

A QUASI-NEWTON APPROACH TO IDENTIFICATION OF A PARABOLIC SYSTEM

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Abstract

A quasi-Newton method (QNM) in infinite-dimensional spaces for identifying parameters involved in distributed parameter systems is presented in this paper. Next, the linear convergence of a sequence generated by the QNM algorithm is also proved. We apply the QNM algorithm to an identification problem for a nonlinear parabolic partial differential equation to illustrate the efficiency of the QNM algorithm.

1. Introduction

Quasi-Newton methods play an important role in numerically solving optimization problems on the Euclidean spaces. But few papers discuss these methods in identification of infinite-dimensional systems.

Formulating parameter estimation problems as constrained, regularized optimization problems, Kunisch *et al.* [13] investigated the reduced SQP (Sequential Quadratic Programming) methods with BFGS (Broyden-Fletcher-Goldfarb-Shanno) update for the identification of an elliptic system.

In this paper we formulate an identification problem as an unconstrained optimization one. We suggest a Quasi-Newton Method (QNM) to solve an unconstrained optimization problem in Section 2. Following Broyden *et al.* [3] and using the Hilbert-Schmidt class defined in [7], we prove that the approximate sequence generated by the QNM procedure converges to the optimal element of the optimization problem if the latter exists. In Section 3 we apply the QNM algorithm to estimating a coefficient appearing in a nonlinear parabolic partial differential equation and we prove that the assumptions, which ensure the convergence of the approximate sequence obtained by the QNM algorithm, are satisfied. Finally, we illustrate a numerical example to show the efficiency of the QNM algorithm.

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There are many papers dealing with the parameter identification problem for distributed parameter systems. Methods of solving some of those problems are listed in the following:

- (1) the gradient or conjugate gradient methods, for example, Chavent *et al.* [4], Seinfeld *et al.* [17, 16], and Yu [18], which need to compute the derivative maps of the operators described by partial differential equations;
- (2) the generalized pulse spectrum technique (GPST), for example, Chen *et al.* [5, 22];
- (3) the finite-dimensional approximate modal methods, for example, Banks *et al.* [1, 2];
- (4) the regularization methods, for example, Yu *et al.* [19, 20, 21];
- (5) the sequential quadratic programming (SQP) methods, for example, Kunisch and Sachs [13] and Huang *et al.* [9];
- (6) the Lagrangian method, for example, Ito and Kunisch [10, 11];
- (7) Quasi-Newton methods for solving unconstrained optimal control problems, for example, Kelley and Sachs [13].

Finally, it should be pointed out that proving a superlinear rate of convergence for quasi-Newton methods in infinite-dimensional spaces is not trivial as it is in finite-dimensional spaces. The Q-superlinear convergence for the above-mentioned sequence can be obtained under an additional condition assumed by Griewank [8].

The QNM algorithm presented in this paper can also be applied to identification problems of other PDS's.

2. A quasi-Newton method in Hilbert spaces

We consider the following unconstrained optimization problem (UOP):

$$\text{minimize } f(x), \quad (2.1)$$

where $f : H \rightarrow \mathbb{R}$, and H is a Hilbert space. A point x^* is called optimal for UOP if f attains a local minimum at x^* .

It is well-known that the necessary condition for x^* being optimal is

$$f'(x^*) = 0, \quad (2.2)$$

where $f'(x^*) \in \mathcal{L}(H; \mathbb{R}) \equiv H'$ is the Fréchet derivative of f at x^* , $\mathcal{L}(X; Y)$ denotes the space of bounded linear operators from a Banach space X to a Banach space Y with the operator norm and H' is the adjoint space of H .

If $f : \mathbb{R}^n \rightarrow \mathbb{R}$, one frequently uses quasi-Newton methods for solving UOP because of their high efficacy. So, we use a quasi-Newton method for solving UOP as

an iterative scheme which generates the sequences $\{x_k\}$ and $\{A_k\}$ from the formulas

$$A_k s_k = -f'(x_k), \tag{2.3}$$

$$x_{k+1} = x_k + s_k, \tag{2.4}$$

$$y_k = f'(x_{k+1}) - f'(x_k), \tag{2.5}$$

$$A_{k+1} = A_k + y_k \langle y_k, \cdot \rangle / \langle y_k, s_k \rangle - A_k s_k \langle A_k s_k, \cdot \rangle / \langle A_k s_k, s_k \rangle, \tag{2.6}$$

where x_0 and A_0 are given, $\langle \cdot, \cdot \rangle$ is the dual product between H' and H , and for any $y \in H'$ the operator $\langle y, \cdot \rangle : H \rightarrow \mathbb{R}$ is defined by

$$\langle y, \cdot \rangle x \equiv \langle y, x \rangle, \quad \forall x \in H.$$

Obviously, $A_k \in \mathcal{L}(H, H')$ and $y_k, f'(x_k) \in H'$.

The above algorithm is just a BFGS formula in a Hilbert space. If set $B_k \equiv A_k^{-1}$, then by the Sherman-Morrison-Woodbury formula, we obtain

$$B_{k+1} = B_k + \frac{(s_k - B_k y_k) \langle \cdot, s_k \rangle + s_k \langle \cdot, s_k - B_k y_k \rangle}{\langle y_k, s_k \rangle} - \frac{\langle y_k, s_k - B_k y_k \rangle}{\langle y_k, s_k \rangle^2} s_k \langle \cdot, s_k \rangle, \tag{2.7}$$

and $B_k \in \mathcal{L}(H'; H)$.

In this paper $K : H \rightarrow H'$ is the canonical isometry, that is, for any $x \in H$ $Kx \in H'$ and

$$\langle Kx, s \rangle = \langle x, s \rangle, \quad \forall s \in H,$$

(\cdot, \cdot) and $((\cdot, \cdot))$ are the inner products of H and H' , respectively.

The following definition can be found in [7].

DEFINITION 2.1. Let $\mathcal{B}_0(H; H')$ be the class of all compact operators on H and H' . For any $T \in \mathcal{B}_0(H; H')$, define

$$\|T\|_2 \equiv \left(\sum_{k=1}^{\infty} \|T\phi_k\|^2 \right)^{1/2}, \tag{2.8}$$

where $\|\cdot\|$ is the norm of H' and $\{\phi_k\}$ is a complete orthonormal family in H . If the series in the right-hand side does not converge, set $\|T\|_2 = +\infty$. Moreover, $\|T\|_2$ is independent of the choice of the complete orthonormal family $\{\phi_k\}$ in (2.8). $\|T\|_2$ is called the Schmidt norm of T . The subset of $\mathcal{B}_0(H; H')$ consisting of all T with $\|T\|_2 < +\infty$ is called the Hilbert-Schmidt class, which is denoted by $\mathcal{B}_2(H; H')$.

$\mathcal{B}_2(H; H')$ is a Banach space with the norm $\|\cdot\|_2$.

DEFINITION 2.2. For any $T \in \mathcal{B}_2(H'; H)$, define the norm

$$\|T\|_M \equiv \|KMTKM\|_2, \tag{2.9}$$

where $M : H \rightarrow H$ is positive and self-adjoint.

$\mathcal{B}_2(H'; H)$ is a Banach space with the norm $\|\cdot\|_M$.

Obviously, we have the following properties.

LEMMA 2.1. *If $T \in \mathcal{B}_2(H; H')$, $S_1 \in \mathcal{L}(H)$, and $S_2 \in \mathcal{L}(H')$, where $\mathcal{L}(X)$ is the space of bounded linear operators with the operator norm from X to X , then S_2T , $TS_1 \in \mathcal{B}_2(H; H')$ and*

$$\|TS_1\|_2 \leq \|S_1\| \|T\|_2, \quad \|S_2T\|_2 \leq \|S_2\| \|T\|_2. \tag{2.10}$$

Moreover, there are positive constants η_1 and η_2 with $\eta_2 \geq 1$ such that $\forall T \in \mathcal{B}_2(H; H')$

$$\eta_1 \|T\|_M \leq \|T\| \leq \eta_2 \|T\|_M. \tag{2.11}$$

In this paper we always suppose that the following assumptions are satisfied:

H1 $f : H \rightarrow \mathbb{R}$ is twice continuously Fréchet differentiable in $D_0 \subset H$, where D_0 is a convex and open set.

