshev polynomials (Boomkamp *et al.* 1997; Barmak *et al.* 2016b):

$$\phi(\zeta) = c_{L0} + \sum_{j=1}^{Np} c_{lj} T_j(\zeta), \quad \psi(\zeta) = c_{G0} + \sum_{j=1}^{Np} c_{gj} T_j(\zeta), \tag{4.13a,b}$$

where T_j are jth-degree Chebyshev polynomials of the first kind, defined on the interval $\zeta \in [-1, 1]$, with

$$\zeta = 2\frac{y}{h_0} - 1 \quad \text{for } 0 \le y \le h_0, \tag{4.14}$$

$$\zeta = 1 - 2\frac{\eta}{d_0} \quad \text{for } 0 \le \eta \le d_0. \tag{4.15}$$

Thus there are $2(N_p + 1)$ unknown coefficients c_{kj}, which are fixed by the eight conditions in (4.10b), (4.10c), (4.10d) and (4.3d), and $2(N_p + 1) - 8$ additional constraints obtained by evaluating the ordinary differential equations (4.10a) and (4.3c) at the inner collocation points $\zeta_2, \ldots, \zeta_{N_p-2}$, defined according to

$$\zeta_i = \cos\left[\frac{i\pi}{N_p}\right] \quad \text{for all } i \in [0, N_p]. \tag{4.16}$$

Instead of solving for the coefficients c_{kj}, we solve directly for the $2(N_p + 2)$ unknowns $\phi(\zeta_i)$ and $\psi(\zeta_i)$, arranged into the solution vectors

$$\boldsymbol{\phi} = \left[\phi(\zeta_0), \ldots, \phi(\zeta_{N_p})\right]^{\mathrm{T}}, \quad \boldsymbol{\psi} = \left[\psi(\zeta_0), \ldots, \psi(\zeta_{N_p})\right]^{\mathrm{T}}. \tag{4.17a,b}$$
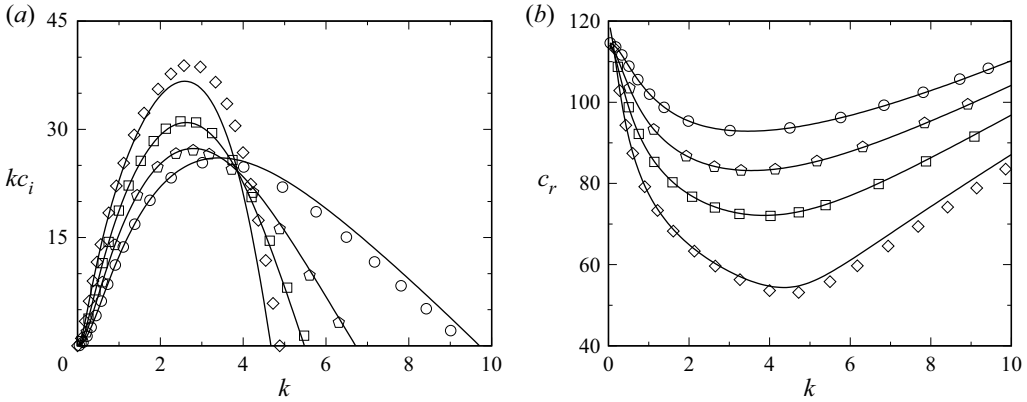
Figure 6. Temporal stability predictions from the OS-OS (solid curves) and WRIBL-OS (open symbols) approaches. Parameters similar to those in figure 5(*a*): $Ka = 3174$, $H^\star = 19$ mm, $\phi = 5°$, $Re_L = 32.7$. Circles indicate passive-gas limit ($\Pi_\rho = \Pi_\mu = 0$ in (3.41)); pentagons indicate $Re_G = -4123$; squares indicate $Re_G = -6173$; diamonds indicate $Re_G = -8220$. (*a*) Growth rate; (*b*) wave speed.

Then, by making use of the Chebyshev differentiation matrix $\boldsymbol{D}$ (Trefethen 2000),

$$\left[\phi^{(i)}(\zeta_0), \dots, \phi^{(i)}(\zeta_{N_p}) \right]^{\mathrm{T}} = \boldsymbol{D}^i \left[\phi(\zeta_0), \dots, \phi(\zeta_{N_p}) \right]^{\mathrm{T}}, \quad (4.18)$$

$$\left[\psi^{(i)}(\zeta_0), \dots, \psi^{(i)}(\zeta_{N_p}) \right]^{\mathrm{T}} = \boldsymbol{D}^i \left[\psi(\zeta_0), \dots, \psi(\zeta_{N_p}) \right]^{\mathrm{T}}, \quad (4.19)$$

where $i = 1, 2, 3, 4$, and (*i*) indicates the order of differentiation with respect to ζ, (4.10) is cast into a generalized eigenvalue problem in matrix form,

$$\underline{\boldsymbol{A}}\boldsymbol{\phi} = \tilde{c}\underline{\boldsymbol{B}}\boldsymbol{\phi}, \quad (4.20)$$

and (4.3) is cast into a linear system of equations,

$$\underline{\boldsymbol{C}}\boldsymbol{\psi} = \boldsymbol{b}, \quad (4.21)$$

introducing the coefficient matrices $\underline{\boldsymbol{A}}$, $\underline{\boldsymbol{B}}$ and $\underline{\boldsymbol{C}}$, and the inhomogeneity $\boldsymbol{b}$. With the help of MATLAB (2015), we first solve (4.21) for $\boldsymbol{\psi}$ by numerical inversion via the / operator and then (4.20) for the eigenvalues $\tilde{c}$ and eigenvectors $\boldsymbol{\phi}$ via the eig function.

Using this approach, the full set of eigenmodes is computed at once. Thus short-wave instability modes, i.e. modes with $c_i \neq 0$ at $k = 0$, can be obtained readily. Once a mode has been identified at a given wavenumber k, it can be tracked by advancing k, using the function eigs, which searches for eigenvalues in the vicinity of a previous solution.

In Appendix A, we validate our OS-OS approach, (4.20) and (4.21), versus Vellingiri *et al.* (2015) and Schmidt *et al.* (2016). Figure 6 confronts temporal linear stability predictions from this approach (solid lines) with predictions from our WRIBL-OS approach (symbols), for parameters similar those in figure 5(*a*). Agreement is good up to $|Re_G| \sim 8000$. Thus our liquid-side WRIBL description suffices to predict the gas effect on the long-wave Kapitza instability.

5. Model validation

To evaluate the linear and nonlinear predictions of our WRIBL-LW model, we confront these with stability predictions from Vellingiri *et al.* (2015) and Samanta (2014), our

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own stability calculations using the WRIBL-OS approach, and experiments from Kofman (2014).

By design, our WRIBL-LW model predicts exactly the neutral linear stability bound of the long-wave Kapitza instability. We consider a temporal linear stability formulation and expand the complex wave speed $c = \omega/k$ in terms of $k \in \mathbb{R}$ around the limit $k = 0$:

$$c = c_0 + k c_1 + O(k^2). \tag{5.1}$$

Inserting this into (3.41), and truncating order by order, we obtain c_0 and c_1:

$$c_0 = 2\, u_{L0}|_{h_0} + \Pi_\mu \Pi_u T_{G0} \left\{ -h_0 + \frac{h_0^2}{d_0} \right\} + Re_L\, \Pi_\rho \Pi_u^2 \frac{h_0^3}{d_0} \left\{ -\frac{\partial_x P_{G0}}{Re_G} + \Pi_u^{-4} \frac{\sin(\phi)}{Fr^2} \right\}, \tag{5.2a}$$

$$c_1 = i\mathcal{R}, \tag{5.2b}$$

where $\mathcal{R} \in \mathbb{R}$ is written out in Appendix B, and the primary flow yields

$$u_{L0}|_{h_0} = \frac{1}{2} \frac{Re_L}{Fr^2} \sin(\phi) h_0^2 + \Pi_\mu \Pi_u T_{G0} h_0 - \frac{1}{2} \Pi_\rho \Pi_u^2 \frac{Re_L}{Re_G} \partial_x P_{G0} h_0^2. \tag{5.3}$$

Thus the asymptotic wave speed is given by c_0, the (temporal) growth rate by $k c_1$, and the neutral stability bound by $\mathcal{R} = 0$.

In the zero-confinement limit $h_0/d_0 \to 0$, c_0 (5.2a) and c_1 (5.2b) should collapse with the expressions in (B4b) and (B7b) of Vellingiri *et al.* (2015). Applying this limit to (5.1) and rescaling appropriately, we obtain

$$\underline{c} = \underline{c}_0 + \underline{k} \underline{c}_1 + O(\underline{k}^2) = 2 + \underline{T}_{G0} + i\underline{k} \left\{ \frac{4}{15} \underline{Re}_L \left(2 + \underline{T}_{G0}\right) - \frac{2}{3} \cot(\phi) \left[1 - \Pi_\rho\right] \right.$$

$$\left. + \frac{1}{3} \Pi_\rho \frac{\underline{Re}_L}{\Pi_\mu^2} \frac{\underline{C}_1}{\underline{d}_0} + \frac{1}{2} \Pi_\mu \frac{1}{\underline{d}_0} \left. \partial_{\underline{\eta}} \underline{U}_1 \right|_{\underline{d}_0} \right\} + O(\underline{k}^2), \tag{5.4}$$

where the underline refers to the scaling of Vellingiri *et al.* (2015), i.e. $\underline{\mathcal{L}} = h_0^\star$ and $\underline{\mathcal{U}} = \underline{\mathcal{U}}_G = \frac{1}{2} \nu_L^{-1} g \sin(\phi) h_0^{\star 2}$. Our result matches that in Vellingiri *et al.* (2015), except for three additional terms: the gas-density correction in the $\cot(\phi)$ term, and the last two terms within the accolades, which stem from the linear perturbations of P_G and T_G. In the laminar limit,

$$\underline{C}_1 = \frac{6}{35} \underline{d}_0^2 \underline{T}_{G0}^2, \quad \left. \partial_{\underline{\eta}} \underline{U}_1 \right|_{\underline{d}_0} = \frac{4}{105} \frac{\Pi_\rho\, \underline{Re}_L}{\Pi_\mu^3} \underline{d}_0^3 \underline{T}_{G0}^2, \tag{5.5a,b}$$

thus these terms do not necessarily vanish for $1/\underline{d}_0 \to 0$. Thus the gas pressure P_G can affect stability even under weak confinement, in line with observations in figures 5(c) and 5(d).

Figure 7 compares spatial linear stability predictions of our WRIBL-LW model (symbols) with calculations using the WRIBL-OS approach (solid lines), for parameters based on figure 3 in Samanta (2014), which are inspired by the experiments of Liu & Gollub (1994) in a water–glycerol film. We fix the channel height at $H^\star = 15\,\mathrm{mm}$, and apply a co-current turbulent gas flow with $Re_G = 2000$. Figure 7(a) represents dispersion curves of the linear wave speed $c_r = k_r/\omega$ around the long-wave limit. We see that the two data sets converge as $k \to 0$. Further, our WRIBL model captures accurately the long-wave
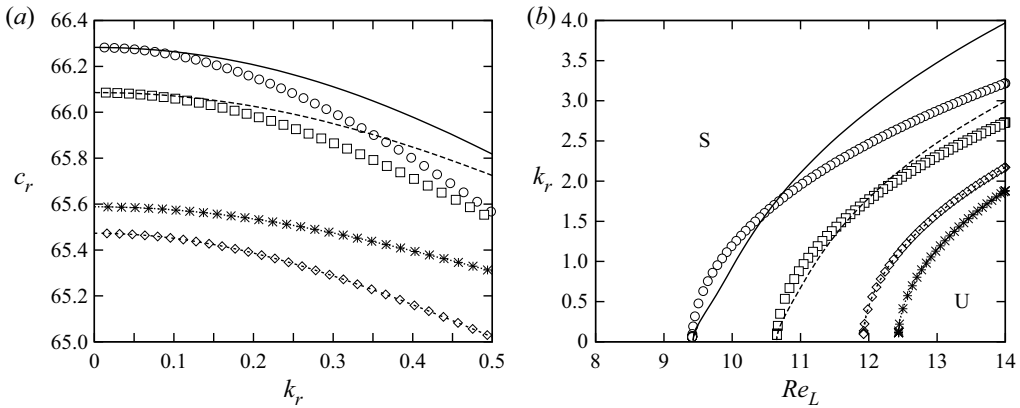
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Figure 7. Spatial linear stability predictions obtained from WRIBL-LW (symbols) and WRIBL-OS (lines) calculations. Inclined falling liquid film sheared by a co-current gas based on parameters in Samanta (2014): $Ka = 963$ (glycerol–water and air II in table 1), $\phi = 4°$, $H^\star = 15$ mm, $Re_G = 2000$. S/U indicate stable/unstable regions. Circles indicate full formulation; squares indicate $\Pi_\rho = 0$ in (3.41); diamonds indicate $T_G = T_{G0}$, $\Pi_\rho = 0$; crosses indicate $\Pi_\mu = \Pi_\rho = 0$. (*a*) Wave speed $c_r = \omega/k_r$ around the long-wave limit $k_r \to 0$; (*b*) neutral stability bound, $k_i = 0$.

instability threshold, as evidenced by the neutral stability bounds plotted in figure 7(*b*). Comparing the circles (full model) with the diamonds (passive-gas limit $\Pi_\rho = \Pi_\mu = 0$), we see that the gas effect is destabilizing, and this is maintained in the limit $\Pi_\rho = 0$ (squares). By contrast, assuming $T_G = $ const and $\Pi_\rho = 0$ (crosses), according to the model of Samanta (2014), results in a qualitatively incorrect prediction of gas-induced stabilization.

We now turn to the experimental conditions of Kofman (2014), who considered a falling liquid film sheared by a turbulent counter-current gas flow. Figure 8 confronts linear spatial growth rate dispersion curves from our WRIBL-LW model (figures 8*a*,*c*) with calculations based on our WRIBL-OS approach (figures 8*b*,*d*). Comparing figures 8(*a*) and 8(*b*), we see that our WRIBL-LW model predicts the gas effect on the maximum growth rate $\{-k_i\}_{max}$ and on the associated angular frequency $\{\omega\}_{max}$ reasonably well. And the AI limit is predicted with precision 10 %, i.e. $Re_G^{AI} = -9157$ from WRIBL-LW versus $Re_G^{AI} = -8220$ from WRIBL-OS. Figures 8(*c*) and 8(*d*) represent corresponding stability calculations in the limit $\Pi_\rho = 0$. Versus figures 8(*a*) and 8(*c*), we observe a qualitative change in the gas effect from destabilizing to stabilizing (similar to figure 5), and our WRIBL-LW model captures this feature accurately. In contrast to Tseluiko & Kalliadasis (2011), our WRIBL-LW model can thus be applied to confinement levels, where the gas pressure plays a role.

