Invariant sets and nilpotency of endomorphisms of algebraic sofic shifts

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Abstract. Let G be a group and let V be an algebraic variety over an algebraically closed field K. Let A denote the set of K-points of V. We introduce algebraic sofic subshifts $\Sigma \subset A^G$ and study endomorphisms $\tau \colon \Sigma \to \Sigma$. We generalize several results for dynamical invariant sets and nilpotency of τ that are well known for finite alphabet cellular automata. Under mild assumptions, we prove that τ is nilpotent if and only if its limit set, that is, the intersection of the images of its iterates, is a singleton. If moreover G is infinite, finitely generated and Σ is topologically mixing, we show that τ is nilpotent if and only if its limit set consists of periodic configurations and has a finite set of alphabet values.

Contents

1. *Introduction*

The main goal of the present paper is to extend and generalize well-known results about limit sets and nilpotency of classical cellular automata, that is, cellular automata with finite alphabets, to the setting of algebraic cellular automata over algebraic sofic subshifts, where the alphabet is the set of rational points of an algebraic variety.

Since the pioneering work of John von Neumann in the 1940s [58], the mathematical theory of cellular automata has led to very interesting questions, with deep connections to areas such as theoretical computer science, decidability, dynamical systems, ergodic theory, harmonic analysis, and geometric group theory. In his empirical classification of the long-term behavior of classical cellular automata, Wolfram [60] introduced the notion of a limit set. For classical cellular automata, properties of limit sets and their relations with various notions of nilpotency were subsequently investigated by several authors (see [18, 24, 25, 34, 51]). In particular, Aanderaa and Lewis [1] and, independently, Kari [25] proved undecidability of nilpotency for classical cellular automata over $\mathbb{Z}$: this undecidability result constitutes one of the most influential results in the theory of cellular automata and one of the main motivations for the study of nilpotency in the symbolic dynamics setting. In general, these properties of limit sets become false when the alphabet is allowed to be infinite. A major problem arising when working with infinite alphabets is that images of subshifts of finite type may fail to be closed (e.g. [10, Example 3.3.3]). Nevertheless, infinite alphabet subshifts and their dynamics are not only intrinsically interesting but also fundamental to the study of smooth dynamical systems (cf. e.g. [8], [28, Ch. 7], [29, 52, 53] and the references therein).

After Gromov [20], the study of injectivity and surjectivity of algebraic cellular automata was pursued in [11, 12, 14, 15, 39] to obtain generalizations of the Ax–Grothendieck theorem [3], [23, Proposition 10.4.11] and of the Moore–Myhill Garden of Eden theorem [35, 36]. Nilpotency is in the opposite direction since a nilpotent map is never injective nor surjective when the underlying set has at least two elements.

To state our results, let us first introduce some terminology and notation. Let $f : X \to X$ be a map from a set X into itself. Given an integer $n \geq 1$, the nth iterate of f is the map $f^n : X \to X$ defined by $f^n := f \circ f \circ \cdots \circ f$ (n times). The sets $f^n(X)$, $n \geq 1$, form a

decreasing sequence of subsets of X. The *limit set* $\Omega(f) := \bigcap_{n \geq 1} f^n(X)$ of f is the set of points that occur after iterating f arbitrarily many times.

Observe that $f(\Omega(f)) \subset \Omega(f)$. The inclusion may be strict, and equality holds if and only if every $x \in \Omega(f)$ admits a *backward orbit*, that is, a sequence $(x_i)_{i \geq 0}$ of points of X such that $x_0 = x$ and $f(x_{i+1}) = x_i$ for all $i \geq 0$. Clearly, f is surjective if and only if $\Omega(f) = X$. Note also that $\mathrm{Per}(f) := \bigcup_{n \geq 1} \{x \in X : f^n(x) = x\} \subset \Omega(f)$ and that $\Omega(f^n) = \Omega(f)$ for every $n \geq 1$. The map f is *stable* if $f^{n+1}(X) = f^n(X)$ for some $n \geq 1$. If f is stable, then $\Omega(f) \neq \varnothing$ unless $X = \varnothing$. Clearly, f is stable whenever X is finite. If X is infinite, there always exist maps $f \colon X \to X$ with $\Omega(f) = \varnothing$ (cf. Lemma A.1).

Assume that X is a topological space and $f \colon X \to X$ is a continuous map. One says that $x \in X$ is a *recurrent* (respectively *non-wandering*) point of f if for every neighborhood U of x, there exists $n \geq 1$ such that $f^n(x) \in U$ (respectively $f^n(U)$ meets U). Let $\mathrm{R}(f)$ (respectively $\mathrm{NW}(f)$) denote the set of recurrent (respectively non-wandering) points of f. It is immediate that $\mathrm{Per}(f) \subset \mathrm{R}(f) \subset \mathrm{NW}(f)$ and that $\mathrm{NW}(f)$ is a closed subset of X. In general, neither $\mathrm{Per}(f)$, nor $\mathrm{R}(f)$, nor $\Omega(f)$ are closed in X (see Example 15.1).

Suppose now that X is a uniform space and $f \colon X \to X$ is a uniformly continuous map. One says that a point $x \in X$ is *chain-recurrent* if for every entourage E of X, there exist an integer $n \geq 1$ and a sequence of points $x_0, x_1, \ldots, x_n \in X$ such that $x = x_0 = x_n$ and $(f(x_i), x_{i+1}) \in E$ for all $0 \leq i \leq n - 1$. We shall denote by $\mathrm{CR}(f)$ the set of chain-recurrent points of f. Observe that $\mathrm{CR}(f)$ is always closed in X.

Let G be a group and let A be a set, called the *alphabet*. The set $A^G := \{x \colon G \to A\}$, consisting of all maps from G to A, is called the set of *configurations* over the group G and the alphabet A. We equip $A^G = \prod_{g \in G} A$ with its *prodiscrete uniform structure*, that is, the product uniform structure obtained by taking the discrete uniform structure on each factor A of A^G. Note that A^G is a totally disconnected Hausdorff space and that A^G is compact if and only if A is finite. The *shift action* of the group G on A^G is the action defined by $(g, x) \mapsto gx$, where $gx(h) := x(g^{-1}h)$ for all $g, h \in G$ and $x \in A^G$. This action is uniformly continuous with respect to the prodiscrete uniform structure.

For a subgroup $H \subset G$, define $\mathrm{Fix}(H) := \{x \in A^G : hx = x \text{ for all } h \in H\}$. Then $\mathrm{Fix}(G)$ is the set of constant configurations while $\mathrm{Fix}(\{1_G\}) = A^G$. A configuration $x \in A^G$ is said to be *periodic* if its G-orbit is finite, that is, there is a finite index subgroup H of G such that $x \in \mathrm{Fix}(H)$.

A G-invariant subset $\Sigma \subset A^G$ is called a *subshift* of A^G. Note that we do not require closedness in A^G in our definition of a subshift.

Given a finite subset $D \subset G$ and a (finite or infinite) subset $P \subset A^D$, the set

$$\Sigma(D, P) := \{x \in A^G : (g^{-1}x)|_D \in P \text{ for all } g \in G\} \tag{1.1}$$

is a closed subshift of A^G (here $(g^{-1}x)|_D \in A^D$ denotes the restriction of the configuration $g^{-1}x$ to D). One says that $\Sigma(D, P)$ is the *subshift of finite type* associated with (D, P) and that D is a *defining memory set* for Σ.

Let B be another alphabet set. A map $\tau \colon B^G \to A^G$ is called a *cellular automaton* if there exist a finite subset $M \subset G$ and a map $\mu \colon B^M \to A$ such that

$$\tau(x)(g) = \mu((g^{-1}x)|_M) \quad \text{for all } x \in B^G \text{ and } g \in G. \tag{1.2}$$

Such a set M is then called a *memory set* and μ is called a *local defining map* for τ. It is clear from the definition that every cellular automaton $\tau \colon B^G \to A^G$ is uniformly continuous and G-equivariant (see [10]).

More generally, if $\Sigma_1 \subset B^G$ and $\Sigma_2 \subset A^G$ are subshifts, a map $\tau \colon \Sigma_1 \to \Sigma_2$ is a *cellular automaton* if it can be extended to a cellular automaton $B^G \to A^G$.

Suppose now that U, V are algebraic varieties (respectively algebraic groups) over a field K, and let $A \coloneqq V(K)$, $B \coloneqq U(K)$ denote the sets of K-points of V and U, that is, the set consisting of all K-scheme morphisms $\mathrm{Spec}(K) \to V$ and $\mathrm{Spec}(K) \to U$, respectively. See [14, Appendix A], [15, §2] for basic definitions and properties of algebraic varieties. The following definition was introduced in the case $U = V$ in [14, Definition 1.1] and [39] after Gromov [20]. A cellular automaton $\tau \colon B^G \to A^G$ is an *algebraic (respectively algebraic group) cellular automaton* if τ admits a memory set M with local defining map $\mu \colon B^M \to A$ induced by some algebraic morphism (respectively homomorphism of algebraic groups) $f \colon U^M \to V$ (here U^M denotes the K-fibered product of a family of copies of U indexed by M). More generally, given subshifts $\Sigma_1 \subset B^G$ and $\Sigma_2 \subset A^G$, a map $\tau \colon \Sigma_1 \to \Sigma_2$ is called an *algebraic* (respectively *algebraic group*) *cellular automaton* if it is the restriction of some algebraic (resp. algebraic group) cellular automaton $\tilde{\tau} \colon B^G \to A^G$ (see §16 for an example).

Every cellular automaton with finite alphabet A is an algebraic cellular automaton over any field K (see [14, remarks after Definition 1]). Indeed, it suffices to embed A as a subset of K and then observe that, if M is a finite set, any map $\mu \colon A^M \to A$ is the restriction of some polynomial map $P \colon K^M \to K$ (which can be made explicit by using Lagrange interpolation formula). Similarly, any linear cellular automaton (cf. [10, Ch. 8], [16]) is an algebraic cellular automaton: if A is a finite-dimensional vector space over a field K and M is a finite set, then any linear map $\mu \colon A^M \to A$ is clearly a polynomial.

Definition 1.1. One says that $\Sigma \subset A^G$ is an *algebraic (respectively algebraic group) subshift of finite type* if there exist a finite subset $D \subset G$ and an algebraic subvariety (respectively algebraic subgroup) $W \subset V^D$ such that, with the notation introduced in (1.1), one has $\Sigma = \Sigma(D, W(K))$.

By analogy with the definition of sofic subshifts in the classical setting, we define algebraic sofic subshifts and algebraic group sofic subshifts as follows (see Definition 16.4 for more general notions).

Definition 1.2. Let G be a group and let V be an algebraic variety (respectively algebraic group) over a field K. Let $A \coloneqq V(K)$. A subset $\Sigma \subset A^G$ is called an *algebraic (respectively algebraic group) sofic subshift* if it is the image of an algebraic (respectively algebraic group) subshift of finite type $\Sigma' \subset B^G$, where $B = U(K)$ and U is a K-algebraic variety (respectively K-algebraic group), under an algebraic (respectively algebraic group) cellular automaton $\tau' \colon B^G \to A^G$.

Every algebraic sofic subshift $\Sigma \subset A^G$ is indeed a subshift but it may fail to be closed in A^G (cf. Example 15.1). However, it turns out that, under suitable natural conditions (see hypotheses (H1), (H2), (H3) below), all algebraic sofic subshifts $\Sigma \subset A^G$ are closed in

A^G (cf. Corollary 8.2). Moreover, we establish a fundamental characterization of algebraic subshifts of finite type by the descending chain property (cf. Theorem 10.1).

With the notation as in Definition 1.2, we shall investigate in this paper various dynamical aspects of an algebraic cellular automaton $\tau : \Sigma \to \Sigma$ over an algebraic sofic subshift $\Sigma \subset A^G$ satisfying one of the following hypotheses (with the same notation throughout the paper):

(H1) K is an uncountable algebraically closed field (e.g. $K = \mathbb{C}$);

(H2) K is algebraically closed and U, V are complete (e.g. projective) algebraic varieties over K;

(H3) K is algebraically closed, V is an algebraic group over K, $\Sigma \subset A^G$ is an algebraic group sofic subshift, and $\tau : \Sigma \to \Sigma$ is an algebraic group cellular automaton.

We shall establish the following result.

THEOREM 1.3. *Let G be a group and let V be an algebraic variety over a field K. Let $A := V(K)$ and let $\Sigma \subset A^G$ be an algebraic sofic subshift. Let $\tau : \Sigma \to \Sigma$ be an algebraic cellular automaton and assume that one of the conditions* (H1), (H2), (H3) *is satisfied. Then the following hold:*

(i) $\Omega(\tau)$ *is a closed subshift of A^G;*

(ii) $\tau(\Omega(\tau)) = \Omega(\tau)$;

(iii) $\mathrm{Per}(\tau) \subset \mathrm{R}(\tau) \subset \mathrm{NW}(\tau) \subset \mathrm{CR}(\tau) \subset \Omega(\tau)$;

(iv)   *if* (H2) *or* (H3) *is satisfied and $\Omega(\tau)$ is a subshift of finite type, then τ is stable;*

(v)   *for every subgroup $H \subset G$, if $\Sigma \cap \mathrm{Fix}(H) \neq \varnothing$, then $\Omega(\tau) \cap \mathrm{Fix}(H) \neq \varnothing$.*

See [16, Theorem 1.5] for a linear version of the above theorem.

One says that a map $f : X \to X$ from a set X into itself is *nilpotent* if there exist a constant map $c : X \to X$ and an integer $n_0 \geq 1$ such that $f^{n_0} = c$. This implies $f^n = c$ for all $n \geq n_0$. Such a constant map c is then unique and we say that the unique point $x_0 \in X$ such that $c(x) = x_0$ for all $x \in X$ is the *terminal point* of f. The terminal point of a nilpotent map is its unique fixed point.

Observe that if $f : X \to X$ is nilpotent with terminal point x_0, then $\Omega(f) = \{x_0\}$ is a singleton. The converse is not true in general. Actually, as soon as the set X is infinite, there exist non-nilpotent maps $f : X \to X$ whose limit set is reduced to a single point (cf. Lemma A.1). However, in the algebraic setting, we obtain the following result.

THEOREM 1.4. *If we keep the same notation and hypotheses as in Theorem 1.3, then the following conditions are equivalent:*

(a) τ *is nilpotent;*

(b)   *the limit set $\Omega(\tau)$ is reduced to a single configuration.*

The analog of Theorem 1.4 for classical cellular automata follows from [18, Theorem 3.5]. However, Theorem 1.4 can be seen as a generalization of an interesting and non-trivial property of endomorphisms of algebraic varieties (by taking $G = \{1_G\}$).

Both Theorems 1.3 and 1.4 become false if we remove the hypothesis that the ground field K is algebraically closed (see Examples 15.1, 15.8, and 15.9). To illustrate the

significance of our results, note that for a group G and a finite set A, the space A^G is compact by Tychonoff's theorem. Consequently, if $\Sigma \subset A^G$ is a closed subshift and $\tau \colon A^G \to A^G$ is a cellular automaton, then $\tau^n(\Sigma)$ is closed in A^G for every $n \geq 1$ and it follows that $\Omega(\tau)$ is a closed subshift of A^G. A standard compactness argument shows also that $\Omega(\tau) \neq \varnothing$ if $\Sigma \neq \varnothing$ (cf. [18]). When A is infinite, A^G is no longer compact and, given a closed subshift $\Sigma \subset A^G$, the limit set of a cellular automaton $\tau \colon \Sigma \to \Sigma$ is, in general, no longer closed in A^G (cf. Example 15.1). Also, when A is infinite, it may happen that $\Omega(\tau) = \varnothing$ while $\Sigma \neq \varnothing$ or even $\tau(\Omega(\tau)) \subsetneq \Omega(\tau)$ (cf. Proposition A.2 and Example 15.8).

A self-map $f \colon X \to X$ on a set X is said to be *pointwise nilpotent* if there exists a point $x_0 \in X$ such that for every $x \in X$, there exists an integer $n_0 \geq 1$ such that $f^n(x) = x_0$ for all $n \geq n_0$.

Consider a group G with the following property: for every finite alphabet A, any cellular automaton $\tau \colon A^G \to A^G$ with $\Omega(\tau)$ finite is nilpotent. Such a group G cannot be finite. Indeed, for G finite and $A := \{0, 1\}$, the identity cellular automaton map $\tau \colon A^G \to A^G$ has a finite limit set $\Omega(\tau) = A^G$ without being nilpotent. By [24, Corollary 4] or [18], we know that $G = \mathbb{Z}$ satisfies the above property. In Theorem 13.1, we show that actually it is satisfied by all infinite groups.

More generally, we obtain the following various characterizations of nilpotent algebraic cellular automata.

THEOREM 1.5. *Let G be an infinite group and let V be an algebraic variety over a field K. Let $A = V(K)$ and let $\Sigma \subset A^G$ be a non-empty topologically mixing algebraic sofic subshift (e.g. A^G for $A \neq \varnothing$). Let $\tau \colon \Sigma \to \Sigma$ be an algebraic cellular automaton. Assume that one of the conditions* (H1), (H2), (H3) *is satisfied. Then the following are equivalent:*

(a)   *τ is nilpotent;*
(b)   *τ is pointwise nilpotent;*
(c)   *the limit set $\Omega(\tau)$ is finite.*

If G is finitely generated, then the above conditions are equivalent to

(d)   *each $x \in \Omega(\tau)$ is periodic and the set $\{x(1_G) \colon x \in \Omega(\tau)\}$ of alphabet values of $\Omega(\tau)$ is finite.*

Note that for classical cellular automata, the equivalence of items (a) and (b) does not require neither the topological mixing nor the soficity conditions on the subshift $\Sigma \subset A^G$ (this is a result going back to Kari, [50]). We do not know whether or not, in our more general setting, the above-mentioned conditions can be dropped. For classical cellular automata, the equivalence of items (b) and (c) is given in Theorem 13.1. Note that, however, if the alphabet A is infinite, for any group G, there exist non-nilpotent cellular automata whose limit set is reduced to a single configuration and therefore is finite (cf. Proposition A.2).

A linear version of the above theorem was given in [16, Theorem 1.9 and Corollary 1.10]. Our general strategy evolves around the analysis of the so-called *space-time inverse system* associated with a cellular automaton (cf. §4). Such inverse systems and their variants as

constructed in the proofs of the main theorems allow us to first conduct a local analysis of the dynamical system as in Theorems 7.1 and 9.1. We can then pass to the inverse limit, by means of the key technical algebro-geometric tools Lemmas 3.1 and 3.3, to obtain global properties such as a closed mapping property in Theorem 8.1 and a characterization of algebraic subshifts of finite type in Theorem 10.1. Variants of space-time inverse systems also allow us to reduce Theorem 1.5 to the finite alphabet case studied in Theorem 13.1.

We remark that by a similar strategy, it is shown in [42] that for a polycyclic-by-finite group G and an algebraic group V over an algebraically closed field K, all algebraic group sofic subshifts of A^G, where $A = V(K)$, are in fact algebraic group subshifts of finite type. Moreover, our techniques and results, notably the closed mapping property (Theorem 8.1) and the Noetherianity of algebraic subshifts of finite type (Theorem 10.1), admit a wide range of applications including the shadowing property of algebraic group cellular automata [43, 44], the Garden of Eden theorem for algebraic group cellular automata [47], a dynamical characterization of the Noetherianity of group rings in terms of the Markov properties [16], properties of images of algebraic subshifts under embeddings of symbolic varieties [45], and extensions of the direct finiteness conjecture of Kaplansky [17, 40, 41, 46, 48]. Finally, for interested readers, we would like to mention the connections of our results and their applications with some finiteness results in difference algebras and proalgebraic groups obtained in, e.g., [38, 56, 59].

