



## PERTURBATION ANALYSIS FOR CONTINUOUS-TIME MARKOV CHAINS IN A WEAK SENSE

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### Abstract

By the technique of augmented truncations, we obtain the perturbation bounds on the distance of the finite-time state distributions of two continuous-time Markov chains (CTMCs) in a type of weaker norm than the  $V$ -norm. We derive the estimates for strongly and exponentially ergodic CTMCs. In particular, we apply these results to get the bounds for CTMCs satisfying Doeblin or stochastically monotone conditions. Some examples are presented to illustrate the limitation of the  $V$ -norm in perturbation analysis and to show the quality of the weak norm.

*Keywords:* Weak norm; augmented truncation; ergodicity coefficient; strong ergodicity; exponential ergodicity

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### 1. Introduction

Let  $X = \{X_t, t \in \mathbb{R}_+\}$  be an irreducible continuous-time Markov chain (CTMC) on state space  $E = \mathbb{Z}_+$  with transition function  $P^t(i, j)$  and regular  $q$ -matrix  $Q = (q(i, j))$ . Let  $X$  be positive recurrent with the unique invariant distribution  $\pi$ . Suppose that  $X$  is perturbed to another irreducible and regular CTMC  $\tilde{X} = \{\tilde{X}_t, t \in \mathbb{R}_+\}$  with transition function  $\tilde{P}^t(i, j)$  and  $q$ -matrix  $\tilde{Q} = (\tilde{q}(i, j))$ . Denote by  $p^t$  and  $\tilde{p}^t$  the state probability vectors of  $X_t$  and  $\tilde{X}_t$ , respectively. In particular, when  $t = 0$ , they represent the initial distributions. Let  $\Delta = \tilde{Q} - Q$  be the perturbation of the  $q$ -matrix. As is shown in [14], a small perturbation may result in a big change in the stability. Hence, it is meaningful to find sufficient conditions that guarantee the stability and, moreover, obtain quantitative bounds on the difference between two chains when the stability is robust.

For discrete-time Markov chains (DTMCs), perturbation bounds with respect to the  $V$ -norms (as defined in Section 2) were developed in the seminal work of [10, 11]. Recent advances in this direction can be found in [1, 13, 23, 24]. For CTMCs, the  $V$ -normwise perturbation bounds have also received recent attention, see [5, 9, 14, 15, 19]. However, as we will see, we have to be careful to deal with a CTMC with an unbounded generator for which the  $V$ -normwise results might be invalid. For instance, consider the following linear birth and death process with catastrophes (see [25]) on state space  $E = \mathbb{Z}_+$ , whose  $q$ -matrix is given by

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$$Q = \begin{pmatrix} -b & b & 0 & 0 & \dots \\ a & -(a+b) & b & 0 & \dots \\ d_2 & 2a & -2(a+b) - d_2 & 2b & \dots \\ d_3 & 0 & 3a & -3(a+b) - d_3 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}. \tag{1}$$

The model parameters are usually estimated based on statistical data, which naturally causes a small deviation from the true value. Hence, it is reasonable to assume that there exist perturbations imposed on the parameters. Specifically, we assume that the parameters  $d_i$ ,  $a$ , and  $b$  in (1) are perturbed to be  $d_i + \varepsilon$ ,  $a + \varepsilon$ , and  $b + \varepsilon$ , respectively. As a consequence, the perturbation matrix  $\Delta(\varepsilon)$ , given by

$$\Delta(\varepsilon) = \begin{pmatrix} -\varepsilon & \varepsilon & 0 & 0 & \dots \\ \varepsilon & -2\varepsilon & \varepsilon & 0 & \dots \\ \varepsilon & 2\varepsilon & -5\varepsilon & 2\varepsilon & \dots \\ \varepsilon & 0 & 3\varepsilon & -7\varepsilon & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}, \tag{2}$$

is unbounded. Observe that, for any finite function  $V: E \rightarrow [1, \infty)$ ,

$$\|\Delta(\varepsilon)\|_V \geq \max_{i \in E} \frac{(2i + 1)\varepsilon V(i)}{V(i)} = \infty.$$

This shows that the  $V$ -normwise perturbation bound (see [14])

$$\|\tilde{\pi} - \pi\|_V \leq C(Q, \tilde{Q}) \|\Delta(\varepsilon)\|_V,$$

where  $C(Q, \tilde{Q})$  is known as a positive condition number, becomes uninformative since its upper bound is always  $\infty$ . From this example, we see that the  $V$ -norm may be too restrictive to characterize unbounded perturbation problems.

For perturbation analysis of DTMCs in a weak sense, [27] first developed a perturbation theory for geometrically ergodic Markov chains which requires controlling perturbations of iterated transition kernels in a weak  $1, V$ -norm (see Section 2 for the detailed definition). Subsequently, [6] obtained explicit bounds on the stationary distributions between two Markov chains via weak perturbation theory. [26] derived the bounds on finite-step state distributions by using an approach based on drift conditions and ergodic convergence rate. [20] further refined and extended this result and applied it to the Monte Carlo within Metropolis algorithms. We aim to develop perturbation bounds on  $\|\tilde{p}^t - p^t\|_1$  in terms of the perturbation  $\Delta$  in the weak  $1, V$ -norm for CTMCs.

It is worth noting that the generators of CTMCs can be unbounded, like (1) mentioned above, for which it is usually infeasible to extend the results of DTMCs to the continuous-time case by the technique of uniformized chains or  $h$ -skeleton chains. Using a uniformized chain introduces the quantity  $\sup_i |q(i, i)|$  which is infinite for unbounded CTMCs, while using  $h$ -skeleton chains will involve a relation between  $\tilde{P}^h - P^h$  and  $\tilde{Q} - Q$  which cannot be

determined explicitly. In this paper, we develop an approach that combines the ergodicity coefficients, drift functions, and the technique of augmented truncations to investigate the perturbation in the weak sense.

This paper is organized as follows. Section 2 contains some preliminaries, such as the definitions of  $V$ -norms and  $1, V$ -norms, and the properties of ergodicity coefficients. In Section 3, we obtain the perturbation bounds for strongly ergodic CTMCs, in particular for those satisfying Doeblin or stochastically monotone conditions. In Section 4, we present the estimates for exponentially ergodic CTMCs, and further apply our results to stochastically monotone CTMCs. Finally, some conclusions are listed in Section 5.

### 2. Preliminaries

For a finite measure  $\mu$  and  $V: E \rightarrow [1, \infty)$ , let  $\mu(V) = \sum_{i \in E} \mu(i)V(i)$  and define its  $V$ -norm to be  $\|\mu\|_V = \sum_{i \in E} |\mu(i)|V(i)$ . The  $V$ -norm for any matrix  $R = (R(i, j))$  on  $E \times E$  is given by

$$\|R\|_V := \sup_{i \in E} \frac{1}{V(i)} \sum_{j \in E} |R(i, j)|V(j).$$

When  $V \equiv 1$ , we replace the subscript  $V$  in  $\|\mu\|_V$  and  $\|R\|_V$  by 1. Note that  $\|\mu R\|_V \leq \|\mu\|_V \|R\|_V$  and  $\|AB\|_V \leq \|A\|_V \|B\|_V$  for any pair of matrices  $A$  and  $B$  on  $E \times E$ . In addition, we define the weak  $1, V$ -norm (see [3]) for any matrix  $R$  by

$$\|R\|_{1, V} := \sup_{i \in E} \frac{1}{V(i)} \sum_{j \in E} |R(i, j)|.$$

The  $V$ -norm ergodicity coefficient of the transition matrix  $P^t$  is defined by

$$\tau_V(P^t) := \sup_{i, j \in E, i \neq j} \frac{\|P^t(i, \cdot) - P^t(j, \cdot)\|_V}{V(i) + V(j)},$$

see [7, 12, 18]. When  $V \equiv 1$ ,  $\tau_1(P^t)$  is the classical Dobrushin coefficient. [18, Proposition 2.1] gives some properties of  $V$ -norm ergodicity coefficients. Based on their results, we can easily obtain the following lemma on the contractivity of  $V$ -norm ergodicity coefficients.

**Lemma 1.** *Let  $\mu, \nu$  be two measures on  $E$  satisfying  $(\mu - \nu)\mathbf{1} = 0$  and  $\|\mu - \nu\|_V < \infty$ , where  $\mathbf{1}$  is a column vector of 1s. For the transition matrix  $P^t$ ,*

$$\|\mu P^t - \nu P^t\|_V \leq \tau_V(P^t) \|\mu - \nu\|_V.$$

*Proof.* Let  $R = \mathbf{1}(\mu - \nu)$ . Since  $(\mu - \nu)\mathbf{1} = 0$  and  $\|\mu - \nu\|_V < \infty$ , we have

$$\sum_{j \in E} R(i, j) = \sum_{j \in E} (\mu(j) - \nu(j)) = 0 \quad \text{for all } i \in E,$$

and

$$\|R\|_V = \sup_{i \in E} \frac{\|R(i, \cdot)\|_V}{V(i)} = \frac{\|\mu - \nu\|_V}{\inf_{i \in E} V(i)} < \infty.$$

It follows from [18, Proposition 2.1(iii)] that

$$\|RP^t\|_V = \frac{\|(\mu - \nu)P^t\|_V}{\inf_{i \in E} V(i)} \leq \tau_V(P^t)\|R\|_V = \frac{\tau_V(P^t)\|\mu - \nu\|_V}{\inf_{i \in E} V(i)}.$$

The assertion follows immediately by the fact that  $\inf_{i \in E} V(i) > 0$ . □

In the following, we present the definitions of strong and exponential ergodicity.