On the downside, our WRIBL-LW model cannot reproduce the strong gas-induced reduction of the cut-off frequency predicted by the WRIBL-OS calculation in figure 8(*b*). This is due to truncating our asymptotic gas-side description (§ 4.2) at $O(\underline{\epsilon}^1)$. However, it is almost inconsequential for the prediction of nonlinear Kapitza waves. Figure 9 compares film thickness time traces at a fixed streamwise position *x*, as obtained from open-domain (dashed black) and TWS (solid green) computations with our WRIBL-LW model, with experimental data (red open circles) from Kofman (2014). In these experiments, the counter-current gas flow rate was increased up to $|Re_G| \sim 7000$. Our WRIBL-LW model accurately captures the gas effect on both the wave height and the number of precursory capillary ripples. The wavenumber *k* of precursory ripples is several tenfold greater than
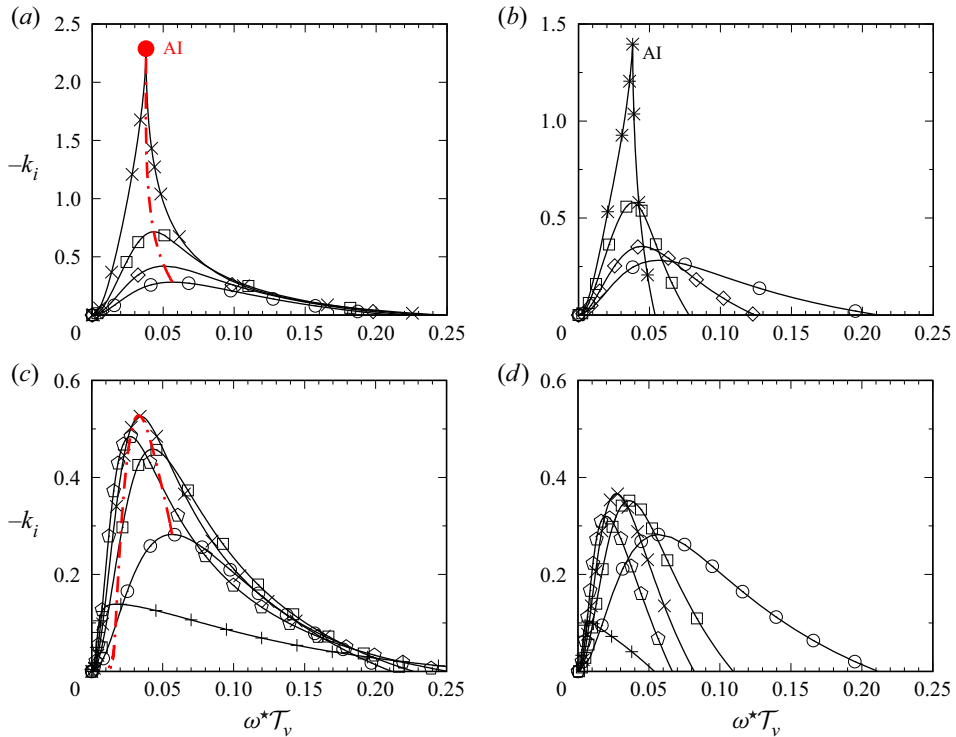
Figure 8. Spatial linear stability predictions from (*a*,*c*) WRIBL-LW and (*b*,*d*) WRIBL-OS approaches. Parameters according to experiments of Kofman (2014): $Ka = 3174$ (water and air I in table 1), $H^\star = 19$ mm, $\phi = 5°$, $Re_L = 32.7$. Open circles indicate passive-gas limit, $\Pi_\rho = \Pi_\mu = 0$ in (3.41). Values of $|Re_G|$ increase in the order diamonds, squares, crosses/asterisks, pentagons, pluses. (*a*,*b*) Full model; (*c*,*d*) $\Pi_\rho = 0$ in (3.41). Here: (*a*) $Re_G = [-4123, -6713, -9157]$; (*b*) $Re_G = [-4123, -6713, -8220]$; (*c*) $Re_G = [-6713, -9100, -11\,000, -15\,000]$; (*d*) $Re_G = [-6713, -9100, -11\,000, -15\,000]$. Red dot-dashed curves track growth rate maximum $\{-k_i\}_{max}$. We have rescaled ω with $\mathcal{T}_v = 2.207 \times 10^{-3}$ s (see (3.34*a*–*c*)).

the cut-off wavenumber k_c of the Kapitza instability (Dietze 2016; Zhou & Prosperetti 2020). As a result, over-prediction of the linear cut-off (figure 8*a*) does not translate to a significant nonlinear error (figure 9).

6. Results

Figure 10 shows top-view snapshots of one of our experiments, where we have successively increased the counter-current gas flow rate from the second snapshot onwards. Guided by this experiment, using the different linear stability calculations as well as nonlinear computations with our WRIBL-LW model, we wish to understand how the waviness of the falling liquid film is altered under the effect of the gas flow. In particular, we are interested in the transition from a regular train of long waves (first snapshot), via an increasingly disordered wave pattern (e.g. tenth snapshot), until the occurrence of upward-travelling short ripples, which lead to a breakdown of our experiment (last snapshot).

6.1. *Gas effect on Kapitza waves*

This subsection is concerned with the linear (§ 6.1.1) and nonlinear (§§ 6.1.2 and 6.1.3) gas effects on the long-wave Kapitza instability. Waves resulting from this instability are

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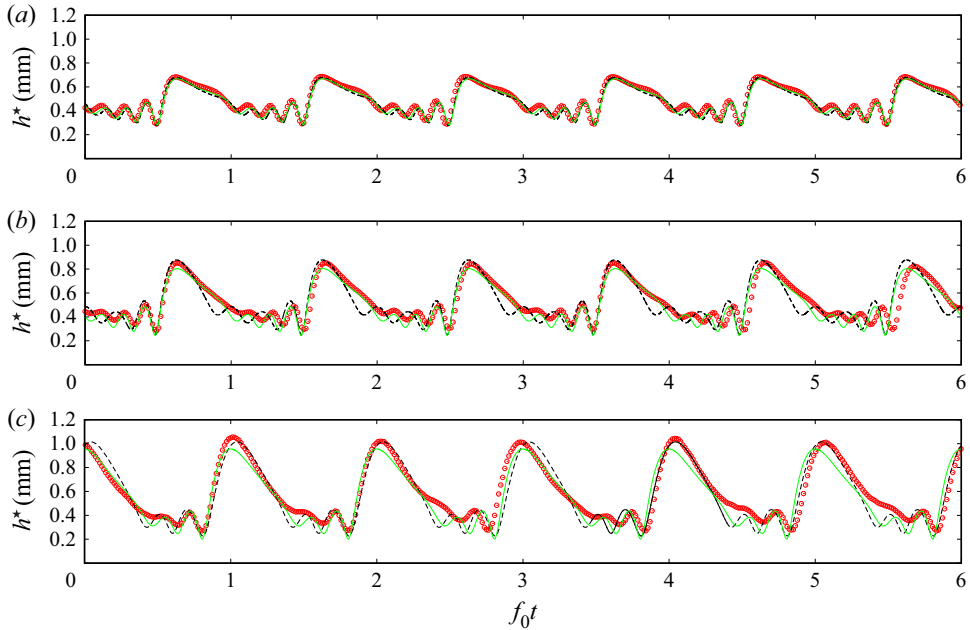
Figure 9. Nonlinear computations (solid and dashed lines) with our WRIBL-LW model (3.6) versus experiments (symbols) of Kofman (2014): $Ka = 3174$ (water and air I in table 1), $H^\star = 19$ mm, $\phi = 5°$, $Re_L = 32.7$, $f_0^\star = 2.8$ Hz ($\omega_0^\star \mathcal{T}_\nu = 0.039$). Film thickness time traces at fixed streamwise position. Solid green lines indicate TWS from numerical continuation; dashed black lines indicate open-domain computations with coherent inlet forcing ($\varepsilon_1 = 0.01$, $\varepsilon_2 = 0$). (a) Quiescent gas ($\Pi_\rho = \Pi_\mu = 0$ in computations); (b) $Re_G = -4123$; (c) $Re_G = -6713$.

dominant at weaker counter-current gas flow rates in figure 10, i.e. $|Re_G| \lesssim 6200$ (first ten snapshots), and the linear instability becomes absolute in this range, as will be shown in figure 12.

6.1.1. *Linear gas effect*

We start by discussing the gas effect on the threshold of the Kapitza instability. Figure 11(a) represents the neutral stability bound, $c_1 = 0$ according to (5.2b), in terms of Re_L and Re_G, for two inclination angles, i.e. $\phi = 5°$ (black curves with circles), which corresponds to our experiment in figure 10, and $\phi = 1°$ (red curves with diamonds). For each ϕ, we have plotted two curves, one obtained from our WRIBL-LW model for turbulent gas flow conditions (filled symbols), and another obtained from the fully coupled governing equations (Tilley *et al.* 1994) for laminar gas flow conditions (open symbols). Only the curve segments within the appropriate Re_G range are represented with solid lines, and the laminar/turbulent transition is highlighted via the shaded region.

For $\phi = 5°$ (black curves with circles), the linear effect of the counter-current gas flow is destabilizing. Further, when the counter-current gas flow rate is sufficiently large, the falling liquid film becomes unconditionally unstable (limit point marked by filled circle), i.e. for all Re_L, in agreement with previous works (Trifonov 2017; Kushnir *et al.* 2021). We find that turbulence in the gas greatly delays this limit versus a laminar prediction (compare filled and open circles).

By contrast, for $\phi = 1°$ (red curves with diamonds), we find a change in nature of the gas effect, as a result of gas-side turbulence. While the gas effect remains destabilizing in
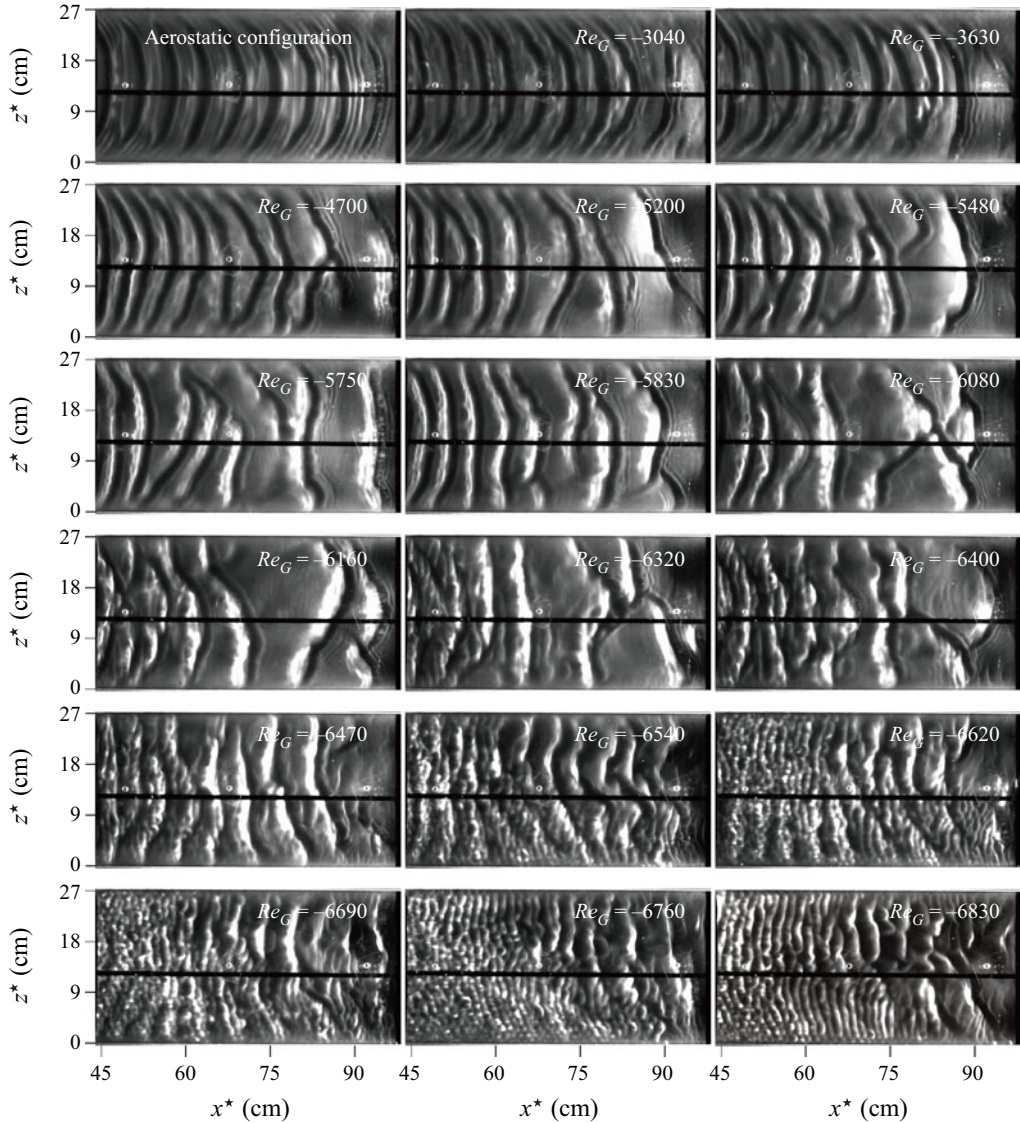
Figure 10. Top view snapshots from one of our experiments. Falling water film sheared by a counter-current air flow and subject to coherent inlet forcing: $H^\star = 13$ mm, $\phi = 5°$, $Re_L^{as} = 44.7$, $Re_L = 43.1$, $f_0^\star = 3.0$ Hz. The first snapshot indicates aerostatic configuration; the second snapshot and onwards indicate counter-current turbulent gas flow with increasing $|Re_G|$. Absolute instability limit from linear stability calculation in figure 12: $Re_G^{AI} = -5182$.