Most of our results for arbitrary groups are inferred from the results for finitely generated groups by the restriction technique applied to cellular automata over *subshifts of sub-finite-type* (cf. §§2.4, 2.5, 2.6).

A detailed analysis is given in Example 15.1 to provide a non-trivial counter-example to Theorems 1.3 and 8.1. Some generalizations of our results are given in §16. In the Appendix, we study pointwise nilpotency over infinite groups and arbitrary alphabets (cf. Proposition A.5).

2. *Preliminaries*

2.1. *Notation.*
We use the symbols $\mathbb{Z}$ for the integers, $\mathbb{N}$ for the non-negative integers, $\mathbb{R}$ for the reals, and $\mathbb{C}$ for the complex numbers.

We write A^B for the set consisting of all maps from a set B into a set A. Let $C \subset B$. If $x \in A^B$, we denote by $x|_C$ the restriction of x to C, that is, the map $x|_C \colon C \to A$ given by $x|_C(c) = x(c)$ for all $c \in C$. If $X \subset A^B$, we denote $X_C := \{x|_C : x \in X\} \subset A^C$. Let E, F be subsets of a group G. We write $EF := \{gh : g \in E, h \in F\}$ and define inductively E^n for all $n \in \mathbb{N}$ by setting $E^0 := \{1_G\}$ and $E^{n+1} := E^n E$.

Let A be a set and let E be a subset of a group G. Given $x \in A^E$, we define $gx \in A^{gE}$ by $(gx)(h) := x(g^{-1}h)$ for all $h \in gE$.

2.2. *Algebraic varieties.*
Let V be an algebraic variety over a field K, that is, a reduced K-scheme of finite type. We equip V with its Zariski topology. Every subset $Z \subset V$ is equipped with the induced topology and we denote by $Z(K)$ the subset of K-points of V lying in Z. Subvarieties of V mean closed subsets with the reduced induced scheme structure.

Remark 2.1. Every subvariety of a complete (that is, proper) algebraic variety is also complete. Images of morphisms of complete algebraic varieties are complete subvarieties (cf. [31, §3.3.2]). Likewise, kernels and images of homomorphisms of algebraic groups are also algebraic subgroups and are thus Zariski closed (cf. [33, Proposition 1.41, Theorems 5.80, 5.81]).

Suppose now that the base field K is algebraically closed. Then we can identify the set of K-points $A = V(K)$ of a K-algebraic variety V with the set of closed points of V (cf. [21, Proposition 6.4.2]). By a common abuse, we regard A as an algebraic variety. Similarly, induced maps on closed points by morphisms of K-algebraic varieties are also called algebraic morphisms.

2.3. *Chain-recurrent points*

PROPOSITION 2.2. *Let X be a uniform space and let $f : X \to X$ be a continuous map. Then* $\mathrm{NW}(f) \subset \mathrm{CR}(f)$.

Proof. (Cf. [55, Proposition 1.7] in the metrizable case) Let $x \in \mathrm{NW}(f)$ and let E be an entourage of X. Choose a symmetric entourage S of X such that $S \circ S \subset E$. By the continuity of f at x, there exists a symmetric entourage T of X with $T \subset S$ such that $(f(x), f(z)) \in S$ whenever $(x, z) \in T$. The set $U \subset X$, consisting of all $z \in X$ such that $(x, z) \in T$, is a neighborhood of x. Since x is non-wandering, there exist an integer $n \geq 1$ and a point $y \in U$ such that $f^n(y) \in U$. Let us show that there is a sequence of points $x_0, x_1, \ldots, x_n \in X$ such that $x = x_0 = x_n$ and $(f(x_i), x_{i+1}) \in E$ for all $0 \leq i \leq n-1$. First observe that since $y \in U$, we have $(x, y) \in T$ and therefore $(f(x), f(y)) \in S$. If $n = 1$, we can take $x_0 = x_1 = x$. Indeed, we then have $f(y) = f^n(y) \in U$ and hence $(f(y), x) \in T \subset S$. Therefore, $(f(x_0), x_1) = (f(x), x) \in S \circ S \subset E$. If $n \geq 2$, we can take the points $x_0, x_1, \ldots, x_n$ defined by $x = x_0 = x_n$ and $x_i = f^i(y)$ for all $1 \leq i \leq n-1$. Indeed, we then have $(f(x_0), x_1) = (f(x), f(y)) \in S \subset S \circ S \subset E$. However, we have $(f(x_i), x_{i+1}) = (f^{i+1}(y), f^{i+1}(y)) \in E$ for all $1 \leq i \leq n-2$. Finally, as $f^n(y) \in U$, we have $(f(x_{n-1}), x_n) = (f^n(y), x) \in T \subset S \subset S \circ S \subset E$. This shows that $x \in \mathrm{CR}(f)$. □

PROPOSITION 2.3. *Let X be a Hausdorff uniform space and let $f : X \to X$ be a uniformly continuous map. Suppose that $f^n(X)$ is closed in X for all $n \in \mathbb{N}$. Then* $\mathrm{CR}(f) \subset \Omega(f)$.

Proof. Denote by $\mathcal{E}$ the set of entourages of X. Let $x \in \mathrm{CR}(f)$. Given $E \in \mathcal{E}$, we define $\nu(E) \in \mathbb{N} \setminus \{0\}$ to be the least $n \in \mathbb{N}$ such that there exists a sequence of points $x_0, x_1, \ldots, x_n \in X$ satisfying that $x = x_0 = x_n$ and $(f(x_i), x_{i+1}) \in E$ for all $0 \leq i \leq n-1$. Note that the map $\nu : \mathcal{E} \to \mathbb{N} \setminus \{0\}$ is decreasing in the sense that if $E, E' \in \mathcal{E}$ and $E \subset E'$, then $\nu(E') \leq \nu(E)$. We distinguish two cases according to whether the map ν is bounded or not.

In the first case, let $k := \max \nu$. Take $E_0 \in \mathcal{E}$ such that $\nu(E_0) = k$. Let $E \in \mathcal{E}$. Choose a symmetric entourage $S \in \mathcal{E}$ such that

$$\underbrace{S \circ S \circ \cdots \circ S}_{k \text{ times}} \subset E.$$

Since f is uniformly continuous, so are $f^2, \ldots, f^k$. Thus, we can find a symmetric entourage $T \subset E_0$ such that $(f^p(y), f^p(z)) \in S$ whenever $(y, z) \in T$ and $0 \le p \le k$. By the maximality of k and the fact that $T \subset E_0$, we have $\nu(T) = k$. Therefore, we can find a sequence of points $x_0, x_1, \ldots, x_k \in X$ such that $x = x_0 = x_k$ and $(f(x_i), x_{i+1}) \in T$ for all $0 \le i \le k - 1$. Looking at the sequence of points $f^k(x) = f^k(x_0), f^{k-1}(x_1), f^{k-2}(x_2), \ldots, f^1(x_{k-1}), x_k = x$ and using the fact that, for all $0 \le i \le k - 1$,

$$(f^{k-i}(x_i), \quad f^{k-i-1}(x_{i+1})) = (f^{k-i-1}(f(x_i)), \quad f^{k-i-1}(x_{i+1}))) \in S$$

since $(f(x_i), x_{i+1}) \in T$, we see that

$$(f^k(x), x) \in \underbrace{S \circ S \circ \cdots \circ S}_{k \text{ times}} \subset E.$$

As the entourage $E \in \mathcal{E}$ was arbitrary and X is Hausdorff, it follows that $x = f^k(x)$. Hence, the point x is periodic and therefore belongs to $\Omega(f)$.

Consider now the second case, where ν is unbounded. Let $m \ge 1$ be an integer. We will show that $x \in f^m(X)$. Take $E_0 \in \mathcal{E}$ so that $\nu(E_0) \ge m$. Let $E \in \mathcal{E}$. Choose a symmetric entourage $S \in \mathcal{E}$ such that

$$\underbrace{S \circ S \circ \cdots \circ S}_{m \text{ times}} \subset E.$$

As in the first case, we can find a symmetric entourage $T \in \mathcal{E}$ such that $T \subset E_0$ and $(f^p(y), f^p(z)) \in S$ whenever $(y, z) \in T$ and $0 \le p \le m$. Observe that $n := \nu(T) \ge \nu(E_0) \ge m$ since $T \subset E_0$. By definition of ν, we can find a sequence of points $x_0, x_1, \ldots, x_n \in X$ such that $x = x_0 = x_n$ and $(f(x_i), x_{i+1}) \in T$ for all $0 \le i \le n - 1$. Looking now at the sequence of points $f^m(x_{n-m}), f^{m-1}(x_{n-m+1}), \ldots, f(x_{n-1}), x_n = x$, and using the fact that, for all $0 \le i \le m - 1$, we have

$$(f^{m-i}(x_{n-m+i}), f^{m-i-1}(x_{n-m+i+1}))$$
$$= (f^{m-i-1}(f(x_{n-m+i})), f^{m-i-1}(x_{n-m+i+1})) \in S$$

since $(f(x_{n-m+i})), x_{n-m+i+1}) \in T$, we see that

$$(f^m(x_{n-m}), x) \in \underbrace{S \circ S \circ \cdots \circ S}_{m \text{ times}} \subset E.$$

As the entourage $E \in \mathcal{E}$ was arbitrary, it follows that x belongs to the closure of $f^m(X)$. Since $f^m(X)$ is closed in X by our hypothesis, we conclude that $x \in f^m(X)$ for every $m \ge 1$. This shows that $x \in \Omega(f)$. $\square$

Using the fact that the topology of any compact Hausdorff space is induced by a unique uniform structure, an immediate consequence of Proposition 2.3 is the following well-known result (see e.g. [37, Ch. 6]).

COROLLARY 2.4. *Let X be a compact Hausdorff space and let $f : X \to X$ be a continuous map. Then* $\mathrm{CR}(f) \subset \Omega(f)$.

2.4. *Subshifts of sub-finite-type.* Let G be a group and let A be a set. A subshift $\Sigma \subset A^G$ is called a *subshift of sub-finite-type* if it is a factor of a subshift of finite type (cf. (1.1)), namely, there exist a set B, a cellular automaton $\tau' \colon B^G \to A^G$, and a subshift of finite type $\Sigma' \subset B^G$ such that $\Sigma = \tau'(\Sigma')$. Note that we do not require Σ to be closed in A^G. In the following, every finite subset D of G containing a defining memory set of Σ' as well as a memory set of τ' will be called a *memory set* of the subshift of sub-finite-type Σ. The existence of such a memory set will be necessary for the restriction technique (cf. §§2.5 and 2.6) when the group G is not finitely generated.

Example 2.5. If G is a group, V is an algebraic variety over a field K, and $A := V(K)$, then it immediately follows from Definition 1.2 in §1 that every algebraic sofic subshift $\Sigma \subset A^G$ is a subshift of sub-finite-type of A^G.

In the rest of the paper, a *memory set* of an algebraic sofic subshift Σ will mean any memory set of Σ regarded as a subshift of sub-finite-type.

Example 2.6. Let A be a set and let Γ be an A-labeled directed graph. This means that Γ is a quintuple $\Gamma = (V, E, \alpha, \omega, \lambda)$, where V, E are sets, and $\alpha, \omega \colon E \to V$, $\lambda \colon E \to A$ are maps. The elements of V are called the *vertices* of Γ, those of E are called its *edges*, and, for every edge $e \in E$, the vertex $\alpha(e)$ (respectively $\omega(e)$) is called the *initial* (respectively *terminal*) vertex of e while $\lambda(e)$ is called its *label*. The *label* of a configuration $x \in E^{\mathbb{Z}}$ is the configuration $\Lambda(x) \in A^{\mathbb{Z}}$ defined by $\Lambda(x)(n) = \lambda(x(n))$ for all $n \in \mathbb{Z}$. Observe that $\Lambda \colon E^{\mathbb{Z}} \to A^{\mathbb{Z}}$ is a cellular automaton admitting $M := \{0\} \subset \mathbb{Z}$ as a memory set and $\lambda \colon E^M = E \to A$ as the associated local defining map. An element $x \in E^{\mathbb{Z}}$ is called a *path* of Γ if it satisfies $\omega(x(n)) = \alpha(x(n+1))$ for all $n \in \mathbb{Z}$. Clearly, the subset $\Sigma' \subset E^{\mathbb{Z}}$ consisting of all paths of Γ is the subshift of finite type $\Sigma(D, P)$ of $E^{\mathbb{Z}}$, where $D := \{0, 1\} \subset \mathbb{Z}$ and $P := \{p \in E^D : \omega(p(0)) = \alpha(p(1))\}$. One says that Σ' is the *Markov shift* associated with the unlabeled graph (V, E, α, ω) (cf. [28, Ch. 7]). We deduce that $\Sigma := \Lambda(\Sigma')$ is a subshift of sub-finite-type of $A^{\mathbb{Z}}$. Conversely, it can be shown that every subshift of sub-finite-type of $A^{\mathbb{Z}}$ can be obtained, up to topological conjugacy, as the set of labels of the paths of a suitably chosen A-labeled graph. The proof of this last result is, *mutatis mutandis*, the one used in the classical setting for showing that every sofic finite alphabet subshift over $\mathbb{Z}$ can be presented by a finite labeled graph (see e.g. [30, Theorem 3.2.1]).

The following result says that the notion of subshifts of sub-finite-type is only interesting when G is not finitely generated.

PROPOSITION 2.7. *Let G be a finitely generated group and let A be a set. Then every subshift $\Sigma \subset A^G$ is a subshift of sub-finite-type.*

Proof. Let D be a finite generating subset of G such that $1_G \in D$ and $D = D^{-1}$. Let $\Sigma \subset A^G$ be a subshift. Let $B := \Sigma$ and define $P := \{y \in B^D : y(g) = g^{-1}(y(1_G))$ for all $g \in D\}$. Consider the subshift of finite type $\Sigma' := \Sigma(D, P)$ of B^G. Since $D = D^{-1}$ generates G and contains 1_G, the map $\mathfrak{X} \mapsto \mathfrak{X}(1_G)$ is a bijection from

Σ' onto Σ. Indeed, for every $g \in G$ and $\mathfrak{X} \in \Sigma'$, by writing $g = s_1 \cdots s_n$ for some $s_1, \ldots, s_n \in D$, we find that

$$\mathfrak{X}(g) = \mathfrak{X}(s_1 \cdots s_n) = s_1^{-1} \mathfrak{X}(s_2 \cdots s_n) = \cdots = s_n^{-1} \cdots s_1^{-1} (\mathfrak{X}(1_G)) = g^{-1} \mathfrak{X}(1_G).$$

Let $\tau : B^G \to A^G$ be the cellular automaton with memory set $\{1_G\}$ and associated local defining map $\mu : B \to A$ given by $x \mapsto x(1_G)$. In other words, $\tau(\mathfrak{X})(g) = (\mathfrak{X}(g))(1_G)$ for every $\mathfrak{X} \in B^G$ and $g \in G$. Hence, for every $\mathfrak{X} \in \Sigma'$, we have $\tau(\mathfrak{X}) = \mathfrak{X}(1_G)$ since for all $g \in G$,

$$\tau(\mathfrak{X})(g) = (\mathfrak{X}(g))(1_G) = (g^{-1}(\mathfrak{X}(1_G)))(1_G) = (\mathfrak{X}(1_G))(g).$$

As $\mathfrak{X}(1_G) \in B = \Sigma$ is arbitrary, we conclude that $\Sigma = \tau(\Sigma')$ is a subshift of sub-finite-type. $\square$

2.5. *Restriction of cellular automata and of subshifts of sub-finite-type.* Let G be a group and let A be a set. Let $\Sigma \subset A^G$ be a subshift of sub-finite-type. Hence, there exist a set B, a cellular automaton $\tau' : B^G \to A^G$, and a subshift of finite type $\Sigma' \subset B^G$ such that $\Sigma = \tau'(\Sigma')$. Let $D \subset G$ be a finite subset such that D is a defining memory set of Σ' as well as a memory set of τ'. Let $H \subset G$ be a subgroup of G containing D. Denote by $G/H := \{gH : g \in G\}$ the set of all right cosets of H in G. As the right cosets of H in G form a partition of G, we have natural factorizations

$$A^G = \prod_{c \in G/H} A^c, \quad B^G = \prod_{c \in G/H} B^c$$

in which each $x \in A^G$ (respectively $x \in B^G$) is identified with $(x|_c)_{c \in G/H} \in \prod_{c \in G/H} A^c$ (respectively $(x|_c)_{c \in G/H} \in \prod_{c \in G/H} B^c$). Since $gD \subset gH$ for every $g \in G$, the above factorization of B^G induces a factorization

$$\Sigma' = \prod_{c \in G/H} \Sigma'_c,$$

where $\Sigma'_c = \{x|_c : x \in \Sigma'\}$ for all $c \in G/H$. Likewise, for each $c \in G/H$, let $\Sigma_c = \{x|_c : x \in \Sigma\}$.

LEMMA 2.8. *The factorization* $A^G = \prod_{c \in G/H} A^c$ *induces a factorization*

$$\Sigma = \prod_{c \in G/H} \Sigma_c.$$

Proof. Since H contains a memory set of τ', we have $\tau' = \prod_{c \in G/H} \tau'_c$, where $\tau'_c : B^c \to A^c$ is given by $\tau'_c(y) := \tau'(x)|_c$ for all $y \in B^c$, where $x \in B^G$ is any configuration extending y. We deduce that $\Sigma_c = (\tau'(\Sigma'))_c = \tau'_c(\Sigma'_c)$ for every $c \in G/H$. Hence,

$$\Sigma = \tau'(\Sigma') = \tau'\left(\prod_{c \in G/H} \Sigma'_c\right) = \prod_{c \in G/H} \tau'_c(\Sigma'_c) = \prod_{c \in G/H} \Sigma_c. \qquad \square$$

Let $T \subset G$ be a complete set of representatives for the right cosets of H in G such that $1_G \in T$. Then, for each $c \in G/H$, we have a uniform homeomorphism $\phi_c \colon \Sigma_c \to \Sigma_H$ given by $\phi_c(y)(h) = y(gh)$ for all $y \in \Sigma_c$, where $g \in T$ represents c. In particular, $\Sigma \neq \varnothing$ if and only if $\Sigma_H \neq \varnothing$.

Now suppose in addition that $\tau \colon \Sigma \to \Sigma$ is a cellular automaton which admits a memory set contained in H. Then we have $\tau = \prod_{c \in G/H} \tau_c$, where $\tau_c \colon \Sigma_c \to \Sigma_c$ is defined by setting $\tau_c(y) := \tau(x)|_c$ for all $y \in \Sigma_c$, where $x \in \Sigma$ is any configuration extending y. Note that for each $c \in G/H$, the maps τ_c and τ_H are conjugate by ϕ_c, that is, we have $\tau_c = \phi_c^{-1} \circ \tau_H \circ \phi_c$. This allows us to identify the action of τ_c on Σ_c with that of the restriction cellular automaton τ_H on Σ_H. See **9** and [**10**, Section 1.7].