**Definition 1.**  $P^t$  is called strongly ergodic if there exist positive constants  $\rho < 1$  and  $C < \infty$  such that, for any  $i$  and  $t$ ,

$$\|P^t(i, \cdot) - \pi\|_1 \leq C\rho^t. \tag{3}$$

**Definition 2.**  $P^t$  is called exponentially ergodic if there exists a positive constant  $\rho < 1$  and a finite function  $C: E \rightarrow (0, \infty)$  such that, for any  $i$  and  $t$ ,

$$\|P^t(i, \cdot) - \pi\|_1 \leq C(i)\rho^t.$$

**Definition 3.**  $P^t$  is called  $V$ -uniformly ergodic if there exist positive constants  $\rho < 1$ ,  $C < \infty$  and a finite function  $V: E \rightarrow [1, \infty)$  such that, for any  $i$  and  $t$ ,

$$\|P^t(i, \cdot) - \pi\|_V \leq CV(i)\rho^t.$$

For irreducible CTMCs, it is well known that exponential ergodicity is equivalent to  $V$ -uniform ergodicity [4, Theorem 3.2]. Observe that the  $V$ -uniform ergodicity of  $P^t$  implies a suitable upper bound on its  $V$ -norm ergodicity coefficient  $\tau_V(P^t)$ . Applying arguments similar to [26, Lemma 3.2], we have the following statement.

**Lemma 2.** *If  $P^t$  is  $V$ -uniformly ergodic, then  $\tau_V(P^t) \leq C\rho^t$ .*

When  $V \equiv 1$ ,  $\tau_V(P^t) = \tau_1(P^t)$  and hence Lemma 2 generalizes the classical Dobrushin coefficient. That is, if  $P^t$  is strongly ergodic, then  $\tau_1(P^t) \leq C\rho^t$ .

### 3. Perturbation analysis for strongly ergodic CTMCs

In this section, we obtain perturbation bounds for strongly ergodic CTMCs by the technique of augmented truncations. First, we obtain the results for finite state spaces with an approach based on ergodicity coefficients and drift functions. Then we derive those of infinitely countable state spaces by letting the truncation size tend to infinity. In particular, the results are applied to get the explicit perturbation bounds for CTMCs satisfying Doeblin or stochastically monotone conditions. Some examples are presented to illustrate our results.

Our results in this section mainly rely on the following two assumptions.

**Assumption 1.**  $P^t$  is strongly ergodic with positive constants  $\rho < 1$  and  $C < \infty$ .

**Assumption 2.** There exists a finite function  $V: E \rightarrow [1, \infty)$  and positive constants  $\delta$  and  $L < \infty$  such that  $(QV)(i) \leq -\delta V(i) + L$ .

#### 3.1. Finite state spaces

Let  $E_n = \{0, 1, 2, \dots, n\}$ ,  $n \geq 0$ . We are now in a position to present the perturbation bounds for CTMCs on finite state space  $E_n$ .

**Proposition 1.** *Let  $X$  be an irreducible CTMC on finite state space  $E_n$ . Suppose that Assumptions 1 and 2 hold. Then we have*

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_1 + \frac{C\kappa \|\Delta\|_{1,V}}{-\log \rho},$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

*Proof.* The vectors  $\tilde{p}^t$  and  $p^t$  satisfy the forward Kolmogorov equations

$$\frac{d\tilde{p}^t}{dt} = \tilde{p}^t \tilde{Q}, \quad \frac{dp^t}{dt} = p^t Q.$$

Therefore, the vector  $z_t = \tilde{p}^t - p^t$  is the solution to the initial-value problem

$$\frac{dz_t}{dt} = z_t Q + \tilde{p}^t (\tilde{Q} - Q), \quad z_0 = \tilde{p}^0 - p^0,$$

which implies that  $\tilde{p}^t - p^t = (\tilde{p}^0 - p^0)P^t + \int_0^t \tilde{p}^{t-u}(\tilde{Q} - Q)P^u \, du$ , and

$$\|\tilde{p}^t - p^t\|_1 \leq \|(\tilde{p}^0 - p^0)P^t\|_1 + \int_0^t \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^u\|_1 \, du;$$

see also the proof of [22, Theorem 2.1]. Since the state space  $E_n$  is finite and  $(\tilde{p}^0 - p^0)\mathbf{1} = 0$ ,  $\tilde{p}^{t-u}(\tilde{Q} - Q)\mathbf{1} = 0$ , it follows from Lemmas 1 and 2 that

$$\begin{aligned} \|(\tilde{p}^0 - p^0)P^t\|_1 &\leq \|\tilde{p}^0 - p^0\|_1 \cdot \tau_1(P^t) \leq C\rho^t \|\tilde{p}^0 - p^0\|_1, \\ \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^u\|_1 &\leq \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_1 \tau_1(P^u). \end{aligned}$$

We also have

$$\begin{aligned} \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_1 &= \sum_{j \in E_n} \left| \sum_{i \in E_n} \tilde{p}^{t-u}(i)(\tilde{q}(i, j) - q(i, j)) \right| \\ &\leq \sum_{i \in E_n} \sum_{j \in E_n} \tilde{p}^{t-u}(i) |\tilde{q}(i, j) - q(i, j)| \\ &= \sum_{i \in E_n} \tilde{p}^{t-u}(i) \|\tilde{Q}(i, \cdot) - Q(i, \cdot)\|_1 \\ &\leq \|\Delta\|_{1,V} \sum_{i \in E_n} \tilde{p}^{t-u}(i)V(i). \end{aligned}$$

Moreover, since  $\tilde{Q}$  satisfies the drift condition  $\tilde{Q}V \leq -\delta V + L\mathbf{1}$ , we have

$$\tilde{Q}^2 V = \tilde{Q}(\tilde{Q}V) \leq (-\delta)\tilde{Q}V + L\tilde{Q}\mathbf{1} = (-\delta)\tilde{Q}V.$$

Using an induction argument yields

$$\tilde{Q}^s V \leq (-\delta)^{s-1} \tilde{Q}V \leq (-\delta)^s V + (-\delta)^{s-1} L\mathbf{1}, \quad s \geq 1.$$

From this inequality, for  $t - u \geq 0$  we can obtain

$$\begin{aligned}
 \sum_{i \in E_n} \tilde{p}^{t-u}(i)V(i) &= \sum_{i \in E_n} \tilde{p}^0 e^{\tilde{Q}(t-u)}(i)V(i) \\
 &= \sum_{i \in E_n} \sum_{s=0}^{\infty} \frac{(t-u)^s}{s!} \sum_{j \in E_n} \tilde{p}^0(j)\tilde{Q}^s(j, i)V(i) \\
 &= \sum_{s=0}^{\infty} \frac{(t-u)^s}{s!} \sum_{j \in E_n} \sum_{i \in E_n} \tilde{p}^0(j)\tilde{Q}^s(j, i)V(i) \\
 &= \sum_{s=1}^{\infty} \frac{(t-u)^s}{s!} \sum_{j \in E_n} \tilde{p}^0(j)\tilde{Q}^s V(j) + \tilde{p}^0(V) \\
 &\leq \sum_{s=1}^{\infty} \frac{(t-u)^s}{s!} \sum_{j \in E_n} \tilde{p}^0(j)((-\delta)^s V(j) + (-\delta)^{s-1}L) + \tilde{p}^0(V) \\
 &= e^{-\delta(t-u)}\tilde{p}^0(V) + (1 - e^{-\delta(t-u)})\frac{L}{\delta} \\
 &\leq \max\{\tilde{p}^0(V), L/\delta\} = \kappa.
 \end{aligned}
 \tag{4}$$

Based on these analyses,  $\|\tilde{p}^t - p^t\|_1 \leq C\rho^t\|\tilde{p}^0 - p^0\|_1 + \kappa\|\Delta\|_{1,V} \int_0^t \tau_1(P^u) du$ . By Lemma 2 we have

$$\int_0^t \tau_1(P^u) du \leq C \int_0^t \rho^u du = \frac{C(1 - \rho^t)}{-\log \rho} \leq \frac{C}{-\log \rho},$$

from which we can finally obtain

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t\|\tilde{p}^0 - p^0\|_1 + \frac{C\kappa\|\Delta\|_{1,V}}{-\log \rho}.$$

Thus, the proof is finished. □

**Remark 1.** This result is parallel to [26, Theorem 3.1] for DTMCs in the case of degenerating the Wasserstein distance to the total variation norm, which can also be derived by the technique of uniformization.

### 3.2. Infinitely countable state spaces

In the following we are going to obtain the bounds for strongly ergodic CTMCs on infinitely countable state spaces  $E = \mathbb{Z}_+$  by the technique of augmented truncations. For any  $n \geq 1$ , let  ${}_{(n)}Q$  be the  $(n + 1) \times (n + 1)$  northwest corner truncation of  $Q$ . For any  $0 \leq h \leq n$ , we denote the  $(h + 1)$ th-column augmentation of  ${}_{(n)}Q$  by  ${}_{(n,h)}Q = ({}_{(n,h)}q(i, j), i, j \in E_n)$ , where

$${}_{(n,h)}q(i, j) = q(i, j) + I_{\{h\}}(j) \cdot \sum_{k \notin E_n} q(i, k) \quad \text{for } i, j \in E_n,$$

with the indicator function

$$I_{\{h\}}(j) = \begin{cases} 1 & \text{if } j = h, \\ 0 & \text{otherwise.} \end{cases}$$

Let  ${}_{(n,h)}P^t(i, j)$  be the minimal transition function of  ${}_{(n,h)}Q$ . From the special construction, the state  $h$  can be reached from every other state in  $E_n$ . Hence,  ${}_{(n,h)}Q$  has a unique invariant distribution  ${}_{(n,h)}\pi$ . Let  ${}_{(n)}p^0 = ({}_{(n)}p^0(i), i \in E_n)$ , where

$${}_{(n)}p^0(i) = \frac{p^0(i)}{\sum_{j=0}^n p^0(j)} \quad \text{for } i \in E_n,$$

be the initial distribution of  ${}_{(n,h)}Q$ , then the state probability vector  ${}_{(n,h)}p^t = {}_{(n)}p^0 {}_{(n,h)}P^t$ .