H2 There exists an $x^* \in D_0$ such that $f'(x^*) = 0$, $\|f''(x^*)\| \leq \beta$, and that

$$\|f''(x) - f''(x^*)\| \leq L \|x - x^*\|, \quad \forall x \in D_0, \tag{2.12}$$

where L is a constant.

H3 $f''(x^*)$ is selfadjoint and strictly positive in the sense that $f''(x^*)h^2 \geq \lambda \|h\|^2$, $\forall h \in H$, where $\lambda > 0$, hence $f''(x^*)$ is invertible, $[f''(x^*)]^{-1} \equiv \Lambda \in \mathcal{L}(H'; H)$ and $\|\Lambda\| \leq \theta$.

LEMMA 2.2. *Let the assumptions H1–H3 be true. In addition, assume that there are non-negative constants α_1 and α_2 such that the operator sequence $\{B_k\}$ defined by (2.7) satisfies*

$$\|B_{n+1} - \Lambda\|_M \leq (1 + \alpha_1 \sigma_n) \|B_n - \Lambda\|_M + \alpha_2 \sigma_n, \tag{2.13}$$

where $\sigma_n \equiv \max\{\|x_n - x^*\|, \|x_{n+1} - x^*\|\}$. Then for each $\gamma \in (0, 1)$ there exist $\epsilon = \epsilon(\gamma)$ and $\delta = \delta(\gamma)$, such that if B_0 and x_0 satisfy

$$\|x_0 - x^*\| \leq \epsilon, \quad \|B_0 - \Lambda\|_M \leq \delta, \tag{2.14}$$

then the sequence $\{x_n\}$ defined by the QNM algorithm is well-defined, converges to x^* , and satisfies

$$\|x_{n+1} - x^*\| \leq \gamma \|x_n - x^*\|, \quad n = 0, 1, \dots \tag{2.15}$$

Furthermore, B_n^{-1} exists and the sequences $\{\|B_n\|\}$ and $\{\|B_n^{-1}\|\}$ are uniformly bounded.

PROOF. By the assumption **H2** for any $\gamma \in (0, 1)$ we can choose $\delta = \delta(\gamma) > 0$ and $\epsilon = \epsilon(\gamma) > 0$ such that

$$6\beta(1 + \gamma)\delta\eta_2 \leq \gamma, \tag{2.16}$$

$$(2\alpha_1\delta + \alpha_2)\epsilon/(1 - \gamma) \leq \delta, \quad \epsilon < \epsilon_0, \tag{2.17}$$

$$(\theta + 4\eta_2\delta)[L\epsilon/2 + 2(1 + \gamma)^2\beta^2\eta_2\delta] \leq \gamma, \tag{2.18}$$

where ϵ_0 is so small that

$$B(x^*, \epsilon_0) \equiv \{x \in H; \|x - x^*\| < \epsilon_0\} \subset D_0.$$

It follows from (2.11) that

$$\|B_0 - \Lambda\| \leq \eta_2\|B_0 - \Lambda\|_M \leq \eta_2\delta \tag{2.19}$$

and

$$\|B_0\| \leq \|\Lambda\| + \|B_0 - \Lambda\| \leq \theta + \eta_2\delta. \tag{2.20}$$

Because $B_0 = \Lambda + (B_0 - \Lambda)$ and $\|B_0 - \Lambda\|_M \leq \delta < 1/\beta \leq \|\Lambda^{-1}\|^{-1}$, by the Banach inverse theorem, we deduce that B_0 is invertible and that

$$\|A_0\| = \|B_0^{-1}\| \leq \|\Lambda^{-1}\|/(1 - \|\Lambda^{-1}\|\|B_0 - \Lambda\|) \leq \beta/(1 - \beta\eta_2\delta) < \beta/(1 - 6\beta\eta_2\delta).$$

But by (2.16)

$$1 - 6\beta\eta_2\delta > 1 - \gamma/(1 + \gamma) = 1/(1 + \gamma),$$

so

$$\|A_0\| = \|B_0^{-1}\| < (1 + \gamma)\beta. \tag{2.21}$$

Furthermore,

$$\begin{aligned} \|A_0 - f''(x^*)\| &= \|A_0(\Lambda - B_0)f''(x^*)\| \leq \|A_0\|\|B_0 - \Lambda\|\|f''(x^*)\| \\ &\leq (1 + \gamma)\beta^2\eta_2\delta. \end{aligned} \tag{2.22}$$

It follows from the mean-value theorem that

$$\begin{aligned} \|x_1 - x^*\| &= \|(x_1 - x_0) + (x_0 - x^*)\| = \|-B_0^{-1}f'(x_0) + (x_0 - x^*)\| \\ &= \|B_0^{-1}\{-[f'(x_0) - f'(x^*) - f''(x^*)(x_0 - x^*)] \\ &\quad + [A_0 - f''(x^*)](x_0 - x^*)\}\| \\ &\leq \|B_0\| \left\{ \left\| \int_0^1 [f''(x^* + t(x_0 - x^*)) - f''(x^*)](x_0 - x^*) dt \right\| \right. \\ &\quad \left. + \|A_0 - f''(x^*)\|\|x_0 - x^*\| \right\} \\ &\leq (\theta + \eta_2\delta)[L\epsilon/2 + (1 + \gamma)\beta^2\eta_2\delta]\|x_0 - x^*\| \leq \gamma\|x_0 - x^*\|. \end{aligned} \tag{2.23}$$

Next, from (2.13), (2.14), and (2.17) we have

$$\|B_1 - \Lambda\|_M \leq (1 + \alpha_1\epsilon)\|B_0 - \Lambda\|_M + \alpha_2\epsilon \leq \delta + (\alpha_1\delta + \alpha_2)\epsilon < 2d\delta. \tag{2.24}$$

Using induction, we prove

$$\|B_k - \Lambda\| \leq 2\delta \quad \text{and} \quad \|x_{k+1} - x^*\| \leq \gamma \|x_k - x^*\|. \tag{2.25}$$

In fact, suppose that (2.25) are true for $k \leq m - 1$. By (2.13)

$$\|B_{k+1} - \Lambda\|_M \leq (1 + \alpha_1\epsilon\gamma^k)\|B_k - \Lambda\|_M + \alpha_2\epsilon\gamma^k,$$

that is,

$$\|B_{k+1} - \Lambda\|_M - \|B_k - \Lambda\|_M \leq 2\alpha_1\epsilon\gamma^k\delta + \alpha_2\epsilon\gamma^k = (2\alpha_1\delta + \alpha_2)\epsilon\gamma^k. \tag{2.26}$$

Adding (2.26) from $k = 0$ to $m - 1$, one gets

$$\begin{aligned} \|B_m - \Lambda\|_M &\leq \|B_0 - \Lambda\|_M + (2\alpha_1\delta + \alpha_2)\epsilon \sum_{k=0}^{m-1} \gamma^k \\ &< \delta + (2\alpha_1\delta + \alpha_2)\epsilon/(1 - \gamma) \leq 2\delta. \end{aligned} \tag{2.27}$$

Therefore

$$\|B_m - B_0\|_M \leq \|B_m - \Lambda\|_M + \|B_0 - \Lambda\|_M < 3\delta \quad \forall m. \tag{2.28}$$