LEMMA 2.9. *The following hold:*
(i) $\Omega(\tau) = \Omega(\tau_H)^{G/H}$;
(ii) τ *is nilpotent if and only if* τ_H *is nilpotent.*

Proof. Observe that the map $x \mapsto (\phi_c(x|_c))_{c \in G/H}$ yields a bijection $\Omega(\tau) \to \prod_{c \in G/H} \Omega(\tau_H) = \Omega(\tau_H)^{G/H}$, and this proves point (i). Point (ii) is clear by the above discussion. $\square$

2.6. *Restriction and the closed image property.*   Let G be a group and let A, B be sets. Let $\Sigma \subset A^G$ be a subshift of sub-finite-type and let now $\tau \colon A^G \to B^G$ be a cellular automaton whose source and domain are the full shifts A^G and B^G, respectively. Let $H \subset G$ be a subgroup of G containing a memory set of Σ and a memory set of τ. As in §2.5, we have the factorizations $\Sigma = \prod_{c \in G/H} \Sigma_c$ (cf. Lemma 2.8) and $\tau = \prod_{c \in G/H} \tau_c$, with $\tau_c \colon A^c \to B^c$ defined by $\tau_c(y) := \tau(x)|_c$ for all $y \in A^c$, where $x \in A^G$ is any configuration extending y.

LEMMA 2.10. *The set $\tau(\Sigma)$ is closed in B^G if and only if $\tau_H(\Sigma_H)$ is closed in B^H.*

Proof. We have $\tau(\Sigma) = \prod_{c \in G/H} \tau_c(\Sigma_c)$. It is immediate that $\tau_H(\Sigma_H)$ is closed in B^H if $\tau(\Sigma)$ is closed in B^G. For the converse implication, we have for every $c \in G/H$ a uniform homeomorphism $\psi_c \colon B^c \to B^H$ by fixing a complete set containing 1_G of representatives for the right cosets of H in G (cf. §2.5). Thus, if $\tau_H(\Sigma_H)$ is closed, then so is $\tau_c(\Sigma_c) = \psi_c^{-1}(\tau_H(\Sigma_H))$. Consequently, $\tau(\Sigma)$ is closed in B^G whenever $\tau_H(\Sigma_H)$ is closed in B^H since the product of closed subspaces is closed in the product topology. $\square$

3. *Inverse limits of countably pro-constructible sets*
Let I be a directed set, that is, a partially ordered set in which every pair of elements admits an upper bound. An *inverse system* of sets *indexed* by I consists of the following data: (1) a set Z_i for each $i \in I$; (2) a *transition map* $\varphi_{ij} \colon Z_j \to Z_i$ for all $i, j \in I$ such that $i \prec j$. Furthermore, the transition maps must satisfy the following conditions:

$$\varphi_{ii} = \mathrm{Id}_{Z_i} \quad \text{(the identity map on } Z_i\text{) for all } i \in I,$$
$$\varphi_{ij} \circ \varphi_{jk} = \varphi_{ik} \quad \text{for all } i, j, k \in I \text{ such that } i \prec j \prec k.$$

One then speaks of the inverse system (Z_i, φ_{ij}), or simply (Z_i) if the index set and the transition maps are clear from the context.

The *inverse limit* of an inverse system (Z_i, φ_{ij}) is the subset

$$\varprojlim_{i \in I}(Z_i, \varphi_{ij}) = \varprojlim_{i \in I} Z_i \subset \prod_{i \in I} Z_i$$

consisting of all $(z_i)_{i \in I}$ such that $\varphi_{ij}(z_j) = z_i$ for all $i \prec j$.

A subset of a topological space X is said to be *locally closed* if it is the intersection of a closed subset and an open subset of X. It is said to be *constructible* if it is a finite union of locally closed subsets of X. It is said to be *proconstructible* if it is the intersection of a family of constructible subsets [**22**, Définition I.9.4]. We shall say that a subset of X is *countably proconstructible* if it is the intersection of a countable family of constructible subsets. It is clear that every countably proconstructible subset can be written as the intersection of a decreasing sequence of constructible subsets.

The following lemma is analogous to [**39**, Lemma 4.1].

LEMMA 3.1. *Let K be an uncountable algebraically closed field and let $f : X \to Y$ be an algebraic morphism of algebraic varieties over K. If $(C_k)_{k \in \mathbb{N}}$ is a decreasing sequence of constructible subsets of X, then*

$$f\left(\bigcap_{k \in \mathbb{N}} C_k(K)\right) = \bigcap_{k \in \mathbb{N}} f(C_k(K)) = \bigcap_{k \in \mathbb{N}} f(C_k)(K).$$

Proof. Since for each $k \in \mathbb{N}$ we have $f(C_k(K)) = f(C_k)(K)$ (cf. for example [**14**, Lemma A.22(v)]), the second equality is verified. For the first equality, we have trivially $f(\bigcap_{k \in \mathbb{N}} C_k(K)) \subset \bigcap_{k \in \mathbb{N}} f(C_k(K))$. Conversely, assume that $y \in \bigcap_{k \in \mathbb{N}} f(C_k(K))$. For each $k \in \mathbb{N}$, set

$$F_k := f^{-1}(y) \cap C_k(K) \subset X(K).$$

Note that F_k is the set of closed points of a constructible subset of X. Remark also that, for every $k \in \mathbb{N}$, we have $F_{k+1} \subset F_k$ and $F_k \neq \varnothing$. Hence, by [**14**, Lemma B.3], there exists $x \in \bigcap_{k \in \mathbb{N}} F_k$. Clearly, $f(x) = y$ and $x \in \bigcap_{k \in \mathbb{N}} C_k(K)$. Therefore, $\bigcap_{k \in \mathbb{N}} f(C_k(K)) \subset f(\bigcap_{k \in \mathbb{N}} C_k(K))$ and the proof is completed. $\square$

In case (H1), we shall make use of the following generalization of [**14**, Lemma B.2] to countable inverse systems of countably proconstructible subsets.

LEMMA 3.2. *Let K be an uncountable algebraically closed field. Let (X_i, f_{ij}) be an inverse system indexed by a countable directed set I, where each X_i is a K-algebraic variety and each transition map $f_{ij} : X_j \to X_i$ is an algebraic morphism. Suppose given, for each $i \in I$, a non-empty countably proconstructible subset $C_i \subset X_i$. Let $Z_i = C_i(K)$ and assume that $f_{ij}(Z_j) \subset Z_i$ for all $i \prec j$ in I. Then the inverse system $(Z_i, \varphi_{ij})_I$, where $\varphi_{ij} : Z_j \to Z_i$ is the restriction of f_{ij} to Z_j, verifies $\varprojlim_{i \in I} Z_i \neq \varnothing$.*

Proof. Since I is a countable directed set, we can find a totally ordered cofinal subset $\{i_n : n \in \mathbb{N}\} \subset I$. As $\varprojlim_{n \in \mathbb{N}} Z_{i_n} = \varprojlim_{i \in I} Z_i$, we can suppose, without any loss of generality, that $I = \mathbb{N}$.

For each $i \in \mathbb{N}$, we can find a decreasing sequence of constructible subsets $(C_{ik})_{k \in \mathbb{N}}$ of X_i such that $C_i = \bigcap_{k \in \mathbb{N}} C_{ik}$. For $k \in \mathbb{N}$, let $Z_{ik} = C_{ik}(K)$. By Lemma 3.1, we have for every $i \leq j$:

$$Z_i = \bigcap_{k=0}^{\infty} Z_{ik} \neq \varnothing, \quad f_{ij}(Z_j) = \bigcap_{k=0}^{\infty} f_{ij}(Z_{jk}). \tag{3.1}$$

Consider the universal inverse system $(Z_i', \varphi_{ij}')_{i,j \in \mathbb{N}}$ of the system $(Z_i, \varphi_{ij})_{i,j \in \mathbb{N}}$, that is, for every $i \in \mathbb{N}$, let

$$Z_i' := \bigcap_{j=i}^{\infty} f_{ij}(Z_j) = \bigcap_{j=i}^{\infty} \varphi_{ij}(Z_j)$$

and let the maps $\varphi_{ij}' : Z_j' \to Z_i'$ be the restrictions of $\varphi_{ij} : Z_j \to Z_i$.

Remark that $\varprojlim_{i \in \mathbb{N}} Z_i' = \varprojlim_{i \in \mathbb{N}} Z_i$. Hence, it suffices to check that the sets Z_i' are non-empty and the transition maps φ_{ij}' are surjective for all $i \leq j$. By equation (3.1), Chevalley's theorem (see for example [57, Theorem 7.4.2], [22, Théorème I.8.4]) implies that each Z_i' is a countable intersection of constructible sets:

$$Z_i' = \bigcap_{j=i}^{\infty} f_{ij}(Z_j) = \bigcap_{j=i}^{\infty} \bigcap_{k=0}^{\infty} f_{ij}(Z_{jk}).$$

For each $n \geq i$, consider the diagonal set

$$Y_n := \bigcap_{j=i}^{n} \bigcap_{k=0}^{n} f_{ij}(Z_{jk}) \subset X_i(K).$$

By Chevalley's theorem, Y_n is a constructible subset of $X_i(K)$. For every $n \geq i$, we have $Y_{n+1} \subset Y_n$ and since $Z_n \neq \varnothing$,

$$Y_n \supset \bigcap_{j=i}^{n} \bigcap_{k=0}^{\infty} f_{ij}(Z_{jk}) = \bigcap_{j=i}^{n} f_{ij}(Z_j) \supset f_{in}(Z_n) = \varphi_{in}(Z_n) \neq \varnothing. \tag{3.2}$$

As $Z_i' = \bigcap_{n=i}^{\infty} Y_n$, [14, Lemma B.2] implies that $Z_i' \neq \varnothing$ for $i \in \mathbb{N}$. Now let $k, i \in \mathbb{N}$ with $k \leq i$ and let $z \in Z_k'$. For each $n \geq i$, by definition of Z_k', there exists $y \in Z_n$ such that $\varphi_{kn}(y) = z$ and thus

$$\varphi_{in}(y) \in \varphi_{ki}^{-1}(z) \cap \varphi_{in}(Z_n) \neq \varnothing. \tag{3.3}$$

By equations (3.2), (3.3), and for $n \geq i$, the constructible subset

$$T_n := \varphi_{ki}^{-1}(z) \cap Y_n \supset \varphi_{ki}^{-1}(z) \cap \varphi_{in}(Z_n) \tag{3.4}$$

is non-empty and $T_{n+1} \subset T_n$ as $Y_{n+1} \subset Y_n$. Finally, we find that

$$(\varphi'_{ki})^{-1}(z) = \varphi_{ki}^{-1}(z) \cap Z'_i = \bigcap_{n=i}^{\infty} \varphi_{ki}^{-1}(z) \cap Y_n = \bigcap_{n=i}^{\infty} T_n$$

is non-empty by [**14**, Lemma B.2]. The proof is thus completed. □

We shall apply repeatedly the following result in cases (H2)–(H3).

LEMMA 3.3. *Let K be an algebraically closed field. Let (X_i, f_{ij}) be an inverse system indexed by a countable index set I, where each X_i is a non-empty K-algebraic variety and each transition map $f_{ij} \colon X_j \to X_i$ is an algebraic morphism such that $f_{ij}(X_j) \subset X_i$ is a closed subset for all $i \prec j$. Then $\varprojlim_{i \in I} X_i(K) \neq \varnothing$.*

Proof. The statement is proved in [**39**, Proposition 4.2]. □

4. *Space-time inverse systems*
Let G be a finitely generated group and let A be a set. Let $\Sigma \subset A^G$ be a closed subshift and assume that $\tau \colon \Sigma \to \Sigma$ is a cellular automaton. Let $\tilde{\tau} \colon A^G \to A^G$ be a cellular automaton extending τ.

Let $M \subset G$ be a memory set of $\tilde{\tau}$. Since every finite subset of G containing a memory set of $\tilde{\tau}$ is itself a memory set of $\tilde{\tau}$, we can choose M such that $1_G \in M$, $M = M^{-1}$, and M generates G. Note that this implies in particular that the sequence $(M^n)_{n \in \mathbb{N}}$ is an *exhaustion* of G, that is:

(Mem1) $M^{n+1} \supset M^n$ for all $n \in \mathbb{N}$; and
(Mem2) $\bigcup_{n \in \mathbb{N}} M^n = G$.

Equip $\mathbb{N}^2$ with the product ordering $\prec$. Thus, given $i, j, k, l \in \mathbb{N}$, we have $(i, j) \prec (k, l)$ if and only if $i \leq k$ and $j \leq l$.

We construct an inverse system $(\Sigma_{ij})_{i, j \in \mathbb{N}}$ indexed by the directed set $(\mathbb{N}^2, \prec)$ in the following way.

First, given $i, j \in \mathbb{N}$, we define Σ_{ij} as being the set consisting of the restrictions to M^{i+j} of all the configurations that belong to Σ, that is,

$$\Sigma_{ij} := \Sigma_{M^{i+j}} = \{x|_{M^{i+j}} : x \in \Sigma\} \subset A^{M^{i+j}}.$$

To define the transition maps $\Sigma_{kl} \to \Sigma_{ij}$ $((i, j) \prec (k, l))$ of the inverse system $(\Sigma_{ij})_{i, j \in \mathbb{N}}$, it is clearly enough to define, for all $i, j \in \mathbb{N}$, the *unit-horizontal* transition map $p_{ij} \colon \Sigma_{i+1,j} \to \Sigma_{ij}$, the *unit-vertical* transition map $q_{ij} \colon \Sigma_{i,j+1} \to \Sigma_{ij}$, and verify that the diagram

$$
\begin{array}{ccc}
\Sigma_{i,j+1} & \xleftarrow{\;p_{i,j+1}\;} & \Sigma_{i+1,j+1} \\
{\scriptstyle q_{ij}}\big\downarrow & & \big\downarrow{\scriptstyle q_{i+1,j}} \\
\Sigma_{ij} & \xleftarrow{\;p_{ij}\;} & \Sigma_{i+1,j}
\end{array}
$$

is commutative, that is,

$$q_{ij} \circ p_{i,j+1} = p_{ij} \circ q_{i+1,j} \quad \text{for all } i, j \in \mathbb{N}. \tag{4.1}$$

We define p_{ij} as being the map obtained by restriction to $M^{i+j} \subset M^{i+j+1}$. Thus for all $\sigma \in \Sigma_{i+1,j}$, we have

$$p_{ij}(\sigma) = \sigma|_{M^{i+j}}. \tag{4.2}$$

To define q_{ij}, we first observe that, given $x \in \Sigma$ and $g \in G$, it follows from equation (1.2) applied to $\widetilde{\tau}$ that $\tau(x)(g)$ only depends on the restriction of x to gM. As $gM \subset M^{i+j+1}$ for all $g \in M^{i+j}$, we deduce from this observation that, given $\sigma \in \Sigma_{i,j+1}$ and $x \in \Sigma$ extending σ, the formula

$$q_{ij}(\sigma) := (\tau(x))|_{M^{i+j}} \tag{4.3}$$

yields a well-defined element $q_{ij}(\sigma) \in \Sigma_{ij}$ and hence a map $q_{ij} \colon \Sigma_{i,j+1} \to \Sigma_{ij}$.

To check that equation (4.1) is satisfied, let $\sigma \in \Sigma_{i+1,j+1}$ and choose a configuration $x \in \Sigma$ extending σ. By applying equation (4.2), we see that $p_{i,j+1}(\sigma) = x|_{M^{i+j+1}}$. Therefore, using equation (4.3), we get

$$q_{ij} \circ p_{i,j+1}(\sigma) = q_{ij}(p_{i,j+1}(\sigma)) = q_{ij}(x|_{M^{i+j+1}}) = (\tau(x))|_{M^{i+j}}. \tag{4.4}$$

However, by applying again equation (4.3), we see that $q_{i+1,j}(\sigma) = (\tau(x))|_{M^{i+j+1}}$. Therefore, using equation (4.2), we get

$$p_{ij} \circ q_{i+1,j}(\sigma) = p_{ij}(q_{i+1,j}(\sigma)) = p_{ij}((\tau(x))|_{M^{i+j+1}}) = (\tau(x))|_{M^{i+j}}. \tag{4.5}$$

We deduce from equations (4.4) and (4.5) that $q_{ij} \circ p_{i,j+1}(\sigma) = p_{ij} \circ q_{i+1,j}(\sigma)$ for all $\sigma \in \Sigma_{i+1,j+1}$. This shows equation (4.1).

Definition 4.1. The inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ is called the *space-time inverse system* associated with the triple (Σ, τ, M).

It might be useful to consider the inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ as a refined diagram of the space-time evolution of the cellular automaton τ that in addition keeps track of the local dynamics. Comparing to the usual space-time diagram of a classical cellular automaton introduced in [61], in [34], or recently in [19], the main difference of our construction is the following. First, the horizontal direction indexed by $i \in \mathbb{N}$ in our space-time inverse system represents the extension of the ambient spaces of 1_G instead of the exact position in the universe G as in the classical diagram. Second, the vertical direction indexed by $j \in \mathbb{N}$ represents the past instead of the future. More precisely, let us fix $i \in \mathbb{N}$ and consider the induced inverse subsystem $(\Sigma_{ij})_{j \in \mathbb{N}}$ lying above $\Sigma_{i0} = \Sigma_{M^i}$. Then each $(\Sigma_{ij})_{j \in \mathbb{N}}$ should be regarded as an approximation of the past light cone of the events happening in M^i, that is, of configurations $\sigma \in \Sigma_{M^i}$.

Remark 4.2. Observe that the inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ is a subsystem of the *full* inverse system $(A^{M^{i+j}})_{i,j \in \mathbb{N}}$ associated with the triple $(A^G, \widetilde{\tau}, M)$. In the following, we shall denote by $\widetilde{p}_{ij} \colon A^{M^{i+j+1}} \to A^{M^{i+j}}$ (respectively $\widetilde{q}_{ij} \colon A^{M^{i+j+1}} \to A^{M^{i+j}}$) the unit horizontal (respectively vertical) transition maps of the full inverse system $(A^{M^{i+j}})_{i,j \in \mathbb{N}}$.

Remark 4.3. For the hypotheses (H1), (H2), and (H3) in §1, we have the following easy but useful remark. If $A = V(K)$ for some algebraic variety V over an algebraically closed field K and if $\widetilde{\tau} \colon A^G \to A^G$ is an algebraic (respectively algebraic group) cellular automaton, then the transition maps of the full inverse system $(A^{M^{i+j}})_{i,j \in \mathbb{N}}$ are algebraic morphisms (respectively homomorphisms of algebraic groups).