To present Theorem 1, we need the following lemma, which includes a simple fact about the augmented truncation. For a function  $V$  on  $E$ , let  $V_n := (V(i), i \in E_n)$  be its corresponding function on  $E_n$ .

**Lemma 3.** *If  $\tilde{Q}$  satisfies Assumption 2 with a nondecreasing function  $V$ , then its augmented truncation  ${}_{(n,h)}\tilde{Q}$  also satisfies it with function  $V_n$  for any  $n$ .*

*Proof.* Since  $V$  is nondecreasing, we have

$$\begin{aligned} \sum_{j \in E_n} {}_{(n,h)}\tilde{q}(i, j)V_n(j) &= \sum_{j \leq n, j \neq h} \tilde{q}(i, j)V(j) + \left( \tilde{q}(i, h) + \sum_{j > n} \tilde{q}(i, j) \right) V(h) \\ &\leq \sum_{j \in E} \tilde{q}(i, j)V(j) \quad \text{for any } n \geq 1 \text{ and } i \in E_n, \end{aligned}$$

which yields the assertion immediately. □

**Theorem 1.** *Let  $X$  be an irreducible CTMC on state space  $E = \mathbb{Z}_+$ . For a large enough integer  $N$  such that  $N \geq h$ , assume that  $\{{}_{(n,h)}P^t, n \geq N\}$  uniformly satisfies Assumption 1, i.e. there exist positive constants  $\rho < 1$  and  $C < \infty$  such that, for any  $i, t$ , and  $n \geq N$ ,  $\|{}_{(n,h)}P^t(i, \cdot) - {}_{(n,h)}\pi\|_1 \leq C\rho^t$ . Moreover, suppose that Assumption 2 holds for a nondecreasing function  $V$ . Then we have*

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_1 + \frac{C\kappa \|\Delta\|_{1,V}}{-\log \rho},$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

*Proof.* Denote by  ${}_{(n,h)}Q_* = ({}_{(n,h)}q_*(i, j), i, j \in E)$  the zero-padded matrix of  ${}_{(n,h)}Q$ . That is,

$${}_{(n,h)}q_*(i, j) = \begin{cases} {}_{(n,h)}q(i, j) & \text{if } i, j \in E_n, \\ 0 & \text{otherwise.} \end{cases}$$

Let  ${}_{(n,h)}P_*^t(i, j)$  be its minimal transition function and  ${}_{(n,h)}p_*^t = {}_{(n)}p_*^0 {}_{(n,h)}P_*^t$ , where  ${}_{(n)}p_*^0$  is the zero-padded vector of  ${}_{(n)}p^0$ . Similarly, we denote by  ${}_{(n)}Q_*$  the zero-padded matrix of  ${}_{(n)}Q$ . Let  ${}_{(n)}P_*^t$  be the transition function of  ${}_{(n)}Q_*$  and  ${}_{(n)}p_*^t = {}_{(n)}p_*^0 {}_{(n)}P_*^t$ . By the triangle inequality, for any  $n$ ,

$$\|\tilde{p}^t - p^t\|_1 \leq \|\tilde{p}^t - {}_{(n,h)}\tilde{p}_*^t\|_1 + \|p^t - {}_{(n,h)}p_*^t\|_1 + \|{}_{(n,h)}\tilde{p}_*^t - {}_{(n,h)}p_*^t\|_1. \tag{5}$$

The following argument parallels the proof of [4, Theorem 2.1], which states that

$${}_{(n)}P_*^t(i, j) \leq {}_{(n,h)}P_*^t(i, j) \leq {}_{(n)}P_*^t(i, j) + f_n^t(i)$$

with  $f_n^t(i) = 1 - \sum_{k=0}^n {}_{(n)}P_*^t(i, k)$ . It follows that

$${}_{(n)}P_*^t(j) \leq {}_{(n,h)}P_*^t(j) \leq {}_{(n)}P_*^t(j) + \sum_{i=0}^{\infty} {}_{(n)}P_*^0(i) f_n^t(i) \cdot I_{E_n}(i). \tag{6}$$

From [2, Proposition 2.2.14], we know that  ${}_{(n)}P_*^t(i, j) \uparrow P^t(i, j)$  as  $n \rightarrow \infty$  for all  $i, j \in E$  and  $t \geq 0$ . Applying the monotone convergence theorem shows that

$$\begin{aligned} \lim_{n \rightarrow \infty} {}_{(n)}P_*^t(j) &= \lim_{n \rightarrow \infty} \frac{1}{\sum_{j=0}^n P^0(j)} \sum_{i=0}^{\infty} P^0(i) {}_{(n)}P_*^t(i, j) \cdot I_{E_n}(i) \\ &= \sum_{i=0}^{\infty} \lim_{n \rightarrow \infty} P^0(i) {}_{(n)}P_*^t(i, j) \cdot I_{E_n}(i) = P^t(j), \\ \lim_{n \rightarrow \infty} \sum_{i=0}^{\infty} {}_{(n)}P_*^0(i) f_n^t(i) \cdot I_{E_n}(i) &= \lim_{n \rightarrow \infty} \frac{1}{\sum_{j=0}^n P^0(j)} \sum_{i=0}^{\infty} P^0(i) \left( 1 - \sum_{k=0}^n {}_{(n)}P_*^t(i, k) \right) \cdot I_{E_n}(i) \\ &= 1 - \sum_{i=0}^{\infty} \lim_{n \rightarrow \infty} P^0(i) \left( \sum_{k=0}^n {}_{(n)}P_*^t(i, k) \right) \cdot I_{E_n}(i) = 0. \end{aligned}$$

Taking limits in  $n$  on both sides of (6), we obtain  $\lim_{n \rightarrow \infty} {}_{(n,h)}P_*^t(j) = P^t(j)$ . This, together with the fact that  $|a| = 2a^+ - a$ , where  $a^+$  is the positive part of  $a$ , yields

$$\begin{aligned} \lim_{n \rightarrow \infty} \|P^t - {}_{(n,h)}P_*^t\|_1 &= \lim_{n \rightarrow \infty} \sum_{j \in E} |P^t(j) - {}_{(n,h)}P_*^t(j)| \\ &= \lim_{n \rightarrow \infty} \left( 2 \sum_{j \in E} [P^t(j) - {}_{(n,h)}P_*^t(j)]^+ - \sum_{j \in E} [P^t(j) - {}_{(n,h)}P_*^t(j)] \right) \\ &= 2 \lim_{n \rightarrow \infty} \sum_{j \in E} [P^t(j) - {}_{(n,h)}P_*^t(j)]^+ \\ &= 2 \sum_{j \in E} \lim_{n \rightarrow \infty} [P^t(j) - {}_{(n,h)}P_*^t(j)]^+ = 0, \end{aligned}$$

where the penultimate equality follows from the dominated convergence theorem and the fact that  $[P^t(j) - {}_{(n,h)}P_*^t(j)]^+ \leq P^t(j)$  and  $\sum_{j \in E} P^t(j) = 1$ . Using similar arguments also gives

$$\lim_{n \rightarrow \infty} \|\tilde{P}^t - {}_{(n,h)}\tilde{P}_*^t\|_1 = 0, \quad \lim_{n \rightarrow \infty} \|{}_{(n)}\tilde{P}_*^0 - {}_{(n)}P_*^0\|_1 = \|\tilde{P}^0 - P^0\|_1. \tag{7}$$

The next step is to figure out the limit of  $\|{}_{(n,h)}\tilde{P}_*^t - {}_{(n,h)}P_*^t\|_1$ . Observe that

$$\|{}_{(n,h)}\tilde{P}_*^t - {}_{(n,h)}P_*^t\|_1 = \|{}_{(n,h)}\tilde{P}^t - {}_{(n,h)}P^t\|_1.$$



Let

$$\|_{(n)}\Delta\|_{1,V} = \sup_{i \in E_n} \frac{\|_{(n,h)}\tilde{Q}(i, \cdot) -_{(n,h)}Q(i, \cdot)\|_1}{V(i)}, \quad (n)\kappa = \max \left\{ {}_{(n)}\tilde{p}^0(V_n), \frac{L}{\delta} \right\}.$$

Since  $_{(n,h)}P^t$  is strongly ergodic for any  $n$  and Assumption 2 holds, it follows from Proposition 1 and Lemma 3 that

$$\|_{(n,h)}\tilde{p}^t -_{(n,h)}p^t\|_1 \leq C\rho^t \|_{(n)}\tilde{p}^0 -_{(n)}p^0\|_1 + \frac{C(n)\kappa \|_{(n)}\Delta\|_{1,V}}{-\log \rho}.$$