In addition, by (2.11), (2.16), (2.21) and the above

$$\|I - B_0^{-1}B_m\| \leq \|B_0^{-1}\| \|B_m - B_0\| < 3(1 + \gamma)\beta\eta_2\delta < \gamma < 1,$$

where $I \in \mathcal{L}(H')$ is the identity operator. By the Banach theorem $(B_0^{-1}B_m)^{-1}$ exists, hence B_m is invertible. Furthermore,

$$\begin{aligned} \|A_m\| &= \|B_m^{-1}\| = \|[B_0 + (B_m - B_0)]^{-1}\| \leq \|B_0^{-1}\| \sum \|B_0^{-1}\|^k \|B_m - B_0\|^k \\ &\leq (1 + \gamma)\beta \sum [3(1 + \gamma)\beta\eta_2\delta]^k = (1 + \gamma)\beta/[1 - 3(1 + \gamma)\beta\eta_2\delta] \\ &< (1 + \gamma)\beta/(1 - 6\beta\eta_2\delta) < (1 + \gamma)^2\beta, \quad \forall m, \end{aligned} \tag{2.29}$$

that is, for any $m \in \mathbb{N}$, B_m is invertible and $\{\|B_m^{-1}\|\}$ is uniformly bounded as well. Moreover,

$$\|B_m\| \leq \|B_0\| + \|B_m - B_0\| \leq (\theta + \eta_2\delta) + 3\eta_2\delta = \theta + 4\eta_2\delta, \tag{2.30}$$

$$\begin{aligned} \|A_m - f''(x^*)\| &= \|A_m(B_m - \Lambda)f''(x^*)\| \leq \|A_m\| \|B_m - \Lambda\| \|f''(x^*)\| \\ &\leq (1 + \gamma)^2\beta\eta_2 2\delta\beta = 2(1 + \gamma)^2\beta^2\eta_2\delta. \end{aligned} \tag{2.31}$$

By the inductive assumption one has $\|x_m - x^*\| < \epsilon$ and so

$$\begin{aligned} \|x_{m+1} - x^*\| &= \|(x_{m+1} - x_m) + (x_m - x^*)\| = \|-B_m^{-1}f'(x_m) + (x_m - x^*)\| \\ &= \|B_m^{-1}\{-[f'(x_m) - f'(x^*) - f''(x^*)(x_m - x^*)] \\ &\quad + [A_m - f''(x^*)](x_m - x^*)\}\| \\ &\leq \|B_m^{-1}\|\left\{\left\|\int_0^1 [f''(x^* + t(x_m - x^*)) - f''(x^*)](x_m - x^*) dt\right\| \right. \\ &\quad \left. + \|A_m - f''(x^*)\|\|x_m - x^*\|\right\} \\ &\leq (\theta + 4\eta_2\delta)[L\epsilon/2 + 2(1 + \gamma)^2\beta^2\eta_2\delta]\|x_m - x^*\| \leq \gamma\|x_m - x^*\|. \end{aligned} \tag{2.32}$$

Furthermore,

$$\|x_{m+1} - x^*\| \leq \gamma\|x_m - x^*\| \leq \dots \leq \gamma^{m+1}\|x_0 - x^*\| < \gamma^{m+1}\epsilon < \epsilon_0. \tag{2.33}$$

Thus $\{x_m\} \subset D_0$, $x_m \rightarrow x^*$ in H , and $\{\|B_m\|\}$ and $\{\|B_m^{-1}\|\}$ are uniformly bounded.

LEMMA 2.3. Let $C, B \in \mathcal{L}(H'; H)$ be selfadjoint, $y \in H'$, $s \in H$ with $\langle y, s \rangle \neq 0$, and set

$$\bar{B} = B + \frac{(s - By)\langle \cdot, s \rangle + s\langle \cdot, s - By \rangle}{\langle y, s \rangle} - \frac{\langle y, s - By \rangle}{\langle y, s \rangle^2} s\langle \cdot, s \rangle. \tag{2.34}$$

If $M \in \mathcal{L}(H)$ is invertible and selfadjoint, then

$$\bar{E} = P^*EP + \frac{KM(s - Cy)}{\langle y, s \rangle} \langle KMs, \cdot \rangle + \frac{KMs}{\langle y, s \rangle} \langle P^*KM(s - Cy), \cdot \rangle, \tag{2.35}$$

where $E = KM(B - C)KM$, $\bar{E} = KM(\bar{B} - C)KM$, $P = I - M^{-1}K^{-1}y\langle KMs, \cdot \rangle/\langle y, s \rangle$, $I \in \mathcal{L}(H)$ is the identity operator, and P^* is the adjoint operator of P .

PROOF. Premultiplying and postmultiplying both sides of (2.34) by KM and subtract-

ing $KMCKM$, we have the simple calculation

$$\begin{aligned}
 \bar{E} &= E + \{KM[(s - Cy) - (B - C)y](KMs, \cdot) + KMs\langle KM[(s - Cy) \\
 &\quad - (B - C)y], \cdot \rangle / \langle y, s \rangle - KMs\langle y, (s - Cy) - (B - C)y \rangle \langle KMs, \cdot \rangle / \langle y, s \rangle^2 \\
 &= E - EM^{-1}K^{-1}y\langle KMs, \cdot \rangle / \langle y, s \rangle - KMs\langle EM^{-1}K^{-1}y, \cdot \rangle / \langle y, s \rangle \\
 &\quad + \{KM(s - Cy)\langle KMs, \cdot \rangle + KMs\langle KM(s - Cy), \cdot \rangle\} / \langle y, s \rangle \\
 &\quad + \langle EM^{-1}K^{-1}y, M^{-1}K^{-1}y \rangle KMs\langle KMs, \cdot \rangle / \langle y, s \rangle^2 \\
 &\quad - \langle y, s - Cy \rangle KMs\langle KMs, \cdot \rangle / \langle y, s \rangle^2 \\
 &= E[I - M^{-1}K^{-1}y\langle KMs, \cdot \rangle / \langle y, s \rangle] + KMs\{\langle EM^{-1}K^{-1}y, M^{-1}y \rangle \langle KMs, \cdot \rangle / \langle y, s \rangle \\
 &\quad - \langle EM^{-1}K^{-1}y, \cdot \rangle\} / \langle y, s \rangle + KM(s - Cy)\langle KMs, \cdot \rangle / \langle y, s \rangle \\
 &\quad + KMs\{\langle KM(s - Cy), \cdot \rangle - \langle y, s - Cy \rangle \langle KMs, \cdot \rangle / \langle y, s \rangle\} / \langle y, s \rangle.
 \end{aligned} \tag{2.36}$$

It is obvious that E and \bar{E} are selfadjoint and that

$$P^* = I - KMs\langle \cdot, M^{-1}K^{-1}y \rangle / \langle y, s \rangle \in \mathcal{L}(H'). \tag{2.37}$$

Considering the above results, from (2.36) we have

$$\begin{aligned}
 \bar{E} &= EP - KMs\langle EM^{-1}K^{-1}y - KMs\langle M^{-1}K^{-1}y, M^{-1}K^{-1}y \rangle / \langle y, s \rangle, \cdot \rangle / \langle y, s \rangle \\
 &\quad + KM(s - Cy)\langle KMs, \cdot \rangle / \langle y, s \rangle + KMs\langle KM(s - Cy) \\
 &\quad - KMs\langle KM(s - Cy), M^{-1}K^{-1}y \rangle / \langle y, s \rangle, \cdot \rangle / \langle y, s \rangle \\
 &= EP - KMs\{\langle I - KMs\langle \cdot, M^{-1}K^{-1}y \rangle / \langle y, s \rangle\}EM^{-1}K^{-1}y, \cdot \rangle / \langle y, s \rangle \\
 &\quad + KM(s - Cy)\langle KMs, \cdot \rangle / \langle y, s \rangle \\
 &\quad + KMs\{\langle I - KMs\langle \cdot, M^{-1}K^{-1}y \rangle / \langle y, s \rangle\}KM(s - Cy), \cdot \rangle / \langle y, s \rangle \\
 &= EP - KMs\langle P^*EM^{-1}K^{-1}y, \cdot \rangle / \langle y, s \rangle + KM(s - Cy)\langle KMs, \cdot \rangle / \langle y, s \rangle \\
 &\quad + KMs\langle P^*KM(s - Cy), \cdot \rangle / \langle y, s \rangle \\
 &= [I - KMs\langle M^{-1}K^{-1}y, \cdot \rangle / \langle y, s \rangle]EP \\
 &\quad + KM(s - Cy)\langle KMs, \cdot \rangle / \langle y, s \rangle + KMs\langle P^*KM(s - Cy), \cdot \rangle / \langle y, s \rangle \\
 &= P^*EP + KM(s - Cy)\langle KMs, \cdot \rangle / \langle y, s \rangle + KMs\langle P^*KM(s - Cy), \cdot \rangle / \langle y, s \rangle.
 \end{aligned}$$