If we fix $j \in \mathbb{N}$ in our space-time inverse system, we get a *horizontal* inverse system $(\Sigma_{ij})_{i \in \mathbb{N}}$ indexed by $\mathbb{N}$ whose transition maps are the restriction maps $p_{ij} \colon \Sigma_{i+1,j} \to \Sigma_{ij}$, $i \in \mathbb{N}$. It immediately follows from the closedness of Σ in A^G and properties (Mem1)–(Mem2) that the limit

$$\Sigma_j := \varprojlim_{i \in \mathbb{N}} \Sigma_{ij} \tag{4.6}$$

can be identified with Σ in a canonical way. Moreover, the maps $q_{ij} \colon \Sigma_{i,j+1} \to \Sigma_{ij}$ define an inverse system morphism from the inverse system $(\Sigma_{i,j+1})_{i \in \mathbb{N}}$ to the inverse system $(\Sigma_{ij})_{i \in \mathbb{N}}$. This yields a limit map $\tau_j \colon \Sigma_{j+1} \to \Sigma_j$. Using the identifications $\Sigma_{j+1} = \Sigma_j = \Sigma$, we have $\tau_j = \tau$ for all $j \in \mathbb{N}$. We deduce that the limit

$$\varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij} = \varprojlim_{j \in \mathbb{N}} \Sigma_j \tag{4.7}$$

is the set of *backward orbits* (or *complete histories* [34]) of τ, that is, the set consisting of all sequences $(x_j)_{j \in \mathbb{N}}$ such that $x_j \in \Sigma$ and $x_j = \tau(x_{j+1})$ for all $j \in \mathbb{N}$. Such a sequence satisfies $x_0 = \tau^n(x_n)$ for all $n \in \mathbb{N}$ and hence $x_0 \in \Omega(\tau)$. Thus, we obtain the following result.

LEMMA 4.4. *We have a canonical map* $\Phi \colon \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij} \to \Omega(\tau)$. *In particular, we have that*

$$\varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij} \neq \varnothing \implies \Omega(\tau) \neq \varnothing.$$

We will see that the map $\Phi \colon \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij} \to \Omega(\tau)$ is surjective in the algebraic setting (cf. Theorem 9.1). Therefore, in this case, every limit configuration $x \in \Omega(\tau)$ admits a backward orbit and $\tau(\Omega(\tau)) = \Omega(\tau)$.

5. *Approximation of subshifts of finite type*

In this section, keeping all the notation and hypotheses introduced in the previous section, we assume in addition that Σ is a subshift of finite type. We fix a finite subset $D \subset G$ and a subset $P \subset A^D$ such that $\Sigma = \Sigma(D, P)$ (cf. equation (1.1)). We begin with a useful observation.

LEMMA 5.1. *For every finite subset $E \subset G$ such that $D \subset E$, we have $\Sigma = \Sigma(D, P) = \Sigma(E, \Sigma_E)$.*

Proof. Let $x \in \Sigma$ and $g \in G$, then clearly $(g^{-1}x)|_E \in \Sigma_E$. Thus, $\Sigma \subset \Sigma(E, \Sigma_E)$. Conversely, let $x \in \Sigma(E, \Sigma_E)$ and $g \in G$, then $(g^{-1}x)|_D = ((g^{-1}x)|_E)|_D \in (\Sigma_E)_D \subset P$ since $D \subset E$. Therefore, $x \in \Sigma(D, P) = \Sigma$ and the conclusion follows. $\square$

For all $i, j \in \mathbb{N}$, we define $D_{ij} := \{g \in G : gD \subset M^{i+j}\}$ and

$$A_{ij} := \{x \in A^{M^{i+j}} : (g^{-1}x)|_D \in P \text{ for all } g \in D_{ij}\}.$$

Remark that $\Sigma_{ij} \subset A_{ij}$. Indeed, we have

$$
\begin{aligned}
\Sigma_{ij} &= \{x \in A^{M^{i+j}} : \text{ there exists } y \in A^G, x = y|_{M^{i+j}}, (g^{-1}y)|_D \in P \text{ for all } g \in G\} \\
&\subset \{x \in A^{M^{i+j}} : \text{ there exists } y \in A^G, x = y|_{M^{i+j}}, (g^{-1}y)|_D \in P \text{ for all } g \in D_{ij}\} \\
&= \{x \in A^{M^{i+j}} : (g^{-1}x)|_D \in P \text{ for all } g \in D_{ij}\} \\
&= A_{ij}.
\end{aligned}
$$

Remark also that for all $(i, j) \prec (k, l)$ in $\mathbb{N}^2$, we have $D_{ij} \subset D_{kl}$ because $M^{i+j} \subset M^{k+l}$ by property (Mem1).

For $i, j, k \in \mathbb{N}$ such that $i \leq k$, consider the canonical projection

$$\widetilde{p}_{ijk} : A^{M^{k+j}} \to A^{M^{i+j}}, \quad x \mapsto x|_{M^{i+j}}. \tag{5.1}$$

Clearly, $\widetilde{p}_{ijk}(A_{kj}) \subset A_{ij}$ since $D_{ij} \subset D_{k+j}$. We thus obtain well-defined projection maps

$$p_{ijk} : A_{kj} \to A_{ij}, \tag{5.2}$$

which extend the horizontal transition maps $\Sigma_{kj} \to \Sigma_{ij}$ of the space-time inverse system $(\Sigma_{ij})_{i,j\in\mathbb{N}}$ associated with $\tau : \Sigma \to \Sigma$ and the memory set M.

Remark 5.2. In general, $(A_{ij})_{i,j\in\mathbb{N}}$ is not a subsystem of the space-time inverse system $(A^{M^{i+j}})_{i,j\in\mathbb{N}}$ associated with $(A^G, \widetilde{\tau}, M)$ (cf. Remark 4.2). There is no trivial reason for $\widetilde{q}_{ij}(A_{i,j+1}) \subset A_{ij}$ unless Σ is the full shift.

The following lemma says that each row of the system $(A_{ij}, p_{ijk})_{i,j,k\in\mathbb{N}}$ gives us an approximation of Σ.

LEMMA 5.3. *For every $j \in \mathbb{N}$, there is a canonical bijection*

$$\Psi_j : \Sigma \to \varprojlim_{i\in\mathbb{N}}(A_{ij}, p_{ijk}).$$

Proof. Since $\Sigma_{ij} \subset A_{ij}$ for all $i, j \in \mathbb{N}$, each $x \in \Sigma$ defines naturally an element $\Psi_j(x) = (x|_{M^{i+j}})_{i\in\mathbb{N}} \in \varprojlim_{i\in\mathbb{N}}(A_{ij}, p_{ijk})$. Conversely, let $(x_i)_{i\in\mathbb{N}} \in \varprojlim_{i\in\mathbb{N}}(A_{ij}, p_{ijk})$. Define $x \in A^G$ by setting, for each $g \in G$, $x(g) := x_i(g)$ for any $i \in \mathbb{N}$ large enough such that $g \in M^{i+j}$. The fact that the configuration $x \in A^G$ is well defined follows from properties (Mem1) and (Mem2). Let $g \in G$. Take i large enough so that $gD \subset M^{i+j}$. Then $g \in D_{ij}$ and $(g^{-1}x)|_D = (g^{-1}x_i)|_D \in P$ since $x_i \in A_{ij}$. This shows that $x \in \Sigma$. □

LEMMA 5.4. *For all $i, j \in \mathbb{N}$, we have*

$$\Sigma_{ij} \subset \bigcap_{k\geq i} p_{ijk}(A_{kj}).$$

Proof. Let $y \in \Sigma$ and let $x = y|_{M^{i+j}} \in \Sigma_{ij}$. Let $k \geq i$. Since $y|_{M^{k+j}} \in \Sigma_{M^{k+j}} \subset A_{kj}$, it follows that

$$x = y|_{M^{i+j}} = p_{ijk}(y|_{M^{k+j}}) \subset p_{ijk}(A_{kj}).$$

As y is arbitrary, the proof is finished. $\qquad\square$

6. *Algebraic subshifts of finite type*

Keeping the notation and hypotheses of §5, we assume in this section that $A = V(K)$ and $P = W(K)$, where V is an algebraic variety over an algebraically closed field K and $W \subset V^D$ is an algebraic subvariety. Thus, $\Sigma = \Sigma(D, P) \subset A^G$ is an algebraic subshift of finite type.

For all $i, j \in \mathbb{N}$, it is clear that A_{ij} is a closed algebraic subset of $A^{M^{i+j}}$ since it is a finite intersection of sets of closed points of closed subvarieties of $V^{M^{i+j}}$:

$$A_{ij} = \bigcap_{g \in D_{ij}} \pi_{ij,g}^{-1}(gW)(K). \tag{6.1}$$

Here, $\pi_{ij,g} \colon V^{M^{i+j}} \to V^{gD}$ is the projection induced by the inclusion $gD \subset M^{i+j}$ for $g \in D_{ij}$. The subset $gW \subset V^{gD}$ is defined as the image of W under the isomorphism $V^D \simeq V^{gD}$ induced by the bijection $D \simeq gD$ given by $h \mapsto gh$ for every $h \in D$.

Observe that the maps $\pi_{ij,g}$ above and the transition maps of the inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ are induced by morphisms of algebraic varieties.

In this section, we consider the following conditions:

(C2) V is a complete K-algebraic variety;

(C3) V is a K-algebraic group and $W \subset V$ is an algebraic subgroup.

Remark 6.1. In case (C3), note that the projections $p_{ijk} \colon A_{kj} \to A_{ij}$ (cf. equation (5.2)) are homomorphisms of algebraic groups.

PROPOSITION 6.2. *With the above notation and hypotheses, suppose in addition that one of the conditions* (H1), (C2), (C3) *is satisfied. Then, for each $i, j \in \mathbb{N}$, we have*

$$\Sigma_{ij} = \bigcap_{k \geq i} p_{ijk}(A_{kj}) \tag{6.2}$$

and Σ_{ij} is a countably proconstructible subset of $A^{M^{i+j}}$. Moreover, in case (C2) *(respectively* (C3)), *Σ_{ij} is a complete subvariety (respectively an algebraic subgroup) of $A^{M^{i+j}}$.*

Proof. The inclusion $\Sigma_{ij} \subset \bigcap_{k \geq i} p_{ijk}(A_{kj})$ follows from Lemma 5.4.

Let $x \in \bigcap_{k \geq i} p_{ijk}(A_{kj}) \subset A^{M^{i+j}}$. We must show that x can be extended to an element of Σ. Consider the following inverse system lying above x. Let $B_i = \{x\}$ and for each $k \geq i$, we set

$$B_k := (p_{ijk})^{-1}(x) \subset A_{kj}, \tag{6.3}$$

which is a closed algebraic subset of $A^{M^{k+j}}$. Since $x \in p_{ijk}(A_{kj})$, each set B_k is non-empty. From equation (6.3), it is clear that for every $k \geq i$, we have

$$\widetilde{p}_{kj}(B_{k+1}) \subset B_k.$$

By restricting the map $\widetilde{p}_{kj}$ to B_{k+1}, we have for each $k \geq i$ a well-defined algebraic map $\pi_k \colon B_{k+1} \to B_k$. Thus, we obtain an inverse subsystem $(B_k)_{k \geq i}$ with transition maps $\pi_{nm} \colon B_m \to B_n$, where $m \geq n \geq i$, as compositions of the maps π_k.

We claim that $\varprojlim_{k \geq i} B_k \neq \varnothing$. Indeed, this follows from Lemma 3.2 if case (H1) is satisfied and from Lemma 3.3 and Remark 2.1 in case (C2). Suppose now that case (C3) is satisfied. Since $x \in \bigcap_{k \geq i} p_{ijk}(A_{kj})$, there exists for each $k \geq i$ a point $z_k \in B_k$ such that $p_{ijk}(z_k) = x$. Let $V_k = \ker p_{ijk}$ be an algebraic subgroup of $A^{M^{k+j}}$, then clearly $B_k = z_k V_k$ where the group law is written multiplicatively. For all integers $m \geq n \geq i$, the map π_{mn} is the restriction of a homomorphism of algebraic groups (cf. Remark 4.3). Therefore, $\pi_{nm}(B_m)$ is a translate of an algebraic subgroup of $A^{M^{n+j}}$ and thus is Zariski closed in B_n (cf. Remark 2.1). Hence, the claim follows, also in case (C3), from Lemma 3.3.

Therefore, we can find $(y_k)_{k \geq i} \in \varprojlim_{k \geq i} B_k$. Let $y \in A^G$ be defined as follows. Given $g \in G$, set $y(g) = y_k(g)$ for any $k \geq i$ such that $g \in M^{k+j}$. Then y is well defined by property (Mem2). For each $g \in G$, choose $k \geq i$ so that $gD \subset M^{k+j}$. Then $(g^{-1}y)|_D = y_k|_{gD} \in W(K)$ which follows from the definition of A_{kj} and since $y_k \in B_{kj} \subset A_{kj}$. Hence, $y \in \Sigma$. By construction, $x = y|_{M^{i+j}}$ and we deduce that $\bigcap_{k \geq i} q_{ijk}(A_{kj}) \subset \Sigma_{M^{i+j}}$. The proof of equation (6.2) is completed. Thus, by Chevalley's theorem, Σ_{ij} is a countably proconstructible subset of $A^{M^{i+j}}$.

Finally, the last statement follows from equation (6.2) and Remark 2.1 and Noetherianity of the Zariski topology of $A^{M^{i+j}}$. Note that the sequence $(q_{ijk}(A_{kj}))_{k \geq i}$ is trivially a descending sequence. $\qquad\square$

COROLLARY 6.3. *With the above notation and hypotheses, suppose that condition* (H1) *(respectively* (C2)*, respectively* (C3)*) is satisfied for* Σ*. Then, for each finite subset* $E \subset G$*, the restriction* Σ_E *is a countably proconstructible subset (respectively a complete subvariety, respectively an algebraic subgroup) of* A^E*.*

Proof. Let $i, j \in \mathbb{N}$ be large enough so that $E \subset M^{i+j}$. Let $\pi \colon A^{M^{i+j}} \to A^E$ be the induced projection. It follows that $\Sigma_E = \pi(\Sigma_{ij})$. In cases (C2) and (C3), Proposition 6.2 and Remark 2.1 imply that Σ_E is respectively a complete subvariety and an algebraic subgroup of A^E. In case (H1), we find by Lemma 3.1 that

$$\Sigma_E = \pi(\Sigma_{ij}) = \pi\left(\bigcap_{k \geq i} p_{ijk}(A_{kj})\right) = \bigcap_{n \in \mathbb{N}} \pi(p_{ijk}(A_{kj})). \tag{6.4}$$

Hence, Σ_E is countably proconstructible by Chevalley's theorem. The proof is completed. $\qquad\square$

7. Algebraic sofic subshifts

Consider the following hypothesis without condition on cellular automata:

($\widehat{\text{H3}}$) K is algebraically closed, V is a K-algebraic group, and $\Sigma \subset A^G$ is an algebraic group sofic subshift.

We can now state the main local result for algebraic sofic subshifts.

THEOREM 7.1. *Let V be an algebraic variety over a field K and let $A = V(K)$. Let G be a finitely generated group and let $\Sigma \subset A^G$ be an algebraic sofic subshift. Let E be a finite subset of G. Suppose that condition* (H1) *(respectively* (H2)*, respectively* ($\widehat{\text{H3}}$)*) is satisfied. Then the restriction $\Sigma_E \subset A^E$ is a countably proconstructible subset (respectively a complete subvariety, respectively an algebraic subgroup) of A^E.*

Proof. By hypothesis, there exist in cases (H1) and (H2) an algebraic variety (respectively in case ($\widehat{\text{H3}}$) an algebraic group) U over K, an algebraic (respectively algebraic group) cellular automaton $\tau' \colon B^G \to A^G$ where $B = U(K)$, and an algebraic (respectively algebraic group) subshift of finite type $\Sigma' \subset B^G$ such that $\Sigma = \tau'(\Sigma')$. Note that U, V are complete varieties in case (H2). Let M be a memory set of τ'. By Corollary 6.3, the set Σ'_{ME} is countably proconstructible. Hence, $\Sigma'_{ME} = \bigcap_{n \in \mathbb{N}} C_n$ where $(C_n)_{n \in \mathbb{N}}$ is some decreasing sequence of constructible subsets of A^{ME}. Let $\varphi \colon B^{ME} \to A^E$ be given by $\varphi(x)(g) = \tau'(y)(g)$ for every $x \in B^{ME}$, $g \in E$ and every $y \in B^G$ extending x. Then φ is algebraic (cf. [14, Lemma 3.2]) and in case ($\widehat{\text{H3}}$), it is a homomorphism of algebraic groups (cf. [39, Lemma 3.4]). In case (H1), we can conclude by Chevalley's theorem since

$$\Sigma_E = (\tau'(\Sigma'))_E = \varphi(\Sigma'_{ME}) = \varphi\left(\bigcap_{n \in \mathbb{N}} C_n\right) = \bigcap_{n \in \mathbb{N}} \varphi(C_n), \tag{7.1}$$

where the last equality follows from Lemma 3.1. Finally, in cases (H2) and ($\widehat{\text{H3}}$), Corollary 6.3 implies that $\Sigma_E = \varphi(\Sigma'_{ME})$ is respectively a complete subvariety and an algebraic subgroup of A^E. $\square$

8. A closed mapping property and chain recurrent sets

Using the space-time inverse system, we give a short proof of the following result saying that the image of an algebraic sofic subshift under an algebraic cellular automaton is closed. It extends the linear case in [16, Theorem 4.1].

Let G be a group. Let V_0, V_1 be algebraic varieties over an algebraically field K. Let $A_0 = V_0(K)$ and let $A_1 = V_1(K)$. Let $\tau \colon A_0^G \to A_1^G$ be an algebraic cellular automaton and let $\Sigma \subset A_0^G$ be an algebraic sofic subshift.

Then Σ is the image of some algebraic subshift of finite type $\Sigma' \subset B^G$ under an algebraic cellular automaton $\tau' \colon B^G \to A_0^G$, where B is the set of K-points of a K-algebraic variety U.

To avoid notational confusion, we introduce in this section the following hypotheses similar to hypotheses (H1), (H2), and (H3), ($\widehat{\text{H3}}$):

($\widetilde{\text{H1}}$) K is uncountable;

($\widetilde{\text{H2}}$) U, V_0 are complete K-algebraic varieties;

(H̃3) U, V_0, and V_1 are K-algebraic groups, $\Sigma' \subset B^G$ is an algebraic group subshift of finite type, and $\tau' \colon B^G \to A_0^G$ and $\tau \colon A_0^G \to A_1^G$ are algebraic group cellular automata.

THEOREM 8.1. *With the above notation, if one of the conditions (H̃1), (H̃2), (H̃3) is satisfied, then $\tau(\Sigma)$ is closed in A_1^G.*

Proof. It is clear that, up to replacing τ by the composition $\tau \circ \tau'$ and Σ by Σ', we can suppose without loss of generality that Σ is an algebraic subshift of finite type. The hypotheses (H̃2), (H̃3) now become respectively:

(P2) V_0 is a complete K-algebraic variety;

(P3) V_0 and V_1 are K-algebraic groups, $\Sigma \subset A_0^G$ is an algebraic group subshift of finite type, and $\tau \colon A_0^G \to A_1^G$ is an algebraic group cellular automaton.

Let $D \subset G$ be a defining memory set of Σ. Let $d \in A_1^G$ be in the closure of $\tau(\Sigma)$. We must show that $d \in \tau(\Sigma)$.