Note that we have, for  $i \neq h$ ,

$$\begin{aligned} & \|_{(n,h)}\tilde{Q}(i, \cdot) -_{(n,h)}Q(i, \cdot)\|_1 \\ &= \sum_{j \in E_n} |_{(n,h)}\tilde{q}(i, j) -_{(n,h)}q(i, j)| \\ &= \sum_{j \leq n, j \neq h} |\tilde{q}(i, j) - q(i, j)| + \left| (\tilde{q}(i, h) - q(i, h)) + \sum_{k > n} (\tilde{q}(i, k) - q(i, k)) \right| \\ &\leq \sum_{j \leq n+1, j \neq h} |\tilde{q}(i, j) - q(i, j)| + \left| (\tilde{q}(i, h) - q(i, h)) + \sum_{k > n+1} (\tilde{q}(i, k) - q(i, k)) \right| \\ &= \|_{(n+1,h)}\tilde{Q}(i, \cdot) -_{(n+1,h)}Q(i, \cdot)\|_1, \end{aligned}$$

and for  $i = h$ ,

$$\begin{aligned} & \|_{(n,h)}\tilde{Q}(h, \cdot) -_{(n,h)}Q(h, \cdot)\|_1 \\ &= \sum_{j \leq n, j \neq h} |\tilde{q}(h, j) - q(h, j)| + \left| - \sum_{j \leq n, j \neq h} (\tilde{q}(h, j) - q(h, j)) \right| \\ &\leq \sum_{j \leq n, j \neq h} |\tilde{q}(h, j) - q(h, j)| + \left| - \sum_{j \leq n+1, j \neq h} (\tilde{q}(h, j) - q(h, j)) \right| + |\tilde{q}(h, n+1) - q(h, n+1)| \\ &= \sum_{j \leq n+1, j \neq h} |\tilde{q}(h, j) - q(h, j)| + \left| - \sum_{j \leq n+1, j \neq h} (\tilde{q}(h, j) - q(h, j)) \right| \\ &= \|_{(n+1,h)}\tilde{Q}(h, \cdot) -_{(n+1,h)}Q(h, \cdot)\|_1. \end{aligned}$$

This, together with the assumption that  $V$  is nondecreasing, implies that both  $\|_{(n)}\Delta\|_{1,V}$  and  $_{(n)}\tilde{p}^0(V_n)$  increase monotonously with  $n$  and  $\|_{(n)}\Delta\|_{1,V} \leq \|\Delta\|_{1,V}$ ,  $(n)\kappa \leq \kappa$ . Applying the monotone convergence theorem gives  $\lim_{n \rightarrow \infty} \|_{(n)}\Delta\|_{1,V} = \|\Delta\|_{1,V}$  and  $\lim_{n \rightarrow \infty} (n)\kappa = \kappa$ . By this fact and (7), we have

$$\lim_{n \rightarrow \infty} \|_{(n,h)}\tilde{p}^t -_{(n,h)}p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_1 + \frac{C\kappa \|\Delta\|_{1,V}}{-\log \rho}.$$

Finally, we complete the proof by taking the limit of both sides of (5). □

If  $\tilde{P}$  has a stationary distribution, say  $\tilde{\pi}$ , as a consequence of the previous theorem, we can easily obtain a bound on the difference between  $\pi$  and  $\tilde{\pi}$ .

**Corollary 1.** *Assume that the conditions in Theorem 1 hold. Then we have*

$$\|\tilde{\pi} - \pi\|_1 \leq \frac{C\kappa' \|\Delta\|_{1,V}}{-\log \rho},$$

where  $\kappa' = \max\{\tilde{\pi}(V), L/\delta\}$ .

*Proof.* With  $p^0 = \pi, \tilde{p}^0 = \tilde{\pi}$ , and by letting  $t \rightarrow \infty$ , we obtain the statement immediately by Theorem 1. □

### 3.3. Explicit results for particular CTMCs

Based on the technique of augmented truncations, our arguments inevitably require that  ${}_{(n,h)}P^t$  uniformly satisfies Assumption 1, i.e. for any  $n \geq 1, {}_{(n,h)}P^t$  satisfies (3) for the same constants  $C$  and  $\rho$ . There are two cases where we can easily verify this condition: CTMCs satisfying Doeblin conditions and stochastically monotone CTMCs. Explicit results for these two cases are given below.

**3.3.1. CTMCs satisfying Doeblin conditions** One of the most significant conditions for ergodicity of Markov chains is Doeblin’s condition.  $Q$  is said to satisfy the Doeblin condition if there exists a finite set  $D \subseteq E$  satisfying  $\sum_{j \in D} q(i, j) \geq \alpha > 0$  for all  $i \in T := E \setminus D$ . It is worth noting that we can estimate the strongly ergodic rate if  $D$  is a single-point set [8, p. 913]. Here we give our proof.

**Lemma 4.** *Suppose  $Q$  satisfies the Doeblin condition with single-point set  $D = \{m\}$  and  $\alpha > 0$ . Then the CTMC  $X$  is strongly ergodic and  $\|P^t(i, \cdot) - \pi\|_1 \leq 2e^{-\alpha t}$ .*

*Proof.* Since  $x > 1 - e^{-x}$  for any  $x > 0$  and  $P^t(i, m) = q(i, m)t + o_i(t)$ , we have

$$\inf_{i \neq m} P^t(i, m) \geq \alpha t + \inf_{i \neq m} o_i(t) > 1 - e^{-\alpha t} + \inf_{i \neq m} o_i(t).$$

For any  $\varepsilon > 0$ , there exists  $t_0$  such that when  $t < t_0, |\inf_{i \neq m} o_i(t)| < \varepsilon$  and

$$\inf_{i \neq m} P^t(i, m) > 1 - e^{-\alpha t} - \varepsilon,$$

from which we can get  $\inf_{i \neq m} P^t(i, m) \geq 1 - e^{-\alpha t}$ . In addition, we have  $P^t(m, m) \geq e^{-qit}$ . Thus, we can choose small enough  $h$  such that  $P^h(i, m) \geq 1 - e^{-\alpha h}$  for all  $i \in E$ . Then, for the  $h$ -skeleton chain with transition probabilities  $P^h(i, j)$ , we know from [21, Theorem 16.2.4] that it is strongly ergodic and

$$\|P^{nh}(i, \cdot) - \pi\|_1 \leq 2[1 - (1 - e^{-\alpha h})]^n = 2e^{-\alpha nh}.$$

For any  $t \in \mathbb{R}_+$  with  $t$  of the form  $t = nh + s$  for some  $s \in [0, h)$ , we have

$$\|P^t(i, \cdot) - \pi\|_1 \leq \sum_{j \in E} \sum_{k \in E} |P^{nh}(i, k) - \pi(k)| P^s(k, j) = \|P^{nh}(i, \cdot) - \pi\|_1 \leq 2e^{-\alpha(t-s)}.$$

Letting  $h \rightarrow 0$ , the assertion follows immediately from the previous inequality and the fact that  $s \rightarrow 0$  as  $h \rightarrow 0$ . □

Theorem 1 and Lemma 4 lead to the following perturbation bounds for CTMCs satisfying Doeblin conditions.

**Theorem 2.** *Let  $X$  be an irreducible CTMC on state space  $E = \mathbb{Z}_+$ . Assume that  $Q$  satisfies the Doeblin condition with single-point set  $D = \{m\}$  and  $\alpha > 0$ . Suppose that Assumption 2 holds true for a nondecreasing function  $V$ . Then we have*

$$\|\tilde{p}^t - p^t\|_1 \leq 2e^{-\alpha t} \|\tilde{p}^0 - p^0\|_1 + \frac{2\kappa\|\Delta\|_{1,V}}{\alpha},$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

*Proof.* Observe that if  $Q$  satisfies the Doeblin condition, then so does its augmented truncation  ${}_{(n,h)}Q$  for any  $n$  such that  $m \in E_n$  and  ${}_{(n,h)}q(i, m) \geq q(i, m) \geq \alpha$  for  $i \in E_n$  and  $i \neq m$ . Due to this fact and Lemma 4, we can obtain the uniform convergence rate of  ${}_{(n,h)}Q$ , which is not smaller than  $\alpha$ . That is, we have  $\|{}_{(n,h)}P^t(i, \cdot) - {}_{(n,h)}\pi\|_1 \leq 2e^{-\alpha t}$ . Then the assertion follows by Theorem 1 immediately. □

We are now in a position to deal with our example of a linear birth and death process with catastrophes as described in Section 1. Note that  $Q$ , written as (1), evidently satisfies the Doeblin condition. For such a model, we will make a comparison of feasibility between the bounds in the  $V$ -norm and the weak norm, and show the quality of the latter.

**Example 1.** Consider a linear birth–death process with catastrophes on state space  $E = \mathbb{Z}_+$  with  $q$ -matrix given by (1). Let  $d = \inf_{i \geq 2} \{d_i, a\} > 0$ . Now suppose that all the parameters are perturbed by the same amount  $\varepsilon$ , which implies  $Q$  is perturbed to be

$$\tilde{Q} = \begin{pmatrix} -b - \varepsilon & b + \varepsilon & 0 & \dots \\ a + \varepsilon & -(a + b + 2\varepsilon) & b + \varepsilon & \dots \\ d_2 + \varepsilon & 2(a + \varepsilon) & -2(a + b + 2\varepsilon) - d_2 - \varepsilon & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix},$$

and the perturbation matrix is given by (2).