LEMMA 2.4. Let $M \in \mathcal{L}(H)$ be a non-singular selfadjoint operator such that

$$\|Ms - M^{-1}K^{-1}y\| \leq \rho\|M^{-1}K^{-1}y\|, \tag{2.38}$$

where $\rho \in (0, 1/3)$, $s \in H$ and $y \in H'$ with $y \neq 0$. Then

$$(1 - \rho)\|M^{-1}K^{-1}y\|^2 \leq \langle y, s \rangle \leq (1 + \rho)\|M^{-1}K^{-1}y\|^2 \tag{2.39}$$

and for each $E \in \mathcal{B}_2(H, H')$,

$$\|E[I - M^{-1}K^{-1}y\langle KM^{-1}K^{-1}y, \cdot \rangle / \langle y, s \rangle]\|_2 \leq (1 - \mu v^2)^{1/2} \|E\|_2, \tag{2.40}$$

$$\begin{aligned} &\|E[I - M^{-1}K^{-1}y\langle KM s, \cdot \rangle / \langle y, s \rangle]\|_2 \\ &\leq \{(1 - \mu v^2)^{1/2} + \|Ms - M^{-1}K^{-1}y\| / [(1 - \rho)\|M^{-1}K^{-1}y\|]\} \|E\|_2, \end{aligned} \tag{2.41}$$

and $\forall y \in H', A \in \mathcal{L}(H, H'), s \in H$:

$$\|(y - As)\langle KM s, \cdot \rangle / \langle y, s \rangle\|_2 \leq 2\|y - As\| / \|M^{-1}K^{-1}y\|, \tag{2.42}$$

where

$$\mu = (1 - 2\rho) / (1 - \rho^2) \in (3/8, 1)$$

and

$$v = \|EM^{-1}K^{-1}y\| / (\|E\|_2 \|M^{-1}K^{-1}y\|) \in (0, 1).$$

PROOF. We have (2.39) from

$$\begin{aligned} \langle y, s \rangle &= \langle K^{-1}y, s \rangle = \langle MM^{-1}K^{-1}y, s \rangle = \langle M^{-1}K^{-1}y, Ms - M^{-1}K^{-1}y + M^{-1}K^{-1}y \rangle \\ &= \|M^{-1}K^{-1}y\|^2 + \langle M^{-1}K^{-1}y, Ms - M^{-1}K^{-1}y \rangle. \end{aligned}$$

Observing that $\forall u, v \in H$,

$$\begin{aligned} &\|E[I - u(v, \cdot)]\|_2^2 \\ &= \sum_k \| [E - Eu(v, \cdot)] \phi_k \|^2 \\ &= \sum_k \langle (E\phi_k - (v, \phi_k)Eu), E\phi_k - (v, \phi_k)Eu \rangle \\ &= \sum_k \langle (E\phi_k, E\phi_k) \rangle - 2 \sum_k (v, \phi_k) \langle (Eu, E\phi_k) \rangle + \sum_k (v, \phi_k)^2 \langle (Eu, Eu) \rangle \\ &= \|E\|_2^2 - 2 \langle (Eu, E \sum_k (v, \phi_k) \phi_k) \rangle + \|v\|^2 \|Eu\|^2 \\ &= \|E\|_2^2 - 2 \langle (Eu, Ev) \rangle + \|Eu\|^2 \|v\|^2, \end{aligned} \tag{2.43}$$

and taking $u = M^{-1}K^{-1}y / \langle y, s \rangle$ and $v = M^{-1}K^{-1}y$, we immediately obtain

$$\begin{aligned} &\|E[I - M^{-1}K^{-1}y\langle M^{-1}K^{-1}y, \cdot \rangle / \langle y, s \rangle]\|_2^2 \\ &= \|E\|_2^2 - 2 \langle EM^{-1}K^{-1}y, EM^{-1}K^{-1}y \rangle / \langle y, s \rangle \\ &\quad + \|EM^{-1}K^{-1}y\|^2 \|M^{-1}K^{-1}y\|^2 / \langle y, s \rangle^2 \\ &= \|E\|_2^2 + \{-2\langle y, s \rangle + \|M^{-1}K^{-1}y\|^2\} \|EM^{-1}K^{-1}y\|^2 / \langle y, s \rangle^2 \\ &\leq \|E\|_2^2 - (1 - 2\rho) \|EM^{-1}K^{-1}y\|^2 / [(1 - \rho)\|M^{-1}K^{-1}y\|^2] = (1 - \mu v^2) \|E\|_2^2, \end{aligned}$$

which reduces to (2.40).

Owing to (2.40), in order to establish (2.41) we need only prove

$$\begin{aligned} & \|EM^{-1}K^{-1}y[\langle KMs, \cdot \rangle - (M^{-1}K^{-1}y, \cdot)]/\langle y, s \rangle\|_2 \\ &= \|EM^{-1}K^{-1}y(M^{-1}K^{-1}y - Ms, \cdot)/\langle y, s \rangle\|_2 \\ &= \|M^{-1}K^{-1}y\| \|M^{-1}K^{-1}y - Ms\|/\langle y, s \rangle \|E\|_2 \\ &\leq \|M^{-1}K^{-1}y - Ms\|/[(1 - \rho)\|M^{-1}K^{-1}y\|] \|E\|_2. \end{aligned}$$

Inequality (2.42) can be reduced in a similar fashion. In fact,

$$\begin{aligned} \|(y - As)\langle KMs, \cdot \rangle/\langle y, s \rangle\|_2^2 &= \sum_k \|(y - As)(Ms, \phi_k)/\langle y, s \rangle\|^2 \\ &= \sum_k \|y - As\|^2 (Ms, \phi_k)^2/\langle y, s \rangle^2 = \|y - As\|^2 \|Ms\|^2/\langle y, s \rangle^2, \end{aligned}$$

so

$$\begin{aligned} \|(y - As)\langle KMs, \cdot \rangle/\langle y, s \rangle\|_2 &= \|y - As\| \|Ms\|/\langle y, s \rangle \\ &\leq \|y - As\|/\langle y, s \rangle \{\|M^{-1}K^{-1}y - Ms\| + \|M^{-1}K^{-1}y\|\} \\ &\leq \|y - As\|/[(1 - \rho)\|M^{-1}K^{-1}y\|^2] (1 + \rho)\|M^{-1}K^{-1}y\| \\ &\leq 2\|y - As\|/\|M^{-1}K^{-1}y\|. \end{aligned}$$

LEMMA 2.5. *Let M satisfy the conditions in Lemma 2.4 and let $B_0 - \Lambda \in \mathcal{B}_2(H)$. Then $\langle s_k, y_k \rangle \neq 0$, and B_{k+1} is well-defined and satisfies*

$$\begin{aligned} \|B_{k+1} - \Lambda\|_M &\leq 2(1 + \rho)\|KM\| \|s_k - \Lambda y_k\|/[(1 - \rho)^2\|M^{-1}K^{-1}y_k\|] \\ &+ \{\sqrt{1 - \mu v^2} + 5/2\|Ms_k - M^{-1}K^{-1}y_k\|/[(1 - \rho)\|M^{-1}K^{-1}y_k\|]\} \|B_k - \Lambda\|_M, \end{aligned} \tag{2.44}$$

where $\mu = (1 - 2\rho)/(1 - \rho^2) \in [3/8, 1]$ and $v = \|KM(B_k - \Lambda)y_k\|/(\|B_k - \Lambda\|_M \|M^{-1}K^{-1}y_k\|)$.