Suppose first that G is finitely generated. Let $M \subset G$ be a finite memory subset of τ containing $\{1_G\} \cup D$ which generates G and satisfies $M = M^{-1}$. Consider the inverse system $(A_0^{M^i})_{i \in \mathbb{N}}$ whose transition maps $p_{ij} \colon A_0^{M^j} \to A_0^{M^i}$, where $0 \le i \le j$, are defined as the canonical projections induced by the inclusions $M^i \subset M^j$. For every $i \ge 1$, the induced map $q_i \colon A_0^{M^i} \to A_1^{M^{i-1}}$ is given as follows. For every $\sigma \in A_0^{M^i}$, we set $q_i(\sigma) := (\tau(x))|_{M^{i-1}}$, where $x \in A_0^G$ is any configuration that extends σ. For every $i \ge 1$, we define

$$Z_i := q_i^{-1}(d|_{M^{i-1}}) \cap \Sigma_{M^i}.$$

Since d belongs to the closure of $\tau(\Sigma)$ in A_1^G, it follows that $Z_i \neq \varnothing$ for every $i \ge 1$. By restricting the projections $p_{ij} \colon A^{M^j} \to A^{M^i}$ to Z_j, we obtain well-defined transition maps $\pi_{ij} \colon Z_j \to Z_i$, where $j \ge i \ge 1$, of the inverse system $(Z_i)_{i \ge 1}$.

It suffices to show that $\varprojlim_{i \ge 1} Z_i \neq \varnothing$ since, by construction of Z_i and Σ_{ij} (see also [14, Lemma 2.1]), we have $\tau(c) = d$ for every $c \in \varprojlim_{i \ge 1} Z_i \subset \varprojlim_{i \ge 1} \Sigma_{M^{i+1}} = \Sigma$ (by equation (4.6) since Σ is closed as it is a subshift of finite type).

Thanks to Theorem 7.1, the conclusion follows by a direct application of Lemma 3.2, respectively Lemma 3.3, to the inverse system $(Z_i)_{i \in \mathbb{N}}$ if case (H̃1), respectively case (P2), is satisfied. Assume now that case (P3) is satisfied. For each $i \ge 1$, choose $z_i \in Z_i$ and let $V_i := \ker q_i \cap \Sigma_{M^i}$ be an algebraic subgroup of Σ_{M^i} (by Theorem 7.1). We have $Z_i = z_i V_i$. Hence (by Remark 4.3), for $j \ge i \ge 1$, $\pi_{ij}(Z_j)$ is a translate of an algebraic subgroup of Σ_{M^i} and thus is Zariski closed in Z_i. Therefore, case (P3) follows from Lemma 3.3.

For a general group G, consider a finite memory set M of τ containing $\{1_G\} \cup D$ and such that $M = M^{-1}$. Let $H \subset G$ be the subgroup generated by M. As Σ_H is clearly an algebraic (respectively in case (H̃3) an algebraic group) subshift of finite type, the above discussion shows that $\tau_H(\Sigma_H)$ is closed in A_1^G and so is $\tau(\Sigma)$ by Lemma 2.10. □

COROLLARY 8.2. *Let G be a group. Let V be an algebraic variety over a field K and let $A := V(K)$. Let $\Sigma \subset A^G$ be an algebraic sofic subshift. If one of the conditions (H1), (H2), (H̃3) is satisfied, then Σ is closed in A^G.*

Proof. It suffices to apply Theorem 8.1 in the case $V_0 = V_1$ to the identity map $\tau = \mathrm{Id}_{A^G}$, where $A = V_0(K) = V_1(K)$. $\qquad\square$

COROLLARY 8.3. *With the notation and hypotheses as in Theorem 1.3, we have* $\mathrm{CR}(\tau) \subset \Omega(\tau)$.

Proof. By Proposition 2.3, we only need to check that $\tau^n(\Sigma)$ is closed in A^G for every $n \geq 1$ and that τ is uniformly continuous. The first property follows from Theorem 8.1. The second is a general property of cellular automata already mentioned in §1. $\qquad\square$

9. *Applications to backward orbits and limit sets*

Thanks to the closedness property of algebraic sofic subshifts, we can establish the following key relation among inverse space-time systems, backward orbits, and limit sets.

THEOREM 9.1. *Let V be an algebraic variety over a field K and let $A = V(K)$. Let G be a finitely generated group and let $\Sigma \subset A^G$ be an algebraic sofic subshift. Let $\tau \colon \Sigma \to \Sigma$ be an algebraic cellular automaton. Assume that one of the conditions (H1), (H2), (H3) is satisfied. Then, with the notation as in §4, we have a surjective map* $\Phi \colon \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij} \to \Omega(\tau)$.

Proof. By Corollary 8.2, the subshift Σ is closed in A^G. Hence, $\varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}$ is the set of backward orbits of τ and we have a canonical map $\Phi \colon \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij} \to \Omega(\tau)$ given in Lemma 4.4. Now let $y_0 \in \Omega(\tau) \subset \Sigma$. We must show that there exists $x \in \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}$ such that $\Phi(x) = y_0$. For every $i, j \in \mathbb{N}$, define a closed subset

$$B_{ij} := (q_{i0} \circ \cdots \circ q_{i,j-1})^{-1}(y_0|_{M^i}) \subset \Sigma_{ij}.$$

By definition of $\Omega(\tau)$, there exists for every $j \in \mathbb{N}$ an element $y_j \in \Sigma$ such that $\tau^j(y_j) = y_0$. Hence, it follows from the definition of the transition maps q_{ik} and of Σ_{ij} that $y_j|_{M^{i+j}} \in B_{ij}$. In particular, $B_{ij} \neq \varnothing$ for every $i, j \in \mathbb{N}$. By restricting the transition maps of the space-time inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ to the sets B_{ij}, we obtain a well-defined inverse subsystem $(B_{ij})_{i,j \in \mathbb{N}}$.

We claim that $\varprojlim_{i,j \in \mathbb{N}} B_{ij} \neq \varnothing$. Indeed, by Theorem 7.1, case (H1) is implied by Lemma 3.2. In case (H2), Theorem 7.1 implies that B_{ij} is a complete algebraic subvariety of Σ_{ij} and thus of $A^{M^{i+j}}$. Hence, case (H2) follows from Lemma 3.3 and Remark 2.1. In case (H3), a similar argument as in the proof of Proposition 6.2 shows that the transition maps of the system $(B_{ij})_{i,j \in \mathbb{N}}$ have Zariski closed images. Therefore, case (H3) follows immediately from Lemma 3.3. Thus, we can find

$$x \in \varprojlim_{i,j \in \mathbb{N}} B_{ij} \subset \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}.$$

It is clear from the constructions of the inverse system $(B_{ij})_{i,j \in \mathbb{N}}$ and of the map Φ (see the proof of Lemma 4.4) that $\Phi(x) = y_0$. The proof of the lemma is completed. $\qquad\square$

COROLLARY 9.2. *With the notation and hypotheses as in Theorem 1.3, we have* $\tau(\Omega(\tau)) = \Omega(\tau)$.

Proof. Let $M \subset G$ be a finite subset containing 1_G, a memory set of τ, and a memory set of Σ and such that $M = M^{-1}$. Let $H \subset G$ be the subgroup generated by M. Since $\tau = \prod_{c \in G/H} \tau_c$ and $\Omega(\tau) = \prod_{c \in G/H} \Omega(\tau_c)$ (cf. Lemma 2.9), we can suppose without loss of generality that $G = H$. Let $x \in \Omega(\tau)$, then $x \in \tau^n(X)$ for every $n \geq 0$. Thus, $\tau(x) \in \tau^{n+1}(X)$ for every $n \geq 0$ and it follows that $\tau(x) \in \Omega(\tau)$. Therefore, $\tau(\Omega(\tau)) \subset \Omega(\tau)$. For the converse inclusion, let $y \in \Omega(\tau)$. By Theorem 9.1, there exists $x = (x_{ij}) \in \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}$ such that $\Phi(x) = y$. However, equation (4.7) tells us that $\Phi^{-1}(y) \subset \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}$ is the set of backward orbits of y under τ. Hence, we can find $z \in \Omega(\tau)$ such that $\tau(z) = y$. Thus, $\Omega(\tau) \subset \tau(\Omega(\tau))$ and the conclusion follows.   □

10. *Noetherianity of algebraic subshifts of finite type*

The goal of this section is to establish the following characterization of algebraic subshifts of finite type by the descending chain property. It extends the linear version in [16, Theorem 1.1 and Corollary 1.2]. The proof is an application of Theorem 7.1 combined with the construction of an inverse system analogous to the space-time inverse system. More precisely, we obtain the following theorem.

THEOREM 10.1. *Let G be a finitely generated group and let V be an algebraic variety (respectively an algebraic group) over an algebraically closed field K. Let $A = V(K)$ and let $\Sigma \subset A^G$ be a subshift. Consider the following properties:*

(a)   *Σ is a subshift of finite type;*
(b)   *Σ is an algebraic (respectively algebraic group) subshift of finite type;*
(c)   *every descending sequence of algebraic (respectively algebraic group) sofic subshifts of A^G*

$$\Sigma_0 \supset \Sigma_1 \supset \cdots \supset \Sigma_n \supset \Sigma_{n+1} \supset \cdots$$

such that $\bigcap_{n \geq 0} \Sigma_n = \Sigma$ eventually stabilizes.

Then we have (b) $\implies$ (a) $\implies$ (c). *Moreover, if $\Sigma \subset A^G$ is an algebraic (respectively algebraic group) sofic subshift, then* (a) $\iff$ (b) $\iff$ (c).

Proof. It is trivial that (b) $\implies$ (a). Assume that Σ is a subshift of finite type. Hence, $\Sigma = \Sigma(D, W)$, where $D \subset G$ is finite and $W \subset A^D$ is some subset. Let $\Sigma_0 \supset \Sigma_1 \supset \cdots$ be a descending sequence of algebraic (respectively algebraic group) sofic subshifts of A^G whose intersection is Σ. Let $M \subset G$ be a finite generating subset containing $\{1_G\} \cup D$ and such that $M = M^{-1}$. Consider the inverse system $(X_{ij})_{i,j \in \mathbb{N}}$ defined by $X_{ij} := (\Sigma_j)_{M^i} \subset A^{M^i}$. Remark that $X_{i,j+1} \subset X_{ij}$ since $\Sigma_{j+1} \subset \Sigma_j$ for all $i, j \in \mathbb{N}$. We define the unit transition maps $p_{ij} : X_{i+1,j} \to X_{ij}$ by $p_{ij}(x) = x|_{M^i}$ for every $x \in X_{i+1,j}$ and $q_{ij} : X_{i,j+1} \to X_{ij}$ simply as the inclusion maps.

For all $i, j \in \mathbb{N}$, Theorem 7.1 implies that every X_{ij} is a complete variety (respectively an algebraic group) over K. By Noetherianity of the Zariski topology, the decreasing sequence $(X_{0j})_{j \in \mathbb{N}}$ of algebraic closed subsets of A^M eventually stabilizes, say, $X_{0j} = X_{0m}$ for all $j \in \mathbb{N}$ for some $m \in \mathbb{N}$. Let $W' := X_{0m}$, then $\Sigma' := \Sigma(M^m, W')$ is an algebraic (respectively algebraic group) subshift of finite type. It is clear that $\Sigma_m \subset \Sigma'$ and hence $\Sigma \subset \Sigma'$. We shall prove the converse inclusion.

Let $w \in W'$. We construct an inverse subsystem $(Z_{ij})_{i \geq m, j \geq 0}$ of $(X_{ij})_{i \geq m, j \geq 0}$ as follows. For $i \geq m$, let $Z_{i0} := \{x \in X_{i0} \colon x|_{M^m} = w\}$ which is clearly an algebraic closed subvariety (respectively a translate of an algebraic subgroup) of X_{i0}. For $i \geq m$, $j \geq 0$, we define an algebraic closed subvariety (respectively a translate of an algebraic subgroup (by Theorem 7.1)) of X_{ij} as follows:

$$Z_{ij} := (q_{i0} \circ \cdots \circ q_{i,j-1})^{-1}(Z_{i0}) \subset X_{ij}.$$

The transition maps of $(Z_{ij})_{i \geq m, j \geq 0}$ are well defined as the restrictions of the transition maps of the system $(X_{ij})_{i \geq m, j \geq 0}$. These transition maps have Zariski closed images (by Remark 2.1).

By our construction, each Z_{ij} is clearly non-empty. Hence, Lemma 3.3 implies that there exists $x = (x_{ij})_{i \geq m, j \geq 0} \in \varprojlim Z_{ij}$. Let $y \in A^G$ be defined by $y(g) = x_{i0}(g)$ for every $g \in G$ and any large enough $i \geq m$ such that $g \in M^i$. Observe that $x_{ij} = x_{ik}$ for every $i \geq m$ and $0 \leq j \leq k$ since the vertical transition maps $X_{ik} \to X_{ij}$ are simply inclusions. Consequently, for every $n \in \mathbb{N}$, we have $y \in \Sigma_n$ by equation (4.6) since Σ_n is closed in A^G (cf. Corollary 8.2). Hence, $y \in \Sigma$. By construction, $y|_{M^m} = w$. Since w was arbitrary, this shows that $W' \subset \Sigma_{M^m}$. Hence, $\Sigma' = \Sigma(M^m, W') \subset \Sigma(M^m, \Sigma_{M^m}) = \Sigma$. The last equality follows from Lemma 5.1 as $D \subset M^m$. Therefore, $\Sigma' = \Sigma$ and $\Sigma_n = \Sigma$ for all $n \geq m$. This proves that (a) $\Longrightarrow$ (c).

Suppose now that $\Sigma \subset A^G$ is an algebraic (respectively algebraic group) sofic subshift which is not a subshift of finite type. Let $M \subset G$ be a finite generating subset containing $\{1_G\}$ such that $M = M^{-1}$. For every $n \in \mathbb{N}$, consider $W_n := \Sigma_{M^n}$ (as in §4). Theorem 7.1 tells us that W_n is a complete algebraic subvariety (respectively an algebraic subgroup) of A^{M^n}. Set $\Sigma_n := \Sigma(M^n, W_n)$ for every $n \in \mathbb{N}$, then Σ_n is an algebraic (respectively algebraic group) subshift of finite type. As $(\Sigma_{M^{n+1}})_{M^n} = \Sigma_{M^n}$, it is clear that $\Sigma \subset \Sigma_{n+1} \subset \Sigma_n$ for every $n \in \mathbb{N}$. We claim that $\Sigma = \bigcap_{n \in \mathbb{N}} \Sigma_n$. Indeed, we only need to prove that $\bigcap_{n \in \mathbb{N}} \Sigma_n \subset \Sigma$. Let $x \in \bigcap_{n \in \mathbb{N}} \Sigma_n$. Then by definition of Σ_n, we find that $x|_{M^n} \in W_n = \Sigma_{M^n}$ for every $n \in \mathbb{N}$. Thus, since Σ is closed (cf. Corollary 8.2), $x \in \varprojlim_{n \in \mathbb{N}} \Sigma_{M^n} = \Sigma$ (cf. equation (4.6)) and hence $\bigcap_{n \in \mathbb{N}} \Sigma_n \subset \Sigma$. However, the descending sequence $(\Sigma_n)_{n \in \mathbb{N}}$ cannot stabilize since otherwise the subshift Σ would be of finite type. This shows that (c) $\Longrightarrow$ (a) if Σ is an algebraic (respectively algebraic group) sofic subshift. The proof is complete. $\qquad\square$

Examples 10.2. (Markov properties) The examples below provide the original sources and motivations for our main result in this section (Theorem 10.1).

(a) Let G be a group and let A be a finite group. Equip the configuration space A^G with the product group structure (thus, given two configurations $x, y \in A^G$, their product is defined as the configuration $xy \in A^G$ given by $(xy)(g) := x(g)y(g)$ for all $g \in G$). A closed subshift $X \subset A^G$ which is also a subgroup of A^G is called a *group subshift*. Group subshifts $X \subset A^{\mathbb{Z}}$ are called *Markov subgroups* in [28, §6.3], and were studied and classified up to topological conjugacy by Kitchens in [27] (see also [28, Theorem 6.3.3]).

One says that a group G is of *finite Markov type* if for any finite group A, every group subshift $\Sigma \subset A^G$ is of finite type. The finite Markov type property is a weakening of the *Markov type property* introduced by Schmidt in [54, Definition 4.1].

The following hold:

(i)   every finite group is of finite Markov type;

(ii) the additive group $\mathbb{Z}$ is of finite Markov type. This result was established by Kitchens in [**27**, Proposition 4] (see also [**28**, Lemma 6.3.5], [**30**, Exercise 2.1.11], and [**13**, Exercise 1.114]);

(iii) every subgroup of a group of finite Markov type is finitely generated (this is also expressed by saying that groups of finite Markov type are *Noetherian*). As a consequence, every group of finite Markov type is countable and contains no non-abelian free subgroups;

(iv) every quotient of a group of finite Markov type is of finite Markov type;

(v) every group containing a finite index subgroup of finite Markov type is itself of finite Markov type;

(vi) a group G is of finite Markov type if and only if G is countable and, for any finite group A, every descending sequence of group subshifts of A^G

$$X_0 \supset X_1 \supset X_2 \supset \cdots \supset X_n \supset X_{n+1} \supset \cdots$$

eventually stabilizes, that is, there exists $n_0 \in \mathbb{N}$ such that $X_n = X_{n_0}$ for all $n \geq n_0$ (cf. [**13**, Exercise 1.112]).

In other words, the class of groups of finite Markov type is closed under the operations of taking subgroups, quotients, and extensions by finite or cyclic groups. As a consequence, all finitely generated abelian groups are of finite Markov type (a result observed by Kitchens and Schmidt [**26**, Remark 3.10(2)]). In fact, more generally, the class of groups of finite Markov type contains all polycyclic-by-finite groups (cf. [**13**, Exercise 4.37]), a particular case of [**54**, Theorem I.4.2]. The question whether or not every group of finite Markov type is polycyclic-by-finite remains, at our present knowledge, open.

(b) Let G be a group, let K be a field, and let A be a finite-dimensional vector space over K. Equip the configuration space A^G with the product vector space structure (thus, given a scalar $\lambda \in K$ and two configurations $x, y \in A^G$, one defines the configuration $\lambda x \in A^G$ (respectively $x + y \in A^G$) by setting $(\lambda x)(g) := \lambda x(g)$ (respectively $(x + y)(g) := x(g) + y(g)$) for all $g \in G$. A closed subshift $\Sigma \subset A^G$ which is also a vector subspace of A^G is called a *linear subshift*. One says that a group G is of *K-linear Markov type* if for any finite-dimensional vector space A over K, every linear subshift $\Sigma \subset A^G$ is of finite type. Analogous properties to items (i)–(vi) in point (a), for groups of K-linear Markov type, are shown in [**16**, §6] (see also [**42**] for some more general results). In other words, the class of K-linear Markov groups is closed under the operations of taking subgroups, quotients, and extensions by finite or cyclic groups, and contains all polycyclic-by-finite groups (cf. [**16**, Corollary 1.4]). In addition, one has the following characterization: a group G is of K-linear Markov type if and only if its group ring $K[G]$ is one-sided Noetherian [**16**, Theorem 1.3].