Observe that  $\inf_{i \geq 1} q_{i0} = d > 0$ , which implies  $Q$  satisfies the Doeblin condition with single-point set  $D = \{0\}$  and  $\alpha = d$ . Let  $\delta = (a - b)/2$  and  $L = (a + b)/2 + \varepsilon$ . Define the function  $V$  by  $V(i) = i + 1, i \geq 0$ . It is easy to verify that  $\tilde{Q}V(i) \leq -\delta V(i) + L, i \in E$ . From

$$\frac{\sum_j |\Delta(i, j)|}{V(i)} = \begin{cases} 2\varepsilon, & i = 0, 1, \\ \frac{4i + 2}{i + 1}\varepsilon, & i \geq 2, \end{cases} \quad \frac{\sum_j |\Delta(i, j)|V(j)}{V(i)} = \begin{cases} 3\varepsilon, & i = 0, \\ 4\varepsilon, & i = 1, \\ \frac{4i^2 + 5i + 2}{i + 1}\varepsilon, & i \geq 2, \end{cases}$$

it follows that

$$\|\Delta\|_{1,V} = \max_i \left\{ 2\varepsilon, \frac{4i + 2}{i + 1}\varepsilon \right\} < 4\varepsilon, \quad \|\Delta\|_V = \max_i \left\{ 4\varepsilon, \frac{4i^2 + 5i + 2}{i + 1}\varepsilon \right\} = \infty.$$

This shows that the  $V$ -norm cannot be used to analyze this perturbation because  $\|\Delta\|_V$  is always  $\infty$  as the perturbation parameter  $\varepsilon \rightarrow 0$ . However, letting

$$\kappa = \max \left\{ \tilde{p}^0(V), \frac{a + b + 2\varepsilon}{a - b} \right\},$$

by our Theorem 2 we have  $\|\tilde{p}^t - p^t\|_1 < 2e^{-dt} \|\tilde{p}^0 - p^0\|_1 + 8\kappa\varepsilon/d$ .

In addition, we give an simple example of a queuing model to demonstrate the applicability of our results.

**Example 2.** Consider an open Jackson network with two servers. We restrict ourselves here to the simplest assumptions: independent Poisson inputs with parameter  $\lambda_i > 0$  for  $i = 1$  or  $2$ , exponential service times with parameter  $\mu_i > 0$ , and first-in-first-out service discipline. Once a customer is served by server 1, they then join the queue at server 2. After they complete service at server 2, they are transferred with probability  $p$  to the end of the queue at server 1, and with probability  $1 - p$  they leave the system. The whole system may experience a breakdown with exponential rate  $\mu_b$ . If a breakdown occurs, all customers leave and the system immediately goes into repair. The repair time is also exponentially distributed with parameter  $\lambda_r$ .

Denote by  $N$  the total number of customers in the system and by  $L$  the number of customers at server 1. Let us define the state by the pair  $(N, L)$ . When the system is empty, it would not be enough to specify that there is no customer in the system (and hence at server 1) as we would also have to know whether the system is broken. So we introduce another state  $(0, 0, b)$  to indicate ‘empty due to breakdown’ and retain  $(0, 0)$  to represent ‘temporarily empty’ while the system is working. Let  $E^k = \{(k, i), 0 \leq i \leq k\}$ ; then we are able to arrange the state space as  $E = \{(0, 0, b), E^0, E^1, \dots\}$ . The generator  $Q$  can be expressed as

$$Q = \begin{matrix} & (0, 0, b) & E^0 & E^1 & E^2 & E^3 & \dots \\ \begin{matrix} (0, 0, b) \\ E^0 \\ E^1 \\ E^2 \\ E^3 \\ \vdots \end{matrix} & \begin{pmatrix} -\lambda_r & \lambda_r & 0 & 0 & 0 & \dots \\ \vec{\mu}_b & Q_{00} & Q_{01} & 0 & 0 & \dots \\ \vec{\mu}_b & Q_{10} & Q_{11} & Q_{12} & 0 & \dots \\ \vec{\mu}_b & 0 & Q_{21} & Q_{22} & Q_{23} & \dots \\ \vec{\mu}_b & 0 & 0 & Q_{32} & Q_{33} & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix} \end{matrix},$$

where  $\vec{\mu}_b$  is a column vector of all  $\mu_b$ s with appropriate length,  $Q_{00} = -\lambda_1 - \lambda_2 - \mu_b$ ,  $Q_{01} = (\lambda_2, \lambda_1)$ , and, for  $k \geq 1$ ,

$$Q_{k,k-1} = \begin{matrix} & (k-1, 0) & (k-1, 1) & \dots & (k-1, k-1) \\ \begin{matrix} (k, 0) \\ (k, 1) \\ \vdots \\ (k, k-1) \\ (k, k) \end{matrix} & \begin{pmatrix} \mu_2(1-p) & 0 & \dots & 0 \\ 0 & \mu_2(1-p) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \mu_2(1-p) \\ 0 & 0 & \dots & 0 \end{pmatrix} \end{matrix},$$

$$Q_{kk} = \begin{matrix} & (k, 0) & (k, 1) & \cdots & (k, k-1) & (k, k) \\ \begin{matrix} (k, 0) \\ (k, 1) \\ \vdots \\ (k, k-1) \\ (k, k) \end{matrix} & \begin{pmatrix} -\lambda_1 - \lambda_2 & \mu_2 p & \cdots & 0 & 0 \\ -\mu_2 - \mu_b & \mu_1 & -\lambda_1 - \lambda_2 - \mu_1 & \ddots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \ddots & -\lambda_1 - \lambda_2 - \mu_1 & \mu_2 p & \\ 0 & 0 & \cdots & \mu_1 & -\lambda_1 - \lambda_2 & -\mu_1 - \mu_b \end{pmatrix} \end{matrix},$$

and

$$Q_{k,k+1} = \begin{matrix} & (k+1, 0) & (k+1, 1) & \cdots & (k+1, k) & (k+1, k+1) \\ \begin{matrix} (k, 0) \\ (k, 1) \\ \vdots \\ (k, k) \end{matrix} & \begin{pmatrix} \lambda_2 & \lambda_1 & \cdots & 0 & 0 \\ 0 & \lambda_2 & \ddots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_2 & \lambda_1 \end{pmatrix} \end{matrix}.$$

It is evident that  $Q$  satisfies the Doeblin condition with single-point set  $D = \{0\}$  and  $\alpha = \mu_b$ . Suppose that the breakdown rate  $\mu_b$  is perturbed to be  $\mu_b + \varepsilon$  and assume that

$$\omega := \min\{\mu_2(1 - p), \mu_1\} > 2(\lambda_1 + \lambda_2 + \mu_2 p).$$

Define a nondecreasing function  $V$  by  $V(i, j) = \max\{s^{i+j}, s^{2i-2}\}$ , where

$$1 < s \leq \sqrt[3]{\omega/2(\lambda_1 + \lambda_2 + \mu_2 p)}.$$

We can check after some calculations that the perturbed continuous-time Markov chain satisfies the drift condition  $\tilde{Q}V \leq -\delta V + L$  with

$$\delta = (\lambda_1 + \lambda_2 + \mu_2 p)(1 - s^2) + \omega(1 - s^{-1}) > 0,$$

$$L = c + \mu_b + \varepsilon + \lambda_1(s^2 - 1) + \lambda_2(s - 1).$$

Then it follows from Theorem 2 that

$$\|\tilde{p}^t - p^t\|_1 \leq 2e^{-\mu_b t} \|\tilde{p}^0 - p^0\|_1 + \frac{4\kappa\varepsilon}{\mu_b},$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

**3.3.2. CTMCs with monotone  $q$ -matrix** The chain  $X$  is said to be stochastically monotone if  $\sum_{j \geq k} P^t(i, j)$  is a nondecreasing function of  $i$  for every fixed  $k$  and  $t$ . For an irreducible CTMC with regular  $q$ -matrix  $Q$ , the chain  $X$  is stochastically monotone if and only if  $Q$  is (stochastically) monotone, i.e.  $\sum_{j \geq k} q(i, j) \leq \sum_{j \geq k} q(m, j)$ , whenever  $i \leq m$ , and  $k$  is such that either

$k \leq i$  or  $k > m$  [2]. Note that if  $Q$  is stochastically monotone, so is its last-column-augmented truncation  ${}_{(n,n)}Q$ .

We now introduce a drift condition that will be used frequently later.

**Assumption 3.** *There exists a fixed state  $m \in E$  and a bounded nonnegative function  $x$  such that*

$$\begin{cases} Qx(i) \leq -1, & i \neq m, \\ x(i) = 0, & i = m. \end{cases}$$

Considering the equivalence between the drift conditions, the following lemma is essentially the same as [16, Lemma 2.2], which presents the explicit uniform convergence rate for stochastically monotone CTMCs.

**Lemma 5.** *If  $Q$  is monotone and satisfies Assumption 3, then, for any  $t \geq 0$ ,*

$$\sup_{i \in E} \|P^t(i, \cdot) - \pi\|_1 \leq 4 \left( \sup_{i \in E} x(i) + 1 \right) e^{-\beta t},$$

where  $0 < \beta \leq 1 / (\sup_{i \in E} x(i) + 1)$ .

Based on Theorem 1, Lemma 5, and the proof of Lemma 3, we can refine the perturbation bounds for stochastically monotone CTMCs.

**Theorem 3.** *Let  $X$  be an irreducible and stochastically monotone CTMC on state space  $E = \mathbb{Z}_+$  satisfying Assumption 3. Suppose that Assumption 2 holds true for a nondecreasing function  $V$ . Let  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ . Then*

$$\begin{aligned} \|\tilde{p}^t - p^t\|_1 &\leq 4 \left( \sup_{i \in E} x(i) + 1 \right) \exp \left\{ - \left( \sup_{i \in E} x(i) + 1 \right)^{-1} t \right\} \|\tilde{p}^0 - p^0\|_1 \\ &\quad + 4 \left( \sup_{i \in E} x(i) + 1 \right)^2 \kappa \|\Delta\|_{1,V}. \end{aligned}$$

As an application, we adopt Theorem 3 to obtain the perturbation bounds for general birth and death processes. In particular instances, we further provide numerical analyses in terms of the relative errors.