PROOF. It follows by the QNM algorithm and (2.39) that $y_k \neq 0$ and $\langle s_k, y_k \rangle \neq 0$. So B_{k+1} is well-defined by (2.7).

According to Lemma 2.3 we have

$$\begin{aligned} E_{k+1} &= P^*E_kP + KM(s_k - \Lambda y_k)\langle KMs_k, \cdot \rangle/\langle y_k, s_k \rangle \\ &+ Ms_k\langle P^*KM(s_k - \Lambda y_k), \cdot \rangle/\langle y_k, s_k \rangle, \end{aligned} \tag{2.45}$$

where $E_{k+1} = KM(B_{k+1} - \Lambda)KM$, $E_k = KM(B_k - \Lambda)KM$, and $P = I - M^{-1}K^{-1}y_k\langle KMs_k, \cdot \rangle/\langle y_k, s_k \rangle$.

Applying Lemma 2.4, we have

$$\|P^*E_kP\|_2 \leq \left\{ \sqrt{1 - \mu\nu^2} + \|Ms_k - M^{-1}K^{-1}y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|] \right\} \|P^*E_k\|_2 \leq \{1 + \|Ms_k - M^{-1}K^{-1}y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|]\} \|E_kP\|_2.$$

Hence,

$$\begin{aligned} \|P^*EP\|_2 &\leq \{1 + \|Ms_k - M^{-1}K^{-1}y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|]\} \\ &\quad \times \left\{ \sqrt{1 - \mu\nu^2} + \|Ms_k - M^{-1}K^{-1}y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|] \right\} \|E_k\|_2 \\ &\leq \left\{ \sqrt{1 - \mu\nu^2} + 5\|Ms_k - M^{-1}K^{-1}y_k\| / [2(1 - \rho)\|M^{-1}K^{-1}y_k\|] \right\} \|E_k\|_2. \end{aligned} \tag{2.46}$$

Next, we estimate the other two terms of (2.45). Since

$$\begin{aligned} \|KM(s_k - \Lambda y_k)\langle KM s_k, \cdot \rangle / \langle y_k, s_k \rangle\|_2^2 &= \sum_n \|(Ms_k, \phi_n)KM(s_k - \Lambda y_k)\|^2 / \langle y_k, s_k \rangle^2 \\ &= \sum_n (Ms_k, \phi_n)^2 \|KM(s_k - \Lambda y_k)\|^2 / \langle y_k, s_k \rangle^2 \\ &= \|Ms_k\|^2 \|KM(s_k - \Lambda y_k)\|^2 / \langle y_k, s_k \rangle^2 \end{aligned}$$

and

$$\|Ms_k\| \leq \|M^{-1}K^{-1}y_k\| + \|Ms_k - M^{-1}K^{-1}y_k\| \leq (1 + \rho)\|M^{-1}K^{-1}y_k\|,$$

we have

$$\begin{aligned} \|KM(s_k - \Lambda y_k)\langle KM s_k, \cdot \rangle / \langle y_k, s_k \rangle\|_2 &= \|Ms_k\| \|KM(s_k - \Lambda y_k)\| / \langle y_k, s_k \rangle \\ &\leq (1 + \rho)\|M^{-1}K^{-1}y_k\| \|KM\| \|s_k - \Lambda y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|^2] \\ &= (1 + \rho)\|KM\| \|s_k - \Lambda y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|]. \end{aligned} \tag{2.47}$$

On the other hand,

$$\begin{aligned} \|P^*\| = \|P\| &\leq \|I\| + \|M^{-1}K^{-1}y_k\langle KM s_k, \cdot \rangle / \langle y_k, s_k \rangle\| \\ &\leq 1 + (1 + \rho) / (1 - \rho) = 2 / (1 - \rho), \end{aligned} \tag{2.48}$$

and hence

$$\begin{aligned} \|KM s_k\langle P^*KM(s_k - \Lambda y_k), \cdot \rangle / \langle y_k, s_k \rangle\|_2 &= \|P^*KM(s_k - \Lambda y_k)\| \|Ms_k\| / \langle y_k, s_k \rangle \\ &\leq \|P^*\| \|KM\| \|s_k - \Lambda y_k\| (1 + \rho)\|M^{-1}K^{-1}y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|^2] \\ &\leq 2(1 + \rho)\|KM\| \|s_k - \Lambda y_k\| / [(1 - \rho)\|M^{-1}K^{-1}y_k\|]. \end{aligned} \tag{2.49}$$

Summing up (2.46), (2.47) and (2.49) and considering $\|B_{k+1} - \Lambda\|_M = \|KM(B_{k+1} - \Lambda)KM\|_2 = \|E_{k+1}\|_2$, we immediately obtain the estimate (2.44) from (2.45).

THEOREM 2.6. *Let assumptions **H1**, **H2**, and **H3** be satisfied. Then the sequence $\{x_n\}$ generated by the QNM algorithm is well-defined and converges to x^* provided that the initial guesses x_0 and B_0 satisfy the conditions of Lemma 2.2.*

PROOF. Because $f''(x^*)[\cdot, \cdot]$ is a bounded symmetric bilinear form on $H \times H$, there is a selfadjoint operator $T \in \mathcal{L}(H)$ such that

$$f''(x^*)[s, t] = (Ts, t), \quad \forall s, t \in H.$$

Moreover, by assumption **H3**, there exists a selfadjoint positive operator $M \in \mathcal{L}(H)$ such that $M^2 = T$. Hence

$$f''(x^*)[s, t] = (M^2s, t) = (Ms, Mt), \quad \forall s, t \in H.$$

For any $y \in H'$ we have $K^{-1}y \in H$ and

$$y - f''(x^*)s(\cdot) = (K^{-1}y - M^2s, \cdot) = K[M(M^{-1}K^{-1}y - Ms)](\cdot). \quad (2.50)$$

But, by assumption **H2** and the QNM algorithm one has

$$\begin{aligned} \|y_k - f''(x^*)s_k\| &= \|f'(x_{k+1}) - f'(x_k) - f''(x^*)s_k\| \\ &= \left\| \int_0^1 [f''(x^* + t(x_{k+1} - x_k)) - f''(x^*)](x_{k+1} - x_k) dt \right\| \\ &\leq L\|x_{k+1} - x_k\|^2/2 = L\|s_k\|^2/2. \end{aligned} \quad (2.51)$$

So

$$\begin{aligned} \|Ms_k - M^{-1}K^{-1}y_k\| &= \|M^{-1}K^{-1}[y_k - f''(x^*)s_k]\| \\ &\leq \|M^{-1}K^{-1}\|L\|s_k\|^2/2. \end{aligned} \quad (2.52)$$

Moreover, by assumption **H3** there is a $\kappa > 0$ such that

$$\|s_k\|/\kappa \leq \|M^{-1}K^{-1}y_k\| \leq \kappa\|s_k\|. \quad (2.53)$$

Summarizing (2.50), (2.51) and (2.53), we have

$$\|Ms_k - M^{-1}y_k\| \leq \rho\|M^{-1}K^{-1}y_k\|, \quad (2.54)$$

where $\rho \in (0, 1/3)$. It follows by Lemma 2.1 that $B_k - \Lambda \in \mathcal{B}_2(H', H)$. Therefore by Lemma 2.5

$$\|B_{k+1} - \Lambda\|_M \leq \left\{ \sqrt{1 - \mu\nu^2} + 5\|Ms_k - M^{-1}K^{-1}y_k\|/[2(1 - \rho)\|M^{-1}K^{-1}y_k\|] \right\} \\ \times \|B_k - \Lambda\|_M + 2(1 + \rho)\|KM\| \|s_k - \Lambda y_k\| / [(1 - \rho)^2 \|M^{-1}K^{-1}y_k\|]. \quad (2.55)$$