11. *Proof of Theorem 1.3*

For item (i), we know that $\Omega(\tau)$ is G-invariant by the G-equivariance of τ. However, as the set of algebraic cellular automata over Σ is closed under the composition of maps (cf. [**14**, Proposition 3.3] for the case of full shifts, the general case is proved similarly), the

map $\tau^n \colon \Sigma \to \Sigma$ is an algebraic cellular automaton for every $n \geq 1$. It then follows from Theorem 8.1 that $\tau^n(\Sigma)$ is closed in A^G for every $n \geq 1$ and thus $\Omega(\tau) = \bigcap_{n \geq 1} \tau^n(\Sigma)$ is also closed in A^G. This shows that $\Omega(\tau)$ is a closed subshift of A^G and item (i) is proved.

For item (v), let $z \in \Sigma \cap \mathrm{Fix}(H)$ for some subgroup $H \subset G$. Let $F \subset G$ be the subgroup generated by a finite subset M containing $\{1_G\}$ and memory sets of τ, Σ, and such that $M = M^{-1}$. Note that $z|_F$ is fixed by the subgroup $R \coloneqq F \cap H$ of F. Consider the space-time inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ associated with the restriction τ_F and M as in Definition 4.1. Keep the notation in §4. For all i, $j \in \mathbb{N}$, let

$$\Delta_{ij} \coloneqq \{p \in A^{M^{i+j}} : p(u) = p(v) \text{ for all } u, v \in M^{i+j} \text{ with } uv^{-1} \in R\}$$

be the restriction to M^{i+j} of R-fixed points in A^H. Clearly, Δ_{ij} is respectively a closed subvariety, a complete algebraic subvariety, and an algebraic subgroup of $A^{M^{i+j}}$ in cases (H1), (H2), and (H3). Define also $Z_{ij} \coloneqq \Sigma_{ij} \cap \Delta_{ij} \subset A^{M^{i+j}}$.

Note that τ_F sends R-fixed points to R-fixed points. Hence, by restricting the transition maps to the sets Z_{ij}, we obtain a well-defined inverse subsystem of $(\Sigma_{ij})_{i,j \in \mathbb{N}}$. Theorem 7.1 implies that respectively in each case (H1), (H2), and (H3), the set $Z_{ij} \subset A^{M^{i+j}}$ is a countably proconstructible subset, a complete algebraic subvariety, and an algebraic subgroup. Each Z_{ij} is non-empty since it contains $z|_{M^{i+j}}$. Hence, Lemmas 3.2 and 3.3 imply that there exists $x \in \varprojlim_{i,j \in \mathbb{N}} Z_{ij} \subset \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}$. By Lemma 4.4, we obtain $y = \Phi(x) \in \Omega(\tau_F) \subset A^H$. By our construction, y is fixed by R. By Lemma 2.9(i), $\Omega(\tau) = \Omega(\tau_F)^{G/F}$. Thus, y induces a configuration of $\Omega(\tau)$ fixed by H. This proves item (v).

To finish the proof of Theorem 1.3, note that item (ii) follows from Corollary 9.2 and item (iii) follows from the general property $\mathrm{Per}(\tau) \subset \mathrm{R}(\tau) \subset \mathrm{NW}(\tau) \subset \mathrm{CR}(\tau)$ and from the inclusion $\mathrm{CR}(\tau) \subset \Omega(\tau)$ proved in Corollary 8.3. Finally, in case (H2) (respectively in case (H3)), item (iv) is a direct consequence of the implication (a) $\Longrightarrow$ (c) in Theorem 10.1 applied to $\Omega(\tau)$ and the decreasing sequence of algebraic (respectively algebraic group) sofic subshifts $\tau(\Sigma) \supset \tau^2(\Sigma) \supset \cdots \supset \tau^n(\Sigma) \supset \tau^{n+1}(\Sigma) \supset \cdots$ which satisfies $\bigcap_{n \geq 1} \tau^n(\Sigma) =: \Omega(\tau)$ by definition.

12. *Proof of Theorem 1.4*

It is clear that (a) $\Longrightarrow$ (b). For the converse implication, suppose that $\Omega(\tau) = \{x_0\}$ for some $x_0 \in \Sigma$. As $\Omega(\tau)$ is G-invariant, there exists an element denoted by $0 \in A$ such that $x_0(g) = 0$ for every $g \in G$, that is, $x_0 = 0^G$. Let $M \subset G$ be a finite subset containing a memory set of τ and a memory set of Σ such that $1_G \in M$ and $M = M^{-1}$. Let H be the subgroup generated by M and consider the restriction τ_H. By Lemma 2.9, we deduce that $\Omega(\tau_H)$ must be a singleton as well and τ is nilpotent if τ_H is. Thus, up to replacing G by H, we can suppose that G is generated by M.

We construct an inverse subsystem $(\Sigma_{ij}^*)_{i,j \in \mathbb{N}}$ of the space-time inverse system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ associated with τ and the memory set M (cf. Definition 4.1) as follows. Let $\Sigma_{i0}^* \coloneqq \Sigma_{i0} \setminus \{x \in \Sigma_{i0} : x(1_G) = 0\}$ for every $i \geq 0$. For all $i \geq 0$ and $j \geq 1$, we define

$$\Sigma_{ij}^* = (q_{i0} \circ \cdots \circ q_{i,j-1})^{-1}(\Sigma_{i0}^*).$$

The unit transition maps $q_{ij}^*\colon \Sigma_{i,j+1}^* \to \Sigma_{ij}^*$ and $p_{ij}^*\colon \Sigma_{i+1,j}^* \to \Sigma_{ij}^*$ of the inverse subsystem $(\Sigma_{ij}^*)_{i,j\in\mathbb{N}}$ are defined respectively by the restrictions of the transition maps q_{ij} and p_{ij} of $(\Sigma_{ij})_{i,j\in\mathbb{N}}$.

Assume in contrast that τ is not nilpotent. We claim that $\Sigma_{ij}^* \neq \varnothing$ for all $i, j \in \mathbb{N}$. Otherwise, $\Sigma_{ij}^* = \varnothing$ for some $i, j \in \mathbb{N}$. If $j = 0$, then $\Sigma_{i0}^* = \varnothing$, that is, $x(1_G) = 0$ for all $x \in \Sigma_{i0}$, and since Σ is G-invariant and $1_G \in M^{i+j}$, we deduce that $\Sigma = \{0^G\}$. Hence, τ is trivially nilpotent and we arrive at a contradiction. Thus, $j \geq 1$ and by definition of Σ_{ij}, we have for every $x \in \Sigma_{ij}$ that

$$(q_{i0} \circ \cdots \circ q_{i,j-1})(x)(1_G) = 0.$$

Since τ^{i+j} is G-equivariant, it follows that $\tau^{i+j}(x) = 0^G$ for every $x \in \Sigma$, which contradicts the assumption that τ is not nilpotent. This proves the claim, that is, $\Sigma_{ij}^* \neq \varnothing$ for all $i, j \in \mathbb{N}$. We are going to show that

$$\varprojlim_{i,j\in\mathbb{N}} \Sigma_{ij}^* \neq \varnothing. \tag{12.1}$$

Indeed, equation (12.1) is a direct application of Theorem 7.1 and Lemma 3.2 to the inverse system $(\Sigma_{ij}^*)_{i,j\in\mathbb{N}}$ in case (H1). For cases (H2) and (H3), observe that for every $(i, j) \prec (k, l)$ in $\mathbb{N}^2$, we have

$$Z := F_{(i,j),(k,l)}(\Sigma_{kl}^*) = F_{(i,j),(k,l)}(\Sigma_{kl}) \cap \Sigma_{ij}^*, \tag{12.2}$$

where $F_{(i,j),(k,l)}\colon \Sigma_{kl} \to \Sigma_{ij}$ is the transition map of the inverse system $(\Sigma_{ij})_{i,j\in\mathbb{N}}$. Indeed, by definition of Σ_{kl}^* and Σ_{ij}^*, and using the equality $F_{(i,0),(k,l)} = F_{(i,0),(i,j)} \circ F_{(i,j),(k,l)}$, we see that

$$
\begin{aligned}
F_{(i,j),(k,l)}(\Sigma_{k,l}^*) &= F_{(i,j),(k,l)}(\Sigma_{k,l} \setminus F_{(i,0),(k,l)}^{-1}(\Sigma_{i,0} \setminus \Sigma_{i,0}^*)) \\
&\supset F_{(i,j),(k,l)}(\Sigma_{kl}) \setminus F_{(i,j),(k,l)}(F_{(i,0),(k,l)}^{-1}(\Sigma_{i0} \setminus A_{i0}^*)) \\
&\supset F_{(i,j),(k,l)}(\Sigma_{kl}) \setminus F_{(i,0),(i,j)}^{-1}(\Sigma_{i0} \setminus \Sigma_{i0}^*) \\
&= F_{(i,j),(k,l)}(\Sigma_{kl}) \setminus (\Sigma_{ij} \setminus \Sigma_{ij}^*) \\
&= F_{(i,j),(k,l)}(\Sigma_{kl}) \cap \Sigma_{ij}^*.
\end{aligned}
$$

However, clearly $F_{(i,j),(k,l)}(\Sigma_{kl}^*) \subset F_{(i,j),(k,l)}(\Sigma_{kl}) \cap \Sigma_{ij}^*$, and equation (12.2) is proved.

In cases (H2) and (H3), the set $F_{(i,j),(k,l)}(\Sigma_{kl})$ is closed in Σ_{ij} by Remarks 2.1, 4.3, and Theorem 7.1. We infer from equation (12.2) that $F_{(i,j),(k,l)}(\Sigma_{kl}^*)$ is a Zariski closed subset of Σ_{ij}^*. Therefore, $\varprojlim_{i,j\in\mathbb{N}} \Sigma_{ij}^* \neq \varnothing$ results from Lemma 3.3 and equation (12.1) is proved in all cases.

We can thus choose $x = (x_{ij})_{i,j\in\mathbb{N}} \in \varprojlim_{i,j\in\mathbb{N}} \Sigma_{ij}^*$. Let $\Phi\colon \varprojlim_{i,j\in\mathbb{N}} \Sigma_{ij} \to \Omega(\tau)$ be the map given in Theorem 9.1. As $\varprojlim_{i,j\in\mathbb{N}} \Sigma_{ij}^* \subset \varprojlim_{i,j\in\mathbb{N}} \Sigma_{ij}$, we obtain $y_0 = \Phi(x) \in \Omega(\tau)$. As $y_0(1_G) = x_{00}(1_G)$ by definition of Φ and as $x_{00}(1_G) \neq 0$ since $x_{00} \in \Sigma_{00}^*$, we deduce that $\Omega(\tau) \neq \{0^G\}$. This contradiction shows that (b) $\implies$ (a).

13. *Nilpotency over finite alphabets*

The following theorem strengthens and extends to any infinite group some results established for full shifts over $G = \mathbb{Z}$ by Culik, Pachl, and Yu [**18**, Theorem 3.5] and by Guillon and Richard [**24**, Corollary 4].

Suppose that X is a topological space equipped with a continuous action of a group G. One says that the dynamical system (X, G) is *topologically mixing* if for each pair of non-empty open subsets U and V of X, there exists a finite subset $F \subset G$ such that $U \cap gV \neq \varnothing$ for all $g \in G \setminus F$. Given a group G and a finite set A, a closed subshift $\Sigma \subset A^G$ is said to be *topologically mixing* provided (Σ, G) is topologically mixing. If (X, G) is a topologically mixing dynamical system and $f : X \to X$ is a continuous G-equivariant map, then the factor system $(f(X), G)$ is also topologically mixing.

THEOREM 13.1. *Let G be an infinite group, let A be a finite set, and let $\Sigma \subset A^G$ be a non-empty topologically mixing subshift of sub-finite-type (e.g. $\Sigma = A^G$, or, if G is finitely generated, Σ is of finite type). Let $\tau : \Sigma \to \Sigma$ be a cellular automaton. Then the following conditions are equivalent:*

(a) *τ is nilpotent;*

(b) *the limit set $\Omega(\tau)$ is reduced to a single configuration;*

(c) *the limit set $\Omega(\tau)$ is finite.*

If G is finitely generated, then the above conditions are equivalent to

(d) *the limit set $\Omega(\tau)$ consists only of periodic configurations.*

Before starting the proof of the above theorem, we present a preliminary lemma. The result is probably well known, but since we could not find any reference, we include a proof for the sake of completeness.

LEMMA 13.2. *Let G be a finitely generated group, let A be a set, and let $\Sigma \subset A^G$ be a finite subshift. Then Σ is of finite type.*

Roughly, the idea is simple. Every configuration $x \in \Sigma$ has a finite orbit, equivalently, its stabilizer $H_x = \operatorname{Stab}_G(x)$ is of finite index in G. Since the intersection of finitely many finite-index subgroups is of finite index, the group $H := \bigcap_{x \in \Sigma} H_x$ is of finite index in G. Moreover, by the Poincaré lemma, there exists a finite index normal subgroup $K \subset H$. This way, we can embed Σ into $A^{G/K}$ (cf. [**10**, Proposition 1.3.7]). As G/K is finite, it follows that Σ is of finite type. The proof below is a detailed and self-contained version of the above idea. See [**16**, Proposition 2.4] for a linear version (where 'finite' becomes 'finite-dimensional').

Proof of Lemma 13.2. Let $S \subset G$ be a finite generating subset of G. After replacing S by $S \cup S^{-1} \cup \{1_G\}$, we can assume that $S = S^{-1}$ and $1_G \in S$. Then, given any element $g \in G$, there exist $n \in \mathbb{N}$ and $s_1, s_2, \ldots, s_n \in S$ such that $g = s_1 s_2 \cdots s_n$. The minimal $n \in \mathbb{N}$ in such an expression of g is the S-length of g, denoted by $\ell_S(g)$.

For all distinct $x, y \in \Sigma$, we can find $g = g_{x,y} \in G$ such that $x(g) \neq y(g)$. Then the finite set $D_0 := \{g_{x,y} : x, y \in \Sigma \text{ such that } x \neq y\} \subset G$ satisfies

$$x|_{D_0} = y|_{D_0} \quad \text{implies } x = y \text{ for all } x \in \Sigma. \tag{13.1}$$

Let us show that $\Sigma = \Sigma(D, P)$ for $D = SD_0$ and $P := \{x|_D : x \in \Sigma\} \subset A^D$. By definition, we have

$$\Sigma(D, P) = \{x \in A^G : \text{ for all } g \in G \text{ there exists } x_g \in \Sigma \text{ such that }$$
$$(g^{-1}x)(d) = x_g(d) \text{ for all } d \in D\}. \tag{13.2}$$

Note that the element $x_g \in \Sigma$ in equation (13.2) is uniquely defined by $x \in \Sigma(D, P)$ and $g \in G$, since $D \supset D_0$ so that $x_g|_D = x'_g|_D$ infers $x_g = x'_g$ by equation (13.1).

We clearly have $\Sigma \subset \Sigma(D, P)$, since Σ is G-invariant.

For the converse inclusion, suppose that $x \in \Sigma(D, P)$ and let us show that $x = x_{1_G} \in \Sigma$. We prove by induction on the S-length of g that

$$x_g = g^{-1}x_{1_G} \tag{13.3}$$

for all $g \in G$. If $\ell_S(g) = 0$, then $g = 1_G$ and equation (13.3) holds trivially. Suppose now that $\ell_S(g) = n$ and let $s \in S$. Given $d_0 \in D_0$ we have, on the one hand, $x(gsd_0) = (g^{-1}x)(sd_0) = x_g(sd_0) = s^{-1}x_g(d_0)$, and, on the other hand, $x(gsd_0) = ((gs)^{-1}x)(d_0) = x_{gs}(d_0)$. This shows that $(s^{-1}x_g)|_{D_0} = x_{gs}|_{D_0}$. Since $s^{-1}x_g$ and x_{gs} both belong to Σ, we deduce from equation (13.1) that $s^{-1}x_g = x_{gs}$. By induction, we have $x_g = g^{-1}x_{1_G}$ so that $x_{gs} = (gs)^{-1}x_{1_G}$. This proves equation (13.3). From equation (13.3) we obtain, for every $g \in G$,

$$x(g) = (g^{-1}x)(1_G) = x_g(1_G) = g^{-1}x_{1_G}(1_G) = x_{1_G}(g).$$

This shows that $x = x_{1_G} \in \Sigma$. $\qquad\square$

Proof of Theorem 13.1. The equivalence (a) $\Longleftrightarrow$ (b) follows from Theorem 1.4. The implication (b) $\Longrightarrow$ (c) is obvious.

Suppose now that $\Omega(\tau)$ is finite. Let $M \subset G$ be a finite subset which serves as a memory set for both τ and Σ, and denote by $H \subset G$ the subgroup it generates. Let $\tau_H : \Sigma_H \to \Sigma_H$ denote the corresponding restriction cellular automaton. It follows from Lemma 2.9 that $\Omega(\tau) = \Omega(\tau_H)^{G/H}$. If G is not finitely generated, then G/H is infinite and necessarily $\Omega(\tau_H)$ and therefore $\Omega(\tau)$ must consist of a single element, as $\Omega(\tau)$ is non-empty (cf. Theorem 1.3). This proves the implication (c) $\Longrightarrow$ (b) for G not finitely generated.

If G is finitely generated, it follows from Lemma 13.2 that $\Omega(\tau)$ is a subshift of finite type. Since A is finite, the characterization of subshifts of finite type in Theorem 10.1 can be applied to the sequence

$$\Sigma \supset \tau(\Sigma) \supset \tau^2(\Sigma) \supset \cdots \supset \Omega(\tau) = \bigcap_{n \in \mathbb{N}} \tau^n(\Sigma),$$

and implies that there exists $n_0 \in \mathbb{N}$ such that $\Omega(\tau) = \tau^{n_0}(\Sigma)$. Therefore, $\Omega(\tau)$ is a factor of Σ. Since Σ is topologically mixing, so is $\Omega(\tau)$. Now let $x, y \in \Omega(\tau)$. As $\Omega(\tau)$ is finite and Hausdorff, $\{x\}$ and $\{y\}$ are open in $\Omega(\tau)$. Thus, by topological mixing of $\Omega(\tau)$, there exists a finite subset $F \subset G$ such that $x = gy$ for all $g \in G \setminus F$. Since $\Omega(\tau)$ is finite, the stabilizer H of y in G is an infinite subgroup of G. It follows that $H \cap (G \setminus F) \neq \varnothing$. Taking $g \in H \cap (G \setminus F)$ yields $x = gy = y$. Hence, $\Omega(\tau)$ is a singleton and this concludes the proof of the implication (c) $\Longrightarrow$ (b).

Finally, suppose that G is finitely generated. As any finite G-invariant subset of A^G necessarily consists only of periodic configurations, we have (c) $\Longrightarrow$ (d). The reverse implication follows from the finiteness of closed subshifts containing only periodic configurations proved in [**4**, Theorem 5.8] and in [**32**, Theorem 1.4] (see also [**5**, Theorem 3.8] for the case $G = \mathbb{Z}^2$). Note that since A^G is compact and τ is continuous, $\Omega(\tau)$ is closed in A^G. $\qquad\square$

14. *Proof of Theorem 1.5*

By Corollary 8.2, we know that Σ is closed in A^G. The equivalence (a) $\Longleftrightarrow$ (b) thus results from Proposition A.5. It is trivial that (a) $\Longrightarrow$ (c) $\Longrightarrow$ (d). For the implications (d) $\Longrightarrow$ (a) and (c) $\Longrightarrow$ (a), let $M \subset G$ be a finite subset containing the memory sets of both τ and Σ such that $1_G \in M$ and $M = M^{-1}$. Let H be the subgroup of G generated by M. Let $\tau_H \colon \Sigma_H \to \Sigma_H$ denote the restriction cellular automaton. By Lemma 2.9(i), we have $\Omega(\tau) = \Omega(\tau_H)^{G/H}$. Thus, if $\Omega(\tau)$ is finite, then so is $\tau(\tau_H)$. Likewise, if item (d) holds for τ, then $\{x(1_G) \colon x \in \Omega(\tau_H)\}$ is finite and $\Omega(\tau_H)$ consists of periodic configurations as well. However, τ is nilpotent if τ_H is nilpotent by Lemma 2.9(ii). Therefore, up to replacing G by H, we can assume that G is finitely generated by M. It then suffices to show that (d) $\Longrightarrow$ (a) as we already know that (c) $\Longrightarrow$ (d).