**Example 3.** Let  $X$  be a birth–death process with  $q$ -matrix  $Q$  which is given by  $q_{i,i+1} = b_i$ ,  $i \in \mathbb{Z}_+$ ;  $q_{i,i-1} = a_i$ ,  $i \in \mathbb{N}$ ;  $q_{ij} = 0$ ,  $|i - j| \geq 2$ , where  $a_i > 0$  for  $i \in \mathbb{N}$  and  $b_i > 0$  for  $i \in \mathbb{Z}_+$ . It is well known that  $Q$  is regular if and only if  $Q$  is conservative and

$$R = \sum_{n=1}^{\infty} \left( \frac{1}{b_n} + \frac{a_n}{b_n b_{n-1}} + \dots + \frac{a_n \cdots a_2}{b_n \cdots b_1} \right) = \infty.$$

It is easy to check that  $Q$  is stochastically monotone and so is  $X$ . From [28], we know that the function  $x$  defined by

$$x(0) = 0, \quad x(i) = \sum_{k=0}^{i-1} \left( \frac{1}{a_{k+1}} + \sum_{j=k+1}^{\infty} \frac{b_{k+1} \cdots b_j}{a_{k+1} \cdots a_{j+1}} \right), \quad i \geq 1,$$

satisfies Assumption 3 with equality. Obviously,  $x(i)$  is strictly increasing and

$$\sup_{i \in E} x(i) = \sum_{k=0}^{\infty} \left( \frac{1}{a_{k+1}} + \sum_{j=k+1}^{\infty} \frac{b_{k+1} \cdots b_j}{a_{k+1} \cdots a_{j+1}} \right) := A.$$

Then from Theorem 3 we have the following statement.

Let  $X$  be a birth–death process with regular  $q$ -matrix  $Q$ . Suppose that  $A < \infty$  and Assumption 2 holds for a nondecreasing function  $V$ . Then

$$\|\tilde{p}^t - p^t\|_1 \leq 4(A + 1)e^{-t/(A+1)} \|\tilde{p}^0 - p^0\|_1 + 4(A + 1)^2 \kappa \|\Delta\|_{1,V}, \tag{8}$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

To present a numerical illustration of our results, we further consider the special case  $b_0 = 1$  and  $a_i = b_i = s^i, i \geq 1$ . Suppose that the birth and death rates are perturbed to be  $b_0 = 1 + \varepsilon$  and  $a_i = b_i = s^i + \varepsilon$  for  $i \geq 1$ . By simple calculations, we have  $A = s/(s - 1)^2$ ,

$$\pi(i) = \pi(0) \frac{1}{s^i}, \quad \tilde{\pi}(i) = \pi(0) \prod_{k=1}^i \frac{s^{k-1} + \varepsilon}{s^k + \varepsilon}.$$

Take  $V \equiv 1$  and note that Assumption 2 is satisfied with  $L = \delta > 0$ . In view of (8), we can bound  $\|\tilde{\pi} - \pi\|_1$  with  $\tilde{p}^0 = p^0$  and by letting  $t \rightarrow \infty$ . It follows that

$$\|\tilde{\pi} - \pi\|_1 \leq 16 \left( \frac{s}{(s - 1)^2} + 1 \right)^2 \varepsilon = U(\varepsilon).$$

For  $U(\varepsilon)$  to become informative,  $\varepsilon$  has to be smaller than 0.0599 for  $s = 4$ , as otherwise  $U(\varepsilon)$  becomes larger than 2. It can be seen that the perturbation bound  $U(\varepsilon)$  diminishes linearly as  $\varepsilon$  tends to 0.

To test the performance of  $U(\varepsilon)$ , we investigate the relative error of the perturbation bound, which was first introduced and discussed in [1] and is given by

$$\eta(\varepsilon) = \frac{U(\varepsilon) - \|\tilde{\pi} - \pi\|_1}{\|\tilde{\pi} - \pi\|_1}.$$

Clearly, a smaller relative error means a sharper bound. In the setting of  $s = 4$ , the relative errors of  $U(\varepsilon)$  are plotted in Figure 1, which shows that the relative error of the condition number bound  $U(\varepsilon)$  converges to a finite non-zero value as  $\varepsilon \rightarrow 0$ , which is consistent with the findings of [1]. Hence, we have to acknowledge that our results might not be that sharp due to the limitations inherent in the arguments of condition number bounds.

#### 4. Perturbation analysis for exponentially ergodic CTMCs

By using similar arguments to Section 3 but with the introduction of multiplicative decomposition, we derive perturbation bounds for exponentially ergodic CTMCs. In particular, estimates for stochastically monotone CTMCs are proposed.

In this part, the following assumptions are considered.

**Assumption 4.**  $P^t$  is  $V$ -uniformly ergodic with positive constants  $\rho < 1$  and  $C < \infty$  and finite function  $V$ .

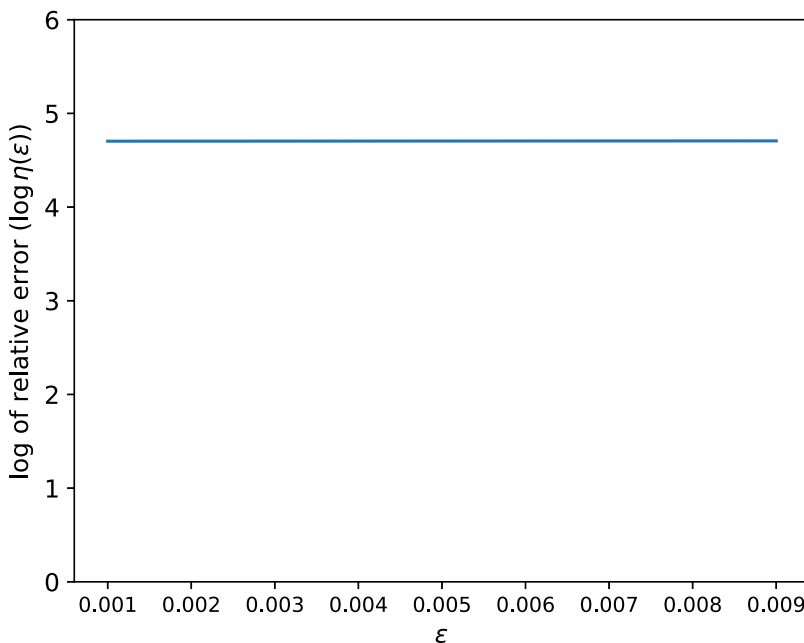


FIGURE 1. Log relative errors  $\log(\eta(\varepsilon))$  for  $\|\tilde{\pi} - \pi\|_1$  with  $\varepsilon \in (0, 0.01]$  in the case of  $s = 4$ .

**Assumption 5.** *There is a constant  $M < \infty$  such that*

$$\|\Delta\|_V = \sup_{i \in E} \frac{\|\tilde{Q}(i, \cdot) - Q(i, \cdot)\|_V}{V(i)} \leq M.$$

**4.1. Finite state spaces**

First, we have the following perturbation bounds for exponentially ergodic CTMCs on a finite state space  $E_n$ .

**Proposition 2.** *Let  $X$  be an irreducible CTMC on finite state space  $E_n$ . Suppose that Assumptions 2, 4, and 5 hold for the same function  $V$ . Then, for  $\|\Delta\|_{1,V} \in (0, 1/e)$  we have*

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_V + \frac{e\kappa \|\Delta\|_{1,V}}{\log \rho} (CM)^{-(\log \|\Delta\|_{1,V})^{-1}} \log \|\Delta\|_{1,V},$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

*Proof.* In the proof of Proposition 1, we obtained

$$\|\tilde{p}^t - p^t\|_1 \leq \|(\tilde{p}^0 - p^0)P^t\|_1 + \int_0^t \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^u\|_1 du.$$

By Lemmas 1 and 2, we have

$$\begin{aligned} \|(\tilde{p}^0 - p^0)P^t\|_1 &\leq \|(\tilde{p}^0 - p^0)P^t\|_V \leq \|\tilde{p}^0 - p^0\|_V \cdot \tau_V(P^t) \leq C\rho^t \|\tilde{p}^0 - p^0\|_V, \\ \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^u\|_V &\leq \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_V \tau_V(P^u). \end{aligned}$$



Fix a real number  $r \in (0, 1)$  and let  $s = 1 - r$ . By considering the definition of  $\tau_1(P^\mu)$ , we can see that  $\tau_1(P^\mu) \leq 1$ . These lead to

$$\begin{aligned} \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^\mu\|_1 &\leq \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^\mu\|_1^r \|\tilde{p}^{t-u}(\tilde{Q} - Q)P^\mu\|_V^s \\ &\leq \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_1^r (\tau_1(P^\mu))^r \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_V^s (\tau_V(P^\mu))^s \\ &\leq \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_1^r \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_V^s (\tau_V(P^\mu))^s. \end{aligned}$$