Considering (2.52) and (2.53), we have

$$\|s_k - \Lambda y_k\| = \|\Lambda(y_k - f''(x^*)s_k)\| \leq \|\Lambda\|L\|s_k\|^2/2 \\ \leq \theta L\kappa \|M^{-1}K^{-1}y_k\|/2\|s_k\|. \quad (2.56)$$

If we set $\alpha_1 = 5L\kappa \|M^{-1}K^{-1}\|/[4(1 - \rho)]$ and $\alpha_2 = (1 + \rho)L\kappa \|KM\|/(1 - \rho)^2$, then from (2.55) we have

$$\|B_{k+1} - \Lambda\|_M \leq (1 + \alpha_1\sigma_k)\|B_k - \Lambda\|_M + \alpha_2\sigma_k,$$

where $\sigma_k \equiv \max(\|x_{k+1} - x^*\|, \|x_k - x^*\|)$.

It follows by Lemma 2.2 that the conclusions of Theorem 2.6 are true.

From [8] we quote the following result.

THEOREM 2.7. *Assume that the requirements in Theorem 2.6 are satisfied and that $A_0 - F'(q^*)$ is compact. Then the sequence $\{x_n\}$ generated by QNM is Q-superlinear convergent, that is,*

$$\lim_{k \rightarrow \infty} \|x_{k+1} - x^*\|/\|x_k - x^*\| = 0,$$

provided $\|x_0 - x^*\|$ is sufficiently small.

3. Identification of a nonlinear parabolic system

The problem we address here is to identify the parameter q appearing in a parabolic semilinear equation

$$\partial_t u - \Delta u + q^2 u^2 = 0, \quad (x, t) \in D \equiv \Omega \times (0, T), \\ u|_{\partial\Omega} = 0, \quad u|_{t=0} = g(x), \quad (3.1)$$

based on the final measurement of the state u

$$u|_{t=T} = z(x), \quad x \in \Omega. \quad (3.2)$$

The assumptions we use in this section are as follows:

- A1. $\Omega \subset \mathbb{R}^m$ is bounded and its boundary $\partial\Omega \in C^{2+\beta}$, where $\beta \in (0, 1)$;
- A2. $g \in C^{2+\beta}(\bar{\Omega})$.

For any $q \in C^\beta(\bar{\Omega})$ it was proved in [14] that problem (3.1) has a unique classical solution, $u \in C^{2+\beta, 1+\beta/2}(\bar{D})$. So, we denote $u = u(q) = u(x, t; q)$ to show the dependence of u on q .

The problem of identification is stated as an optimization problem

$$I(q) = 1/2\|u(\cdot, T; q) - z\|_{L^2(\Omega)}^2 \rightarrow \min. \tag{3.3}$$

But the above problem is, usually, ill-posed in the Hadamard sense. Thus, we introduce a regularization term as follows:

$$J(q) = 1/2\|u(\cdot, T; q) - z\|_{L^2(\Omega)}^2 + \alpha/2\|q\|_H^2, \tag{3.4}$$

where $\alpha > 0$ is a constant, $H = H^l(\Omega)$, and the order l of the Sobolev space is chosen such that H is compactly embedded in $C^\beta(\bar{\Omega})$. For example, $l = 1$ when $m = 1$ and $l = 2$ when $m = 2$ or 3 .

It follows by [21] that the optimal parameter for the problem (3.4) converges to the optimal parameter of the problem (3.3) as $\alpha \rightarrow 0$.

THEOREM 3.1. *The function $u : H \rightarrow V \equiv C^{2+\beta, 1+\beta/2}(\bar{D})$ defined by (3.1) is infinitely differentiable, that is, $u \in C^N(H; V)$, $\forall N \in \mathbb{N} \cup \{0\}$, where $C^N(H; V)$ denotes the linear space of N -times continuously Fréchet differentiable functions on H to V . Moreover, the first Fréchet derivative $u'(\cdot) : H \rightarrow \mathcal{L}(H; V)$ and the second Fréchet derivative $u''(\cdot) : H \rightarrow \mathcal{L}(H; \mathcal{L}(H; V))$ of u at q are implicitly determined by $u'(q)h = \dot{u}$ and $u''(q)hk = \ddot{u}$, $\forall h, k \in H$, respectively, where \dot{u} and \ddot{u} are determined by the problems*

$$\begin{aligned} \partial_t \dot{u} - \Delta \dot{u} + 2q^2 u \dot{u} &= -2qu^2 h, & (x, t) \in D \\ \dot{u}|_{\partial\Omega} &= 0, & \dot{u}|_{t=0} = 0, \end{aligned} \tag{3.5}$$

and

$$\begin{aligned} \partial_t \ddot{u} - \Delta \ddot{u} + 2q^2 u \ddot{u} &= -4qu \dot{v} h - 4qu \dot{u} k - 2q^2 \dot{u} \dot{v} - 2u^2 h k, & (x, t) \in D \\ \ddot{u}|_{\partial\Omega} &= 0, & \ddot{u}|_{t=0} = 0, \end{aligned} \tag{3.6}$$

where $u = u(q)$ is determined by (3.1), $\dot{u} = u'(q)h$ and $\dot{v} = u'(q)k$ are determined by (3.5), respectively.

PROOF. First, we prove $u \in C^N(H; V)$.

Take, for example, $N = 0$. The proof is similar for any order N . Let $q, \bar{q} \in H$. Then it follows from (3.1) that $\bar{u} = u(\bar{q})$ and $u = u(q)$. Set $h = \bar{q} - q$ and $\delta u = \bar{u} - u$, so δu satisfies

$$\begin{aligned} \partial_t(\delta u) - \Delta(\delta u) + q^2(\bar{u} + u)(\delta u) &= -(\bar{q} + q)\bar{u}^2h, & (x, t) \in D, \\ (\delta u)|_{\partial\Omega} &= 0, & (\delta u)|_{t=0} = 0. \end{aligned} \tag{3.7}$$

It is obvious by [14] that $\|\delta u\|_V = O(\|h\|_H)$. Hence $u(\cdot) \in C(H; V)$.

Secondly, we prove $u'(q)h = \dot{u}$. For $q, h \in H$, there exists a unique solution $\dot{u} \in V$ to the problem (3.5). Thus, set $\bar{q} = q + h$, $u = u(q)$, $\bar{u} = u(\bar{q})$, and $\tilde{u} = \bar{u} - u - \dot{u} = \delta u - \dot{u}$. It is evident that \tilde{u} satisfies

$$\begin{aligned} \partial_t\tilde{u} - \Delta\tilde{u} + q^2(\bar{u} + u)\tilde{u} &= -q^2\dot{u}\delta u - (\bar{q} + q)(\bar{u} + u)h\delta u - u^2h^2, & (x, t) \in D, \\ \tilde{u}|_{\partial\Omega} &= 0, & \tilde{u}|_{t=0} = 0. \end{aligned}$$

It follows from (3.5) by [14] that $\dot{u} = O(\|h\|_H)$. Moreover, by the above argument we obtain $\delta u = o(1)$. Therefore, $\tilde{u} = o(\|h\|)$. Hence, $u'(q)h = \dot{u}$. It is similar to prove $u''(q)hk = \ddot{u}$.

Next, we give the following result.