Assume that item (d) holds. Then $T := \{x(1_G) \colon x \in \Omega(\tau)\}$ is finite. As $\Omega(\tau)$ is G-invariant, $x(g) \in T$ for every $x \in \Omega(\tau)$ and $g \in G$.

Let $(\Sigma_{ij})_{i,j \in \mathbb{N}}$ be the space-time inverse system associated with τ and the memory set M. We set $\Sigma_{i0}^* := \Sigma_{i0} \setminus \{x \in \Sigma_{i0} \colon x(1_G) \in T\}$ for every $i \geq 0$, and define for every $i \geq 0$ and $j \geq 1$:

$$\Sigma_{ij}^* = (q_{i0} \circ \cdots \circ q_{i,j-1})^{-1}(\Sigma_{i0}^*) \subset \Sigma_{ij}.$$

The unit transition maps $p_{ij}^* \colon \Sigma_{i+1,j}^* \to \Sigma_{ij}^*$ and $q_{ij}^* \colon \Sigma_{i,j+1}^* \to \Sigma_{ij}^*$ are respectively the restrictions of the transition maps p_{ij} and q_{ij} of the system $(\Sigma_{ij})_{i,j \in \mathbb{N}}$.

Suppose first that $\Sigma_{ij}^* \neq \varnothing$ for all $i, j \in \mathbb{N}$. Then exactly as in the proof of Theorem 1.4, there exists $x = (x_{ij})_{i,j \in \mathbb{N}} \in \varprojlim_{i,j \in \mathbb{N}} \Sigma_{ij}^*$ and we obtain $y_0 = \Phi(x) \in \Omega(\tau)$ with $y_0(1_G) = x_{00}(1_G)$. However, $x_{00}(1_G) \notin T$ because $x_{00} \in \Sigma_{00}^*$, we find that $\Omega(\tau) \not\subset T^G$, which is a contradiction.

Therefore, we must have $\Sigma_{ij}^* = \varnothing$ for some $i, j \in \mathbb{N}$. If $j = 0$, then $\Sigma_{i0}^* = \varnothing$ and $x(1_G) \in T$ for all $x \in \Sigma_{i0}$. We deduce that $A^G \subset T^G$ and thus $A \subset T$ is finite. As G is infinite and $\Omega(\tau)$ contains only periodic configurations, Theorem 13.1 implies that τ is nilpotent. If $j \geq 1$, then by definition of Σ_{ij}, we have for every $x \in \Sigma_{ij}$ that

$$(q_{i0} \circ \cdots \circ q_{i,j-1})(x)(1_G) \in T.$$

Hence, as τ^j is G-equivariant, we deduce that $\tau^j(x) \in T^G$ for every $x \in A^G$. Thus, the restriction $\sigma := \tau^j|_{T^G} \colon T^G \to T^G$ is a well-defined cellular automaton. As a subset of $\Omega(\tau)$, the set $\Omega(\sigma)$ also consists of periodic configurations. We deduce from Theorem 13.1 that σ is nilpotent, say, $\sigma^m(x) = x_0$ for all $x \in T^G$ for some $m \in \mathbb{N}$ and $x_0 \in A^G$. It follows that $\tau^{(m+1)j}(x) = \sigma^m(\tau^j(x)) = x_0$ for all $x \in A^G$. We conclude that τ is nilpotent. The proof of the theorem is completed.

15. *Counter-examples*

The following example (cf. [**11**, Example 5.1] and [**14**, Example 8.1]) shows that Theorem 8.1 and assertions (i) and (iii) of Theorem 1.3 become false if we remove the hypothesis that the ground field K is algebraically closed.

Example 15.1. Let $G := \mathbb{Z}$ be the additive group of integers and let $V := \mathrm{Spec}(\mathbb{R}[t]) = \mathbb{A}^1_{\mathbb{R}}$ denote the affine line over $\mathbb{R}$. Then $A := V(\mathbb{R}) = \mathbb{R}$. Consider the cellular automaton $\tau : \mathbb{R}^{\mathbb{Z}} \to \mathbb{R}^{\mathbb{Z}}$ with memory set $M := \{0, 1\} \subset G$ and associated local defining map $\mu : \mathbb{R}^M \to \mathbb{R}$ defined by $\mu(p) = p(1) - p(0)^2$ for all $p \in \mathbb{R}^M$. Clearly, τ is an algebraic cellular automaton over $(G, V, \mathbb{R})$. Indeed, μ is induced by the algebraic morphism $f : V^2 \to V$ associated with the morphism of $\mathbb{R}$-algebras

$$\mathbb{R}[t] \to \mathbb{R}[t_0, t_1]$$
$$t \mapsto t_1 - t_0^2.$$

Note that $\tau : \mathbb{R}^{\mathbb{Z}} \to \mathbb{R}^{\mathbb{Z}}$ is given by

$$\tau(c)(n) = c(n + 1) - c(n)^2 \quad \text{for all } c \in \mathbb{R}^{\mathbb{Z}} \text{ and } n \in \mathbb{Z}.$$

CLAIM 15.2. *The limit set $\Omega(\tau)$ is a dense non-closed subset of $\mathbb{R}^{\mathbb{Z}}$. In particular, $\Omega(\tau)$ is not a closed subshift of $\mathbb{R}^{\mathbb{Z}}$.*

Proof. Let $c \in \mathbb{R}^{\mathbb{Z}}$ and let $F \subset \mathbb{Z}$ be a finite subset. Choose an integer $m \in \mathbb{Z}$ such that $F \subset [m, \infty)$ and consider the configuration $d \in \mathbb{R}^{\mathbb{Z}}$ defined by $d(n) := 0$ if $n < m$ and $d(n) := c(n)$ if $n \geq m$. For each $k \in \mathbb{N}$, define by induction on k a configuration $d_k \in \mathbb{R}^{\mathbb{Z}}$ in the following way. We first take $d_0 = d$. Then, assuming that the configuration d_k has been defined, we define the configuration d_{k+1}, using induction on n, by $d_{k+1}(n) := 0$ if $n \leq m$ and $d_{k+1}(n + 1) := d_k(n) + d_{k+1}(n)^2$ if $n \geq m$. Clearly, $\tau(d_{k+1}) = d_k$ so that $d = d_0 = \tau^k(d_k)$ for all $k \in \mathbb{N}$. Therefore, $d \in \Omega(\tau)$. Since c and d coincide on $[m, \infty)$ and hence on F, this shows that c is in the closure of $\Omega(\tau)$. Thus, $\Omega(\tau)$ is dense in $\mathbb{R}^{\mathbb{Z}}$.

In [**11**, Example 5.1] and [**14**, Example 8.1], it is shown that $\mathrm{Im}(\tau)$ is not closed of $R^{\mathbb{Z}}$ and the constant configuration $e \in \mathbb{R}^{\mathbb{Z}}$, defined by $e(n) := 1$ for all $n \in \mathbb{Z}$, does not belong to $\mathrm{Im}(\tau)$. This implies that $e \notin \Omega(\tau)$. As $\Omega(\tau)$ is dense in $\mathbb{R}^{\mathbb{Z}}$, we deduce that $\Omega(\tau)$ is not closed in $\mathbb{R}^{\mathbb{Z}}$.   □

Remark that $\mathrm{Im}(\tau)$ is an algebraic sofic subshift of $\mathbb{R}^{\mathbb{Z}}$ since it is the image of the full shift $\mathbb{R}^{\mathbb{Z}}$ under the algebraic cellular automaton τ. Thus, an algebraic sofic subshift may fail to be closed in the ambient full shift.

For every integer $n \geq 1$, the set $M_n := \{0, \ldots, n\}$ is a memory set for τ^n. Let $\mu_n : \mathbb{R}^{M_n} \to \mathbb{R}$ denote the associated local defining map. We shall use the fact that for each $n \geq 1$, there exists a polynomial $v_n \in \mathbb{R}[t_0, \ldots, t_{n-1}]$ such that for every $p \in \mathbb{R}^{M_n}$,

$$\mu_n(p) = p(n) + v_n(p(0), \ldots, p(n - 1)). \tag{15.1}$$

This fact can be proved by an easy induction. For $n = 1$, we have $\mu_1(p) = \mu(p) = p(1) - p(0)^2$ for every $p \in \mathbb{R}^{M_1}$ so that we can take $v_1(t_0) = -t_0^2$. Suppose now that the assertion

holds for some $n \geq 1$. Let $c \in \mathbb{R}^{\mathbb{Z}}$ and let $d = \tau^n(c)$. By the induction hypothesis, we have that $d(0) = \mu_n(c(0), \ldots, c(n))$ and

$$d(1) = \mu_n(c(1), \ldots, c(n+1)) = c(n+1) + \nu_n(c(1), \ldots, c(n)).$$

Therefore, we get

$$\begin{aligned}
\tau^{n+1}(c)(0) = \tau(\tau^n(c))(0) = \tau(d)(0) &= d(1) - d(0)^2 \\
&= c(n+1) + \nu_k(c(1), \ldots, c(n)) - \mu_n(c(0), \ldots, c(k))^2 \\
&= c(n+1) + \nu_{n+1}(c(0), \ldots, c(n)),
\end{aligned}$$

where $\nu_{n+1} \in \mathbb{R}[t_0, \ldots, t_n]$ is given by the formula

$$\nu_{n+1}(t_0, \ldots, t_n) := \nu_n(t_1, \ldots, t_n) - \mu_n(t_0, \ldots, t_n)^2.$$

Thus, for every $p \in \mathbb{R}^{M_{n+1}}$,

$$\mu_{n+1}(p) = p(n+1) + \nu_{n+1}(p(0), \ldots, p(n)),$$

and the assertion follows by induction.

CLAIM 15.3. *For every configuration $c \in \mathbb{R}^{\mathbb{Z}}$ and any integer $n \geq 1$, there exists $d \in \mathbb{R}^{\mathbb{Z}}$ such that $d(k) = c(k)$ for all $k \leq 0$ and $\tau^n(d)(k) = c(k)$ for all $k \geq -n + 1$.*

Proof. Let $c \in \mathbb{R}^{\mathbb{Z}}$. We define $d \in \mathbb{R}^{\mathbb{Z}}$ by

$$d(k) = c(k) \quad \text{if } k \leq 0,$$

and inductively for $k \geq 1$ by

$$d(k) := c(k - n) - \nu_n(d(k - n), \ldots, d(k - 1)). \tag{15.2}$$

By applying equations (15.1) and (15.2), we obtain, for every $k \geq -n + 1$,

$$\begin{aligned}
\tau^n(d)(k) = \mu_n(d(k), \ldots, d(n+k)) &= d(n+k) + \nu_n(d(k), \ldots, d(k+n-1)) \\
&= c(k),
\end{aligned}$$

and the claim is proved. $\qquad\square$

CLAIM 15.4. *The set $\mathrm{R}(\tau)$ is a dense non-closed subset of $\mathbb{R}^{\mathbb{Z}}$. In particular, $\mathrm{R}(\tau)$ is not a closed subshift of $\mathbb{R}^{\mathbb{Z}}$.*

Proof. Let $c \in \mathbb{R}^{\mathbb{Z}}$. For each $n_0 \geq 1$, define by induction on $n \geq n_0$ a configuration $d_n \in \mathbb{R}^{\mathbb{Z}}$ in the following way. Let $d_{n_0} = c$. Then, assuming that the configuration d_n has been defined, we can choose by Claim 15.3 and the $\mathbb{Z}$-equivariance of τ a configuration d_{n+1} satisfying $d_{n+1}(k) = d_n(k)$ for $k \leq 2 \cdot 3^n$ and $\tau^{3^{n+1}}(d_{n+1})(k) = d_n(k)$ for $k \geq -3^n + 1$.

Hence, we can define $d \in \mathbb{R}^{\mathbb{Z}}$ by setting $d(k) = d_n(k)$ for any $n \geq n_0$ such that $k \leq 2 \cdot 3^n$. Let $n \geq n_0$. Remark that $M_{3^{n+1}}$ is a memory set of $\tau^{3^{n+1}}$ and $d(k) = d_{n+1}(k)$

for $k \leq 2 \cdot 3^{n+1}$. Hence, for $-3^n + 1 \leq k \leq 3^n$ so that in particular $3^{n+1} + k \leq 2 \cdot 3^{n+1}$, we have

$$\tau^{3^{n+1}}(d)(k) = \tau^{3^{n+1}}(d_{n+1})(k) = d_n(k) = d(k). \tag{15.3}$$

Since this holds for all $n \geq n_0$ and as every finite subset is contained in $\{-3^n + 1, \ldots, 3^n\}$ for any large enough n, we deduce that $d \in R(\tau)$.

It is clear from the construction that $d_n(k) = c(k)$ for every $n \geq n_0$ and $k \leq 2 \cdot 3^{n_0}$. Thus, $d(k) = c(k)$ for every $k \leq 2 \cdot 3^{n_0}$. As $n_0 \geq 1$ is arbitrary, it follows that every $c \in \mathbb{R}^{\mathbb{Z}}$ belongs to the closure of $R(\tau)$. In other words, $R(\tau)$ is dense in $\mathbb{R}^{\mathbb{Z}}$.

The set $R(\tau)$ is not closed in $\mathbb{R}^{\mathbb{Z}}$. Indeed, the configuration $e \in \mathbb{R}^{\mathbb{Z}}$, given by $e(k) = 1$ for all $k \in \mathbb{Z}$, does not belong to $R(\tau)$ since $\tau^n(e)(0) = 0 \neq c(0)$ for all $n \geq 1$. □

CLAIM 15.5. *One has* $NW(\tau) = CR(\tau) = \mathbb{R}^{\mathbb{Z}}$.

Proof. By Claim 15.4, the set $R(\tau)$ is dense in $\mathbb{R}^{\mathbb{Z}}$. Since $NW(\tau)$ and $CR(\tau)$ are closed in $\mathbb{R}^{\mathbb{Z}}$ and contain $R(\tau)$, we deduce that $NW(\tau) = CR(\tau) = \mathbb{R}^{\mathbb{Z}}$. □

CLAIM 15.6. *One has* $R(\tau) \not\subset \Omega(\tau)$ *and* $\Omega(\tau) \not\subset R(\tau)$.

Proof. By the proof of Claim 15.2, we know that the configuration $c \in \mathbb{R}^{\mathbb{Z}}$, given by $c(k) = 0$ if $k \leq -1$ and $c(k) = 1$ if $k \geq 0$, belongs to $\Omega(\tau)$. However, as $\tau^n(c)(0) = 0 \neq c(0)$ for every $n \geq 1$, it follows that $c \notin R(\tau)$.

However, reconsider the configuration $e \in \mathbb{R}^{\mathbb{Z}}$ given by $e(k) = 1$ for every $k \in \mathbb{Z}$. The proof of Claim 15.4 actually shows that there exists $d \in R(\tau)$ such that $d(k) = e(k) = 1$ for all $k \leq 0$. Suppose that there exists $b \in \mathbb{R}^{\mathbb{Z}}$ such that $\tau(b) = d$. Then $b(k + 1) = 1 + b(k)^2$ for all $k \leq 0$. Thus, $1 \leq b(k) \leq b(k + 1)$ for all $k \leq 0$, so that the limit $t := \lim_{k \to -\infty} b(k)$ exists and is finite. By passing to the limit in the relation $b(k + 1) = 1 + b(k)^2$, we find that $t = 1 + t^2$, which is a contradiction as t must be real. This shows that $d \notin \tau(\mathbb{R}^{\mathbb{Z}})$ and thus $d \notin \Omega(\tau)$. The proof is completed. □

Remark 15.7. Consider the complex version of Example 15.1, that is, let $\tau_{\mathbb{C}} \colon \mathbb{C}^{\mathbb{Z}} \to \mathbb{C}^{\mathbb{Z}}$ be the algebraic cellular automaton over $(\mathbb{Z}, \mathbb{A}_{\mathbb{C}}^1, \mathbb{C})$ with memory set $M = \{0, 1\} \subset \mathbb{Z}$ and associated local defining map $\mu_{\mathbb{C}} \colon \mathbb{C}^M \to \mathbb{C}$ defined by $\mu_{\mathbb{C}}(p) = p(1) - p(0)^2$ for all $p \in \mathbb{C}^M$.

Then the same proofs as in Claims 15.4 and 15.5 show that $R(\tau_{\mathbb{C}})$ is a dense non-closed subset of $\mathbb{C}^{\mathbb{Z}}$ and that $NW(\tau_{\mathbb{C}}) = CR(\tau_{\mathbb{C}}) = \mathbb{C}^{\mathbb{Z}}$. By applying Theorem 1.3(ii), we deduce that $\Omega(\tau_{\mathbb{C}}) = \mathbb{C}^{\mathbb{Z}}$, that is, $\tau_{\mathbb{C}}$ is surjective, which can also be easily checked by a direct verification.

The following example shows that assertion (v) of Theorem 1.3 becomes false if we remove the hypothesis that the ground field K is algebraically closed.

Example 15.8. Let G be a group and let $V := \mathrm{Spec}(\mathbb{R}[t]) = \mathbb{A}_{\mathbb{R}}^1$ denote the affine line over $\mathbb{R}$. Consider the algebraic morphism $f \colon V \to V$ given by $t \mapsto t^2 + 1$. Take $A := V(\mathbb{R}) = \mathbb{R}$ and let $\tau \colon A^G \to A^G$ denote the cellular automaton with memory set $M := \{1_G\}$ and associated local defining map $\mu \colon A^M = A \to A$ given by $a \mapsto a^2 + 1$. The cellular

automaton τ is algebraic since μ is induced by f but its limit set $\Omega(\tau)$ is clearly empty. Remark also that τ is not stable since otherwise, $\Omega(\tau)$ would be non-empty.

The following example shows that Theorem 1.4 becomes false if we remove the hypothesis that the ground field K is algebraically closed.

Example 15.9. Let G be a group and let $V := \mathbb{P}^1_{\mathbb{R}}$ denote the projective line over $\mathbb{R}$. Consider the algebraic morphism $f : V \to V$ given by $(x : y) \mapsto (x^2 + y^2 : y^2)$. Take $A := V(\mathbb{R}) = \mathbb{P}^1(\mathbb{R}) = \mathbb{R} \cup \{\infty\}$ and let $\tau : A^G \to A^G$ denote the cellular automaton with memory set $M := \{1_G\}$ and associated local defining map $\mu : A^M = A \to A$ given by $a \mapsto a^2 + 1$. The cellular automaton τ is algebraic since μ is induced by f. Clearly, the limit set $\Omega(\tau)$ is reduced to the constant configuration $g \mapsto \infty$ but τ is not nilpotent.