the laminar limit (red curve with open diamond), it switches to stabilizing when turbulence is accounted for (red curve with filled diamond). This is illustrated further in figure 11(*b*), which represents dispersion curves of the linear spatial growth rate for increasing $|Re_G|$ at $Re_L = 1.5$ $(5/6)\cot(\phi)$. Thus turbulence allows us to achieve a gas-induced suppression of the Kapitza instability for the current confinement, $H^\star \sim 10$ mm, which is much weaker than the confinement studied in Lavalle *et al.* (2019), namely $H^\star \sim 1$ mm, where the gas flow was laminar. And the counter-current gas flow can render the falling liquid film unconditionally stable to long-wave disturbances at the limit point marked by a filled
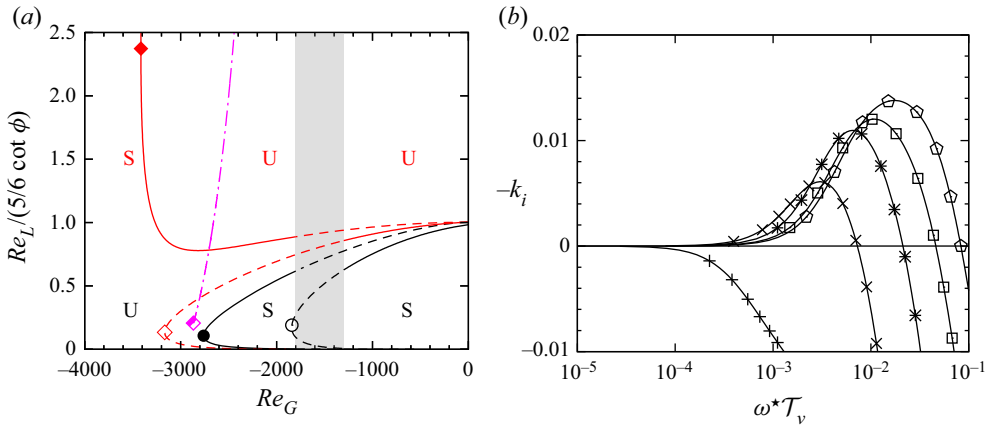
Figure 11. Gas effect on threshold of long-wave Kapitza instability. Linear stability predictions for a falling liquid film sheared by a counter-current gas flow: $Ka = 3174$ (water and air I in table 1), $H^{\star} = 13$ mm. (*a*) Neutral stability bounds. Black curves with circles indicate $\phi = 5°$; red curves with diamonds indicate $\phi = 1°$. Curves with filled symbols indicate WRIBL-LW/WRIBL-OS prediction for turbulent gas flow; curves with open symbols indicate fully coupled prediction for laminar gas flow (Tilley *et al.* 1994); dot-dashed magenta curve indicates short-wave instability mode (§ 6.2) at $\phi = 1°$; shaded zone indicates turbulence transition, $Re_G \in [-1800, -1300]$. S/U denote stable/unstable regions. (*b*) Spatial growth rate dispersion curves from WRIBL-OS: $\phi = 1°$, $Re_L = 1.5$ (5/6) cot(ϕ). Pentagons indicate $\Pi_{\rho} = \Pi_{\mu} = 0$ in (3.41); squares to pluses indicate $Re_G = -1000, -2000, -3000, -3600$.

diamond in figure 11(*a*). However, as we will discover in § 6.2, the film can become unstable to a short-wave instability mode at small ϕ, and the threshold for this mode (dot-dashed curve in figure 11*a*) lies below the neutral stability bound of the Kapitza instability for the parameters considered here. Thus the falling liquid film cannot be fully stabilized in this case.

Gas-induced stabilization of the Kapitza mode is limited to small inclination angles, and plays no role in our current experiments, where the effect of the counter-current gas flow on the falling liquid film is destabilizing. In this case, it is interesting to determine the AI limit and to confront it with the Re_G range of our experiments. Figure 12 represents WRIBL-OS spatial linear stability predictions for the experimental parameters in figure 10. Upon increasing the counter-current gas flow rate (from circles to crosses), the $-k_i$ versus ω curve in figure 12(*a*) and the c_r versus ω curve in figure 12(*b*) develop a cusp at $Re_G = -5114$. This cusp corresponds to a pinch point in the $-k_i$ versus k_r curve (inset of figure 12*a*), which indicates the AI limit (Kupfer, Bers & Ram 1987). Thus the falling liquid film in figure 10 is absolutely unstable from the fifth snapshot onwards, i.e. well before the breakdown of our experiment due to upward-travelling ripples ($Re_G \sim -6800$). Consequently, AI does not seem to play a role in the flooding onset. On the contrary, well-defined downward-travelling Kapitza waves persist far beyond the AI limit (up to the tenth snapshot in figure 10), and we will discuss the nonlinear dynamics of these waves in the following subsections.

6.1.2. *Nonlinear gas effect: TWS*
We wish to know whether the nonlinear response of the wavy falling liquid film is in line with the linear gas effect discussed in the previous subsubsection. Figure 13 compares the wave height (figures 13*a,c*) and wave speed (figures 13*b,d*) of nonlinear TWS
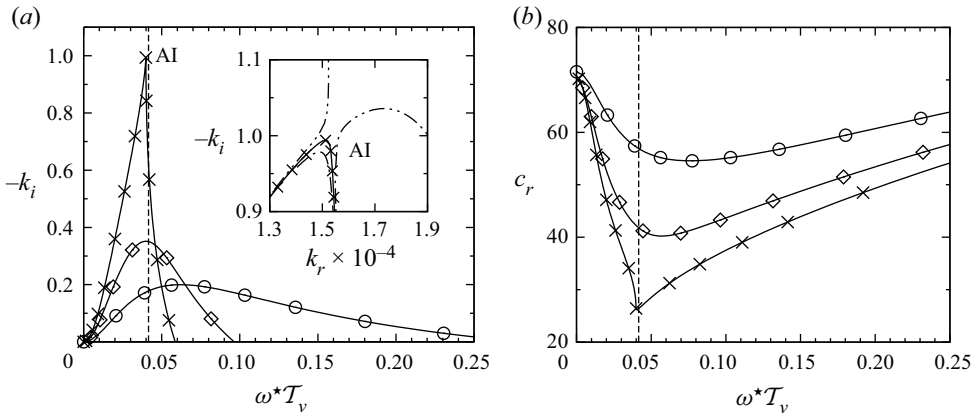
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Figure 12. Transition to AI predicted by spatial linear stability analysis with our WRIBL-OS approach. Parameters according to experiment in figure 10: $Ka = 3174$ (water and air I in table 1), $H^\star = 13$ mm, $\phi = 5°$, $Re_L = 43.1$. Circles indicate $\Pi_\rho = \Pi_\mu = 0$ in (3.41); diamonds indicate $Re_G = -4000$; crosses indicate $Re_G = -5181$. (*a*) Growth rate $-k_i$ versus ω. Inset shows $-k_i$ versus k_r. Dot-dashed line indicates $Re_G = -5180$; dot-dot-dashed line indicates $Re_G = Re_G^{AI} = -5182$. (*b*) Wave speed $c_r = \omega/k_r$. Vertical dashed line indicates forcing frequency $f_0^\star = 3$ Hz from figure 10. We have rescaled ω with $\mathcal{T}_v = 2.207 \times 10^{-3}$ s (see (3.34*a–c*)).

obtained from our WRIBL-LW model at fixed frequency f (solid curves), with experiments (symbols) from our current work (figures 13*a*,*b*), where $H^\star = 13$ mm, and from Kofman *et al.* (2017) (figures 13*c*,*d*), where $H^\star = 19$ mm. The experimental wave height data in figure 13(*a*) were selected from film thickness time trace measurements performed over the entire channel length, which will be discussed in § 6.1.3 (see figure 14). The wave speed data in figure 13(*b*) were obtained via video image processing from our experiment in figure 10, where the Re_L value is slightly different to that in figure 13(*a*).

Different solid curves in figure 13 correspond to different branches of TWS, which are associated with different numbers of precursory capillary ripples (CR) and distinguished by different filled symbols. For the experimental data points, the number of CR is distinguished via corresponding open symbols. Error bars in figure 13(*a*) represent the standard deviation of experimental film thickness time traces, which increases with increasing $|Re_G|$ as a result of wave coalescence events (§ 6.1.3). Beyond a certain $|Re_G|$, coalescence destroys entirely the coherence of the wave train, and comparison with TWS is futile.

Overall, our WRIBL-LW predictions in figures 13(*a*), 13(*b*), 13(*c*) and 13(*d*) are in reasonable agreement with the experimental data. Both the gas effect on the wave height and the wave speed are captured quantitatively, when accounting for the number of CR.

Based on these predictions, we may make the following observations. Downward-travelling TWS exist far beyond the AI limit, marked by open (WRIBL-LW calculation) and filled (WRIBL-OS calculation) red arrows in figures 13(*a*) and 13(*c*). Below the AI limit, the wave height h_{max} increases with increasing $|Re_G|$, while the wave speed mainly decreases. And we have checked that the relative wave amplitude $h_{max}/\bar{h}$ (not shown here) also increases. Thus the nonlinear gas effect is destabilizing, in line with the linear effect discussed in § 6.1.1.

For the 0-CR, 1-CR and 2-CR branches, the h_{max} versus $|Re_G|$ trend in figures 13(*a*) and 13(*c*) changes beyond the AI limit, i.e. h_{max} now decreases with $|Re_G|$ (except for
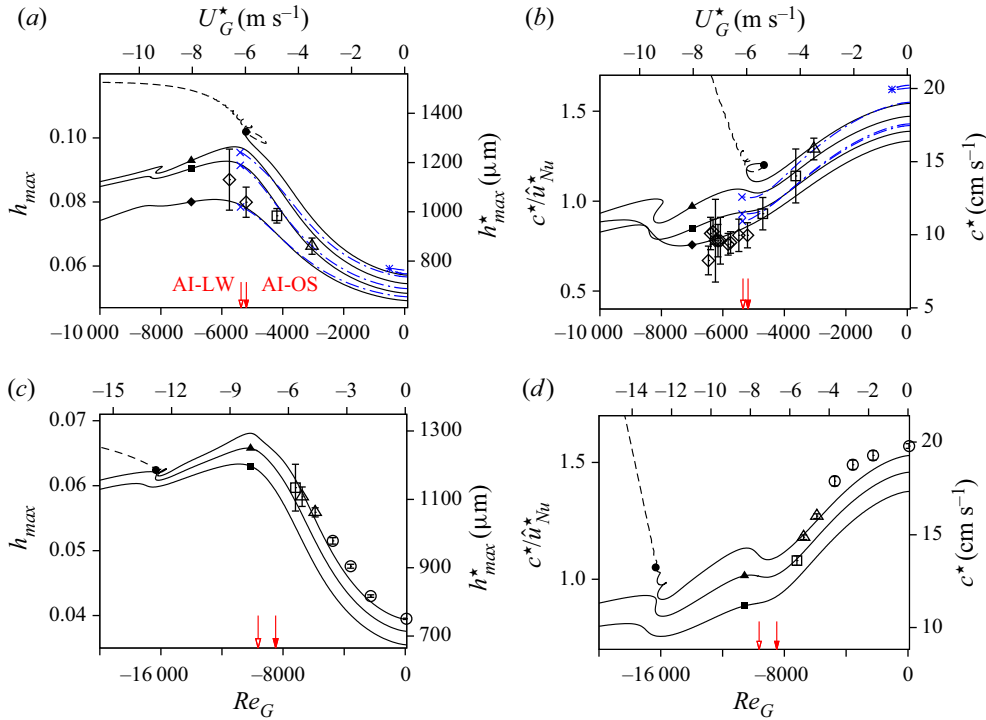
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Figure 13. Gas effect on nonlinear TWS obtained with our WRIBL-LW model (curves) versus experiments (empty symbols). Inclined falling liquid film sheared by counter-current turbulent gas flow: $Ka = 3174$ (water and air I in table 1), $\phi = 5°$. Filled/open symbols distinguish number of capillary ripples (CR): diamonds indicate 0-CR; squares indicate 1-CR; triangles indicate 2-CR; circles indicate 3-CR; dashed line indicates >3-CR. Solid curves indicate $f^\star = f_0^\star$; dot-dashed curves indicate $f^\star = f_{max}^\star$. Crosses indicate AI limit; asterisks indicate nonlinear limit points. Open/filled red arrows mark AI limits obtained from WRIBL-LW/WRIBL-OS. (a,c) Wave height; (b,d) wave speed scaled with $\hat{u}_{Nu}^\star = (3/2)q_{L0}^\star/h_{Nu}^\star$, where $h_{Nu}^\star = (3q_{L0}^\star \nu_L/(g\sin(\phi)))^{1/3}$. (a,b) Versus our experiments: $H^\star = 13$ mm, $f_0^\star = 3.0$ Hz, with (a) $Re_L = 44.2 \pm 0.3$, (b) $Re_L = 43.1$. Filled arrow indicates $Re_G^{AI} = -5194$; empty arrow indicates $Re_G^{AI} = -5366$. (c,d) Versus experiments of Kofman *et al.* (2017): $H^\star = 19$ mm, $Re_L = 45$, $f_0^\star = 3.05$ Hz. Filled arrow indicates $Re_G^{AI} = -8490$; empty arrow indicates $Re_G^{AI} = -9633$.

small non-monotonic regions). For the 3-CR branches (solid curves with filled circles), the trend beyond the AI limit is more complicated, i.e. h_{max} first decreases with $|Re_G|$, and then increases, beyond $|Re_G| = 8000$ in figure 13(a), and beyond $|Re_G| = 16\,000$ in figure 13(c). This increase is associated with the formation of an increasing number of additional CR (dashed curve segments), and a strong increase of the wave speed c is observed in figures 13(b) and 13(d), whereas c mostly decreases with $|Re_G|$ for the other solution branches (solid curves with filled diamonds, squares and triangles).