Further, we also have

$$\begin{aligned} \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_1 &\leq \sum_{i \in E_n} \tilde{p}^{t-u}(i) \|\tilde{Q}(i, \cdot) - Q(i, \cdot)\|_1 \leq \|\Delta\|_{1,V} \sum_{i \in E_n} \tilde{p}^{t-u}(i) V(i), \\ \|\tilde{p}^{t-u}(\tilde{Q} - Q)\|_V &\leq \sum_{i \in E_n} \tilde{p}^{t-u}(i) \|\tilde{Q}(i, \cdot) - Q(i, \cdot)\|_V \leq M \sum_{i \in E_n} \tilde{p}^{t-u}(i) V(i). \end{aligned}$$

From the proof of the inequality (4) and the drift condition in Assumption 2, we have, for  $t - u \geq 0$ ,

$$\sum_{i \in E_n} \tilde{p}^{t-u}(i) V(i) \leq \max \left\{ \tilde{p}^0(V), \frac{L}{\delta} \right\} = \kappa.$$

Then we get

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_V + \kappa (\|\Delta\|_{1,V})^r M^s \int_0^t (\tau_V(P^\mu))^s du.$$

Finally, it follows from Lemma 2 that

$$\int_0^t (\tau_V(P^\mu))^s du \leq C^s \int_0^t \rho^{su} du = \frac{C^s(1 - \rho^{st})}{-s \log \rho} \leq \frac{C^s}{-s \log \rho},$$

and hence

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_V + \frac{\kappa (\|\Delta\|_{1,V})^r (CM)^s}{-s \log \rho}.$$

For  $\|\Delta\|_{1,V} \in (0, 1/e)$ , we can choose the numbers  $r = 1 + (\log \|\Delta\|_{1,V})^{-1}$  and  $s = -(\log \|\Delta\|_{1,V})^{-1}$ , which leads to  $\|\Delta\|_{1,V}^r = e \|\Delta\|_{1,V}$  and allows us to complete the proof. □

**Remark 2.** This result parallels [26, Theorem 3.2] for DTMCs, which can also be derived through the uniformization technique.

### 4.2. Infinitely countable state spaces

By the technique of augmented truncations used in Section 3, we can get our results for exponentially ergodic CTMCs on an infinitely countable state space.

**Theorem 4.** *Let  $X$  be an irreducible CTMC on state space  $E = \mathbb{Z}_+$ , and  $V: E \rightarrow [1, \infty)$  a nondecreasing function. For a large enough integer  $N$  such that  $N \geq h$ , assume that  $\{(n,h)P^t, n \geq N\}$  uniformly satisfies Assumption 4 with  $V_n$ , i.e. there exist positive constants  $\rho < 1$  and  $C < \infty$  such that, for any  $i, t$ , and  $n \geq N$ ,*

$$\|(n,h)P^t(i, \cdot) - (n,h)\pi\|_{V_n} \leq CV_n(i)\rho^t.$$

Moreover, suppose that Assumptions 2 and 5 hold for  $V$ . Then, for  $\|\Delta\|_{1,V} \in (0, 1/e)$ ,

$$\|\tilde{p}^t - p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_V + \frac{e\kappa \|\Delta\|_{1,V}}{\log \rho} (CM)^{-(\log \|\Delta\|_{1,V})^{-1}} \log \|\Delta\|_{1,V},$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

*Proof.* Referring to the proof of Theorem 1, we know that

$$\|\tilde{p}^t - p^t\|_1 \leq \|\tilde{p}^t - (n,h)\tilde{p}_*^t\|_1 + \|p^t - (n,h)p_*^t\|_1 + \|(n,h)\tilde{p}_*^t - (n,h)p_*^t\|_1, \tag{9}$$

and  $\lim_{n \rightarrow \infty} \|p^t - (n,h)p_*^t\|_1 = 0$ ,  $\lim_{n \rightarrow \infty} \|\tilde{p}^t - (n,h)\tilde{p}_*^t\|_1 = 0$ . Since  $V$  is nondecreasing, we can see that, for  $i \neq h$ ,

$$\begin{aligned} & \|_{(n,h)}\tilde{Q}(i, \cdot) - (n,h)Q(i, \cdot)\|_{V_n} \\ &= \sum_{j \leq n, j \neq h} |\tilde{q}(i, j) - q(i, j)|V(j) + \left| (\tilde{q}(i, h) - q(i, h)) + \sum_{j > n} (\tilde{q}(i, j) - q(i, j)) \right| V(h) \\ &\leq \sum_{\substack{j \leq n+1, \\ j \neq h}} |\tilde{q}(i, j) - q(i, j)|V(j) + \left| (\tilde{q}(i, h) - q(i, h)) + \sum_{j > n+1} (\tilde{q}(i, j) - q(i, j)) \right| V(h) \\ &= \|_{(n+1,h)}\tilde{Q}(i, \cdot) - (n+1,h)Q(i, \cdot)\|_{V_{n+1}}, \end{aligned}$$

and for  $i = h$ ,

$$\begin{aligned} & \|_{(n,h)}\tilde{Q}(h, \cdot) - (n,h)Q(h, \cdot)\|_{V_n} \\ &= \sum_{j \leq n, j \neq h} |\tilde{q}(h, j) - q(h, j)|V(j) + \left| - \sum_{j \leq n, j \neq h} (\tilde{q}(h, j) - q(h, j)) \right| V(h) \\ &\leq \sum_{j \leq n, j \neq h} |\tilde{q}(h, j) - q(h, j)|V(j) + \left| - \sum_{j \leq n+1, j \neq h} (\tilde{q}(h, j) - q(h, j)) \right| V(h) \\ &\quad + |\tilde{q}(h, n+1) - q(h, n+1)|V(h) \\ &\leq \sum_{j \leq n+1, j \neq h} |\tilde{q}(h, j) - q(h, j)|V(j) + \left| - \sum_{j \leq n+1, j \neq h} (\tilde{q}(h, j) - q(h, j)) \right| V(h) \\ &= \|_{(n+1,h)}\tilde{Q}(h, \cdot) - (n+1,h)Q(h, \cdot)\|_{V_{n+1}}, \end{aligned}$$

which implies

$$\sup_{i \in E} \frac{\|_{(n,h)}\tilde{Q}(i, \cdot) - (n,h)Q(i, \cdot)\|_{V_n}}{V(i)} \leq \sup_{i \in E} \frac{\|\tilde{Q}(i, \cdot) - Q(i, \cdot)\|_V}{V(i)} < M.$$

Let  $\|_{(n)}\Delta\|_{1,V} = \sup_{i \in E_n} \|_{(n,h)}\tilde{Q}(i, \cdot) - (n,h)Q(i, \cdot)\|_1/V(i)$  and  ${}_{(n)}\kappa = \max\{\tilde{p}^0(V_n), L/\delta\}$ . Since  ${}_{(n,h)}P^t$  uniformly satisfies  $V$ -uniform ergodicity and Assumption 2 holds true for  $V$ , it

follows from Lemma 3 and Proposition 2 that, for  $\|(n)\Delta\|_{1,V} \in (0, 1/e)$ ,

$$\begin{aligned} \|(n,h)\tilde{p}^t - (n,h)p^t\|_1 &\leq C\rho^t \|(n)\tilde{p}^0 - (n)p^0\|_{V_n} \\ &\quad + \frac{e_{(n)\kappa} \|(n)\Delta\|_{1,V}}{\log \rho} (CM)^{-(\log \|(n)\Delta\|_{1,V})^{-1}} \log \|(n)\Delta\|_{1,V}. \end{aligned}$$

Using similar arguments to the proof of Theorem 1 gives  $\lim_{n \rightarrow \infty} \|(n)\Delta\|_{1,V} = \|\Delta\|_{1,V}$ ,  $\lim_{n \rightarrow \infty} (n)\kappa = \kappa$ , and  $\lim_{n \rightarrow \infty} \|(n)\tilde{p}^0 - (n)p^0\|_{V_n} = \|\tilde{p}^0 - p^0\|_V$ . Hence, for  $\|\Delta\|_{1,V} \in (0, 1/e)$  we have

$$\lim_{n \rightarrow \infty} \|(n,h)\tilde{p}^t - (n,h)p^t\|_1 \leq C\rho^t \|\tilde{p}^0 - p^0\|_V + \frac{e\kappa \|\Delta\|_{1,V}}{\log \rho} (CM)^{-(\log \|\Delta\|_{1,V})^{-1}} \log \|\Delta\|_{1,V}.$$

By taking the limit of both sides of (9), we obtain the assertion immediately. □

As a consequence of the previous theorem, we have the following results on the distance between the two stationary distributions  $\tilde{\pi}$  and  $\pi$ .

**Corollary 2.** *Assume that the conditions in Theorem 4 hold. Then, for  $\|\Delta\|_{1,V} \in (0, 1/e)$ ,*

$$\|\tilde{\pi} - \pi\|_1 \leq \frac{e\kappa' \|\Delta\|_{1,V}}{\log \rho} (CM)^{-(\log \|\Delta\|_{1,V})^{-1}} \log \|\Delta\|_{1,V},$$

where  $\kappa' = \max\{\tilde{\pi}(V), L/\delta\}$ .

### 4.3. Explicit results for CTMCs with monotone $q$ -matrix

For a class of exponentially ergodic CTMCs, the condition in Theorem 4 that  $(n,h)P^t$  uniformly satisfies Assumption 4 is easy to verify. In the remainder of this part, we give explicit results for stochastically monotone CTMCs that satisfy the following drift condition.

**Assumption 6.** *There exists a nondecreasing function  $V: E \rightarrow [1, \infty)$  and positive constants  $c$  and  $K < \infty$  such that  $QV(i) \leq -cV(i) + K \cdot I_{\{0\}}(i)$ .*

Based on this drift condition, [17] proposed an exponential convergence rate for stochastically monotone CTMCs.