16. *Generalizations*

Using basic properties of proper morphisms, it is not hard to see that all the results for case (H2) (respectively for case $(\widetilde{H2})$ in Theorem 8.1) remain valid if V (respectively V_0) is assumed to be separated (and not necessarily complete). For this, it suffices to remark that images of morphisms from a complete algebraic variety to a separated algebraic variety (cf. [**31**, §3.3.1]) are Zariski closed complete subvarieties (cf. [**31**, §3.3.2]). This leads us to the following definition.

Definition 16.1. Let G be a group and let V be a separated algebraic variety over a field K. Let $A := V(K)$. A subset $\Sigma \subset A^G$ is called a *complete algebraic sofic subshift* if it is the image of an algebraic subshift of finite type $\Sigma' \subset B^G$, where $B = U(K)$ and U is a complete K-algebraic variety, under an algebraic cellular automaton $\tau' : B^G \to A^G$.

With the above definition, Theorem 10.1 can also be extended as follows without any changes in the proof.

THEOREM 16.2. *Let G be a finitely generated group. Let V be a separated algebraic variety over an algebraically closed field K. Let $A = V(K)$ and let $\Sigma \subset A^G$ be a complete algebraic sofic subshift. Then following are equivalent:*
(a) Σ *is a subshift of finite type;*
(b) Σ *is an algebraic subshift of finite type;*
(c)   *every descending sequence of algebraic sofic subshifts of A^G*

$$\Sigma_0 \supset \Sigma_1 \supset \cdots \supset \Sigma_n \supset \Sigma_{n+1} \supset \cdots$$

    such that $\bigcap_{n \geq 0} \Sigma_n = \Sigma$ eventually stabilizes.

Now, let G be a group and let V be an algebraic variety over a field K. Let $A = V(K)$ and let $\Sigma \subset A^G$ be a subset.

Definition 16.3. $\Sigma \subset A^G$ is called a *countably proconstructible subshift of finite type* (CPSFT) if there exist a finite subset $D \subset G$ and a subset $W \subset V^D$ which is the complement in V^D of a countable number of constructible subsets (cf. §3), such that

$\Sigma = \Sigma(D, W(K))$. Similarly, $\Sigma \subset A^G$ is a *countably proconstructible sofic subshift* (CPS subshift) if it is the image of a CPSFT under an algebraic cellular automaton with range A^G.

Our proofs actually show that Theorem 1.3 (except point (iv)), Theorem 1.4 (respectively Theorem 1.5) still hold if we replace hypotheses (H1), (H2), and (H3) and the assumption $\Sigma \subset A^G$ being an algebraic sofic subshift (respectively a topologically mixing algebraic sofic subshift) by a more general hypothesis:

(H) K is an uncountable algebraically closed field and $\Sigma \subset A^G$ is a CPS subshift (respectively topologically mixing CPS subshift) and $\tau \colon \Sigma \to \Sigma$ is an algebraic cellular automaton.

In fact, it can be directly checked from our proofs that results for case (H1) in §6 (respectively §§7 and 8) remain valid if we assume that K is an uncountable algebraically closed field and Σ is a CPSFT (respectively a CPS subshift).

We now introduce a non-trivial class of non-empty CPSFT (cf. Theorem 16.6).

Definition 16.4. Let G be a group. Let V be an algebraic variety over a field K and let $A = V(K)$. A subshift $\Sigma \subset A^G$ is called a *full* CPSFT if there exist a finite subset $D \subset G$ and a subset $W = V^D \setminus (\bigcup_{n \in \mathbb{N}} U_n)$ where each $U_n \subset V^D$ is a constructible subset satisfying $\dim U_n < \dim V^D$, such that $\Sigma = \Sigma(D, W(K))$. Here, $\dim Z$ denotes the Krull dimension of a constructible subset Z (see for example [15]).

Remark that if V is finite, that is, $\dim V = 0$, the conditions $\dim U_n < \dim V^D$ imply that $U_n = \varnothing$ for every $n \in \mathbb{N}$, thus $W = V^D$. Hence, when the alphabet is finite, the only full CPSFT is the full shift.

Example 16.5. If $G = \mathbb{Z}$, $A = \mathbb{C}$, $D = \{0, 1\} \subset \mathbb{Z}$, $W = \mathbb{C}^D \setminus E$, where $E \subset \mathbb{C}^D \simeq \mathbb{C}^2$ is any countable union of complex algebraic curves and points, then $\Sigma' = \Sigma(D, W) \subset \mathbb{C}^{\mathbb{Z}}$ is a *non-empty* full CPSFT (by Theorem 16.6). Let $\tau' \colon \mathbb{C}^{\mathbb{Z}} \to \mathbb{C}^{\mathbb{Z}}$ be given by $\tau'(x)(n) = x(n)^2 - x(n + 1) + 1$ for every $x \in \mathbb{C}^{\mathbb{Z}}$, $n \in \mathbb{Z}$, then $\Sigma := \tau'(\Sigma')$ is a non-empty *closed* CPS subshift of $\mathbb{C}^{\mathbb{Z}}$ (by Theorem 8.1 which is true under the condition (H)). Note that $\tau := \tau'|_{\Sigma} \colon \Sigma \to \Sigma$ is an algebraic cellular automaton.

THEOREM 16.6. *Let G be a group. Let V be a non-empty algebraic variety over an uncountable algebraically closed field K and let $A = V(K)$. Then every full CPSFT $\Sigma \subset A^G$ is non-empty.*

Proof. We write $\Sigma = \Sigma(D, W(K))$ for some finite subset $D \subset G$ and $W = V^D \setminus (\bigcup_{n \in \mathbb{N}} U_n)$, where $U_n \subset V^D$, $n \in \mathbb{N}$, is a constructible subset such that $\dim U_n < \dim V^D$. In particular, W is a countably proconstructible subset of V^D. Suppose first that G is finitely generated and let the notation be as in §5. Then the same proof for case (H1) of Proposition 6.2 actually implies that $\Sigma_{ij} = \bigcap_{k \geq i} p_{ijk}(A_{kj})$ for $i, j \in \mathbb{N}$, where $A_{ij} = \bigcap_{g \in D_{ij}} \pi_{ij,g}^{-1}(gW)(K) \subset A^{M^{i+j}}$ (cf. equation (6.1)). Note that D_{ij} is finite

and $gW \simeq W$ for all $g \in G$. It follows immediately that A_{ij} is also a complement of a countable number of constructible subsets Z_n such that $\dim Z_n < \dim A^{M^{i+j}}$ for every $n \in \mathbb{N}$. Hence, for every finite subset $I \subset \mathbb{N}$, the constructible set $\bigcap_{n \in I}(A^{M^{i+j}} \setminus Z_n) \neq \varnothing$ by the dimensional reason. By Lemma 3.2, we deduce that $A_{ij} = \bigcap_{n \in \mathbb{N}}(A^{M^{i+j}} \setminus Z_n) \neq \varnothing$ for every $i, j \in \mathbb{N}$. Always by Lemma 3.2, $\Sigma_{ij} = \bigcap_{k \geq i} p_{ijk}(A_{kj}) \neq \varnothing$ for all $i, j \in \mathbb{N}$ and thus $\varprojlim_{i \in \mathbb{N}} \Sigma_{ij} \neq \varnothing$. Finally, the bijection $\Sigma \simeq \varprojlim_{i \in \mathbb{N}} \Sigma_{ij}$ (cf. equation (4.6)) implies that $\Sigma \neq \varnothing$.

For an arbitrary group G, let H be the subgroup generated by D. Then by Lemma 2.8, we have a factorization $\Sigma = \prod_{c \in G/H} \Sigma_c$ where the sets Σ_c are pairwise homeomorphic. By the above paragraph, we know that $\Sigma_H \neq \varnothing$ and therefore $\Sigma \neq \varnothing$. $\qquad\square$

Theorem 16.6 serves as a motivation for the notion of full CPSFT as we see in the following comparison with the finite alphabet case. It is well known that for $G = \mathbb{Z}^d$, $d \geq 2$, and for a finite set A of cardinality at least 2, it is algorithmically undecidable whether the subshift of finite type $\Sigma(D, P) \subset A^G$ is non-empty for a given finite subset $D \in G$ and a given subset $P \subset A^D$. This is known as the domino problem (cf. [2, 7, 49]; see also the recent [6], where a notion of 'simulation' for labeled graphs is introduced and applied to the domino problem for the Cayley graph of the lamplighter group and, more generally, to Diestel–Leader graphs).

A. *Appendix*

A.1. *Limit sets and nilpotency of general maps.*

Given a set X, recall that a map $f: X \to X$ is *pointwise nilpotent* if there exists $x_0 \in X$ such that for every $x \in X$, there exists an integer $n_0 \geq 1$ such that $f^n(x) = x_0$ for all $n \geq n_0$. Such an x_0 is then the unique fixed point of f and is called the *terminal point* of the pointwise nilpotent map f. Clearly, if f is nilpotent, then it is pointwise nilpotent and the terminal point of f as a nilpotent map coincides with its terminal point as a pointwise nilpotent map. Moreover, if f is pointwise nilpotent, then its limit set is reduced to its terminal point. When the set X is finite, the three conditions: (i) f is nilpotent; (ii) f is pointwise nilpotent; and (iii) the limit set of f is a singleton, are all equivalent. This becomes false when X is infinite. Actually, we have the following lemma.

LEMMA A.1. *Let X be an infinite set. Then the following hold:*
 (i) *there exists a map $f: X \to X$ such that $\Omega(f) = \varnothing$;*
 (ii) *there exists a map $f: X \to X$ which is not pointwise nilpotent (and hence not nilpotent) such that $\Omega(f)$ is a singleton;*
 (iii) *there exists a map $f: X \to X$ such that $f(\Omega(f)) \subsetneq \Omega(f)$;*
 (iv) *there exists a surjective (and hence non-nilpotent) pointwise nilpotent map $f: X \to X$.*

Proof. (i) Since X is infinite, there exists a bijective map $\psi: \mathbb{N} \times X \to X$. Then the map $f: X \to X$ defined by $f := \psi \circ g \circ \psi^{-1}$, where $g: \mathbb{N} \times X \to \mathbb{N} \times X$ is given by $g(n, x) = (n + 1, x)$ for all $(n, x) \in \mathbb{N} \times X$, satisfies $\Omega(f) = \Omega(g) = \varnothing$. This shows item (i).

(ii) Let $\widehat{\mathbb{N}} := \mathbb{N} \cup \{\infty\}$. Since X is infinite, there exists an injective map $\varphi \colon \widehat{\mathbb{N}} \to X$ that is not surjective. Then the map $f \colon X \to X$ defined by $f(\varphi(n)) = \varphi(n+1)$ for all $n \in \mathbb{N}$ and $f(x) = \varphi(\infty)$ for all $x \in X \setminus \varphi(\mathbb{N})$ satisfies $\Omega(f) = \{\varphi(\infty)\}$ but is clearly not pointwise nilpotent.

(iii) Consider, for each $n \geq 1$, the set $I_n := \{0, 1, \ldots, n\}$ and the map $g_n \colon I_n \to I_n$ given by $g_n(k) := k - 1$ if $k \geq 1$ and $g_n(0) = 0$. Let Y be the set obtained by taking disjoint copies of the sets I_n, $n \geq 1$, and identifying all copies of 0 in a single point y_0 and all copies of 1 in a single point $y_1 \neq y_0$. Then the maps g_n induce a well-defined quotient map $g \colon Y \to Y$. Clearly, $\Omega(g) = \{y_0, y_1\}$ while $g(\Omega(g)) = \{y_0\}$. As X is infinite, the set Y can be regarded as a subset of X. Then the map $f \colon X \to X$, defined by $f(x) = g(x)$ if $x \in Y$ and $f(x) = x$ otherwise, satisfies $\Omega(f) = \{y_0, y_1\} \cup (X \setminus Y)$ while $f(\Omega(f)) = \{y_0\} \cup (X \setminus Y) \subsetneqq \Omega(f)$.

(iv) Choose a point $x_0 \in X$ and a bijective map $\xi \colon \mathbb{N} \times X \to X \setminus \{x_0\}$. Then the map $f \colon X \to X$, defined by $f(\xi(n, x)) = \xi(n-1, x)$ if $n \geq 1$ and $f(x_0) = f(\xi(0, x)) = x_0$ for all $x \in X$, is clearly surjective and pointwise nilpotent (with terminal point x_0). $\qquad\square$

A.2. *Limit sets and nilpotency of general cellular automata*

PROPOSITION A.2. *Let A be an infinite set and let G be a group. Then the following hold:*
  (i)   *there exists a cellular automaton $\tau \colon A^G \to A^G$ with $\Omega(\tau) = \varnothing$;*
  (ii) *there exists a non-nilpotent cellular automaton $\tau \colon A^G \to A^G$ such that $\Omega(\tau)$ is reduced to a single configuration;*
  (iii) *there exists a cellular automaton $\tau \colon A^G \to A^G$ which satisfies $\tau(\Omega(\tau)) \subsetneqq \Omega(\tau)$;*
  (iv) *if the group G is finite, then there exists a pointwise nilpotent cellular automaton $\tau \colon A^G \to A^G$ which is not nilpotent.*

Proof. Given a map $f \colon A \to A$, we consider the cellular automaton $\tau \colon A^G \to A^G$ with memory set $M := \{1_G\}$ and associated local defining map $\mu := f \colon A = A^M \to A$, that is, $\tau = \prod_{g \in G} f$.

By Lemma A.1(i), there exists $f \colon A \to A$ whose limit set is empty. Clearly, the associated cellular automaton $\tau \colon A^G \to A^G$ has also empty limit set, showing item (i).

By Lemma A.1(ii), there exists a non-nilpotent map $f \colon A \to A$ such that $\Omega(f) = \{a_0\}$ for some $a_0 \in A$. Then, for such a choice of f, the cellular automaton $\tau \colon A^G \to A^G$ is not nilpotent and $\Omega(\tau) = \{x_0\}$, where $x_0 \in A^G$ is the constant configuration defined by $x_0(g) := a_0$ for all $g \in G$. This shows item (ii).

By Lemma A.1(iii), we can find a map $f \colon A \to A$ which satisfies $f(\Omega(f)) \subsetneqq \Omega(f)$. Then, for such a choice of f, the cellular automaton $\tau \colon A^G \to A^G$ clearly satisfies $\tau(\Omega(\tau)) \subsetneqq \Omega(\tau)$. This shows item (iii).

Finally, by Lemma A.1(iv), there exists a surjective map $f \colon A \to A$ which is pointwise nilpotent. The associated cellular automaton $\tau \colon A^G \to A^G$ is surjective and hence not nilpotent. For G finite, τ is clearly pointwise nilpotent. This shows item (iv). $\qquad\square$

A.3. *Nilpotency and pointwise nilpotency of general cellular automata*

LEMMA A.3. *Let A be a set and let G be a group. Let $\Sigma \subset A^G$ be a topologically transitive closed subshift. Suppose that $X \subset \Sigma$ is a closed subshift of A^G with non-empty interior in Σ. Then one has $X = \Sigma$.*

Proof. Let $U \subset \Sigma$ be a non-empty open subset of Σ. Let V denote the interior of X in Σ. Note that V is G-invariant. By topological transitivity, there exists $g \in G$ such that $U \cap gV \neq \varnothing$. As $U \cap gV = U \cap V \subset U \cap X$, we deduce that $U \cap X \neq \varnothing$. Hence, X is dense in Σ. Since X is also closed in Σ, we conclude that $X = \Sigma$. □

LEMMA A.4. *Let A be a set and let G be an infinite group. Let $\Sigma \subset A^G$ be a topologically mixing closed subshift of sub-finite-type. Suppose that $\tau \colon \Sigma \to \Sigma$ is a cellular automaton satisfying the following property: there exists a constant configuration $x_0 \in \Sigma$ such that, for every $x \in \Sigma$, there is an integer $n \geq 1$ such that $\tau^n(x) = x_0$. Then τ is nilpotent with terminal point x_0.*

Proof. Suppose first that G is countable. As A^G is a countable product of discrete spaces, it admits a complete metric compatible with its topology. Since Σ is closed in A^G, it follows that the topology induced on Σ is completely metrizable and hence that Σ is a Baire space. For each integer $n \geq 1$, the set

$$X_n := (\tau^n)^{-1}(x_0) = \{x \in \Sigma : \tau^n(x) = x_0\}$$

is a closed subshift of A^G. We have $\Sigma = \bigcup_{n \geq 1} X_n$ by our hypothesis on τ. By the Baire category theorem, there is an integer $n_0 \geq 1$ such that X_{n_0} has a non-empty interior. The subshift Σ is topologically mixing and therefore topologically transitive since G is infinite. It follows that $X_{n_0} = \Sigma$ by Lemma A.3. Thus, $\tau^{n_0}(x) = x_0$ for all $x \in \Sigma$. This shows that τ is nilpotent with terminal point x_0. Note that we have not used the hypothesis that Σ is of sub-finite-type in this part of the proof.

Let us treat now the general case. Suppose that G is an infinite (possibly uncountable) group. Let $M \subset G$ be a finite memory set for both τ and Σ. As G is infinite, there exists an infinite countable subgroup $H \subset G$ containing M. Let $\tau_H \colon \Sigma_H \to \Sigma_H$ denote the restriction cellular automaton (cf. §2.5). Thanks to the decompositions $\tau = \prod_{c \in G/H} \tau_c$ and $\Sigma = \prod_{c \in G/H} \Sigma_c$ where $\tau_c \colon \Sigma_c \to \Sigma_c$ (cf. §2.5), it is not hard to see that Σ_H and τ_H satisfy similar hypotheses as Σ and τ with the constant terminal point $x_0|_H$. Remark that Σ_H is topologically mixing since H is infinite and Σ is topologically mixing. Hence, τ_H is nilpotent by the above paragraph. Therefore, τ is itself nilpotent by Lemma 2.9(ii). □

The following result is well known, at least in the case of full shifts with finite alphabets (cf. [**24**, Proposition 2], [**50**, Proposition 1], [**32**]).

PROPOSITION A.5. *Let A be a set and let G be an infinite group. Let $\Sigma \subset A^G$ be a topologically mixing closed subshift of sub-finite-type. Suppose that $\tau \colon \Sigma \to \Sigma$ is a cellular automaton. Then the following conditions are equivalent:*
  (i)   *τ is nilpotent;*
 (ii)   *τ is pointwise nilpotent;*

(iii)   there exists a constant configuration $x_0 \in \Sigma$ such that, for every $x \in \Sigma$, there is an integer $n \geq 1$ such that $\tau^n(x) = x_0$.

Proof. The implication (i) $\implies$ (ii) is obvious and (ii) $\implies$ (iii) immediately follows from G-equivariance of τ. The implication (iii) $\implies$ (i) follows from Lemma A.4. $\square$

Remark A.6. The equivalences (i) $\iff$ (ii) $\iff$ (iii) hold trivially true when A and G are both finite. The implication (i) $\implies$ (ii) and the equivalence (ii) $\iff$ (iii) remain valid for G finite. However, it follows from Proposition A.2(iv) that the implication (ii) $\implies$ (i) becomes false for A infinite and G finite.

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