Focusing now on the experimental data points (open symbols in figures 13a,b), we observe that the number of CR decreases when increasing $|Re_G|$ (from open circles to open diamonds). According to the computations with our WRIBL-LW model (solid curves), this corresponds to a switching of TWS branches in the direction of lowest wave speed. This is surprising, because one would expect the fastest TWS to persist in an experiment at fixed Re_G. Additional effects must thus play a role in the wave selection.
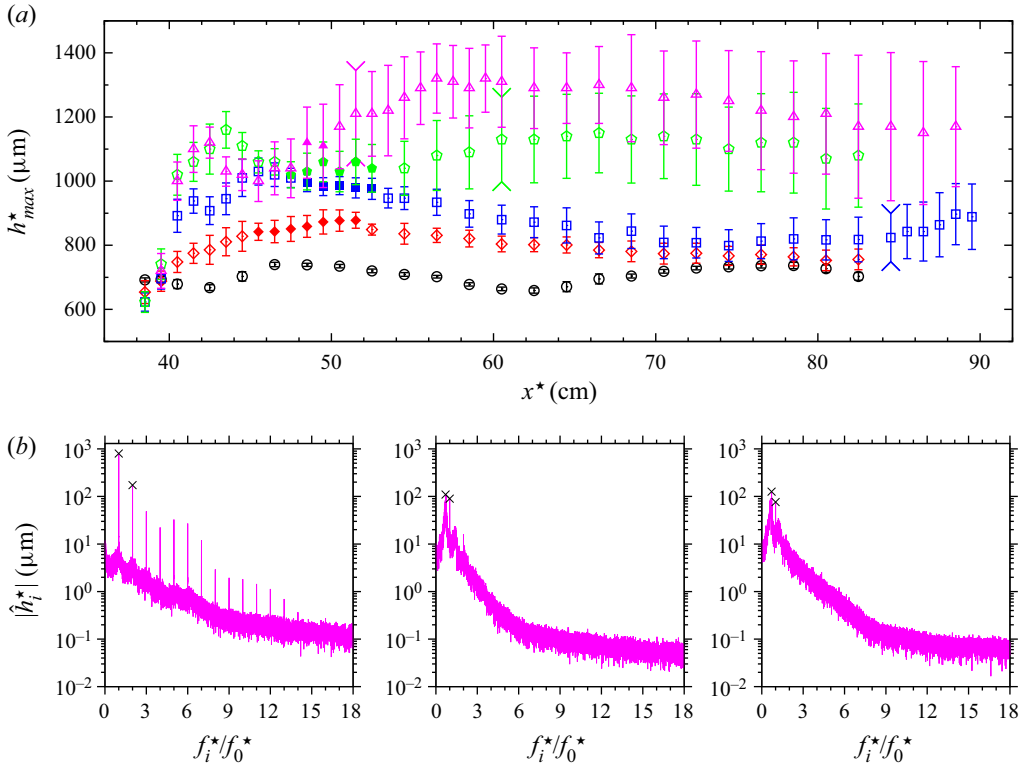
Figure 14. Gas effect on streamwise evolution of the wavy liquid film. Compilation of our experiments: water/air, $H^\star = 13$ mm, $\phi = 5°$, $Re_L^{as} = 46$, $Re_L = 44.2 \pm 0.3$, $f_0^\star = 3$ Hz, $Re_G^{AI} = -5194$. (*a*) Ensemble-averaged wave height $h_{max}^\star$. Error bars represent standard deviation, and check marks mark the start of the coalescence-dominated region. Filled symbols mark data points used in figure 13(*a*). Circles indicate aerostatic configuration; diamonds indicate $Re_G = -3040$; squares indicate $Re_G = -4190$; pentagons indicate $Re_G = -5200$; triangles indicate $Re_G = -5750$. (*b*) Frequency spectra of the film height $h^\star$, with $Re_G = -5750$, where $|\hat{h}_i^\star|$ denotes the amplitude of the Fourier mode with $f_i^\star$. Crosses mark primary and secondary peaks. Left, $x^\star = 41.5$ cm; middle, $x^\star = 51.5$ cm; right, $x^\star = 58.5$ cm.

In our experiment, saturated waves of fixed frequency $f_0^\star$ are formed before entering into contact with the counter-current gas flow. In figures 13(*a*) and 13(*b*), we have compared the gas effect on such waves, i.e. TWS at $f^\star = f_0^\star = 3$ Hz (solid curves), with TWS at the linearly most-amplified frequency, i.e. $f^\star = f_{max}^\star$ (dot-dashed blue curves). Except for the 3-CR branch (dot-dashed curve with asterisk), both types of TWS behave quite similarly until the AI limit (where the $f_{max}^\star$ branches break down). This is because $f_{max}^\star$ does not vary much with Re_G, thus the forcing frequency $f_0^\star$ chosen in the experiment remains close to $f_{max}^\star$. By contrast, in the case of the 3-CR branch, the most-amplified TWS are lost due to a nonlinear limit point (blue asterisk), before the gas flow reaches the fully turbulent regime ($|Re_G| < 1800$).

6.1.3. *Nonlinear gas effect: spatio-temporal wave dynamics*

In a spatially evolving falling liquid film, the counter-current gas flow not only acts on nonlinear Kapitza waves individually, but can trigger interactions between consecutive waves. Thus we study the gas effect on the spatio-temporal dynamics of such waves.
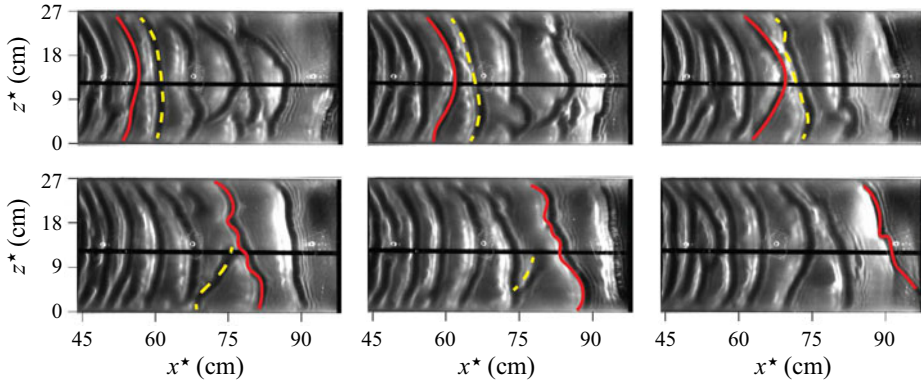
Figure 15. Wave coalescence event. Top-view snapshots from our experiment in figure 10 (parameters similar to pentagons in figure 14a): $Re_L = 43.1$, $Re_G = -5200$. Time increases from top left to bottom right with increment 0.48 s. Solid red and dashed yellow lines highlight two consecutive wave fronts.

Figure 14(*a*) summarizes spatial profiles of film thickness data obtained from our experiments at $Re_L^{as} = 46$, $Re_L = 44.2 \pm 0.7$ and $f_0^\star = 3$ Hz, under increasing $|Re_G|$. Symbols represent the ensemble average of the wave height $h_{max}^\star$ (over at least 100 waves) at a given streamwise position $x^\star$, and error bars represent the corresponding standard deviation. Filled symbols identify the TWS data reported in figures 13(*a*) and 13(*b*).

In the aerostatic configuration (open circles in figure 14*a*), the error bars are very short, implying that waves are highly regular in time. However, $h_{max}^\star$ varies in space as the result of the well-known secondary instability discovered by Liu & Gollub (1993).

In the counter-current configuration (from diamonds to triangles in figure 14*a*), we observe that $h_{max}^\star$ in the lower half of the channel ($x^\star \gtrsim 50$ cm) increases significantly when $|Re_G|$ is increased. On the one hand, this is due to the gas-induced amplification of TWS discussed in § 6.1.2. On the other hand, the standard deviation of the $h_{max}^\star$ data increases significantly as $|Re_G|$ is increased. This is the signature of wave coalescence events that can suddenly increase the wave height. Figure 15 represents a sequence of snapshots illustrating such an event for $Re_G = -5200$ (pentagons in figure 14*a*). The solid red and dashed yellow lines highlight the fronts of two consecutive waves that eventually coalesce.

In figure 14(*a*), we have marked the streamwise position beyond which such coalescence events become prevalent via check marks on the corresponding error bars. This position, which we will designate as $x_c^\star$, is determined from the spatial evolution of the frequency spectrum of $h^\star$, as illustrated in figure 14(*b*) for $Re_G = -5750$ (triangles in figure 14*a*). We see that the spectrum evolves from that of a regular wave train, with clear peaks at the forcing frequency $f_0^\star$ and its harmonics (left-hand plot), to a form where the dominant frequency $f_{max}^\star$ is lower than the forcing frequency (right-hand plot). The streamwise locations of the transition, i.e. where $f_{max}^\star$ becomes smaller than $f_0^\star$ (middle plot), is defined as $x_c^\star$.

Judging by the standard deviation of the $h_{max}^\star$ profiles in figure 14(*a*), wave coalescence becomes more prominent as $|Re_G|$ is increased. We have seen in figure 13(*b*) that the counter-current gas flow reduces the wave speed of TWS. At fixed wave frequency $f^\star$, this leads to a reduction of the wave separation distance, thus favouring wave interaction and coalescence. Figure 16 provides a direct comparison of wave trains for two of the experiments from figure 14(*a*). Figure 16(*a*) confronts film thickness
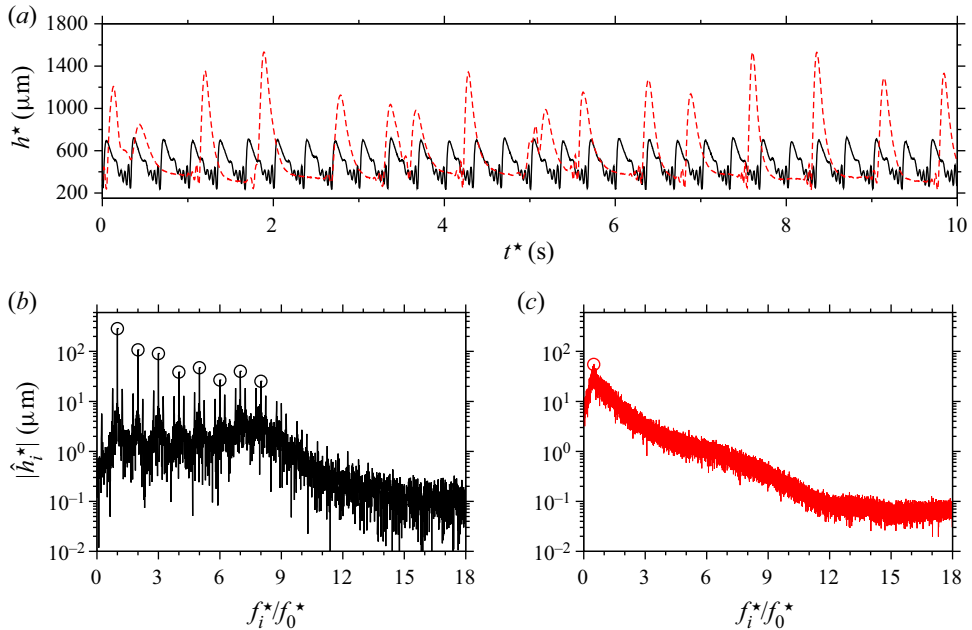
Figure 16. Wave trains for two data sets from figure 14(*a*). (*a*) Film thickness time traces at $x^\star = 82.5$ cm. Solid line indicates aerostatic configuration (circles in figure 14*a*), $Re_L^{as} = 46.0$; dashed line indicates counter-current configuration (triangles in figure 14*a*), $Re_L = 44.2$, $Re_G = -5750$. (*b*,*c*) Corresponding frequency spectra, where $|\hat{h}_i^\star|$ is the amplitude of the Fourier mode with $f_i^\star$. (*b*) Aerostatic configuration; open circles mark peaks at $f_0^\star$ and its harmonics. (*c*) Counter-current configuration; open circle marks global peak at most-amplified frequency $f_{max}^\star/f_0^\star = 0.49$.

time traces measured at $x^\star = 82.5$ cm for the aerostatic configuration (solid black curve) and for the counter-current configuration at $Re_G = -5750$ (dashed red curve). Whereas the former represents a regular train of waves responding well to the forcing frequency, the latter displays clear signs of coalescence-induced wave coarsening, leading to large-amplitude tsunami waves with a wave height much greater than the TWS in figure 13(*a*). Figures 16(*b*) and 16(*c*) represent corresponding frequency spectra for the two data sets. Whereas the forcing frequency $f_0^\star = 3$ Hz is dominant in the spectrum for the aerostatic configuration (figure 16*b*), a lower frequency emerges for the counter-current configuration, where periodicity is lost entirely (figure 16*c*).

In figure 17, we have plotted the starting location $x_c^\star$ of the coalescence-dominated region versus Re_G, based on all of our experiments for two values of Re_L. The error bars on $x_c^\star$ correspond to the increment with which the *x*-position was varied in the experimental runs reported in figure 14(*a*). According to figure 17, coalescence is greatly precipitated by the (turbulent) counter-current gas flow, and this effect is stronger, the lower the liquid flow rate.

The nonlinear wave phenomena discussed in figures 14–17 do not seem to be disrupted by AI, even though we have considered values of $|Re_G|$ quite far beyond the AI limit, i.e. $Re_G^{AI} = -5194$ at $Re_L = 44.2$. This is favoured by the protected zone used in our experiments, where Kapitza waves are allowed to complete their linear and nonlinear growth in a quiescent gas, and where the Kapitza instability remains convective. Only after having attained a saturated nonlinear state do these waves come into contact with the gas flow, and consequently, the AI is bypassed.
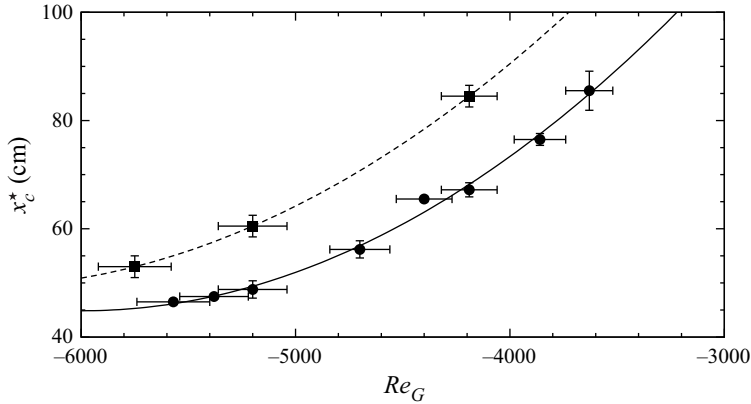
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Figure 17. Gas effect on the starting position $x_c^\star$ of the coalescence-dominated region. Compilation of our experiments: water/air, $H^\star = 13\,\text{mm}$, $\phi = 5°$, $f_0^\star = 3\,\text{Hz}$. Circles indicate $Re_L = 32.5 \pm 0.6$; squares indicate $Re_L = 44.3 \pm 0.3$; curves indicate polynomial fits to guide the eye.

Next, we employ open-domain computations with our WRIBL-LW model to study the linear and nonlinear spatio-temporal evolution of Kapitza waves that feel the gas effect from the start. In these computations, the turbulent counter-current gas flow is applied over the entire domain length. Of course, our WRIBL-LW model can capture only long-wave instabilities, such as the Kapitza instability, on which we focus in the current subsection.