**Lemma 6.** *Suppose that  $X$  is an irreducible and stochastically monotone CTMC on the state space  $E = \mathbb{Z}_+$  satisfying Assumption 6. Then*

$$\|P^t(i, \cdot) - \pi\|_V \leq 2e^{-ct} \left[ V(i)(1 - I_{\{0\}}(i)) + \frac{K}{c} \right].$$

As an immediate consequence of Lemma 6 and Theorem 4, we obtain the following theorem.

**Theorem 5.** *Let  $X$  be an irreducible and stochastically monotone CTMC on the state space  $E = \mathbb{Z}_+$  satisfying Assumption 6. Moreover, suppose that Assumptions 2 and 5 hold for the nondecreasing function  $V$ . Then, for  $\|\Delta\|_{1,V} \in (0, 1/e)$ ,*

$$\begin{aligned} \|\tilde{p}^t - p^t\|_1 &\leq 2 \left( 1 + \frac{K}{c} \cdot \frac{1}{\inf_{i \in E} V(i)} \right) e^{-ct} \|\tilde{p}^0 - p^0\|_V \\ &\quad + \frac{e\kappa \|\Delta\|_{1,V}}{-c} \left[ 2M \left( 1 + \frac{K}{c} \cdot \frac{1}{\inf_{i \in E} V(i)} \right) \right]^{-(\log \|\Delta\|_{1,V})^{-1}} \log \|\Delta\|_{1,V}, \end{aligned}$$

where  $\kappa = \max\{\tilde{p}^0(V), L/\delta\}$ .

*Proof.* Note that if  $Q$  is stochastically monotone, so is its  $(n + 1) \times (n + 1)$  northwest corner truncation  ${}_{(n,n)}Q$  augmented in the last column. Since  $V$  is nondecreasing, it follows from the proof of Lemma 3 that  ${}_{(n,n)}Q$  uniformly satisfies the conditions of Lemma 6 with  $V_n$ , and

$$\begin{aligned} \|{}_{(n,n)}P^t(i, \cdot) - {}_{(n,n)}\pi\|_{V_n} &\leq 2e^{-ct} \left[ V_n(i)(1 - I_{\{0\}}(i)) + \frac{K}{c} \right] \\ &\leq 2 \left( 1 + \frac{K}{c} \cdot \frac{1}{\inf_{i \in E} V(i)} \right) V_n(i) e^{-ct}. \end{aligned}$$

By taking  $h = n$  and using similar arguments to the proof of Theorem 4, we can obtain the statement immediately. □

In the following, we show, through an example of birth and death processes with catastrophes, that our results in the weak sense are more feasible than  $V$ -normwise bounds in some cases.

**Example 4.** Consider a birth–death process with catastrophes on the state space  $E = \mathbb{Z}_+$  with  $q$ -matrix

$$Q = \begin{pmatrix} -b & b & 0 & 0 & \cdots \\ a + \varepsilon & -(a + b + \varepsilon) & b & 0 & \cdots \\ d_2 + \varepsilon & 2a & -2(a + b) - d_2 - \varepsilon & 2b & \cdots \\ d_3 + \varepsilon & 0 & 3a & -3(a + b) - d_3 - \varepsilon & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix},$$

where  $d_i, i \geq 2$ , is a nonnegative decreasing sequence and  $a, b, \varepsilon$  are positive constants such that  $a > \max\{b, d_2\}$ . Suppose the  $q$ -matrix is perturbed to be

$$\tilde{Q} = \begin{pmatrix} -b & b & 0 & 0 & \cdots \\ a & -(a + b) & b & 0 & \cdots \\ d_2 & 2a & -2(a + b) - d_2 & 2b & \cdots \\ d_3 & 0 & 3a & -3(a + b) - d_3 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}.$$

It is obvious that  $Q$  is monotone. Define the function  $V$  by  $V(i) = 1 + (i + 1)/\varepsilon, i \geq 0$ . Then we can easily verify that

$$QV(i) \leq -\frac{a - b}{\varepsilon + 2} V(i) + \frac{a\varepsilon + a + b}{\varepsilon^2 + 2\varepsilon} \cdot I_{\{0\}}(i), \quad i \in E.$$

Let

$$c = \frac{a - b}{\varepsilon + 2}, \quad K = \frac{a\varepsilon + a + b}{\varepsilon^2 + 2\varepsilon}.$$

To use [14, Theorem 3.3], we only need to check that  $\|\Delta\|_V < c/(1 + \pi(V))$  or  $\|\Delta\|_V < c^2/(K + c)$ . Observe that  $M = \|\Delta\|_V = (2\varepsilon^2 + 3\varepsilon)/(\varepsilon + 2) \rightarrow 0$  as  $\varepsilon \rightarrow 0$ . Unfortunately, when

$a - b < \min\{3, \sqrt{3(a + b)}\}$ , we can get

$$\frac{c}{1 + \pi(V)} < \frac{c}{1 + (1 + 1/\varepsilon)} = \frac{1}{\varepsilon + 2} \cdot \frac{(a - b)\varepsilon}{2\varepsilon + 1} < \frac{2\varepsilon^2 + 3\varepsilon}{\varepsilon + 2} = \|\Delta\|_V,$$

$$\frac{c^2}{K + c} = \frac{c}{(K/c) + 1} = \frac{1}{\varepsilon + 2} \cdot \frac{a - b}{(K/c) + 1} < \frac{2\varepsilon^2 + 3\varepsilon}{\varepsilon + 2} = \|\Delta\|_V.$$

Hence, in the case where  $a - b < \min\{3, \sqrt{3(a + b)}\}$ , the condition cannot be satisfied and the results of [14, Theorem 3.3] fail.

However, our results in the weak sense are still valid for such a case. For the same function  $V$ , we can also see that  $\tilde{Q}V(i) \leq -cV(i) + K, i \in E$ . To use our Theorem 5, we only require that

$$\|\Delta\|_{1,V} = \sup_{i \in E} \frac{\|\Delta(i, \cdot)\|_1}{V(i)} = \frac{2\varepsilon^2}{\varepsilon + 2} < \frac{1}{e}.$$

Therefore, if  $\varepsilon$  is small enough, the condition will be satisfied and we can obtain

$$\|\tilde{p}^t - p^t\|_1 \leq 2 \left( 1 + \frac{a\varepsilon + a + b}{(a - b)(\varepsilon + 1)} \right) \exp \left\{ -\frac{a - b}{\varepsilon + 2} t \right\} - \frac{2\varepsilon^2 e \kappa'}{a - b} \log \left[ \frac{2\varepsilon^2}{\varepsilon + 2} \right] \left\{ \frac{4\varepsilon^2 + 6\varepsilon}{\varepsilon + 2} \left( 1 + \frac{a\varepsilon + a + b}{(a - b)(\varepsilon + 1)} \right) \right\}^{-(\log(2\varepsilon^2/(\varepsilon + 2)))^{-1}}, \tag{10}$$

where

$$\kappa = \max \left\{ \tilde{p}^0(V), \frac{K}{c} \right\} = \max \left\{ \tilde{p}^0(V), \frac{a\varepsilon + a + b}{(a - b)\varepsilon} \right\}.$$

Obviously, the second term on the right-hand side of (10) is

$$\frac{2\varepsilon^2 e \kappa'}{a - b} \log \left[ \frac{2\varepsilon^2}{\varepsilon + 2} \right] \left\{ \frac{4\varepsilon^2 + 6\varepsilon}{\varepsilon + 2} \left( 1 + \frac{a\varepsilon + a + b}{(a - b)(\varepsilon + 1)} \right) \right\}^{-(\log(2\varepsilon^2/(\varepsilon + 2)))^{-1}} = O(\varepsilon \log \varepsilon).$$

This shows that the weak norm is a better choice than the  $V$ -norm to analyze the perturbation for this example, and our bounds are more feasible than the bounds in [14].

### 5. Conclusion

By the technique of augmented truncations, we obtained accurate bounds on  $\|\tilde{p}^t - p^t\|_1$  in terms of the convergence rate and drift condition for strongly and exponentially ergodic CTMCs, respectively. In particular, the explicit results were derived for CTMCs satisfying Doeblin or stochastically monotone conditions. Through some examples, we showed that when the perturbation matrices are unbounded, the  $V$ -normwise bounds may fail while our bounds in the weak norm still hold. We now discuss possible extensions and improvements of the results in this paper.

In Theorems 1 and 4, it is required that  $(_{n,h})P^t$  has a uniform convergence rate, which may be difficult to verify for general CTMCs. We may expect a more straightforward condition on  $P^t$  rather than  $(_{n,h})P^t$ . However, our arguments with the approach of augmented truncations fail to do that. It may be interesting to investigate this in different ways.

Observe that for exponentially ergodic CTMCs, our bounds rely on the boundedness of  $\|\Delta\|_V$ . When the perturbation matrix is unbounded, this condition cannot be satisfied and the bounds given in Section 4 may fail to hold. To investigate this issue requires some different methods, which is a topic for future research.

Following [1], the perturbation bounds we presented are condition number bounds. Example 3 illustrates that the relative error of our bound converges to a finite non-zero value as the perturbation size  $\varepsilon \rightarrow 0$ . It is open to find a good way to derive bounds in the weak sense whose relative error vanishes.

One possible extension is to consider a perturbation for a continuous-time Markov process on a continuous state space, say  $[0, \infty)$ . To the best of our knowledge, this is a quite new topic which is worthy of further research. However, working with the extended generator may require different arguments.

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There were no competing interests to declare which arose during the preparation or publication process of this article.

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