THEOREM 3.2. *There exists an optimal element for the optimization problem (3.4).*

PROOF. Suppose that $\{q_n\}$ is a minimizing sequence for the optimization problem (3.4), that is,

$$J(q_n) \rightarrow h \equiv \inf_{q \in H} J(q). \tag{3.8}$$

Thus $\{q_n\}$ is bounded in H . Since H is a Hilbert space, there exists a subsequence, which is still denoted $\{q_n\}$, such that $q_n \xrightarrow{w} \bar{q}$, in H .¹ By the property of compact embeddedness of H , it follows that $q_n \xrightarrow{s} \bar{q}$ in $C^\beta(\bar{\Omega})$. Furthermore, by Theorem 3.1 we obtain that $u(q_n) \xrightarrow{s} u(\bar{q})$ in $C^{2+\beta, 1+\beta/2}(\bar{D})$.

We can write $J(q_n)$ as

$$J(q_n) = 1/2\|u(\cdot, T; q_n) - z\|_{L^2(\Omega)}^2 + \alpha/2\|q_n\|_H^2 \equiv J_1(q_n) + J_2(q_n). \tag{3.9}$$

Obviously, $J_2(q_n) \equiv \alpha/2\|q_n\|_H^2$ is convex and strongly lower semi-continuous, so it is also weakly lower semi-continuous. Letting $n \rightarrow \infty$ in (3.9) and considering (3.8), we obtain

$$J(\bar{q}) = 1/2\|u(\cdot, T; \bar{q}) - z\|_{L^2(\Omega)}^2 + \alpha/2\|\bar{q}\|_H^2 = \inf_{q \in H} J(q).$$

That is, \bar{q} is the optimal element.

¹" $x_n \xrightarrow{s} \bar{x}$ (or $x_n \xrightarrow{w} \bar{x}$), in X " means that x_n strongly (or weakly) converges to \bar{x} in X .

For calculating $J'(q)$ we have the following results.

THEOREM 3.3. *The functional $J(q)$ defined by (3.4) is twice continuously Fréchet differentiable and its first Fréchet differential $J'(q)h$ is determined by the formula*

$$J'(q)h = \langle \tilde{j}(q), h \rangle, \quad \forall h \in H, \tag{3.10}$$

where $\tilde{j}(q) \in H'$ is defined by

$$\tilde{j}(q) \equiv -2 \int_0^T qp(q)u^2(q) dt + \alpha Kq, \tag{3.11}$$

$K : H \rightarrow H'$ is the canonical isometry, $u(q) = u$ is determined by (3.1), and $p(q) = p$ is defined by the problem

$$\begin{aligned} -\partial_t p - \Delta p + 2q^2up &= 0, & (x, t) \in D, \\ p|_{\partial\Omega} &= 0, & p|_{t=T} = u(T; q) - z. \end{aligned} \tag{3.12}$$

Moreover, the second Fréchet differential $J''(q)hk$ is determined by the formula

$$\begin{aligned} J''(q)hk &= \int_0^T (-4qu\dot{u}k - 4qu\dot{v}h - 2q^2\dot{u}\dot{v} - 2u^2hk, p) dt \\ &+ \langle \dot{u}(T), \dot{v}(T) \rangle + \alpha(h, k), \quad \forall h, k \in H, \end{aligned} \tag{3.13}$$

where $\dot{u} = u'(q)h$ and $\dot{v} = u'(q)k$ are determined by (3.5) and $\langle \cdot, \cdot \rangle$ and (\cdot, \cdot) denote the inner products in $L^2(\Omega)$ and H , respectively.

PROOF. It follows from the calculation

$$\begin{aligned} J(q+h) - J(q) - \{ \langle \dot{u}(T; q), u(T; q) - z \rangle + \alpha(q, h) \} \\ = 1/2 \langle u(T; q+h) - u(T; q) - u'(q)h(T), u(T; q+h) - z \rangle \\ + 1/2 \langle u'(q)h(T), u(T; q+h) - u(T; q) \rangle \\ + 1/2 \langle u(T; q) - z, u(T; q+h) - u(T; q) - u'(q)h(T) \rangle + \alpha/2 \|h\|_H^2 \\ = o(\|h\|), \end{aligned}$$

that

$$J'(q)h = \langle \dot{u}(T; q), u(T; q) - z \rangle + \alpha(q, h), \quad \forall h \in H. \tag{3.14}$$

Consideration of $\dot{u}(0; q) = 0$ and $p(T; q) = u(T; q) - z$ and use of Green's formula lead to

$$\begin{aligned} \langle \dot{u}(T; q), u(T; q) - z \rangle &= \langle \dot{u}(T; q), p(T; q) \rangle = \int_0^T \partial_t \langle \dot{u}, p \rangle dt \\ &= \int_0^T \{ \langle \partial_t \dot{u}, p \rangle + \langle \dot{u}, \partial_t p \rangle \} dt = \int_0^T \{ \langle \partial_t \dot{u}, p \rangle + \langle \dot{u}, -\Delta p + 2q^2 up \rangle \} dt \\ &= \int_0^T \langle \partial_t \dot{u} - \Delta \dot{u} + 2q^2 u \dot{u}, p \rangle dt = \left\langle - \int_0^T 2qu^2 p dt, h \right\rangle. \end{aligned} \tag{3.15}$$

Since H is a Sobolev space of order l with $l > 0$, H is compactly embedded in $L^2(\Omega)$. If we choose $L^2(\Omega)$ to be a pivot space, that is, $L^2(\Omega) = [L^2(\Omega)]'$, then

$$H \subset L^2(\Omega) \subset H'. \tag{3.16}$$

Because K is the canonical isometry from H onto H' ,

$$\langle q, h \rangle = \langle Kq, h \rangle_{L^2(\Omega)}, \quad \forall q, h \in H. \tag{3.17}$$

Substitution of (3.15) and (3.17) into (3.14) leads to

$$J'(q)h = \left\langle -2 \int_0^T qu^2 p dt + Kq, h \right\rangle, \quad \forall h \in H. \tag{3.18}$$

From (3.11) we see that (3.10) holds.

Furthermore, by (3.14) we obtain

$$\begin{aligned} J'(q+k)h - J'(q)h &- \{ \langle u''(q)hk(T), u(T; q) - z \rangle + \langle \dot{u}(T), \dot{v}(T) \rangle + \alpha(h, k) \} \\ &= \{ \langle u'(q+k)h(T), u(T; q+k) - z \rangle + \alpha(q+k, h) \} \\ &\quad - \{ \langle u'(q)h(T), u(T; q) - z \rangle + \alpha(q, h) \} \\ &\quad - \{ \langle \ddot{u}(T), u(T; q) - z \rangle + \langle \dot{u}(T), \dot{v}(T) \rangle + \alpha(h, k) \} \\ &= \langle u'(q+k)h(T) - u'(q)h(T) - \ddot{u}(T), u(T; q) - z \rangle \\ &\quad + \langle u'(q+k)h(T), u(T; q+k) - u(T; q) - \dot{v}(T) \rangle \\ &\quad + \langle u'(q+k)h(T) - u'(q)h(T), \dot{v}(T) \rangle = o(\|h\|^2 + \|k\|^2). \end{aligned}$$

Thus, $J(q)$ is twice Fréchet differentiable and its second Fréchet differential is

$$J''(q)hk = \langle \ddot{u}(T), u(T; q) - z \rangle + \langle \dot{u}(T), \dot{v}(T) \rangle + \alpha(h, k) \quad \forall h, k \in H. \tag{3.19}$$

Using $u(T; q) - z = p(T; q)$ from (3.12) and using an argument similar to (3.15), we have

$$\begin{aligned} \langle \ddot{u}(T), u(T; q) - z \rangle &= \langle \ddot{u}(T), p(T; q) \rangle = \int_0^T \partial_t \langle \ddot{u}, p \rangle dt \\ &= \int_0^T \{ \langle \partial_t \ddot{u}, p \rangle + \langle \ddot{u}, -\Delta p + 2q^2 u p \rangle \} dt = \int_0^T \langle \partial_t \ddot{u} - \Delta \ddot{u} + 2q^2 u \ddot{u}, p \rangle dt \\ &= \int_0^T \langle -4qu\ddot{u}k - 4qu\dot{v}h - 2q^2\dot{u}\dot{v} - 2u^2hk, p \rangle dt. \end{aligned} \tag{3.20}$$

Substituting (3.20) for the first term of (3.19) we obtain immediately (3.13).