We start by studying the gas effect on the dynamics of naturally evolving Kapitza waves, which are more relevant for industrial applications. Here, the liquid flow rate q at the liquid inlet is subject to a noisy perturbation according to (3.46), with $\varepsilon_1 = 0$, $\varepsilon_2 = 5 \times 10^{-5}$. Figure 18 represents snapshots of our open-domain WRIBL-LW computations for parameters according to three of the experiments in figure 14(a) (circles, squares and triangles there). In figure 18(a) (aerostatic configuration) and figure 18(b) ($Re_G = -4190$), the AI limit $Re_G^{AI} = -5114$ (obtained from the WRIBL-LW model) has not been reached, and we observe the same phenomena as in our experiments from figure 14. In particular, the counter-current gas flow exacerbates coalescence events, leading to large-amplitude tsunami waves, which move very rapidly and absorb numerous smaller waves in their path. This gas-assisted coarsening dynamics is illustrated in figure 19(a), representing a spatio-temporal diagram for the computation in figure 18(b) (see also supplementary movie 1 available at https://doi.org/10.1017/jfm.2023.670).

A very different dynamics unfolds when $|Re_G|$ is increased beyond the AI limit, as shown in figures 18(c) and 19(b), which correspond to $Re_G = -5750$ (see also supplementary movie 2). Here, coalescence events are absent, and a highly regular train of saturated-amplitude solitary waves develops. The height h_{max} of these waves is significantly smaller than that of the tsunami waves in figure 18(b), thus limiting the risk of flooding. At the same time, h_{max} is large enough that a significant wave-induced intensification of heat and mass transport can be expected (Dietze 2019). Thus AI is not necessarily dangerous in our configuration. On the contrary, the unbounded linear spatial growth rate associated with AI represents an effective linear wave selection mechanism that produces highly regular nonlinear surfaces waves of the absolute frequency $f_{AI}^\star = 3.35\,\text{Hz}$ from ambient noise (where $f_{AI}^\star$ is obtained from a WRIBL-LW calculation based on figure 12a). Thereby, nonlinear effects, which set in very close to the liquid inlet, allow
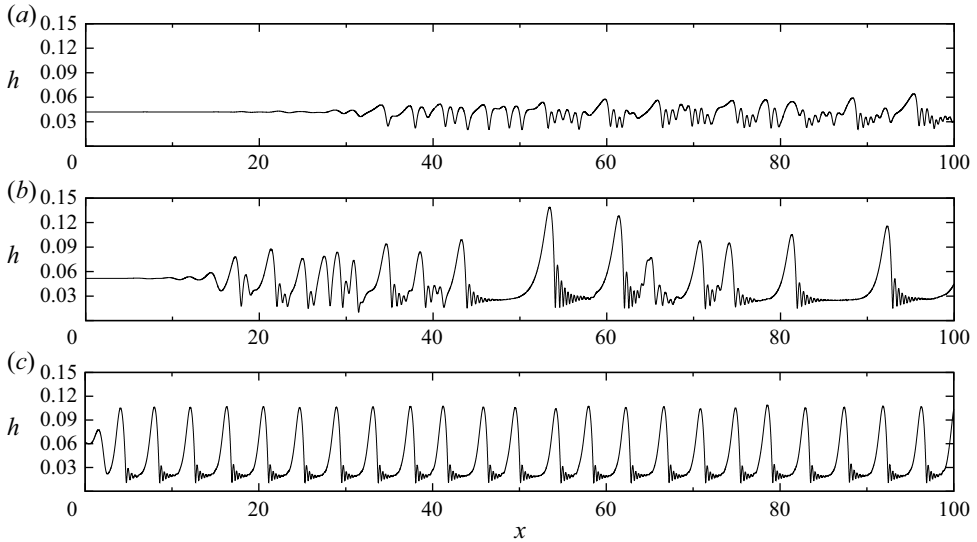
Figure 18. Gas effect on spatial evolution of naturally-evolving Kapitza waves. Open-domain computations using our WRIBL-LW model on a domain of length $L^\star = 1.50$ m. The gas flow is applied over the entire domain length. Noisy inlet perturbation according to (3.46): $\varepsilon_1 = 0$, $\varepsilon_2 = 5 \times 10^{-5}$. Parameters according to experiments in figure 14(a) (circles, squares and triangles there): $Ka = 3174$ (water and air I in table 1), $H^\star = 13$ mm, $\phi = 5°$, $Re_L = 43.1$. Plots for: (a) $\Pi_\rho = \Pi_\mu = 0$ in (3.6a); (b) $Re_G = -4190$; (c) $Re_G = -5750$. The AI limits, obtained from WRIBL-LW and WRIBL-OS, are $Re_G^{AI} = -5347$ and $Re_G^{AI} = -5182$.

the Kapitza waves to travel downstream, notwithstanding the temporal nature of the linear growth. As far as we know, such a dynamics has not been shown before, and we have checked that it persists at $Re_G = -6500$ (not shown here), i.e. far beyond the value of $|Re_G|$ in figure 19(b).

By contrast, it is very hard to produce a regular wave train below the AI limit via coherent inlet forcing. This is demonstrated in figure 20, which represents computations similar to those in figure 18, except that we have additionally applied a harmonic inlet perturbation at frequency $f_0^\star = 3$ Hz, using $\varepsilon_1 = 0.01$ and $\varepsilon_2 = 5 \times 10^{-5}$ in (3.46). Although the applied coherent forcing produces a regular wave train in the aerostatic configuration (figure 20a), coalescence events cannot be avoided for $Re_G = -4190$ (figure 20b). We have not shown the corresponding computation beyond the AI limit (see figure 21(b) for this), because it produces almost exactly the same wave train as in figure 18(c).

Figure 21 summarizes the wave characteristics of our different WRIBL-LW open-domain computations from figures 18 and 20 by plotting the maximum wave height h_{max} versus the streamwise position x. Error bars represent the range of temporal variation of h_{max} at a given position. We see that AI-induced wave selection allows us to (1) reduce the maximum wave height in the lower portion of the domain by about 40 %, and (2) suppress its variance over the entire domain length. For completeness, the diamonds in figure 21(b) report results from our computation with additional coherent inlet forcing for the parameters in figure 18(c), i.e. beyond the AI limit, evidencing that the wave train is not altered meaningfully by this additional forcing.
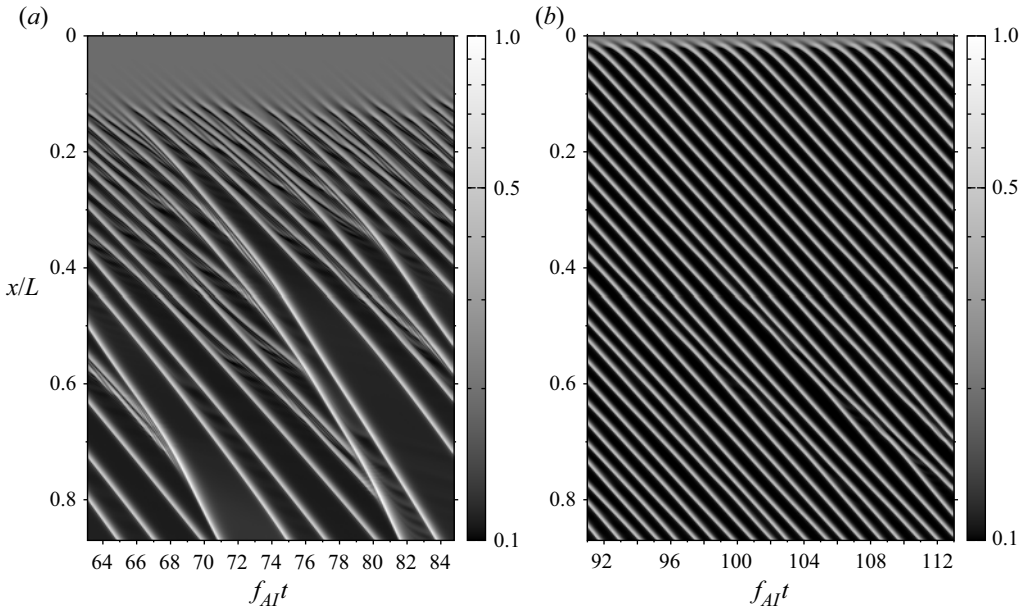
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Figure 19. Spatio-temporal diagrams of the normalized film height h/h_{max} for the computations in figures 18(b) and 18(c): (a) $Re_G = -4190$, (b) $Re_G = -5750$. The AI frequency is $f_{AI}^{\star} = 3.35$ Hz, as obtained from linear stability analysis based on our WRIBL-LW model.
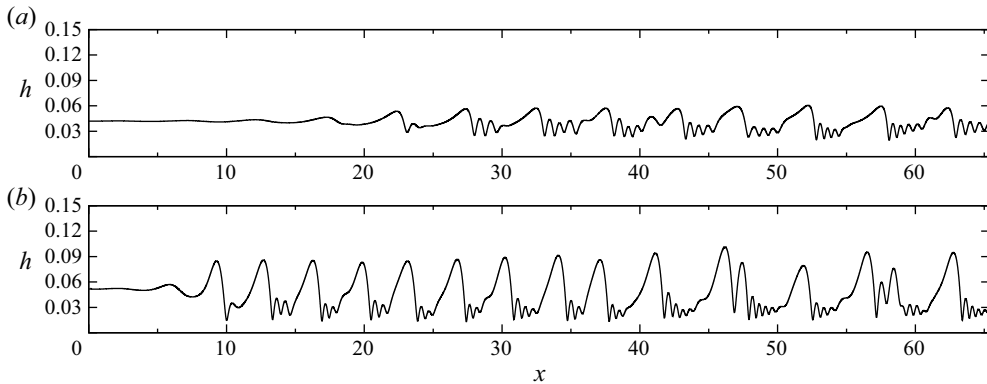

Figure 20. Computations according to figures 18(a) and 18(b), but with additional coherent inlet forcing (3.46): $f_0^{\star} = 3$ Hz, $\varepsilon_1 = 0.01$, $\varepsilon_2 = 5 \times 10^{-5}$. Plots for: (a) $\Pi_\rho = \Pi_\mu = 0$ in (3.6a); (b) $Re_G = -4190$.

6.1.4. *Standing ripples in a vertically falling liquid film*

Our nonlinear spatio-temporal WRIBL-LW computations in §6.1.3 did not reveal any evidence of the gas-induced oscillatory secondary instability (OI) discovered by Lavalle *et al.* (2020) for the configuration of a vertically falling liquid film sheared by a superconfined counter-current laminar gas flow. In a spatially evolving regular train of surface waves formed by coherent inlet forcing at frequency f_0, this instability leads to a periodic spatial modulation of the wave height, which entails an intensification of mixing.

To check whether this dynamics can be recovered in our current weak-confinement setting with a turbulent counter-current gas flow, we perform open-domain WRIBL-LW
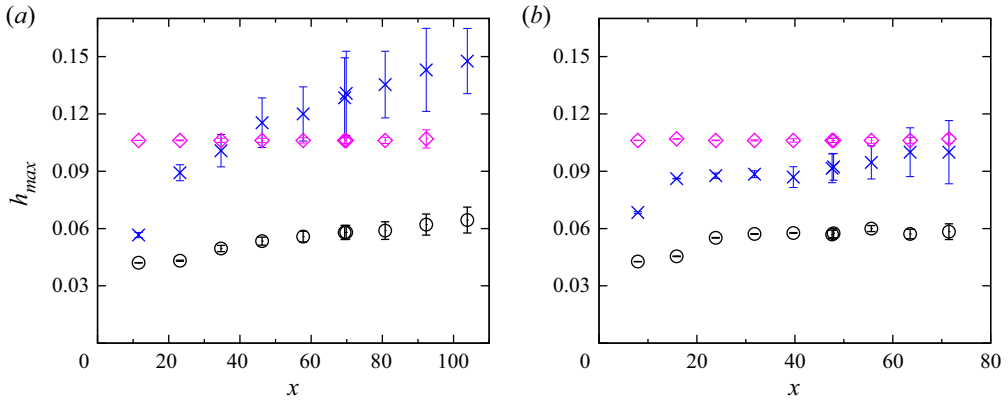
Figure 21. Summary of wave data from our computations in figures 18 and 20. Maximum wave height h_{max} versus the streamwise location. Circles indicate $\Pi_\rho = \Pi_\mu = 0$; crosses indicate $Re_G = -4190$; diamonds indicate $Re_G = -5750$. Naturally evolving versus forced waves. (*a*) Noisy inlet perturbation: $\varepsilon_1 = 0$, $\varepsilon_2 = 5 \times 10^{-5}$ in (3.46). (*b*) Additional coherent inlet forcing: $f_0^\star = 3.0$ Hz, $\varepsilon_1 = 0.01$, $\varepsilon_2 = 5 \times 10^{-5}$ in (3.46).

computations for the same liquid-side parameters as in figure 3(*a*) of Lavalle *et al.* (2020), i.e. $Ka = 509.5$, $\phi = 90°$, $Re_L = 15$ and $f_0^\star = 16$ Hz. Further, we set $\varepsilon_1 = 0.01$ and $\varepsilon_2 = 0$ in (3.46), and we apply the counter-current gas flow over the entire domain length $L^\star = 0.84$ m. In terms of confinement, we set $H^\star = 10$ mm, in contrast to $H^\star = 1$ mm used by Lavalle *et al.* (2020). The forcing frequency $f_0^\star = 16$ Hz corresponds to the linearly most-amplified value in the limit ($\Pi_\rho = \Pi_\mu = 0$), which is quite different from the AI frequency $f_{AI}^\star = 26.8$ Hz, as obtained from our WRIBL-LW model. We search for signs of the OI by increasing $|Re_G|$.

Figure 22 reports results of computations for two values of $|Re_G|$. The first computation (figure 22*a*) corresponds exactly to the AI limit $Re_G = Re_G^{AI} = -6500$ and represents the same features as other computations at lower $|Re_G|$ (not shown here): an unaltered regular wave train of frequency $f = f_0$ persists over the entire domain length.

In the second computation (figure 22*b*), where the AI limit has been surpassed ($Re_G = -7500$), a more interesting dynamics unfolds. Here, a quite regular wave train of frequency $f = f_{AI}$ emerges near the liquid inlet, as a result of linear wave selection at the AI frequency. However, the coherent inlet forcing at frequency f_0 competes with this wave selection, leading to a slight perturbation of the wave train, which grows spatially and eventually disrupts the wave train. As a result, large-amplitude tsunami waves form due to coalescence events. These waves travel extremely fast and absorb all smaller waves travelling in front.

