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Semantic geometric fusion multi-object tracking and lidar odometry in dynamic environment – CORRIGENDUM

Tingchen Ma, Guolai Jiang, Yongsheng Ou and Sheng Xu

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Upon publication of this article the 2nd affiliation for author Tingchen Ma was listed incorrectly as Shenzhen College of Advanced Technology, University of Chinese Academy of Sciences, Shenzhen, 518055

The correct affiliations for Tingchen Ma are

¹Shenzhen Institute of Advanced Technology, Chinese Academy of Sciences, Shenzhen 518055, China

²University of Chinese Academy of Sciences, Beijing 100049, China

The article has been updated

Reference

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