The following Lemma is quoted from [7].

LEMMA 3.4. *Let (S, Σ, μ) be a positive measure space. Then an operator A in the Hilbert space $L^2(S, \Sigma, \mu)$ is of Hilbert-Schmidt class if and only if there exists a $\mu \times \mu$ measurable function $A(\cdot, \cdot)$ on $S \times S$ such that*

$$\left\{ \iint_S \iint_S |A(x, t)|^2 \mu(ds)\mu(dt) \right\}^{1/2} < \infty \tag{3.21}$$

and such that

$$Af(s) \equiv \int_S A(s, t)f(t)\mu(dt), \quad f \in L^2(S, \Sigma, \mu), \tag{3.22}$$

for μ -almost all s . Moreover, $\|A\|_2$ is exactly equal to the finite quantity (3.21).

LEMMA 3.5. *The operator $I''(q) : L^2(\Omega) \rightarrow L^2(\Omega)$ is of Hilbert-Schmidt class, where $I(q)$ is defined by (3.3).*

PROOF. It is obvious that

$$I''(q)hk = \langle u'(T; q)k, u'(T; q)h \rangle + \langle u''(q)hk(T), u(T; q) - z \rangle \tag{3.23}$$

and

$$I''(q)h = [u'(T; q)]^* u'(q)h(T) + [u''(T; q)h]^* [u(T; q) - z], \tag{3.24}$$

where $[u'(T; q)]^*$ and $[u''(T; q)h]^*$ are the dual operators of $u'(T; q)$ and $u''(T; q)h$, respectively. Moreover, from [14] and problem (3.5), it is easy to see that

$$u'(T; q)h(x) = -2 \int_0^T \int_\Omega G(x, \xi, T, \tau)q(\xi)u^2(\xi, \tau; q)h(\xi) d\xi d\tau, \tag{3.25}$$

where $G(x, \xi, t, \tau)$ is the Green function of the problem (3.5), and hence

$$[u'(T; q)]^*k(x) = -2q(x) \int_{\Omega} \int_0^T G(\xi, x, T, \tau)u^2(x, \tau; q) d\tau k(\xi) d\xi \quad \forall k \in H. \tag{3.26}$$

Substitution of (3.25) into (3.26) and consideration of Lemma 3.4 lead to the conclusion that the operator

$$[u'(T; q)]^*u'(T; q) : L^2(\Omega) \rightarrow L^2(\Omega)$$

is of Hilbert-Schmidt class.

We need the following assumption.

A3. Suppose that there exists a $q^* \in H$ such that

$$I(q^*) = \min_{q \in H} I(q). \tag{3.27}$$

It is obvious that assumption **A3** implies $I'(q^*) = 0$ and $I''(q^*) \geq 0$. Thus,

$$J''(q^*)h^2 = I''(q^*)h^2 + \alpha(h, h) \geq \alpha \|h\|_H^2, \quad \forall h \in H, \tag{3.28}$$

that is, $J''(q^*)$ is strictly positive. Therefore, q^* solves the following operator equation

$$K^{-1}I'(q^*) = 0. \tag{3.29}$$

When α is small, instead of (3.29) we consider the equation

$$f'(q) \equiv K^{-1}J'(q) \equiv K^{-1}I'(q) + \alpha q = 0. \tag{3.30}$$

Using the QNM algorithm stated in Section 2, we obtain an approximate sequence $\{q_n\}$, and its convergence is proved in the following theorem.

THEOREM 3.6. *Let assumptions **A1**, **A2**, and **A3** be true. The sequence $\{q_n\}$ determined by the QNM algorithm is superlinearly convergent providing that q_0 and A_0 satisfy the conditions of Lemma 2.2 and that $A_0 - f''(q^*)$ is compact.*

PROOF. Under assumptions **A1–A3**, the function $f'(q)$ defined by (3.30) satisfies assumptions **H1–H3** of Section 2. Thus, by Theorem 2.7 the conclusions of Theorem 3.6 follow immediately.

In order to solve (3.30) we used the QNM algorithm for the one-dimensional case, that is, $\Omega = (0, 1)$. Moreover, we take $H = H_0^1(\Omega)$, and hence $K = -\partial^2/\partial x^2$.

Suppose that $g(x) = \sin^2 \pi x$ and that the true parameter in (3.1) is $q_{rr}(x) = x(1-x)$. Then z in (3.2) is $z = u(T; q_{rr})$. We used the Crank-Nicholson implicit finite difference method, for example see [15], to discretize (3.1) and (3.2), that is, we could, for example, replace $\partial_t u(i \Delta x, j \Delta t)$ with

$$\partial_t u(i \Delta x, (j + 1/2) \Delta t) \approx 2(u_{i,j+1/2} - u_{i,j})/\Delta t,$$

where $u_{i,j} = u(i \Delta x, j \Delta t)$ and $u_{i,j+1/2} = u(i \Delta x, (j + 1/2) \Delta t)$.

Therefore one could obtain the three-level stable approximate equations

$$\frac{1}{\Delta x^2} (u_{i+1,j+1/2} - 2u_{i,j+1/2} + u_{i-1,j+1/2}) = \frac{2}{\Delta t} (u_{i,j+1/2} - u_{i,j}) + q_i^2 u_{i,j}^2$$

and

$$\begin{aligned} & u_{i-1,j+1}/\Delta x^2 - 2(1/\Delta x^2 + 1/\Delta t)u_{i,j+1} + u_{i+1,j+1}/\Delta x^2 \\ & = -u_{i-1,j}/\Delta x^2 + 2(1/\Delta x^2 - 1/\Delta t)u_{i,j} - u_{i+1,j}/\Delta x^2 + q_i^2 u_{i,j+1/2}^2. \end{aligned}$$

We also have similar discrete equations for problem (3.12).

In this paper we took $T = 1$, $\Delta x = 0.1$, $\Delta t = 0.05$, and $N_x = 1/\Delta x$.

The computational results are summarized in Table 1, where

$$\begin{aligned} \Delta q_i &= q(i \Delta x) - q_{rr}(i \Delta x), \\ m_1 &= \sum_{i=0}^{N_x} \Delta q_i / (N_x + 1), \\ \sigma_1 &= \sqrt{\sum_{i=0}^{N_x} [\Delta q_i - m_1]^2 / N_x}, \\ s &= \sqrt{\sum_{i=0}^{N_x} [\Delta q_i]^2}, \\ y_i &= u(i \Delta x) - z(i \Delta x) \\ m_2 &= \sum_{i=0}^{N_x} y_i / (N_x + 1), \\ \sigma_2 &= \sqrt{\sum_{i=0}^{N_x} [y_i - m_2]^2 / N_x}, \\ J &= \Delta x \sum_{i=0}^{N_x} y_i^2 / 2 + \alpha \sum_{i=0}^{N_x} [q((i+1)\Delta x) - q(i\Delta x)]^2 / 2\Delta x. \end{aligned}$$

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TABLE 1. Convergence for the algorithm QNM

Iteration Times	m_1	σ_1	s	m_2	σ_2	J
1	-8.359	14.087	53.841	$1.25E-5$	$1.309E-5$	635.135
2	-2.057	4.466	38.353	$1.68E-6$	$1.724E-6$	78.117
3	0.849	$9.4E-2$	$4.37E-5$	$5.21E-7$	$7.459E-7$	$1.084E-5$
4	0.85	$9.06E-2$	$2.33E-7$	$3.22E-7$	$3.007E-7$	$1.381E-13$

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