This gas-induced coarsening dynamics, which is well illustrated by the spatio-temporal diagram in figure 23(*a*), leads to long portions of thin residual film in between two consecutive tsunami waves. There, the liquid flow rate $q_L(x, t)$ is very small (see the q_L profile in figure 23*c*), thus $|Re_G|$ is even further beyond the AI limit than for the primary flow q_{L0}. This leads to the formation of small-amplitude ripples on the residual film. We call these standing ripples because they are almost fixed in space, as evidenced by several features in figures 22 and 23.

First, the dot-dashed red profile segment in figure 22(*b*), which corresponds to a slightly later time than the main profile, shows no significant translation of the ripples. Second, the wave fronts of the standing ripples in the spatio-temporal plot in figure 23(*a*) are almost
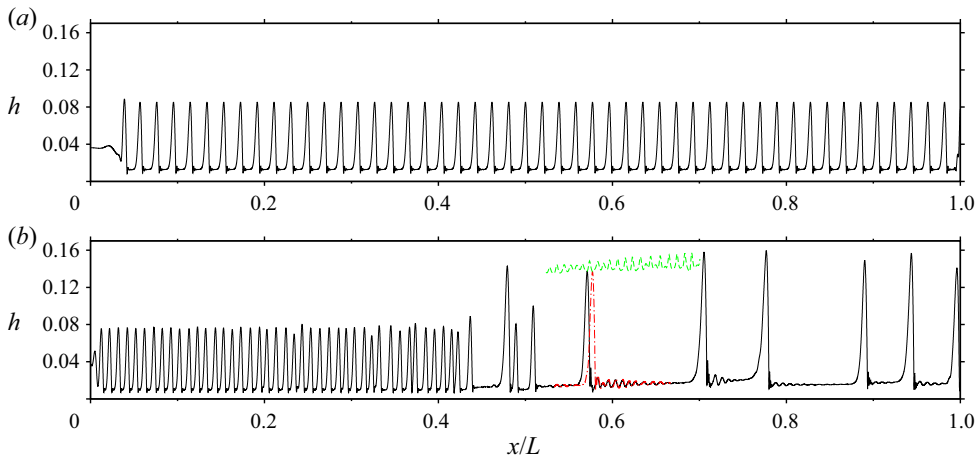
Figure 22. Vertically falling liquid film sheared by a turbulent counter-current gas flow. Liquid-side conditions according to figure 3(*a*) in Lavalle *et al.* (2020): $Ka = 509.46$ (DMSO–water and air II in table 1), $Re_L = 15$, $f_0^\star = 16\,\mathrm{Hz}$, $Re_G^{AI} = -6500$. WRIBL computation on an open domain of length $L^\star = 0.843\,\mathrm{m}$. Snapshots of the film height profile $h(x)$ at $f_0 t = 61.4$. (*a*) At AI limit: $Re_G = Re_G^{AI} = -6500$. (*b*) Beyond AI limit: $Re_G = -7500$. Dot-dashed red line indicates $f_0 t = 61.6$; green dashed line indicates Lagrangian path of a wave crest.
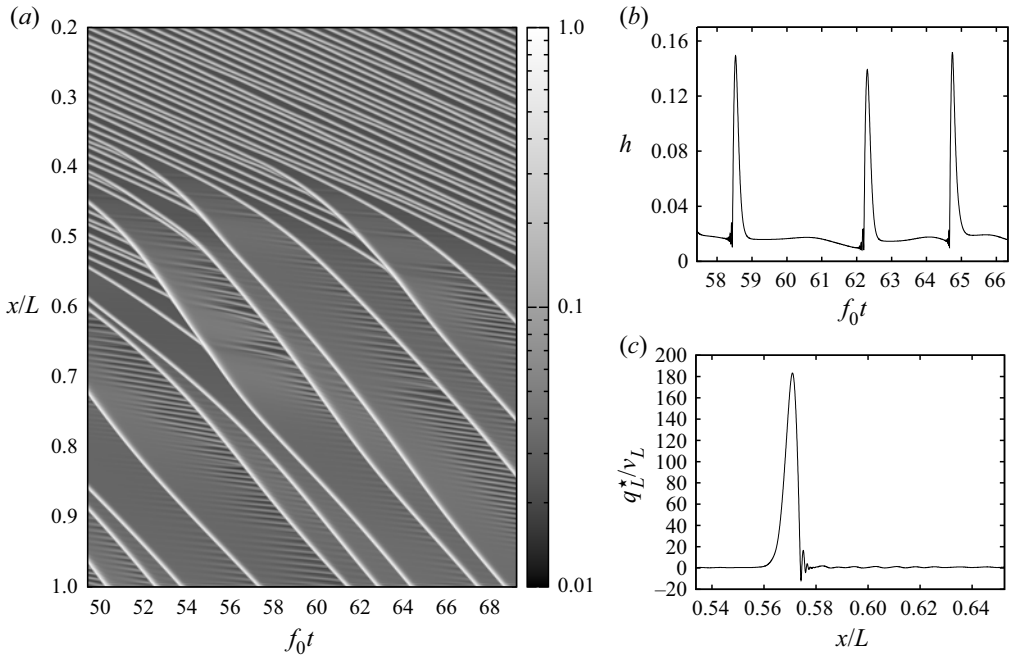
Figure 23. Standing ripples beyond the AI limit $Re_G^{AI} = -6500$. Computation from figure 22(*b*): $Re_G = -7500$. (*a*) Spatio-temporal diagram of the normalized film height h/h_{max}. (*b*) Film height time trace $h(t)$ at $x/L = 0.6$. (*c*) Spatial profile of the liquid flow rate $q_L(x)$ at $f_0 t = 61.4$.

horizontal. Third, the film height time trace in figure 23(*b*) does not show any signature of the ripples in between two main wave humps.

The standing ripples are felt like a surface roughness by the tsunami waves propagating over the residual film. This leads to a spatial modulation of the film height h_{max}, similar to falling liquid films flowing on a corrugated substrate (Dietze 2019), where they have been shown to intensify mixing and inter-phase mass transfer. This modulation is evidenced by the dashed green curve in figure 22(*b*), which represents the Lagrangian path of the crest of one of the tsunami waves as it propagates through the domain. The absolute nature of the standing ripples and their interaction with the large tsunami waves is illustrated further in supplementary movie 3.

In conclusion, although we have not found any sign of the OI reported by Lavalle *et al.* (2020) for our confinement level, we nonetheless observe a similar gas-induced spatial modulation of the Kapitza waves, albeit due to an entirely different mechanism.

6.2. *Upward-travelling ripples: a new short-wave instability*

We now turn to the upward-travelling ripples observed for $|Re_G| \gtrsim 6200$ in our experiment of figure 10 (see the last eight snapshots there). These ripples eventually lead to a breakdown of our experiment due to the accumulation of liquid droplets in the gas loop, thus can be considered as the onset of flooding. In the current subsection, we seek to identify the origin of these ripples via linear stability calculations using our OS-OS approach, which allows us to capture long- and short-wave instability modes.

Figure 24 represents temporal OS-OS linear stability predictions for parameters from the experiment. The different symbols correspond to five different values of Re_G, according to the 4th ($Re_G = -4700$), 5th ($Re_G = -5200$), 7th ($Re_G = -5750$), 12th ($Re_G = -6400$) and 17th ($Re_G = -6760$) snapshots in figure 10. The last snapshot in figure 10 ($Re_G = -6830$) corresponds to the breakdown of our experiment, and is not considered here.

Figures 24(*a*) and 24(*c*) represent growth rate dispersion curves for different instability modes, and figures 24(*b*) and 24(*d*) represent the corresponding dispersion curves for the linear wave speed. We have separated the different plots into two pairs in order to better distinguish the different modes. Red dot-dashed curves in figure 24(*a*) belong to the long-wave Kapitza mode, which we have discussed in § 6.1. The growth rate of this mode increases with increasing $|Re_G|$ (from pluses to pentagons), while its cut-off wavenumber decreases.

The blue dashed curves in figure 24(*c*) belong to a new short-wave instability mode, which emerges upon increasing $|Re_G|$ beyond $|Re_G| = 4837$ (between crosses and pentagons). We call this new instability mode a short-wave mode, because the growth rate kc_i is positive only within a finite span of the wavelength $\Lambda = 2\pi/k$, and because the maximum growth rate is observed at a large wavenumber, i.e. $k_{max} \sim 10$ versus $k_{max} \sim 2$ for the long-wave Kapitza instability mode. The short-wave mode appears for $|Re_G| \gg 1800$, and this suggests that turbulence in the gas is required to generate this instability mode. This may explain why previous stability investigations (Schmidt *et al.* 2016; Trifonov 2017), where the gas flow was assumed laminar, did not find the short-wave mode.

At $Re_G = -5200$ (pentagons in figure 24), the growth rate of the short-wave mode (figure 24*c*) has surpassed that of the Kapitza mode (figure 24*a*). However, our experiments in figure 10 do not show any clear signature of the short-wave mode, except maybe slight modulations on the crests of the first two wave fronts (see e.g. 8th snapshot in figure 10).
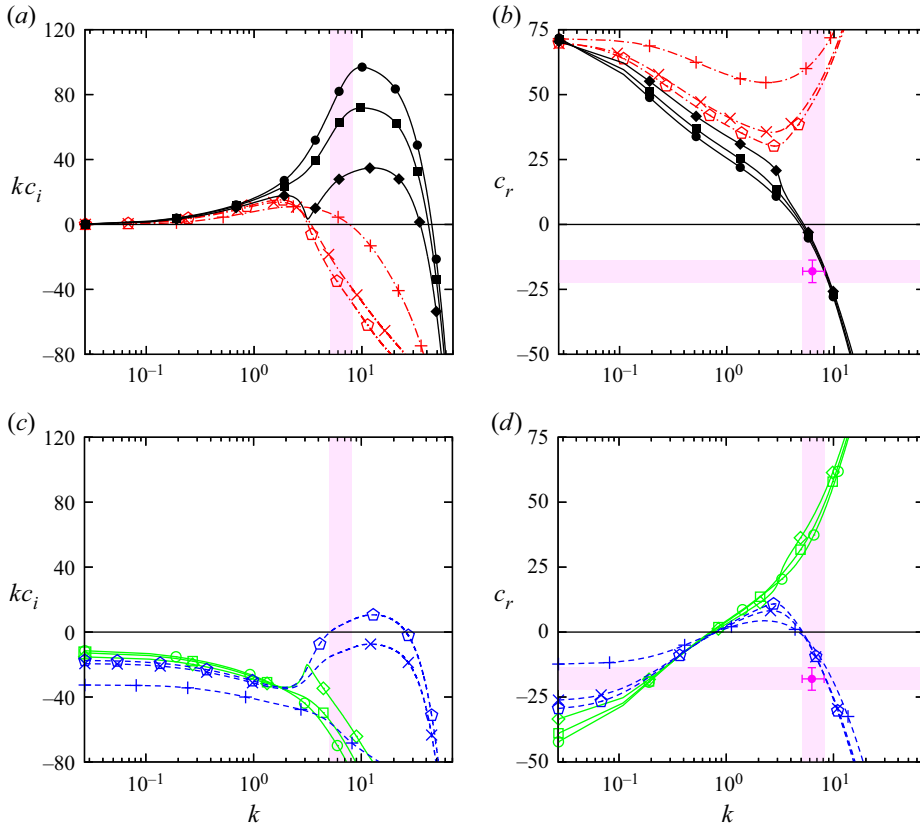
Figure 24. New short-wave instability mode. Falling liquid film sheared by a turbulent counter-current gas flow: $Ka = 3174$ (water and air I in table 1), $H^\star = 13$ mm, $\phi = 5°$, $Re_L = 43.1$, $Re_G^{AI} = -5182$. Temporal linear stability predictions using the OS-OS approach. Dashed blue indicates new short-wave mode; dot-dashed red indicates long-wave Kapitza mode; solid black with filled symbols indicates unstable merged mode; solid green with open symbols indicates stable merged mode. Pluses indicate $\Pi_\rho = \Pi_\mu = 0$ in (3.41); crosses indicate $Re_G = -4700$; pentagons indicate $Re_G = -5200$; diamonds indicate $Re_G = -5750$; squares indicate $Re_G = -6400$; circles indicate $Re_G = -6760$. (*a,c*) Growth rate; (*b,d*) wave speed. Shaded magenta bands and filled magenta circles with error bars represent our experiment from figure 10: $Re_L = 43.1$, $Re_G = -6760$, $\Lambda_{ripples}^\star = (13 \pm 3)$ mm, $c_{ripples}^\star = (-6.2 \pm 1.5)$ cm s^{-1}.

This can be attributed to the protected zone in our current experimental set-up, where Kapitza waves are allowed to develop in a virtually quiescent atmosphere, before entering the gas-sheared zone. In other words, the gas-induced short-wave instability mode has to compete with saturated fully-nonlinear Kapitza waves. We demonstrate this via an additional set of experiments that was focused on detecting the first signs of ripples for the parameters in figure 10. Figure 25 shows spatio-temporal diagrams of the film surface slope obtained from these experiments, using the synthetic schlieren technique (Moisy, Rabaud & Salsac 2009; Kofman *et al.* 2014). In figure 25(*a*), with $Re_G = -5200$, wave fronts of upward-travelling ripples are clearly visible in between downward-travelling Kapitza waves. However, these ripples cannot yet compete with the large-amplitude Kapitza wave humps, and thus remain hidden in the dark inter-wave regions of figure 10.

Upon increasing Re_G further (diamonds in figure 24), the short-wave mode and the Kapitza mode merge into a new unstable merged mode (filled diamonds in figure 24*a*),
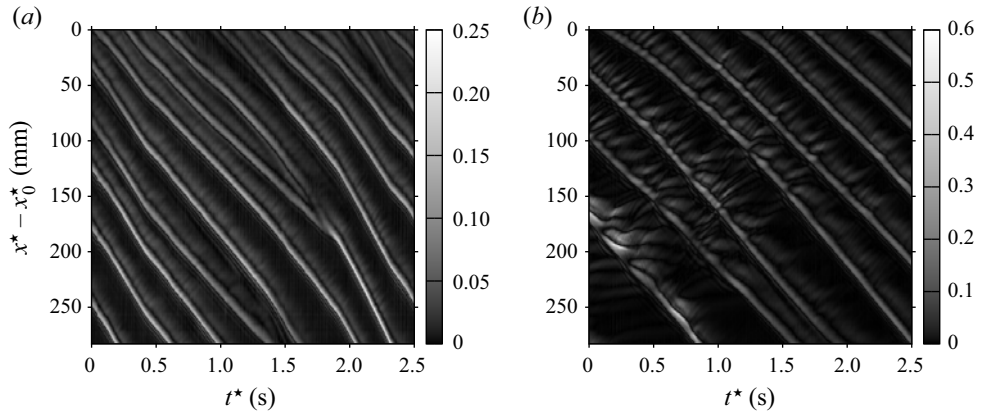
Figure 25. First signature of upward-travelling ripples in our experiments. Spatio-temporal diagrams of the film surface slope $\|\nabla h\|$ for parameters in figure 10, obtained with the synthetic schlieren technique (Kofman *et al.* 2014): $H^\star = 13$ mm, $\phi = 5°$, $Re_L = 43.1$, $f_0^\star = 3$ Hz, $x_0^\star = 48$ cm, $z^\star = 13$ cm. (*a*) For $Re_G = -5200$, ripples start to appear in between Kapitza wave humps. (*b*) For $Re_G = -6080$, ripples deform crests of Kapitza waves.
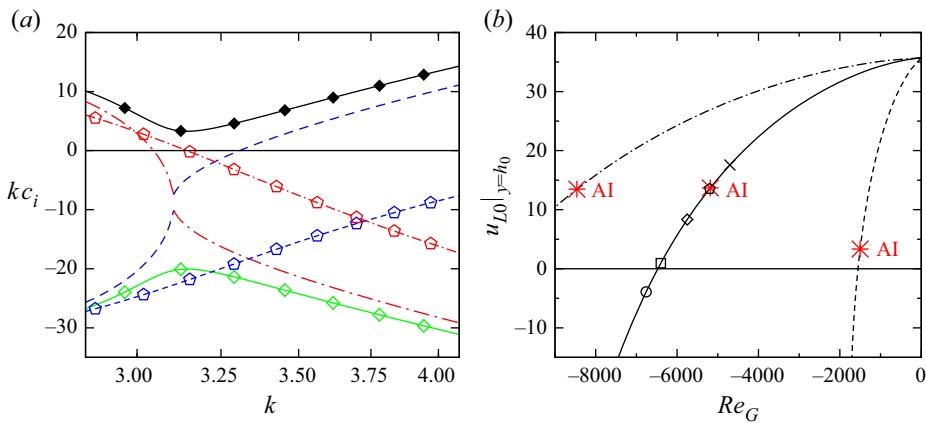

Figure 26. Details of OS-OS linear stability predictions from figure 24: $Ka = 3174$, $Re_L = 43.1$, $H^\star = 13$ mm, $\phi = 5°$. (*a*) Merging between the short-wave and long-wave instability modes from figures 24(*a*) and 24(*c*). Diamonds indicate $Re_G = -5750$; lines without symbols indicate $Re_G = -5680$, pentagons indicate $Re_G = -5200$. (*b*) Primary-flow liquid velocity at the film surface. Solid line indicates $H^\star = 13$ mm, $Re_G^{AI} = -5182$; dot-dashed line indicates $H^\star = 19$ mm, $Re_G^{AI} = -8461$; dashed line indicates $H^\star = 5$ mm, $Re_G^{AI} = -1501$. Asterisks indicate the AI limit from WRIBL-OS spatial linear stability calculations.

which initially displays a two-humped growth rate dispersion curve, and a new stable merged mode (open diamonds in figure 24*c*). Figure 26(*a*) shows the merging of the growth rate curves in detail. According to this, the long-wave portion of the long-wave mode (red dot-dashed curves) merges with the short-wave portion of the short-wave mode (blue dashed curves), creating the unstable merged mode (solid black curve with filled diamonds). Vice versa, the short-wave portion of the long-wave mode merges with the long-wave portion of the short-wave mode, creating the stable merged mode (solid green curve with open diamonds).

A direct consequence of the mode merging is a change in trend of the cut-off wavenumber k_c versus Re_G when considering the growth rate curves originating at $k = 0$,

$kc_i = 0$ in figure 24(a). Before the merging (pluses to pentagons), these curves are associated with the long-wave Kapitza instability, and k_c decreases with increasing $|Re_G|$. After the merging (diamonds to circles), k_c jumps to a much greater value and its trend is reversed. This could explain the sudden change in trend of the neutral stability bounds in figure 11 of Vellingiri *et al.* (2015), which we have reproduced with our WRIBL-OS approach in figure 29(a) of Appendix A.

As $|Re_G|$ is increased beyond $|Re_G| = 5750$ in figure 24(a) (from diamonds to circles), the short-wave growth rate maximum of the unstable merged mode becomes dominant and attains very large values. It is here that upward-travelling ripples become strong enough to deform the crests of the Kapitza waves (see figure 25b), and thus become clearly visible in our experiments (last eight snapshots of figure 10). The shaded magenta band in figure 24(a) represents the experimental range of the wavenumber k for these ripples at $Re_G = -6760$ (next to last snapshot in figure 10), and this compares reasonably well with the most-amplified wavenumber k_{max} of the corresponding unstable merged mode (curve with filled circles in figure 24a). Better agreement is expected without the protected region used in our current experimental set-up. In our set-up, short-wave ripples originate on the residual film in between two pre-existing large-amplitude nonlinear Kapitza waves, which is not quite comparable to the primary flow underlying figure 24.

The most important feature of the new short-wave instability mode observed in figures 24(c) and 24(d) is that it displays negative wave speeds ($c_r < 0$ in figure 24d) in the range of unstable wavenumbers. And this property is endowed to the unstable merged mode in figure 24(b). In particular, the linear wave speed c_r for $Re_G = -6760$ (solid curve with open circles in figure 24b) is negative across the entire wavenumber span of the upward-travelling ripples observed in the corresponding experiment (vertical shaded magenta band in figure 24b). Moreover, the ripple wave speed estimated from our experiments (filled magenta circle with error bars in figure 24b) agrees quite well with the linear wave speed. Thus we are confident that the short-wave instability uncovered in figure 24 is at the origin of the upward-travelling ripples observed in our experiment of figure 10.

Upward travelling linear waves linked to the short-wave mode, or the unstable merged mode, do not necessarily require a negative liquid velocity. This is shown in figure 26(b), where we have plotted the primary-flow liquid velocity at the liquid–gas interface, $u_{L0}|_{y=h_0}$, in terms of Re_G for the liquid-side parameters from figure 24. Here, we confront our current confinement (solid curve with symbols, $H^\star = 13$ mm) with those of Kofman *et al.* (2017) (dot-dashed curve, $H^\star = 19$ mm) and Mergui *et al.* (2023) (dashed curve, $H^\star = 5$ mm). Focusing on the solid curve, where symbols mark $|Re_G|$ values from figures 24(b) and 24(d), we see that $u_{L0}|_{y=h_0}$ becomes negative far beyond the onset of the short-wave instability (between the square and circle in figure 26b). Thus the gas-induced linear short waves can travel upwards even though the liquid moves downwards across the entire film thickness h_0.

To characterize further the nature of the short-wave instability mode, figure 27 presents (normalized) profiles of the liquid-side (figure 27a) and gas-side (figure 27b) eigenfunctions, ϕ and ψ (see (4.13a,b)), for the most-amplified long-wave (red solid curves) and short-wave (blue dashed curves) instability modes at $Re_G = -5200$ (pentagons in figures 24a,c). We see that ϕ is maximal at the liquid–gas interface, $y = h_0$, for both the long-wave and short-wave modes. We may thus conclude that the short-wave mode is an interfacial mode, strengthening our assertion that it lies at the origin of the upward-travelling ripples observed in our experiments.
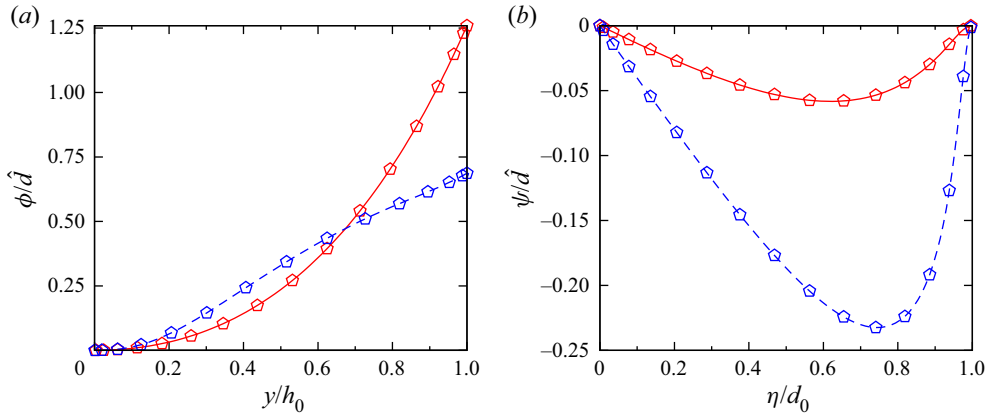
Figure 27. Eigenfunctions (4.13*a,b*) for different instability modes from figure 24. Turbulent counter-current gas flow: $Re_G = -5200$. Linearly most-amplified short-wave (dashed blue lines, $k = 12.8$) and long-wave (solid red lines, $k = 1.6$) instability modes. (*a*) Liquid film, ϕ; (*b*) gas layer, ψ.

Interestingly, the onset of the short-wave instability mode in figure 24(*c*), i.e. $Re_G = -5100$ (between crosses and pentagons), is very close to the AI limit of the Kapitza instability observed in figure 12, i.e. $Re_G^{AI} = -5115$. This may explain why flooding predictions based on the AI limit (Vellingiri *et al.* 2015) are reasonably good, even though AI does not seem to produce any dangerous events in our experiments and nonlinear WRIBL-LW computations.

7. Conclusion

We have studied the effect of a confined turbulent counter-current gas flow on the linear and nonlinear dynamics of a wavy falling liquid film, focusing on regimes beyond the absolute instability (AI) limit of the Kapitza instability. We have done this via experiments and numerical computations based on a new low-dimensional model, which we have introduced and validated here. This model captures accurately the gas-induced transition to AI as well as the nonlinear gas effect on travelling Kapitza waves. In addition, we have performed linear stability calculations based on the full Orr–Sommerfeld equations in the gas and the liquid.

From our investigation, we may draw the following conclusions.

(1) AI is not necessarily dangerous, i.e. no flooding events linked to Kapitza waves were observed even far beyond the AI limit. On the contrary, AI can act as an effective linear wave selection mechanism in a naturally evolving falling liquid film, leading to highly regular downward-travelling nonlinear waves, precluding dangerous coalescence events.

(2) Flooding is eventually triggered by upward-travelling ripples, which were discovered in the experiments of Kofman *et al.* (2017) and reproduced here. We find that these ripples result from a short-wave interfacial instability associated with a negative linear wave speed. As far as we know, this short-wave instability has not yet been reported in the literature. On the contrary, the instability was not found in several previous stability investigations of falling liquid films (Schmidt *et al.* 2016; Trifonov 2017). In these investigations, the counter-current gas flow was assumed laminar, even though the gas Reynolds number Re_G was increased far beyond the turbulence threshold. We may thus surmise that Reynolds stresses associated with gas-side turbulence are essential for

generating the short-wave instability, at least in the parameter range where ripples are observed experimentally.

(3) The onset of the short-wave instability coincides approximately with the AI limit of the long-wave Kapitza instability. This could explain why predictions of the flooding threshold based on the AI limit have been found to agree reasonably well with experiments (Vellingiri *et al.* 2015), even though the trends of these two thresholds with respect to the liquid Reynolds number are opposed.

(4) At larger counter-current gas flow rates, the short-wave instability mode merges with the long-wave Kapitza mode, leading to a sudden and drastic increase of the cut-off wavenumber. This may explain the sudden change in the θ trend of the neutral stability curves reported in figure 11 of Vellingiri *et al.* (2015), which we have reproduced in figure 29(*a*) based on our own computations.

(5) Absolute instability of the long-wave Kapitza mode and instability of the new short-wave mode can coincide in a certain parameter range (see figures 12(*a*) and 24(*c*)). It remains to be seen how downward-travelling long waves generated by AI interact/compete with upward-travelling ripples generated by the short-wave instability in a naturally evolving falling liquid film. Unravelling the interaction between these two wave types may be the key to understanding flooding in gas-sheared falling liquid films. In our current experiments, this could not be studied, as fixed-frequency saturated-amplitude nonlinear waves were allowed to develop in a protected region, before entering into contact with the counter-current gas flow. In this configuration, Kapitza waves are privileged until the growth rate of the merged instability mode (figure 24*a*) becomes dominant and upward-travelling ripples appear.

Conversely, computations with our current WRIBL-LW model cannot capture the new short-wave instability. Although this is a limitation of the model, it allowed us to show that the long-wave AI alone does not produce any catastrophic events. An interesting goal for future work is to extend our model to overcome this limitation. For this, the gas-side representation, which currently relies on an $O(\epsilon)$ long-wave approximation, needs to be improved. This will require relaxing our symmetry condition (3.13*b*). Velocimetry experiments similar to those of Cohen & Hanratty (1968) would allow to gauge the extent of asymmetry in the gas flow.

By contrast, our $O(\epsilon^2)$ liquid-side WRIBL representation is capable of capturing short waves, as evidenced by the precursory capillary ripples in figure 9, which have a smaller wavelength than the upward-travelling ripples. Also, our comparisons between WRIBL-OS and OS-OS linear stability calculations show good agreement (figure 6), including for the short-wave mode (figure 30).

Finally, a detailed study of the new short-wave instability is necessary, and we intend to pursue our work in this direction. For example, it should be verified whether the instability also occurs for the conditions studied by Trifonov (2017) and Schmidt *et al.* (2016). And the mechanism of the instability should be elucidated. For example, how does it compare to the Kelvin–Helmholtz instability and the generation of wind-driven waves?

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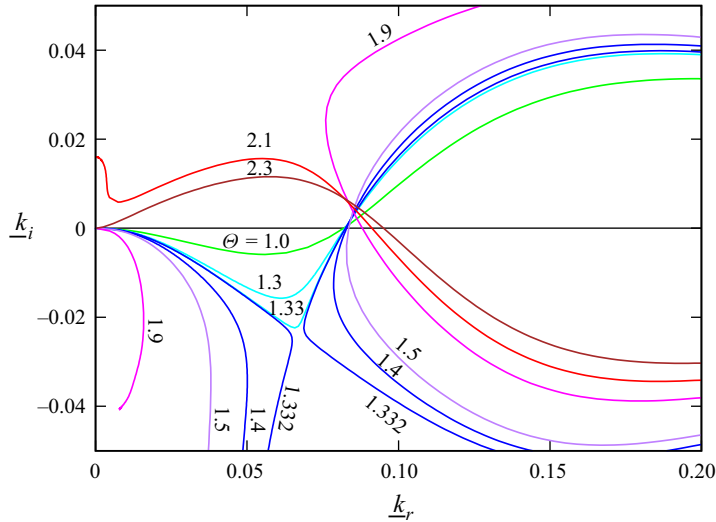Ⓘ Sophie Mergui https://orcid.org/0000-0002-9529-5133;

Figure 28. Validation of our WRIBL-OS approach (§ 4.1). Spatial linear stability predictions for parameters in figure 15 of Vellingiri *et al.* (2015): $Ka = 2000$ (methanol and helium in table 1), $\phi = 90°$, $\underline{Re}_0 = 3Re_L/\sin(\phi) = 10$, $H^\star = 30$ mm, $\Pi_\rho = 0$, (3.6a) truncated at $O(\epsilon)$. Quantities are scaled with $\mathcal{L} = h_0^\star$ and $\underline{\mathcal{U}} = h_0^{\star 2} g \sin(\phi)/(2\nu_L)$. The counter-current gas shear stress is quantified via $\Theta = \left|T_{G0}^\star\right|/(\mu_L \underline{\mathcal{U}}/\mathcal{L})$.

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Appendix A. Validation of WRIBL-OS and OS-OS approaches

In figure 28, we have used our WRIBL-OS approach from § 4.1 to reproduce the growth rate dispersion curves obtained from temporal linear stability analysis in figure 15 of Vellingiri *et al.* (2015), for a vertically falling liquid film sheared by an unconfined counter-current turbulent gas flow. To recover the formulation used in that reference, we have truncated our liquid-side WRIBL model (3.6a) at $O(\epsilon)$, set $\Pi_\rho = 0$, and increased $H^\star$ until it no longer affected our results. All quantities in figure 28 have been scaled with $\mathcal{L} = h_0^\star$ and $\underline{\mathcal{U}} = h_0^{\star 2} g \sin(\phi)/2/\nu_L$, according to Vellingiri *et al.* (2015). Thus results are directly comparable with data in figure 15 of that reference, exhibiting very good agreement.

In figure 29, we have used our OS-OS approach from § 4.2 to reproduce several temporal linear stability predictions from Vellingiri *et al.* (2015) and Schmidt *et al.* (2016). In figure 29(a), we have reproduced the neutral stability predictions in figure 11 of Vellingiri *et al.* (2015), where a vertically falling liquid film sheared by an unconfined turbulent counter-current gas flow was considered. Crosses correspond to our OS-OS prediction, and open circles to calculations of Vellingiri *et al.* (2015). In the same figure, we have also plotted predictions obtained from our WRIBL-OS approach (curves). To reproduce the unconfined configuration considered in Vellingiri *et al.* (2015), we have once again increased $H^\star$ until it no longer affected our results meaningfully.

Agreement between crosses and circles in figure 29(a) is good, except for data at $\Theta = \left|T_{G0}^\star\right|/(\mu_L \underline{\mathcal{U}}/\mathcal{L}) = 3$. This is where the trend of the cut-off wavenumber k in terms of the dimensionless gas shear stress Θ changes. We believe that this is the result of the mode merging that we have observed in § 6.2. At thresholds where the stability
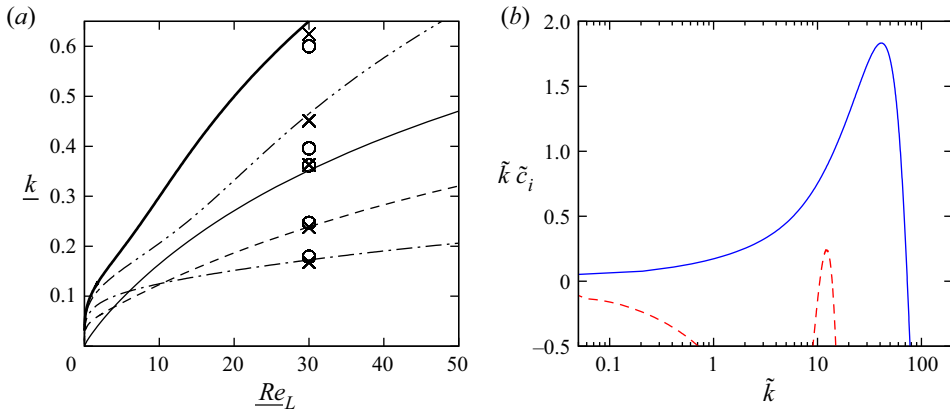
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Figure 29. Validation of our WRIBL-OS (§ 4.1) and OS-OS (§ 4.2) approaches. Temporal linear stability predictions for a gas-sheared vertically falling liquid film. (*a*) Neutral stability curves for parameters according to figure 11 in Vellingiri *et al.* (2015): $Ka = 2000$, $H^\star = 300$ mm. Crosses indicate OS-OS; solid lines indicate WRIBL-OS; open circles indicate data from Vellingiri *et al.* (2015). Thin solid line, $\Theta = 0$; dashed line, $\Theta = 1$; dot-dashed line, $\Theta = 2$; dot-dot-dashed line, $\Theta = 3$; thick solid line, $\Theta = 3.5$. Same scaling as in figure 28. (*b*) Growth rate dispersion curves for parameters according to figure 4(*e*) in Schmidt *et al.* (2016): $H^\star = 10$ mm, $\rho_L = 1000$ kg m^{-3}, $\mu_L = 0.5 \times 10^{-3}$ Pa s, $\rho_G = 1$ kg m^{-3}, $\mu_G = 1 \times 10^{-6}$ Pa s, $\sigma = 1$ mN m^{-1}, $\delta_L = h_0^\star/H^\star = 0.08$, $\widetilde{Fr} = \tilde{\mathcal{U}}/\sqrt{g\tilde{\mathcal{L}}} = 3$, $Re_L = 6166$, $Re_G = 48\,322$. Tildes indicate scaling with $\tilde{\mathcal{L}} = H^\star$ and $\tilde{\mathcal{U}} = [\partial_{x^\star} P_{G0}^\star H^\star/\rho_G]^{1/2}$. Solid blue line indicates long-wave Kapitza mode; dashed red line indicates short-wave Tollmien–Schlichting mode.

behaviour changes, large discrepancies between two calculations may occur as a result of small differences between the employed procedures. In particular, we have used a set of curvilinear coordinates different to that used by Vellingiri *et al.* (2015). We believe that this explains the discrepancy between the cross and circle for $\Theta = 3$.

Interestingly, we have observed that our OS-OS predictions in figure 29(*a*) change significantly when setting $\Pi_\rho = 0$ (not shown). This confirms our conclusion based on (5.5*a,b*) that P_G can affect stability even in the unconfined limit.

In figure 29(*b*), we have reproduced with our OS-OS approach the growth rate dispersion curves in figure 4(*e*) of Schmidt *et al.* (2016), where a vertically falling liquid film sheared by a confined laminar ($\tilde{l}_t = 0$ in (3.27) and (3.28)) counter-current gas flow was considered. All quantities have been scaled with $\tilde{\mathcal{L}} = H^\star$ and $\tilde{\mathcal{U}} = [\partial_{x^\star} P_{G0}^\star H^\star/\rho_G]^{1/2}$, according to Schmidt *et al.* (2016). Thus results are comparable directly with data in figure 4(*e*) of that reference, exhibiting very good agreement, for both the long-wave Kapitza mode (solid blue curve) and the Tollmien–Schlichting mode (dashed red curve).

Appendix B. Neutral stability bound based on (5.2)

In (5.2), we have introduced the first-order contribution c_1, arising in the long-wave expansion ($k \to 0$) of the linear wave speed c:

$$\left.\begin{aligned} c &= c_0 + k c_1 + O(k^2), \\ c_1 &= i\mathcal{R}. \end{aligned}\right\} \tag{B1}$$

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The neutral stability bound is given by $\mathcal{R} = 0$, and the solution for $\mathcal{R}$ obtained from our WRIBL-LW model (3.6) is

$$
\begin{aligned}
\mathcal{R} = {}& \frac{1}{3} \cos(\phi) \frac{Re_L}{Fr^2} h_0^3 \left\{ -1 + \frac{\Pi_\rho}{\Pi_u^2} \right\} \\
& + \frac{\sin^2(\phi)}{Fr^4} Re_L^3 \left\{ \frac{2}{15} h_0^6 + \frac{2}{5} \frac{\Pi_\rho^2}{\Pi_u^4} \frac{h_0^8}{d_0^2} + \frac{10}{21} \frac{\Pi_\rho}{\Pi_u^2} \frac{h_0^7}{d_0} \right\} \\
& + \Pi_\mu \frac{\sin(\phi)}{Fr^2} Re_L^2 T_{G0} \left\{ \frac{\Pi_\rho}{\Pi_u} \left[\frac{7}{24} \frac{h_0^6}{d_0} + \frac{4}{5} \frac{h_0^7}{d_0^2} \right] + \Pi_u \left[\frac{2}{15} h_0^5 + \frac{10}{21} \frac{h_0^6}{d_0} \right] \right\} \\
& + \Pi_\mu^2 \Pi_u^2 Re_L T_{G0}^2 \left\{ \frac{7}{24} \frac{h_0^5}{d_0} + \frac{2}{5} \frac{h_0^6}{d_0^2} \right\} \\
& - \Pi_\mu \Pi_\rho \frac{Re_L}{Re_G} \Pi_u^3 T_{G0} \, \partial_x P_{G0} \left\{ \frac{2}{15} h_0^5 + \frac{43}{56} \frac{h_0^6}{d_0} + \frac{4}{5} \frac{h_0^7}{d_0^2} \right\} \\
& - \frac{\sin(\phi)}{Fr^2} \frac{Re_L^3}{Re_G} \, \partial_x P_{G0} \left\{ \Pi_\rho^2 \left[\frac{10}{21} \frac{h_0^7}{d_0} + \frac{4}{5} \frac{h_0^8}{d_0^2} \right] + \Pi_\rho \Pi_u^2 \left[\frac{4}{15} h_0^6 + \frac{10}{21} \frac{h_0^7}{d_0} \right] \right\} \\
& + \frac{Re_L^3}{Re_G^2} \Pi_\rho^2 \Pi_u^2 \, \partial_x P_{G0}^2 \left\{ \frac{2}{15} h_0^6 + \frac{10}{21} \frac{h_0^7}{d_0} + \frac{2}{5} \frac{h_0^8}{d_0^2} \right\} \\
& + \frac{1}{2} \Pi_\mu \Pi_u \frac{h_0^2}{d_0} \, \partial_\eta U_1 \big|_{d_0} + \frac{1}{3} \Pi_\rho \Pi_u^2 Re_L \frac{h_0^3}{d_0} C_1,
\end{aligned}
\tag{B2}
$$

where C_1 and U_1 are obtained by solving (3.27) and (3.28). Solutions for C_1 and $\partial_\eta U_1 |_{d_0}$ in the laminar limit are given in (5.5a,b).

Appendix C. Accounting for derivatives of T_G and P_G in (3.6a)

We check to what extent the temporal and spatial derivatives of T_G and P_G, which appear in (3.6a) and which we have neglected in our WRIBL-LW and WRIBL-OS computations, play a role in the linear stability of a gas-sheared falling liquid film. Figure 30 presents linear stability predictions obtained with three approaches for conditions according to figure 24. Solid curves correspond to OS-OS calculations based on (4.20) and (4.21), dot-dashed curves to WRIBL-OS calculations based on (3.41), and dashed curves to WRIBL-OS calculations with account of the space and time derivatives of T_G and P_G in (3.6a).

According to this, both WRIBL approaches capture accurately the gas effect on the long-wave Kapitza instability mode (red curves in figure 30a), and accounting for the derivatives of T_G and P_G does not bear much benefit. By contrast, not surprisingly, the growth rate of the new short-wave mode is less well predicted by both WRIBL approaches (blue curves in figure 30a). Here, accounting for the derivatives of T_G and P_G (dashed blue curve) improves predictions at intermediate k, but the standard WRIBL-OS approach performs better at large k. Finally, both WRIBL approaches produced quite good predictions of the merged instability mode (figure 30b), whereby the standard WRIBL-OS approach behaves better.
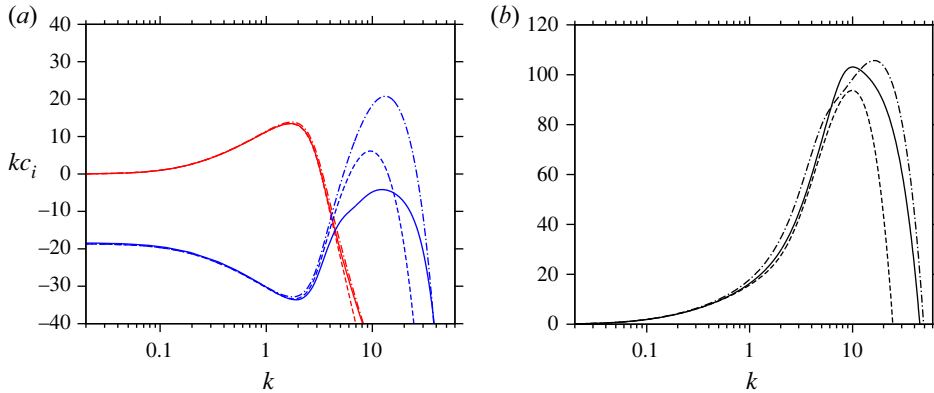
Figure 30. Accounting for temporal and spatial derivatives of T_G and P_G in (3.6a). Temporal linear stability predictions based on three approaches for conditions according to figure 24: $Ka = 3174$ (water and air I in table 1), $H^\star = 13$ mm, $\phi = 5°$, $Re_L = 43.1$. Dot-dashed lines indicate WRIBL-OS (3.41); solid lines indicate OS-OS (4.20) and (4.21); dashed lines indicate WRIBL-OS, including derivatives of T_G and P_G in (3.6a). (a) Here, $Re_G = -4700$. Red lines indicate long-wave Kapitza mode, blue lines indicate short-wave mode. (b) Here, $Re_G = -6760$, merged mode.

In summary, accounting for the derivatives of T_G and P_G does not meaningfully improve predictions at low wavenumbers k. And at large k, it may even deteriorate them. This is because the WRIBL-OS description becomes unbalanced at large k, as a result of truncating the governing equations at different orders in the liquid (truncate at $O(\epsilon^2)$ and neglect $O(\epsilon^2 Re_L)$ inertial corrections) and gas (full governing equations). Retaining supplementary terms in the governing equations has been shown to deteriorate long-wave model predictions in other configurations (Oron & Gottlieb 2004; Thompson *et al.* 2019). It is interesting to note that both the new short-wave (figure 30a) and merged (figure 30b) instability modes can be captured by the WRIBL approach.

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